# RANDOM MORSE FUNCTIONS AND SPECTRAL GEOMETRY 

LIVIU I. NICOLAESCU


#### Abstract

We study random Morse functions on a Riemann manifold $(M, g)$ defined as random Gaussian weighted superpositions of eigenfunctions of the Laplacian of the metric $g$. The weight is biased against the high eigenmodes in the superposition. We investigate the behavior of the expected distribution of critical values of such a random function under the singular rescaling $g \rightarrow \varepsilon^{-2} g, \varepsilon \rightarrow 0$. We first show that this behavior is independent of $(M, g)$ and the expected distribution of critical values is closely related to the expected distribution of eigenvalues of certain universal ensemble of random $(m+1) \times(m+1)$ symmetric matrices. Next we prove a central limit theorem describing what happens to the expected distribution of critical values when the dimension of the manifold is very large. Finally, we explain how to use the statistics of the Hessians of the random function for small $\varepsilon$ to recover the Riemannian geometry of $(M, g)$.


## Contents

1. Overview ..... 2
1.1. The setup ..... 2
1.2. Statements of the main results ..... 4
1.3. Organization of the paper ..... 8
2. Proofs ..... 9
2.1. A Kac-Rice type formula ..... 9
2.2. Proof of Theorem 1.2 ..... 10
2.3. Proof of Corollary 1.3 ..... 15
2.4. Proof of Theorem 1.4 ..... 15
2.5. Proof of Corollary 1.5 . ..... 18
2.6. Proof of Theorem 1.6. ..... 19
3. Some examples ..... 19
4. A probabilistic proof of the Gauss-Bonnet theorem ..... 25
Appendix A. Jets of the distance function ..... 28
Appendix B. Spectral estimates ..... 31
Appendix C. Gaussian measures and Gaussian vectors ..... 39
Appendix D. A class of random symmetric matrices ..... 41
Appendix E. Notations ..... 44
References ..... 45
[^0]
## 1. OvERVIEW

1.1. The setup. The present paper is a natural sequel to [26, 27]. Suppose that $(M, g)$ is a smooth, compact, connected Riemann manifold of dimension $m>1$. We denote by $\left|d V_{g}\right|$ the volume density on $M$ induced by $g$. We assume that the metric is normalized so that

$$
\begin{equation*}
\operatorname{vol}_{g}(M)=1 \tag{*}
\end{equation*}
$$

For any $\boldsymbol{u}, \boldsymbol{v} \in C^{\infty}(M)$ we denote by $(\boldsymbol{u}, \boldsymbol{v})_{g}$ their $L^{2}$ inner product defined by the metric $g$. The $L^{2}$-norm of a smooth function $\boldsymbol{u}$ is denoted by $\|\boldsymbol{u}\|$.

Let $\Delta_{g}: C^{\infty}(M) \rightarrow C^{\infty}(M)$ denote the scalar Laplacian defined by the metric $g$. Fix an orthonormal Hilbert basis $\left(\Psi_{k}\right)_{k \geq 0}$ of $L^{2}(M)$ consisting of eigenfunctions of $\Delta_{g}$,

$$
\Delta_{g} \Psi_{k}=\lambda_{k} \Psi_{k}, \quad\left\|\Psi_{k}\right\|=1, \quad k_{0}<k_{1} \Rightarrow \lambda_{k_{0}} \leq \lambda_{k_{1}}
$$

Fix an even Schwartz function $w: \mathbb{R} \rightarrow[0, \infty)$. For $\varepsilon>0$ we set

$$
w_{\varepsilon}(t):=w(\varepsilon t), \quad \forall t \in \mathbb{R}
$$

Consider random functions on $M$ of the form

$$
\begin{equation*}
\boldsymbol{u}_{\varepsilon}=\sum_{k \geq 0} u_{k} \Psi_{k} \tag{1.1}
\end{equation*}
$$

where the coefficients $u_{k}$ are independent Gaussian random variables with

$$
\begin{equation*}
\boldsymbol{E}\left(u_{k}\right)=0, \quad \boldsymbol{v a r}\left(u_{k}\right)=w_{\varepsilon}\left(\sqrt{\lambda_{k}}\right) . \tag{1.2}
\end{equation*}
$$

Note that

$$
\Delta^{N} \boldsymbol{u}_{\varepsilon}=\sum_{k \geq 0} \lambda_{k}^{N} u_{k} \Psi_{k}, \quad \forall N>0
$$

The fast decay of $w$, the Weyl asymptotic formula, [10, VI.4], coupled with the Borel-Cantelli lemma imply that for any $N>0$ the function $\Delta^{N} u_{\varepsilon}$ is almost surely (a.s.) in $L^{2}$. In particular, this shows that $\boldsymbol{u}_{\varepsilon}$ is a.s. smooth.

The covariance kernel of the Gaussian random function $\boldsymbol{u}_{\varepsilon}$ is given by the function

$$
\mathscr{E}^{\varepsilon}: M \times M \rightarrow \mathbb{R}, \quad \mathscr{E}^{\varepsilon}(\boldsymbol{p}, \boldsymbol{q})=\boldsymbol{E}\left(\boldsymbol{u}_{\varepsilon}(p) \boldsymbol{u}_{\varepsilon}(q)\right)=\sum_{k \geq 0} w_{\varepsilon}\left(\sqrt{\lambda_{k}}\right) \Psi_{k}(\boldsymbol{p}) \Psi_{k}(\boldsymbol{q}) .
$$

The eigenfunctions $\Psi_{k}$ satisfy the known pointwise estimates (see [22, Thm. 17.5.3] or [28, Thm 1.6.1]),

$$
\left\|\Psi_{k}\right\|_{C^{\nu}(M)}=O\left(\lambda_{k}^{\frac{m+\nu}{2}}\right) \text { as } k \rightarrow \infty, \quad \forall \nu \geq 0
$$

Since $w_{\varepsilon}$ is rapidly decresing the above estimates imply that $\mathscr{E}^{\varepsilon}$ is a smooth function. More precisely, $\mathscr{E}^{\varepsilon}$ is the Schwartz kernel of the smoothing operator

$$
w(\varepsilon \sqrt{\Delta}): C^{\infty}(M) \rightarrow C^{\infty}(M)
$$

Let us observe that if $w(0)=1$, then as $\varepsilon \searrow 0$ the function $w_{\varepsilon}$ converges uniformly on compacts to the constant function $w_{0}(t) \equiv 1$ and $w_{\varepsilon}(\sqrt{\Delta})$ converges weakly to the identity operator. The Schwartz kernel of this limiting operator is the $\delta$-function on $M \times M$ supported along the diagonal. It defines a generalized random function in the sense of [16] usually known as white noise. For this reason, we will refer to the $\varepsilon \rightarrow 0$ limits as white noise limits.

The asymptotic estimates in Proposition 2.2 show that the random field $d \boldsymbol{u}_{\varepsilon}$ satisfies the hypotheses of [1, Cor. 11.2.2] for $\varepsilon \ll 1$. Invoking [1, Lemma 11.2.11] we obtain the following technical result.
Proposition 1.1. The random function $\boldsymbol{u}_{\varepsilon}$ is almost surely Morse if $\varepsilon \ll 1$.

For any $\boldsymbol{u} \in C^{1}(M)$ we denote by $\mathbf{C r}(\boldsymbol{u}) \subset M$ the set of critical points of $\boldsymbol{u}$ and by $\boldsymbol{D}(\boldsymbol{u})$ the set of critical values ${ }^{1}$ of $\boldsymbol{u}$. To a Morse function $\boldsymbol{u}$ on $M$ we associate a Borel measure $\mu_{\boldsymbol{u}}$ on $M$ and a Borel measure $\sigma_{u}$ on $\mathbb{R}$ defined by the equalities

$$
\mu_{\boldsymbol{u}}:=\sum_{\boldsymbol{p} \in \mathbf{C r}(\boldsymbol{u})} \delta_{\boldsymbol{p}}, \quad \boldsymbol{\sigma}_{\boldsymbol{u}}:=\boldsymbol{u}_{*}\left(\mu_{\boldsymbol{u}}\right)=\sum_{t \in \mathbb{R}}\left|\boldsymbol{u}^{-1}(t) \cap \mathbf{C r}(\boldsymbol{u})\right| \delta_{t} .
$$

Observe that

$$
\operatorname{supp} \mu_{\boldsymbol{u}}=\mathbf{C r}(\boldsymbol{u}), \operatorname{supp} \boldsymbol{\sigma}_{\boldsymbol{u}}=\boldsymbol{D}(\boldsymbol{u})
$$

When $\boldsymbol{u}$ is not Morse, we set

$$
\mu_{\boldsymbol{u}}:=\left|d V_{g}\right|, \quad \sigma_{\boldsymbol{u}}=\delta_{0}=\text { the Dirac measure on } \mathbb{R} \text { concentrated at the origin. }
$$

Observe that for any Morse function $\boldsymbol{u}$ and any Borel subset $B \subset \mathbb{R}$ the number $\boldsymbol{\sigma}_{\boldsymbol{u}}(B)$ is equal to the number of critical values of $\boldsymbol{u}$ in $B$ counted with multiplicity. We will refer to $\sigma_{u}$ as the variational complexity of $\boldsymbol{u}$.

To the random function $\boldsymbol{u}_{\varepsilon}$ we associate the random (or empirical) measure $\boldsymbol{\sigma}_{\boldsymbol{u}_{\varepsilon}}$. Its expectation

$$
\boldsymbol{\sigma}^{\varepsilon}=\boldsymbol{E}\left(\sigma_{\boldsymbol{u}_{\varepsilon}}\right)
$$

is the measure on $\mathbb{R}$ uniquely determined by the equality

$$
\int_{\mathbb{R}} f(t) \boldsymbol{\sigma}^{\varepsilon}(d t)=\boldsymbol{E}\left(\int_{\mathbb{R}} f(t) d \boldsymbol{\sigma}_{\boldsymbol{u}_{\varepsilon}}(d t)\right),
$$

for any continuous and bounded function $f: \mathbb{R} \rightarrow \mathbb{R}$. In $\S 2.1$ we show that the measure $\sigma^{\varepsilon}$ is well defined for $\varepsilon \ll 1$. We will refer to it as the expected variational complexity of the random function $\boldsymbol{u}_{\varepsilon}$.
(i) Describe the white noise limit of $\boldsymbol{\sigma}^{\varepsilon}$.
(ii) Recover the geometry of $(M, g)$ from white noise statistics of the random function $\boldsymbol{u}_{\varepsilon}$.

Before we state precisely our main results we believe that it is instructive to discuss some elementary topologic and geometric features of the white noise behavior of $\boldsymbol{u}_{\varepsilon}$. For simplicity we assume that $w(0)=1$ so that $\boldsymbol{u}_{\varepsilon}$ does converge to the white noise on $M$.

It is not hard to prove that for any given Morse function $f: M \rightarrow \mathbb{R}$ and any $\hbar>0$, the probability that $\left\|f-\boldsymbol{u}_{\varepsilon}\right\|_{C^{3}}<\hbar$ is positive for $\varepsilon$ sufficiently small. If $f$ happens to be a stable Morse function, i.e., it has at most one critical point per level set, then for $\hbar$ sufficiently small, any $C^{3}$-function $g: M \rightarrow \mathbb{R}$ satisfying $\|f-g\|_{C^{3}}<\hbar$ is topologically equivalent to $f$. Thus as $\varepsilon \rightarrow 0$ the random function $\boldsymbol{u}_{\varepsilon}$ samples all the topological types of Morse functions.

The rescaling $w_{\varepsilon}$ can be alternatively realized as as follows. Consider the rescaled metric $g_{\varepsilon}:=$ $\varepsilon^{-2} g$. As $\varepsilon \rightarrow 0$ the metric $g_{\varepsilon}$ becomes flatter and flatter. The Laplacian of $g_{\varepsilon}$ is $\Delta_{g_{\varepsilon}}=\varepsilon^{2} \Delta_{g}$. Its eigevalues are $\lambda_{k}^{\varepsilon}=\varepsilon^{2} \lambda_{k}$ and the collection $\Psi_{k}^{\varepsilon}=\varepsilon^{\frac{m}{2}} \Psi_{k}$ is an orthonormal eigen-basis of $L^{2}\left(M,\left|d V_{g_{\varepsilon}}\right|\right)$. We define the random function

$$
\boldsymbol{v}_{\varepsilon}=\sum_{k \geq 0} X_{k} \sqrt{v_{k}^{\varepsilon}} \Psi_{k}^{\varepsilon},
$$

where $v_{k}^{\varepsilon}=w\left(\sqrt{\lambda_{k}^{\varepsilon}}\right)$ and the coefficients $X_{k}$ are independent Gaussian random variable with mean zero and variance 1. Observe that $\boldsymbol{v}_{\varepsilon}=\varepsilon^{\frac{m}{2}} \boldsymbol{u}_{\varepsilon}$. This shows that the expected distribution $\boldsymbol{\sigma}^{\varepsilon}(\boldsymbol{v})$ of critical values of $\boldsymbol{v}_{\varepsilon}$ is a rescaling of $\boldsymbol{\sigma}^{\varepsilon}$.

We will prove a universality result stating that as $\varepsilon \rightarrow 0$ the measures $\boldsymbol{\sigma}^{\varepsilon}(\boldsymbol{v})$ converge weakly to a finite measure on $\mathbb{R}$ that depends only the moments of $w$ of orders $m-1, m+1, m+3$, but it is

[^1]independent of the metric $g$. This limit measure is intimately related to the distribution of eigenvalues in a Gaussian Wigner ensemble of symmetric $(m+1) \times(m+1)$-matrices.

The probabilistic reconstruction of the metric in the white noise limit is possible, but it is a rather delicate undertaking. The metric $g$ together with the Riemann tensor can be recovered from the statistics of the Hessians of $\boldsymbol{u}_{\varepsilon}$. However, this is not a first-order phenomenon. We extract the information about the metric by looking at finer scales and investigating the rate of convergence of $\boldsymbol{u}_{\varepsilon}$ to the white noise.
1.2. Statements of the main results. Observe that if $\boldsymbol{u}: M \rightarrow \mathbb{R}$ is a fixed Morse function and $c$ is a constant, then

$$
\mathbf{C r}(c+\boldsymbol{u})=\mathbf{C r}(\boldsymbol{u}), \quad \mu_{c+\boldsymbol{u}}=\mu_{\boldsymbol{u}},
$$

but

$$
\boldsymbol{D}(\boldsymbol{u}+c)=c+\boldsymbol{D}(\boldsymbol{u}), \quad \boldsymbol{\sigma}_{\boldsymbol{u}+c}=\delta_{c} * \boldsymbol{\sigma}_{\boldsymbol{u}},
$$

where $*$ denotes the convolution of two finite measures on $\mathbb{R}$. More generally, if $X$ is a scalar random variable with probability distribution $\nu_{X}$, then the expected variational complexity of the random function $X+\boldsymbol{u}$ is the measure $\boldsymbol{E}\left(\boldsymbol{\sigma}_{X+\boldsymbol{u}}\right)=\nu_{X} * \boldsymbol{\sigma}_{\boldsymbol{u}}$. If $\boldsymbol{u}$ itself is a random function, and $X$ is independent of $\boldsymbol{u}$, then the above equality can be rephrased as

$$
\boldsymbol{E}\left(\boldsymbol{\sigma}_{X+\boldsymbol{u}}\right)=\nu_{X} * \boldsymbol{E}\left(\boldsymbol{\sigma}_{u}\right) .
$$

In particular, if the distribution $\nu_{X}$ is a Gaussian, then the measure $\boldsymbol{E}\left(\boldsymbol{\sigma}_{u}\right)$ is uniquely determined by the measure $\boldsymbol{E}\left(\boldsymbol{\sigma}_{X+\boldsymbol{u}}\right)$ since the convolution with a Gaussian is an injective operation. It turns out that it is easier to understand the statistics of the variational complexity of a perturbation of $\boldsymbol{u}_{\varepsilon}$ with an independent Gaussian variable of cleverly chosen variance.

To explain this perturbation we need to introduce several quantities that will play a crucial role throughout this paper. We define

$$
\begin{align*}
s_{m}:=\frac{1}{(2 \pi)^{m}} \int_{\mathbb{R}^{m}} w(|x|) d x, d_{m} & :=\frac{1}{(2 \pi)^{m}} \int_{\mathbb{R}^{m}} x_{1}^{2} w(|x|) d x, \\
h_{m} & :=\frac{1}{(2 \pi)^{m}} \int_{\mathbb{R}^{m}} x_{1}^{2} x_{2}^{2} w(|x|) d x . \tag{1.3}
\end{align*}
$$

The statistical relevance of these quantities is explained in Proposition 2.2. If we set

$$
\begin{equation*}
I_{k}(w):=\int_{0}^{\infty} w(r) r^{k} d r \tag{1.4}
\end{equation*}
$$

then we deduce from [25, Lemma 9.3.10]

$$
\begin{gathered}
(2 \pi)^{m} s_{m}=\left(\int_{|x|=1} d A(x)\right) I_{m-1}(w)=\frac{2 \pi^{\frac{m}{2}}}{\Gamma\left(\frac{m}{2}\right)} I_{m-1}(w), \\
(2 \pi)^{m} d_{m}=\left(\int_{|x|=1} x_{1}^{2} d A(x)\right) I_{m+1}(w)=\frac{\pi^{\frac{m}{2}}}{\Gamma\left(1+\frac{m}{2}\right)} I_{m+1}(w)=\frac{2 \pi^{\frac{m}{2}}}{m \Gamma\left(\frac{m}{2}\right)} I_{m+1}(w), \\
(2 \pi)^{m} h_{m}=\left(\int_{|x|=1} x_{1}^{2} x_{2}^{2} d A(x)\right) I_{m+1}(w)=\frac{\pi^{\frac{m}{2}}}{2 \Gamma\left(2+\frac{m}{2}\right)} I_{m+3}(w)=\frac{2 \pi^{\frac{m}{2}}}{m(m+2) \Gamma\left(\frac{m}{2}\right)} I_{m+3}(w) .
\end{gathered}
$$

We set

$$
q_{m}:=\frac{s_{m} h_{m}}{d_{m}^{2}}=\frac{m}{m+2} \frac{I_{m-1}(w) I_{m+3}(w)}{I_{m+1}(w)^{2}} .
$$

The Cauchy inequality implies that $I_{m+1}(w)^{2} \leq I_{m-1}(w) I_{m+3}(w)$ so that

$$
\begin{equation*}
q_{m} \geq \frac{m}{m+2} \tag{1.5}
\end{equation*}
$$

The sequence $\left(q_{m}\right)_{m \geq 1}$ can be interpreted as a measure of the tail of $w$, the heavier the tail, the faster the growth of $q_{m}$ as $m \rightarrow \infty$; see Section 3 for more details. We set

$$
r_{n}:=\max \left(1, q_{n}\right)
$$

and define $\boldsymbol{\omega}_{m} \geq 0$ via the equality

$$
\begin{equation*}
r_{n}=\frac{\left(s_{m}+\boldsymbol{\omega}_{m}\right) h_{m}}{d_{m}^{2}} \tag{1.6}
\end{equation*}
$$

Set $\check{s}_{m}:=s_{m}+\boldsymbol{\omega}_{m}$ so that

$$
\begin{equation*}
r_{m}=\frac{\check{s}_{m} h_{m}}{d_{m}^{2}} \tag{1.7}
\end{equation*}
$$

Observe that

$$
\begin{equation*}
\boldsymbol{\omega}_{m}=0 \Longleftrightarrow q_{m}=r_{m} \geq 1 \Longleftrightarrow \check{s}_{m}=s_{m} \tag{1.8}
\end{equation*}
$$

while the inequality (1.5) implies that

$$
\begin{equation*}
\lim _{m \rightarrow \infty} \frac{\boldsymbol{\omega}_{m}}{s_{m}}=0, \quad \lim _{m \rightarrow \infty} \frac{r_{m}}{q_{m}}=1 \tag{1.9}
\end{equation*}
$$

Choose a scalar Gaussian random variable $X_{\boldsymbol{\omega}(\varepsilon)}$ with mean 0 and variance $\boldsymbol{\omega}(\varepsilon):=\boldsymbol{\omega}_{m} \varepsilon^{-m}$ independent of $\boldsymbol{u}_{\varepsilon}$ and form the new random function

$$
\check{\boldsymbol{u}}_{\varepsilon}:=X_{\boldsymbol{\omega}(\varepsilon)}+\boldsymbol{u}_{\varepsilon} .
$$

We denote by $\check{\boldsymbol{\sigma}}^{\varepsilon}$ the expected variational complexity of $\check{\boldsymbol{u}}_{\varepsilon}$. We have the equality

$$
\begin{equation*}
\check{\boldsymbol{\sigma}}^{\varepsilon}=\boldsymbol{\gamma}_{\boldsymbol{\omega}(\varepsilon)} * \boldsymbol{\sigma}^{\varepsilon}, \quad \boldsymbol{\omega}(\varepsilon):=\boldsymbol{\omega}_{m} \varepsilon^{-m} \tag{1.10}
\end{equation*}
$$

Note that

$$
\boldsymbol{N}^{\varepsilon}=\int_{\mathbb{R}} \check{\boldsymbol{\sigma}}^{\varepsilon}(d t)=\int_{\mathbb{R}} \boldsymbol{\sigma}^{\varepsilon}(d t)
$$

is the expected number of critical points of the random function $\boldsymbol{u}_{\varepsilon}$.
To formulate our main results we need to briefly recall some terminology from random matrix theory.

For $v \in(0, \infty)$ and $N$ a positive integer we denote by $\mathrm{GOE}_{N}^{v}$ the space $\mathrm{Sym}_{N}$ of real, symmetric $N \times N$ matrices $A$ equipped with a Gaussian measure such that the entries $a_{i j}$ are independent, zero-mean, normal random variables with variances

$$
\boldsymbol{v} \boldsymbol{\operatorname { a r }}\left(a_{i i}\right)=2 v, \quad \boldsymbol{\operatorname { v a r }}\left(a_{i j}\right)=v, \quad \forall 1 \leq i<j \leq N
$$

Let $\rho_{N, v}: \mathbb{R} \rightarrow \mathbb{R}$ be the normalized correlation function of $\mathrm{GOE}_{N}^{v}$. It is uniquely determined by the equality

$$
\int_{\mathbb{R}} f(\lambda) \rho_{N, v}(\lambda) d \lambda=\frac{1}{N} \boldsymbol{E}_{\mathrm{GOE}_{N}^{v}}(\operatorname{tr} f(A))
$$

for any continuous bounded function $f: \mathbb{R} \rightarrow \mathbb{R}$. The function $\rho_{N, v}(\lambda)$ also has a probabilistic interpretation: for any Borel set $B \subset \mathbb{R}$ the expected number of eigenvalues in $B$ of a random $A \in \mathrm{GOE}_{N}^{v}$ is equal to

$$
N \int_{B} \rho_{N, v}(\lambda) d \lambda
$$

For any $t>0$ we denote by $\mathcal{R}_{t}: \mathbb{R} \rightarrow \mathbb{R}$ the rescaling map $\mathbb{R} \ni x \mapsto t x \in \mathbb{R}$. If $\mu$ is a Borel measure on $\mathbb{R}$ we denote by $\left(\mathcal{R}_{t}\right)_{*} \mu$ its pushforward via the rescaling map $\mathcal{R}_{t}$. The celebrated Wigner semicircle theorem, [3, 24], states that as $N \rightarrow \infty$ the rescaled probability measures

$$
\left(\mathcal{R}_{\frac{1}{\sqrt{N}}}\right)_{*}\left(\rho_{N, v}(\lambda) d \lambda\right)
$$

converge weakly to the semicircle measure given by the density

$$
\rho_{\infty, v}(\lambda):=\frac{1}{2 \pi v} \times \begin{cases}\sqrt{4 v-\lambda^{2}}, & |\lambda| \leq \sqrt{4 v} \\ 0, & |\lambda|>\sqrt{4 v}\end{cases}
$$

We can now state the main results of this paper.
Theorem 1.2. For $v>0$ and $N \in \mathbb{Z}_{>0}$ we set

$$
\theta_{N, v}^{ \pm}(x):=\rho_{N, v}(x) e^{ \pm \frac{x^{2}}{4 v}}
$$

(a) There exists a constant $C=C_{m}(w)$ that depends only on the dimension $m$ and the weight $w$ such that

$$
\begin{equation*}
\boldsymbol{N}^{\varepsilon} \sim C_{m}(w) \varepsilon^{-m}(1+O(\varepsilon)) \text { as } \varepsilon \rightarrow 0 \tag{1.11}
\end{equation*}
$$

More precisely

$$
\begin{equation*}
C_{m}(w)=2^{\frac{m+4}{2}} r_{m}^{\frac{1}{2}}\left(\frac{h_{m}}{2 \pi d_{m}}\right)^{\frac{m}{2}} \Gamma\left(\frac{m+3}{2}\right) \int_{\mathbb{R}}\left(\gamma_{r_{m}-1} * \theta_{m+1, r_{m}}^{+}\right)(y) \gamma_{1}(y) d y \tag{1.12}
\end{equation*}
$$

(b) As $\varepsilon \searrow 0$ the rescaled probability measures

$$
\frac{1}{\boldsymbol{N}^{\varepsilon}}\left(\mathcal{R} \frac{1}{\sqrt{s_{m} \varepsilon^{-m}}}\right)_{*} \check{\boldsymbol{\sigma}}^{\varepsilon}
$$

converge weakly to a probability measure $\check{\boldsymbol{\sigma}}_{m}$ on $\mathbb{R}$ uniquely determined by the proportionalities

$$
\begin{align*}
\check{\boldsymbol{\sigma}}_{m} \propto & \left(\gamma_{r_{m}-1} * \theta_{m+1, r_{m}}^{+}(y)\right) \gamma_{1}(y) d y  \tag{1.13a}\\
& \propto \theta_{m+1, \frac{1}{r_{m}}}^{-} * \gamma_{\frac{r_{m-1}}{r_{m}}}(y) d y . \tag{1.13b}
\end{align*}
$$

One immediate consequence of Theorem 1.2 is the following universality result.
Corollary 1.3 (Universality). As $\varepsilon \rightarrow 0$ the rescaled probability measures

$$
\frac{1}{\boldsymbol{N}^{\varepsilon}}\left(\mathcal{R} \frac{1}{\sqrt{s_{m} \varepsilon^{-m}}}\right)_{*} \boldsymbol{\sigma}^{\varepsilon}
$$

converge weakly to a probability measure $\boldsymbol{\sigma}_{m}$ uniquely determined by the convolution equation

$$
\gamma{\overline{\omega_{\overline{\boldsymbol{j}}}^{m}}} * \boldsymbol{\sigma}_{m}=\check{\boldsymbol{\sigma}}_{m} .
$$

Wigner's semicircle theorem [3, Thm. 2.1.1] allows us extract a bit more about the measure $\boldsymbol{\sigma}_{m}$ for $m$ large, provided that the behavior of $w$ at $\infty$ is not too chaotic.

Theorem 1.4 (Central limit theorem). Suppose that the weight $w$ is regular, i.e., the sequence $r_{m}$ has a limit $r \in[1, \infty]$ as $m \rightarrow \infty$. Then

$$
\lim _{m \rightarrow \infty} \boldsymbol{\sigma}_{m}=\gamma_{\frac{r+1}{r}}
$$

The above regularity assumption on $w$ is a constraint on the behavior of its tail. In Section 3 we describe many classes of regular weights.

Corollary 1.5. As $m \rightarrow \infty$ we have

$$
\begin{align*}
C_{m}(w) & \sim \frac{8}{\sqrt{\pi m}} \Gamma\left(\frac{m+3}{2}\right)\left(\frac{h_{m}}{\pi d_{m}}\right)^{\frac{m}{2}}  \tag{1.14}\\
& \sim \frac{8}{\sqrt{\pi m}} \Gamma\left(\frac{m+3}{2}\right)\left(\frac{2 I_{m+3}(w)}{\pi(m+2) I_{m+1}(w)}\right)^{\frac{m}{2}} .
\end{align*}
$$

Following [1, §12.2] we define symmetric ( 0,2 )-tensor $h^{\varepsilon}$ on $M$ given by

$$
\begin{equation*}
h^{\varepsilon}(X, Y)=\frac{\varepsilon^{m+2}}{d_{m}} \boldsymbol{E}\left(X \boldsymbol{u}_{\varepsilon}(\boldsymbol{p}), Y \boldsymbol{u}_{\varepsilon}(\boldsymbol{p})\right), \quad \forall \boldsymbol{p} \in M, \quad X, Y \in \operatorname{Vect}(M), \tag{1.15}
\end{equation*}
$$

where $X u$ denotes the derivative of the smooth function $u$ along the vector field $X$.
Theorem 1.6 (Probabilistic reconstruction of the geometry). (a) For $\varepsilon>0$ sufficiently small the tensor $h^{\varepsilon}$ defines a Riemann metric on $M$.
(b) For any vector fields $X, Y$ on $M$ the function $h^{\varepsilon}(X, Y)$ converges uniformly to $g(X, Y)$ as $\varepsilon \searrow 0$.
(c) The sectional curvatures on $h^{\varepsilon}$ converge to the corresponding sectional curvatures of $g$ as $\varepsilon \searrow 0$.

The $C^{0}$-convergence of $h^{\varepsilon}$ towards the original metric was observed earlier by S. Zelditch [33]. The main novelty of the above theorem is part (c) which, as detailed below, implies the $C^{\infty}$ convergence of $h^{\varepsilon}$ to $g$. However, the qualitative jump from $C^{0}$ to $C^{\infty}$-converges requires requires a substantial amount of extra work.

The construction of the metrics $h^{\varepsilon}$ generalizes the construction in [6]. Note that for any $\varepsilon>0$ we have a smooth map $\boldsymbol{\Xi}_{\varepsilon}: M \rightarrow L^{2}(M, g)$

$$
M \ni p \mapsto \boldsymbol{\Xi}_{\varepsilon}(\boldsymbol{p}):=\left(\frac{\varepsilon^{m+2}}{d_{m}}\right)^{\frac{1}{2}} \sum_{k \geq 0} w_{\varepsilon}\left(\sqrt{\lambda_{k}}\right)^{\frac{1}{2}} \Psi_{k}(\boldsymbol{p}) \Psi_{k} \in L^{2}(M, g) .
$$

Then $h^{\varepsilon}$ is the pullback by $\boldsymbol{\Xi}_{\varepsilon}$ of the Euclidean metric on $L^{2}(M, g)$. Let us point out that [6, Thm.5] is a special case of Theorem 1.6 corresponding to the weight $w(t)=e^{-t^{2}}$.

Theorem 1.6 coupled with the results in [30] imply that the metrics $h^{\varepsilon}$ converge $C^{1, \alpha}$ to $g$ as $\varepsilon \searrow 0$. The convergence of sectional curvatures coupled with the technique of harmonic coordinates in $[2,30]$ can be used to bootstrap this convergence to a $C^{\infty}$ convergence.

We should add a few words about the nontrivial analytic result hiding behind Theorem 1.6. Fix a point $\boldsymbol{p} \in M$ and normal coordinates $\left(x^{i}\right)$ at $\boldsymbol{p}$. The techniques pioneered by L. Hörmander [20] show that as $\varepsilon \searrow 0$ we have the 1 -term asymptotic expansions

$$
\begin{align*}
& \boldsymbol{E}\left(\partial_{x^{i} x^{i}}^{2} \boldsymbol{u}^{\varepsilon}(\boldsymbol{p}) \cdot \partial_{x^{j} x^{j}}^{2} \boldsymbol{u}^{\varepsilon}(\boldsymbol{p})\right)=h_{m} \varepsilon^{-(m+4)}\left(1+O\left(\varepsilon^{2}\right)\right),  \tag{1.16a}\\
& \boldsymbol{E}\left(\partial_{x^{i} x^{j}}^{2 i} \boldsymbol{u}^{\varepsilon}(\boldsymbol{p}) \cdot \partial_{x^{i} x^{j}}^{2} \boldsymbol{u}^{\varepsilon}(\boldsymbol{p})\right)=h_{m} \varepsilon^{-(m+4)}\left(1+O\left(\varepsilon^{2}\right)\right) . \tag{1.16b}
\end{align*}
$$

These and several other similar 1-term asymptotic expansions involving the Schwartz kernel of $w_{\varepsilon}(\sqrt{\Delta})$ (see Proposition 2.2) are responsible for Theorem 1.2. All these 1-term expansions are independent of the background metric $g$. Note that (1.16a) and (1.16b) imply the estimate

$$
\begin{equation*}
\boldsymbol{E}\left(\partial_{x^{i} x^{i} \boldsymbol{u}}^{2} \boldsymbol{\varepsilon}^{\varepsilon}(\boldsymbol{p}) \cdot \partial_{x^{j} x^{j}}^{2} \boldsymbol{u}^{\varepsilon}(\boldsymbol{p})\right)-\boldsymbol{E}\left(\partial_{x^{i} x^{j}}^{2} \boldsymbol{u}^{\varepsilon}(\boldsymbol{p}) \cdot \partial_{x^{i} x^{j}}^{2} \boldsymbol{u}^{\varepsilon}(\boldsymbol{p})\right)=O\left(\varepsilon^{-(m+2)}\right) . \tag{1.17}
\end{equation*}
$$

Theorem 1.6 is equivalent with the following sharp estimate

$$
\boldsymbol{E}\left(\partial_{x^{i} x^{i}}^{2} \boldsymbol{u}^{\varepsilon}(\boldsymbol{p}) \cdot \partial_{x^{j} x^{j}}^{2} \boldsymbol{u}^{\varepsilon}(\boldsymbol{p})\right)-\boldsymbol{E}\left(\partial_{x^{i} x^{j}}^{2} \boldsymbol{u}^{\varepsilon}(\boldsymbol{p}) \cdot \partial_{x^{i} x^{j}}^{2} \boldsymbol{u}^{\varepsilon}(\boldsymbol{p})\right) \sim d_{m} K_{i j}^{g}(\boldsymbol{p}) \varepsilon^{-(m+2)},
$$

where $K_{i j}^{g}(\boldsymbol{p})$ denotes the sectional curvature of $g$ at $\boldsymbol{p}$ along the 2 -plane spanned by $\partial_{x^{i}}, \partial_{x^{j}}$ which is an obvious refinement of (1.17). In fact the proof of Theorem 1.6 is based on refinements of the 1 -term expansions (1.16a) and (1.16b) to 2 -term expansions.

The Schwartz kernel of $w_{\varepsilon}(\sqrt{\Delta})$ has a complete asymptotic expansion as $\varepsilon \searrow 0$ (see [31, Chap. XII]) and Theorem 1.6 shows that the metric $g$ becomes visible, and it is completely detected by the second order terms of this expansion.

The convergence of the metrics $h^{\varepsilon}$ leads to a cute probabilistic proof of the Gauss-Bonnet theorem for the original metric $g$ (and thus for any metric on $M$ ). Here is the simple principle behind this proof.

Assume for simplicity that $M$ is oriented and $m=\operatorname{dim} M$ is even. To a Morse function $f$ we associate the signed measure

$$
\nu_{f}=\sum_{d f(\boldsymbol{p})=0}(-1)^{\operatorname{ind}(f, p)} \delta_{\boldsymbol{p}}
$$

where ind $(f, \boldsymbol{p})$ denotes the Morse index of the critical point of the Morse function $f$. The PoincaréHopf theorem implies that

$$
\begin{equation*}
\int_{M} \nu_{f}=\chi(M) \tag{1.18}
\end{equation*}
$$

We can also think of $\nu_{f}$ as a degree 0 -current. The random function $\boldsymbol{u}^{\varepsilon}$ then determines a random 0 -current $\nu_{\boldsymbol{u}^{\varepsilon}}$. It turns out (see Section 4) that the expectation of this current is a current represented by a rather canonical top degree form. More precisely, we prove that,

$$
\begin{equation*}
\boldsymbol{E}\left(\nu_{\boldsymbol{u}^{\varepsilon}}\right)=\boldsymbol{e}_{h^{\varepsilon}}(M), \tag{1.19}
\end{equation*}
$$

where $\boldsymbol{e}_{h^{\varepsilon}}(M)$ is the Euler form defined by the metric $h^{\varepsilon}$ which appears in the Gauss-Bonnet theorem. Using (1.18) we conclude that

$$
\int_{M} \boldsymbol{e}_{h^{\varepsilon}}(M)=\int_{M} \boldsymbol{E}\left(\nu_{\boldsymbol{u}^{\varepsilon}}\right)=\boldsymbol{E}\left(\int_{M} \nu_{\boldsymbol{u}^{\varepsilon}}\right)=\chi(M),
$$

and as a bonus we the Gauss-Bonnet theorem for the metric $h^{\varepsilon}$. Letting $\varepsilon \rightarrow 0$ we obtain the GaussBonnet theorem for $g$ since $h^{\varepsilon} \rightarrow g$ and $\boldsymbol{e}_{h^{\varepsilon}}(M) \rightarrow \boldsymbol{e}_{g}(M)$. In particular, this shows that $\boldsymbol{E}\left(\nu_{\boldsymbol{u}^{\varepsilon}}\right)$ converges in the sense of currents to $\boldsymbol{e}_{g}(M)$, the Euler form determined by the metric $g$.
1.3. Organization of the paper. The remainder of the paper is organized as follows. Section 2 contains the proofs of the main results. In Section 3 we describe many classes of regular weights $w$. In particular, these examples show that the limit $r=\lim _{m \rightarrow \infty} r_{m}$ that appears in the statement of Theorem 1.4 can have any value in $[1, \infty]$. Section 4 contains the details of the probabilistic proof of the Gauss-Bonnet theorem outlined above.

To smooth the flow of the presentation we gathered in Appendices various technical results used in the proofs of the mains results. In Appendix A we describe the jets of order $\leq 4$ along the diagonal of the square of the distance function dist $_{g}: M \times M \rightarrow \mathbb{R}$ which are needed in the two-step asymptotics of the correlation kernel. This feels like a classical problem, but since precise references are hard to find we decided to include a complete proof. Our approach, based on the Hamilton-Jacobi equation satisfied by the distance function is similar to the one sketched in [12, p.281-282].

In Appendix B we describe small $\varepsilon$ asymptotics of the Schwartz kernel of $w(\varepsilon \sqrt{\Delta})$ using a strategy pioneered L. Hörmander [20] based on a good understanding of the short time asymptotics for the wave kernel. For the applications in this paper we need explicit, two-term asymptotics. The central
result in this appendix is Theorem B. 5 which seems to be new. It essentially states that the Riemann curvature tensor can be recovered from the second order terms of the $\varepsilon \rightarrow 0$ asymptotics of the fourth order jets along the diagonal of the Schwartz kernel of $w(\varepsilon \sqrt{\Delta})$.

In Appendix C we describe a few facts about Gaussian measures in a coordinate free form suitable for our geometric purposes. Finally, in Appendix D we have collected some facts about a family of Gaussian random symmetric matrices that appear in our investigation.

## 2. Proofs

2.1. A Kac-Rice type formula. The key result behind Theorem 1.2 is a Kac-Rice type result which we intend to discuss in some detail in this section. This result gives an explicit, yet quite complicated description of the measure $\check{\boldsymbol{\sigma}}^{\varepsilon}$. More precisely, for any Borel subset $B \subset \mathbb{R}$, the Kac-Rice formula provides an integral representation of $\check{\boldsymbol{\sigma}}^{\varepsilon}(B)$ of the form

$$
\check{\boldsymbol{\sigma}}^{\varepsilon}(B)=\int_{M} f_{\varepsilon, B}(\boldsymbol{p})\left|d V_{g}(\boldsymbol{p})\right|,
$$

for some integrable function $f_{\varepsilon, B}: M \rightarrow \mathbb{R}$. The core of the Kac-Rice formula is an explicit probabilistic description of the density $f_{\varepsilon, B}$.

Fix a point $\boldsymbol{p} \in M$. This determines three Gaussian random variables

$$
\begin{equation*}
\check{\boldsymbol{u}}_{\varepsilon}(\boldsymbol{p}) \in \mathbb{R}, d \check{\boldsymbol{u}}_{\varepsilon}(\boldsymbol{p}) \in T_{\boldsymbol{p}}^{*} M, \quad \operatorname{Hess}_{\boldsymbol{p}}\left(\check{\boldsymbol{u}}_{\varepsilon}\right) \in \operatorname{Sym}\left(T_{\boldsymbol{p}} M\right), \tag{RV}
\end{equation*}
$$

where $\operatorname{Hess}_{\boldsymbol{p}}\left(\check{\boldsymbol{u}}_{\varepsilon}\right): T_{\boldsymbol{p}} M \times T_{\boldsymbol{p}} M \rightarrow \mathbb{R}$ is the Hessian of $\boldsymbol{u}_{\boldsymbol{\omega}}$ at $\boldsymbol{p}$ defined in terms of the Levi-Civita connection of $g$ and then identified with a symmetric endomorphism of $T_{p} M$ using again the metric $g$. More concretely, if $\left(x^{i}\right)_{1 \leq i \leq m}$ are $g$-normal coordinates at $\boldsymbol{p}$, then

$$
\operatorname{Hess}_{\boldsymbol{p}}\left(\check{\boldsymbol{u}}_{\varepsilon}\right) \partial_{x^{j}}=\sum_{i=1}^{m} \partial_{x^{i} x^{j}}^{2} \check{\boldsymbol{u}}_{\varepsilon}(\boldsymbol{p}) \partial_{x^{i}} .
$$

For $\varepsilon>0$ sufficiently small the covariance form of the Gaussian random vector $d \check{\boldsymbol{u}}_{\varepsilon}(\boldsymbol{p})$ is positive definite; see (2.3). We can identify it with a symmetric, positive definite linear operator

$$
\boldsymbol{S}\left(d \check{\boldsymbol{u}}_{\varepsilon}(\boldsymbol{p})\right): T_{\boldsymbol{p}} M \rightarrow T_{\boldsymbol{p}} M .
$$

More concretely, if $\left(x^{i}\right)_{1 \leq i \leq m}$ are $g$-normal coordinates at $\boldsymbol{p}$, then we identify $\boldsymbol{S}\left(d \check{\boldsymbol{u}}_{\varepsilon}(\boldsymbol{p})\right)$ with a $m \times m$ real symmetric matrix whose $(i, j)$-entry is given by

$$
\boldsymbol{S}_{i j}\left(d \check{\boldsymbol{u}}_{\varepsilon}(\boldsymbol{p})\right)=\boldsymbol{E}\left(\partial_{x_{i}} \check{\boldsymbol{u}}_{\varepsilon}(\boldsymbol{p}) \cdot \partial_{x^{j}} \check{\boldsymbol{u}}_{\varepsilon}(\boldsymbol{p})\right) .
$$

Theorem 2.1. Fix a Borel subset $B \subset \mathbb{R}$. For any $\boldsymbol{p} \in M$ define

$$
f_{\varepsilon, B}(\boldsymbol{p}):=\left(\operatorname{det}\left(2 \pi \boldsymbol{S}\left(\check{\boldsymbol{u}}_{\varepsilon}(\boldsymbol{p})\right)\right)^{-\frac{1}{2}} \boldsymbol{E}\left(\left|\operatorname{det} \operatorname{Hess}_{\boldsymbol{p}}\left(\check{\boldsymbol{u}}_{\varepsilon}\right)\right| \cdot \boldsymbol{I}_{B}\left(\check{\boldsymbol{u}}_{\varepsilon}(\boldsymbol{p})\right) \mid d \check{\boldsymbol{u}}_{\varepsilon}(\boldsymbol{p})=0\right),\right.
$$

where $\boldsymbol{E}(\operatorname{var} \mid$ cons $)$ stands for the conditional expectation of the variable var given the constraint cons. Then

$$
\begin{equation*}
\check{\boldsymbol{\sigma}}^{\varepsilon}(B)=\int_{M} f_{\varepsilon, B}(\boldsymbol{p})\left|d V_{g}(\boldsymbol{p})\right| . \tag{2.1}
\end{equation*}
$$

This theorem is a special case of a general result of Adler-Taylor, [1, Cor. 11.2.2]. Proposition 2.2 below shows that the technical assumptions in [1, Cor. 11.2.2] are satisfied if $\varepsilon \ll 1$.

For the above theorem to be of any use we need to have some concrete information about the Gaussian random variables ( $R V$ ). All the relevant statistical invariants of these variables can be extracted from the covariance kernel of the random function $\check{\boldsymbol{u}}_{\varepsilon}$.
2.2. Proof of Theorem 1.2. Fix $\varepsilon>0$. For any $\boldsymbol{p} \in M$, we have the centered Gaussian random vector

$$
\left(\check{\boldsymbol{u}}_{\varepsilon}(\boldsymbol{p}), d \check{\boldsymbol{u}}_{\varepsilon}(\boldsymbol{p}), \operatorname{Hess}_{\boldsymbol{p}}\left(\check{\boldsymbol{u}}_{\varepsilon}\right)\right) \in \mathbb{R} \oplus T_{\boldsymbol{p}}^{*} M \oplus \operatorname{Sym}\left(T_{\boldsymbol{p}} M\right) .
$$

We fix normal coordinates $\left(x^{i}\right)_{1 \leq i \leq m}$ at $\boldsymbol{p}$ and we can identify the above Gaussian vector with the centered Gaussian vector

$$
\left(\check{\boldsymbol{u}}_{\varepsilon}(\boldsymbol{p}),\left(\partial_{x^{i}} \check{\boldsymbol{u}}_{\varepsilon}(p)\right)_{1 \leq i \leq m}, \partial_{x^{i} x^{j}}^{2}\left(\check{\boldsymbol{u}}_{\varepsilon}(\boldsymbol{p})\right)_{1 \leq i, j \leq m}\right) \in \mathbb{R} \oplus \mathbb{R}^{m} \oplus \operatorname{Sym}_{m} .
$$

The next result is the key reason the Kac-Rice formula can be applied succesfully to the problem at hand.

Proposition 2.2. For any $1 \leq i, j, k, \ell \leq m$ we have the uniform in $\boldsymbol{p}$ asymptotic estimates as $\varepsilon \searrow 0$

$$
\begin{gather*}
\boldsymbol{E}\left(\check{\boldsymbol{u}}_{\varepsilon}(p)^{2}\right)=\check{s}_{m} \varepsilon^{-m}\left(1+O\left(\varepsilon^{2}\right)\right),  \tag{2.2a}\\
\boldsymbol{E}\left(\partial_{x^{i}} \check{\boldsymbol{u}}_{\varepsilon}(\boldsymbol{p}) \partial_{x^{j}} \check{\boldsymbol{u}}_{\varepsilon}(\boldsymbol{p})\right)=d_{m} \varepsilon^{-(m+2)} \delta_{i j}\left(1+O\left(\varepsilon^{2}\right)\right),  \tag{2.2b}\\
\boldsymbol{E}\left(\partial_{x^{i} x^{j}}^{2} \check{\boldsymbol{u}}_{\varepsilon}(\boldsymbol{p}) \partial_{x^{k} x}^{2} \check{u}_{\varepsilon}(\boldsymbol{p})\right)=h_{m} \varepsilon^{-(m+4)}\left(\delta_{i j} \delta_{k \ell}+\delta_{i k} \delta_{j \ell}+\delta_{i \ell} \delta_{j k}\right)\left(1+O\left(\varepsilon^{2}\right)\right),  \tag{2.2c}\\
\boldsymbol{E}\left(\check{\boldsymbol{u}}_{\varepsilon}(\boldsymbol{p}) \partial_{x^{i} x j}^{2} \check{\boldsymbol{u}}_{\varepsilon}(\boldsymbol{p})\right)=-d_{m} \varepsilon^{-(m+2)} \delta_{i j}\left(1+O\left(\varepsilon^{2}\right)\right),  \tag{2.2d}\\
\boldsymbol{E}\left(\check{\boldsymbol{u}}_{\varepsilon}(p) \partial_{x^{i} i} \check{\boldsymbol{u}}_{\varepsilon}(\boldsymbol{p})\right)=O\left(\varepsilon^{-m}\right), \boldsymbol{E}\left(\partial_{x^{i}} \check{\boldsymbol{u}}_{\varepsilon}(\boldsymbol{p}) \partial_{x^{j} x^{j}}^{2} \check{\boldsymbol{u}}_{\varepsilon}(\boldsymbol{p})\right)=O\left(\varepsilon^{-(m+2)}\right), \tag{2.2e}
\end{gather*}
$$

where $\check{s}_{m}=s_{m}+\boldsymbol{\omega}_{m}$ and the constants $s_{m}, d_{m}, h_{m}$ are defined by (1.3).

Proof. Denote by $\check{\mathscr{E} \varepsilon}$ the covariance kernel of the random function

$$
\check{\boldsymbol{u}}_{\varepsilon}=X_{\boldsymbol{\omega}(\varepsilon)}+\boldsymbol{u}_{\varepsilon} .
$$

Note that

$$
\check{\mathscr{E}}^{\varepsilon}(\boldsymbol{p}, \boldsymbol{q})=\boldsymbol{\omega}(\varepsilon)+\mathscr{E}^{\varepsilon}(\boldsymbol{p}, \boldsymbol{q})=\boldsymbol{\omega}_{m} \varepsilon^{-m}+\mathscr{E}^{\varepsilon}(\boldsymbol{p}, \boldsymbol{q})
$$

Fix a point $\boldsymbol{p}_{0} \in M$ and normal coordinates at $\boldsymbol{p}_{0}$ defined in an open neighborhood $\mathcal{O}_{0}$ of $\boldsymbol{p}_{0}$. The restriction of $\mathscr{E} \varepsilon$ to $\mathcal{O}_{0} \times \mathcal{O}_{0}$ can be viewed as a function $\mathscr{E}^{\mathscr{E}}(x, y)$ defined in an open neighborhood of $(0,0)$ in $\mathbb{R}^{m} \times \mathbb{R}^{m}$. For any $\alpha,\left.\beta \in\left(\mathbb{Z}_{\geq 0}\right)\right|^{m}$ we have

$$
\boldsymbol{E}\left(\partial_{x}^{\alpha} \check{\boldsymbol{u}}_{\varepsilon}\left(\boldsymbol{p}_{0}\right) \partial_{x}^{\beta}\left(\check{\boldsymbol{u}}_{\varepsilon}\right)\right)=\partial_{x}^{\alpha} \partial_{y}^{\beta} \check{\mathscr{E}}^{\varepsilon}(x, y)_{x=y=0} .
$$

Proposition 2.2 is now a consequence of the spectral estimates (B.1) in Appendix B.
From the estimate (2.2b) we deduce that

$$
\begin{equation*}
\boldsymbol{S}\left(d \check{\boldsymbol{u}}_{\varepsilon}(\boldsymbol{p})\right)=d_{m} \varepsilon^{-(m+2)}\left(\mathbb{1}_{m}+O\left(\varepsilon^{2}\right)\right), \tag{2.3}
\end{equation*}
$$

so that

$$
\begin{equation*}
\sqrt{\left|\operatorname{det} \boldsymbol{S}\left(\check{\boldsymbol{u}}_{\varepsilon}(p)\right)\right|}=\left(d_{m}\right)^{\frac{m}{2}} \varepsilon^{-\frac{m(m+2)}{2}}\left(1+O\left(\varepsilon^{2}\right)\right) \text { as } \varepsilon \rightarrow 0 . \tag{2.4}
\end{equation*}
$$

Consider the rescaled random vector

$$
\left(\check{s}^{\varepsilon}, v^{\varepsilon}, H^{\varepsilon}\right)=:=\left(\varepsilon^{\frac{m}{2}} \check{\boldsymbol{u}}_{\varepsilon}(\boldsymbol{p}), \varepsilon^{\frac{m+2}{2}} d \check{\boldsymbol{u}}_{\varepsilon}(p), \varepsilon^{\frac{m+4}{2}} \nabla^{2} \check{\boldsymbol{u}}_{\varepsilon}(\boldsymbol{p})\right) .
$$

Form Proposition 2.2 we deduce the following (uniform in $\boldsymbol{p}$ ) estimates as $\varepsilon \searrow 0$.

$$
\begin{gather*}
\boldsymbol{E}\left(\left(\check{s}^{\varepsilon}\right)^{2}\right)=\check{s}_{m}\left(1+O\left(\varepsilon^{2}\right)\right),  \tag{2.5a}\\
\boldsymbol{E}\left(v_{i}^{\varepsilon} v_{j}^{\varepsilon}\right)=d_{m} \delta_{i j}\left(1+O\left(\varepsilon^{2}\right)\right),  \tag{2.5b}\\
\boldsymbol{E}\left(H_{i j}^{\varepsilon} H_{k l}^{\varepsilon}\right)=h_{m}\left(\delta_{i j} \delta_{k \ell}+\delta_{i k} \delta_{j \ell}+\delta_{i \ell} \delta_{j k}\right)\left(1+O\left(\varepsilon^{2}\right)\right),  \tag{2.5c}\\
\boldsymbol{E}\left(\check{s}^{\varepsilon} H_{i j}^{\varepsilon}\right)=-d_{m} \delta_{i j}\left(1+O\left(\varepsilon^{2}\right)\right),  \tag{2.5d}\\
\boldsymbol{E}\left(\breve{s}^{\varepsilon} v_{i}^{\varepsilon}\right)=O(\varepsilon), \quad \boldsymbol{E}\left(v_{i}^{\varepsilon} H_{j k}^{\varepsilon}\right)=O(\varepsilon) . \tag{2.5e}
\end{gather*}
$$

The probability distribution of the variable $s^{\varepsilon}$ is

$$
d \gamma_{\check{s}_{m}(\varepsilon)}(x)=\frac{1}{\sqrt{2 \pi \check{s}_{m}(\varepsilon)}} e^{-\frac{x^{2}}{2 \check{s}_{m}(\varepsilon)}}|d x|
$$

where

$$
\check{s}_{m}(\varepsilon)=\check{s}_{m}+O(\varepsilon)
$$

Fix a Borel set $B \subset \mathbb{R}$. We have

$$
\begin{array}{r}
\boldsymbol{E}\left(\left|\operatorname{det} \nabla^{2} \check{\boldsymbol{u}}_{\varepsilon}(\boldsymbol{p})\right| \boldsymbol{I}_{B}\left(\check{\boldsymbol{u}}_{\varepsilon}(\boldsymbol{p})\right) \mid d \check{\boldsymbol{u}}_{\varepsilon}(\boldsymbol{p})=0\right)=\varepsilon^{-\frac{m(m+4)}{2}} \boldsymbol{E}\left(\left.\left|\operatorname{det} H^{\varepsilon}\right| \boldsymbol{I} \varepsilon_{\varepsilon^{\frac{m}{2}} B}\left(\check{s}^{\varepsilon}\right) \right\rvert\, v^{\varepsilon}=0\right) \\
=\varepsilon^{-\frac{m(m+4)}{2}} \underbrace{\int_{\varepsilon^{\frac{m}{2}} B} \boldsymbol{E}\left(\left|\operatorname{det} H^{\varepsilon}\right| \mid \check{s}^{\varepsilon}=x, v^{\varepsilon}=0\right) \frac{e^{-\frac{x^{2}}{2 s_{m}(\varepsilon)}}}{\sqrt{2 \pi \check{s}_{m}(\varepsilon)}}|d x|}_{=: q_{\varepsilon, \boldsymbol{p}}\left(\varepsilon^{\frac{m}{2}} B\right)} \tag{2.6}
\end{array}
$$

Using (2.4) and (2.6) we deduce from Theorem 2.1 that

$$
\check{\boldsymbol{\sigma}}^{\varepsilon}(B)=\varepsilon^{-m}\left(\frac{1}{2 \pi d_{m}}\right)^{\frac{m}{2}} \int_{M} q_{\varepsilon, \boldsymbol{p}}\left(\varepsilon^{\frac{m}{2}} B\right) \rho_{L}(\boldsymbol{p})\left|d V_{g}(\boldsymbol{p})\right|,
$$

where $\rho_{\varepsilon}: M \rightarrow \mathbb{R}$ is a function that satisfies the uniform in $\boldsymbol{p}$ estimate

$$
\begin{equation*}
\rho_{\varepsilon}(p)=1+O(\varepsilon) \text { as } \varepsilon \rightarrow 0 \tag{2.7}
\end{equation*}
$$

Hence

$$
\begin{equation*}
\varepsilon^{m}\left(\mathcal{R}_{\varepsilon} \frac{m}{2}\right)_{*} \check{\boldsymbol{\sigma}}^{\varepsilon}(B)=\left(\frac{1}{2 \pi d_{m}}\right)^{\frac{m}{2}} \int_{M} q_{\varepsilon, \boldsymbol{p}}(B) \rho_{\varepsilon}(\boldsymbol{p})\left|d V_{g}(\boldsymbol{p})\right| \tag{2.8}
\end{equation*}
$$

To continue the computation we need to investigate the behavior of $q_{\varepsilon, \boldsymbol{p}}(B)$ as $\varepsilon$. More concretely, we need to elucidate the nature of the Gaussian vector

$$
\left(H^{\varepsilon} \mid \check{s}^{\varepsilon}=x, v^{\varepsilon}=0\right)
$$

We will achieve this via the regression formula (C.3). For simplicity we set

$$
Y^{\varepsilon}:=\left(\check{s}^{\varepsilon}, v^{\varepsilon}\right) \in \mathbb{R} \oplus \mathbb{R}^{m}
$$

The components of $Y^{\varepsilon}$ are

$$
Y_{0}^{\varepsilon}=\check{s}^{\varepsilon}, \quad Y_{i}^{\varepsilon}=v_{i}^{\varepsilon}, \quad 1 \leq i \leq m
$$

Using (2.5a), (2.5b) and (2.5e) we deduce that for any $1 \leq i, j \leq m$ we have

$$
\boldsymbol{E}\left(Y_{0}^{\varepsilon} Y_{i}^{\varepsilon}\right)=\check{s}_{m} \delta_{0 i}+O(\varepsilon), \quad \boldsymbol{E}\left(Y_{i}^{\varepsilon} Y_{j}^{\varepsilon}\right)=d_{m} \delta_{i j}+O\left(\varepsilon^{2}\right)
$$

If $\boldsymbol{S}\left(Y^{\varepsilon}\right)$ denotes the covariance operator of $Y$, then we deduce that

$$
\begin{equation*}
\boldsymbol{S}\left(Y^{\varepsilon}\right)_{0, i}^{-1}=\frac{1}{\check{s}_{m}} \delta_{0 i}+O(\varepsilon), \quad \boldsymbol{S}\left(Y^{\varepsilon}\right)_{i j}^{-1}=\frac{1}{d_{m}} \delta_{i j}+O(\varepsilon) \tag{2.9}
\end{equation*}
$$

We now need to compute the covariance operator $\boldsymbol{\operatorname { C o v }}\left(H^{\varepsilon}, Y^{\varepsilon}\right)$. To do so we equip $\operatorname{Sym}_{m}$ with the inner product

$$
(A, B)=\operatorname{tr}(A B), \quad A, B \in \operatorname{Sym}_{m}
$$

The space $\mathrm{Sym}_{m}$ has a canonical orthonormal basis

$$
\widehat{E}_{i j}, \quad 1 \leq i \leq j \leq m
$$

where

$$
\widehat{\boldsymbol{E}}_{i j}= \begin{cases}\boldsymbol{E}_{i j}, & i=j \\ \frac{1}{\sqrt{2}} \boldsymbol{E}_{i j}, & i<j\end{cases}
$$

and $\boldsymbol{E}_{i j}$ denotes the symmetric matrix nonzero entries only at locations $(i, j)$ and $(j, i)$ and these entries are equal to 1 . Thus a matrix $A \in \operatorname{Sym}_{m}$ can be written as

$$
A=\sum_{i \leq j} a_{i j} \boldsymbol{E}_{i j}=\sum_{i \leq j} \hat{a}_{i j} \widehat{\boldsymbol{E}}_{i j},
$$

where

$$
\widehat{a}_{i j}= \begin{cases}a_{i j}, & i=j, \\ \sqrt{2} a_{i j}, & i<j .\end{cases}
$$

The covariance operator $\boldsymbol{\operatorname { C o v }}\left(H^{\varepsilon}, Y \varepsilon\right)$ is a linear map

$$
\operatorname{Cov}\left(H^{\varepsilon}, Y^{\varepsilon}\right): \mathbb{R} \oplus \mathbb{R}^{m} \rightarrow \operatorname{Sym}_{m}
$$

given by

$$
\boldsymbol{\operatorname { C o v }}\left(H^{\varepsilon}, Y^{\varepsilon}\right)\left(\sum_{\alpha=0}^{m} y_{\alpha} \boldsymbol{e}_{\alpha}\right)=\sum_{i<j, \alpha} \boldsymbol{E}\left(\widehat{H}_{i j}^{\varepsilon} Y_{\alpha}^{\varepsilon}\right) y_{\alpha} \widehat{\boldsymbol{E}}_{i j}=\sum_{i<j, \alpha} \boldsymbol{E}\left(H_{i j}^{\varepsilon} Y_{\alpha}^{\varepsilon}\right) y_{\alpha} \boldsymbol{E}_{i j},
$$

where $\boldsymbol{e}_{0}, \boldsymbol{e}_{1}, \ldots, \boldsymbol{e}_{m}$ denotes the canonical orthonormal basis in $\mathbb{R} \oplus \mathbb{R}^{m}$. Using (2.5d) and (2.5e) we deduce that

$$
\begin{equation*}
\boldsymbol{\operatorname { C o v }}\left(H^{\varepsilon}, Y^{\varepsilon}\right)\left(\sum_{\alpha=0}^{m} y_{\alpha} \boldsymbol{e}_{\alpha}\right)=-y_{0} d_{m} \mathbb{1}_{m}+O(\varepsilon) \tag{2.10}
\end{equation*}
$$

We deduce that the transpose $\boldsymbol{\operatorname { C o v }}\left(H^{\varepsilon}, Y^{\varepsilon}\right)^{\vee}$ satisfies

$$
\begin{equation*}
\boldsymbol{\operatorname { C o v }}\left(H^{\varepsilon}, Y^{\varepsilon}\right)^{\vee}\left(\sum_{i \leq j} \hat{\boldsymbol{a}}_{i j} \widehat{\boldsymbol{E}}_{i j}\right)=-d_{m} \operatorname{tr}(A) \boldsymbol{e}_{0}+O(\varepsilon) . \tag{2.11}
\end{equation*}
$$

Set

$$
Z^{\varepsilon}:=\left(H^{\varepsilon} \mid \check{s}^{\varepsilon}=x, v^{\varepsilon}=0\right)-\boldsymbol{E}\left(H^{\varepsilon}| |^{\varepsilon}=x, v^{\varepsilon}=0\right) .
$$

Above, $Z^{\varepsilon}$ is a centered Gaussian random matrix with covariance operator

$$
\boldsymbol{S}\left(Z^{\varepsilon}\right)=\boldsymbol{S}\left(H^{\varepsilon}\right)-\boldsymbol{C o v}\left(H^{\varepsilon}, Y^{\varepsilon}\right) \boldsymbol{S}\left(Y^{\varepsilon}\right)^{-1} \boldsymbol{C o v}\left(H^{\varepsilon}, Y^{\varepsilon}\right)^{\vee} .
$$

This means that

$$
\boldsymbol{E}\left(\widehat{z}_{i j}^{\varepsilon} \widetilde{z}_{k \ell}^{\varepsilon}\right)=\left(\widehat{\boldsymbol{E}}_{i j}, \boldsymbol{S}\left(Z^{\varepsilon}\right) \widehat{\boldsymbol{E}}_{k \ell}\right) .
$$

Using (2.9), (2.10) and (2.11) we deduce that

$$
\begin{gathered}
\boldsymbol{\operatorname { C o v }}\left(H^{\varepsilon}, Y^{\varepsilon}\right) \boldsymbol{S}\left(Y^{\varepsilon}\right)^{-1} \boldsymbol{\operatorname { C o v }}\left(H^{\varepsilon}, Y^{\varepsilon}\right)^{\vee}\left(\sum_{i \leq j} \hat{a}_{i j} \widehat{\boldsymbol{E}}_{i j}\right)=\frac{d_{m}^{2}}{\grave{s}_{m}} \operatorname{tr}(A) \mathbb{1}_{m}+O(\varepsilon) \\
\boldsymbol{E}\left(\left(z_{i j}^{\varepsilon}\right)^{2}\right)=h_{m}+O(\varepsilon), \boldsymbol{E}\left(z_{i i}^{\varepsilon} z_{j j}^{\varepsilon}\right)=h_{m}-\frac{d_{m}^{2}}{\breve{s}_{m}}+O(\varepsilon), \quad \forall i<j, \\
\boldsymbol{E}\left(\left(z_{i i}^{\varepsilon}\right)^{2}\right)=3 h_{m}-\frac{d_{m}^{2}}{\check{s}_{m}}+O(\varepsilon), \quad \forall i
\end{gathered}
$$

and

$$
\boldsymbol{E}\left(z_{i j}^{\varepsilon} z_{k \ell}^{\varepsilon}\right)=O(\varepsilon), \quad \forall i<j, \quad k \leq \ell, \quad(i, j) \neq(k, \ell) .
$$

We can rewrite these equalities in the compact form

$$
\boldsymbol{E}\left(z_{i j}^{\varepsilon} z_{k \ell}^{\varepsilon}\right)=\left(h_{m}-\frac{d_{m}^{2}}{s_{m}}\right) \delta_{i j} \delta_{k \ell}+h_{m}\left(\delta_{i k} \delta_{j \ell}+\delta_{i \ell} \delta_{j k}\right)+O(\varepsilon) .
$$

Note that

$$
h_{m}-\frac{d_{m}^{2}}{\check{s}_{m}} \stackrel{(1.7)}{=} \frac{r_{m}-1}{r_{m}} h_{m} .
$$

We set

$$
\kappa_{m}:=\frac{\left(r_{m}-1\right)}{2 r_{m}},
$$

so that

$$
\boldsymbol{E}\left(z_{i j}^{\varepsilon} z_{k \ell}^{\varepsilon}\right)=2 \kappa_{m} h_{m} \delta_{i j} \delta_{k \ell}+h_{m}\left(\delta_{i k} \delta_{j \ell}+\delta_{i \ell} \delta_{j k}\right)+O(\varepsilon) .
$$

Using (C.4) we deduce that

$$
\begin{equation*}
\boldsymbol{E}\left(H^{\varepsilon} \mid \check{s}^{\varepsilon}=x, v^{\varepsilon}=0\right)=\boldsymbol{\operatorname { C o v }}\left(H^{\varepsilon}, Y^{\varepsilon}\right) \boldsymbol{S}\left(Y^{\varepsilon}\right)^{-1}\left(x \boldsymbol{e}_{0}\right)=-\frac{x d_{m}}{\check{s}_{m}} \mathbb{1}_{m}+O(\varepsilon) \tag{2.12}
\end{equation*}
$$

We deduce that the Gaussian random matrix $\left(H^{\varepsilon} \mid \check{s}^{\varepsilon}=x, v^{\varepsilon}=0\right)$ converges uniformly in $\boldsymbol{p}$ as $\varepsilon \rightarrow 0$ to the random matrix $A-\frac{x}{r_{m}(m+4)} \mathbb{1}_{m}$, where $A$ belongs to the Gaussian ensemble $\mathrm{Sym}_{m}^{2 \kappa h_{m}, h_{m}}$ described in Appendix D. Thus

$$
\begin{gathered}
\lim _{\varepsilon \rightarrow 0} q_{\varepsilon, \boldsymbol{p}}(B)=q_{\infty}(B):=\int_{B} \boldsymbol{E}_{\mathrm{Sym}_{m}^{2 \kappa_{m} h_{m}, h_{m}}}\left(\left|\operatorname{det}\left(A-\frac{x d_{m}}{\check{s}_{m}} \mathbb{1}_{m}\right)\right|\right) \frac{e^{-\frac{x^{2}}{2 s_{m}}}}{\sqrt{2 \pi \check{s}_{m}^{2}}} d x \\
=\left(h_{m}\right)^{\frac{m}{2}} \int_{B} \boldsymbol{E}_{\mathrm{Sym}_{m}^{2 \kappa_{m}, 1}}\left(\left|\operatorname{det}\left(A-\frac{x}{\check{s}_{m} \sqrt{h_{m}}} \mathbb{1}_{m}\right)\right|\right) \frac{e^{-\frac{x^{2}}{2 \check{s}_{m}}}}{\sqrt{2 \pi \check{s}_{m}}} d x \\
=\left(h_{m}\right)^{\frac{m}{2}} \int_{\left(\check{s}_{m}\right)^{-\frac{1}{2}}}{ }_{B} \boldsymbol{E}_{\mathrm{Sym}_{m}^{2 \kappa_{m}, 1}}\left(\left|\operatorname{det}\left(A-\alpha_{m} y \mathbb{1}_{m}\right)\right|\right) \frac{e^{-\frac{y^{2}}{2}}}{\sqrt{2 \pi}} d x,
\end{gathered}
$$

where

$$
\alpha_{m}=\frac{d_{m}}{\sqrt{\breve{s}_{m} h_{m}}} \stackrel{(1.7)}{=} \frac{1}{\sqrt{r_{m}}} .
$$

This proves that

$$
\lim _{\varepsilon \searrow 0} \mathcal{R}_{\left(\check{s}_{m}\right)^{-\frac{1}{2}}} q_{\varepsilon, \boldsymbol{p}}(B)=\left(h_{m}\right)^{\frac{m}{2}} \underbrace{\int_{B} \boldsymbol{E}_{\delta_{m}^{2 \kappa_{m}, 1}}\left(\left|\operatorname{det}\left(A-\frac{y}{\sqrt{r_{m}}} \mathbb{1}_{m}\right)\right|\right) \frac{e^{-\frac{y^{2}}{2}}}{\sqrt{2 \pi}} d y}_{=: \mu_{m}(B)} .
$$

Using the last equality, the normalization assumption $(*)$ and the estimate (2.7) in (2.8) we conclude

$$
\begin{equation*}
\left(\mathcal{R}_{\left(\check{s}_{m} \varepsilon^{-m}\right)^{-\frac{1}{2}}}\right)_{*} \check{\sigma}^{\varepsilon}(B)=\varepsilon^{-m}\left(\left(\frac{h_{m}}{2 \pi d_{m}}\right)^{\frac{m}{2}} \mu_{m}(B)+O(\varepsilon)\right) \text { as } \varepsilon \rightarrow 0 \tag{2.13}
\end{equation*}
$$

In particular

$$
\begin{equation*}
\boldsymbol{N}^{\varepsilon}=\varepsilon^{-m}\left(\left(\frac{h_{m}}{2 \pi d_{m}}\right)^{\frac{m}{2}} \mu_{m}(\mathbb{R})+O(\varepsilon)\right) \text { as } \varepsilon \rightarrow 0 \tag{2.14}
\end{equation*}
$$

Observe that the density of $\mu_{m}$ is

$$
\begin{equation*}
\frac{d \mu_{m}}{d y}=\boldsymbol{E}_{\operatorname{Sym}_{m}^{2 \kappa_{m}, 1}}\left(\left|\operatorname{det}\left(A-\frac{y}{\sqrt{r_{m}}} \mathbb{1}_{m}\right)\right|\right) \frac{e^{-\frac{y^{2}}{2}}}{\sqrt{2 \pi}} \tag{2.15}
\end{equation*}
$$

$\left(\tilde{A}=\sqrt{r_{m}} A\right)$

$$
=r_{m}^{-\frac{m}{2}} \boldsymbol{E}_{\operatorname{Sym}_{m}^{2 \kappa_{m} r_{m}, r_{m}}}\left(\left|\operatorname{det}\left(\tilde{A}-y \mathbb{1}_{m}\right)\right|\right) \frac{e^{-\frac{y^{2}}{2}}}{\sqrt{2 \pi}}
$$

$\left(2 k_{m} r_{m}=r_{m}-1\right)$

$$
\begin{gathered}
\stackrel{(D .7 b)}{=} r_{m}^{-\frac{m}{2}} 2^{\frac{3}{2}}\left(2 r_{m}\right)^{\frac{m+1}{2}} \Gamma\left(\frac{m+3}{2}\right)\left(\gamma_{r_{m}-1} * \theta_{m+1, r_{m}}^{+}\right)(y) \gamma_{1}(y) \\
\quad=2^{\frac{m+4}{2}} r_{m}^{\frac{1}{2}} \Gamma\left(\frac{m+3}{2}\right)\left(\gamma_{r_{m}-1} * \theta_{m+1, r_{m}}^{+}\right)(y) \gamma_{1}(y)
\end{gathered}
$$

This proves part (a) and (1.13a) in Theorem 1.2. To prove (1.13b) we distinguish two cases.
Case 1. $r_{m}>1$. From Lemma D. 2 we deduce that

$$
\begin{gather*}
\boldsymbol{E}_{\mathrm{Sym}_{m}^{2 \kappa_{m}, 1}}\left(\left|\operatorname{det}\left(A-\frac{y}{\sqrt{r_{m}}} \mathbb{1}_{m}\right)\right|\right) \\
=2^{\frac{m+3}{2}} \Gamma\left(\frac{m+3}{2}\right) \frac{1}{\sqrt{2 \pi \kappa_{m}}} \int_{\mathbb{R}} \rho_{m+1,1}(\lambda) e^{-\frac{1}{4 \tau_{m}^{2}}\left(\lambda-\left(\tau_{m}^{2}+1\right) \frac{y}{\sqrt{r_{m}}}\right)^{2}+\frac{\left(\tau_{m}^{2}+1\right) y^{2}}{4 r_{m}}} d \lambda \tag{2.16}
\end{gather*}
$$

where

$$
\tau_{m}^{2}:=\frac{\kappa_{m}}{\kappa_{m}-1}=\frac{r_{m}-1}{r_{m}+1}
$$

Thus

$$
\begin{aligned}
\frac{d \mu_{m}}{d y} & =2^{\frac{m+3}{2}} \Gamma\left(\frac{m+3}{2}\right) \frac{1}{\sqrt{2 \pi \kappa_{m}}} e^{\frac{\left(\tau_{m}^{2}+1-2 r_{m}\right) y^{2}}{4 r_{m}}} \int_{\mathbb{R}} \rho_{m+1,1}(\lambda) e^{-\frac{1}{4 \tau_{m}^{2}}\left(\lambda-\left(\tau_{m}^{2}+1\right) \frac{y}{\sqrt{r_{m}}}\right)^{2}} d \lambda \\
& =2^{\frac{m+3}{2}} \Gamma\left(\frac{m+3}{2}\right) \frac{1}{\sqrt{2 \pi \kappa_{m}}} \int_{\mathbb{R}} \rho_{m+1,1}(\lambda) e^{-\frac{1}{4 \tau_{m}^{2}}\left(\lambda-\left(\tau_{m}^{2}+1\right) \frac{y}{\left.\sqrt{r_{m}}\right)^{2}-\frac{r_{m} y^{2}}{2\left(r_{m}+1\right)}} d \lambda\right.}
\end{aligned}
$$

An elementary computation yields a pleasant surprise

$$
-\frac{1}{4 \tau_{m}^{2}}\left(\lambda-\left(\tau_{m}^{2}+1\right) \frac{y}{\sqrt{r_{m}}}\right)^{2}-\frac{r_{m} y^{2}}{2\left(r_{m}+1\right)}=-\frac{1}{4} \lambda^{2}-\left(\sqrt{\frac{1}{2\left(r_{m}-1\right)}} \lambda-y \sqrt{\frac{r_{m}}{2\left(r_{m}-1\right)}}\right)^{2}
$$

Now set

$$
\beta_{m}:=\frac{1}{\left(r_{m}-1\right)}
$$

We deduce

$$
\frac{d \mu_{m}}{d y}=2^{\frac{m+3}{2}} \Gamma\left(\frac{m+3}{2}\right) \frac{1}{2 \pi \sqrt{\kappa_{m}}} \int_{\mathbb{R}} \rho_{m+1,1}(\lambda) e^{-\frac{1}{4} \lambda^{2}} e^{-\frac{\beta_{m}}{2}\left(\lambda-\sqrt{r_{m}} y\right)^{2}} d \lambda
$$

$(\lambda:=\sqrt{r} \lambda)$

$$
\begin{aligned}
& =2^{\frac{m+3}{2}} \Gamma\left(\frac{m+3}{2}\right) \frac{1}{\sqrt{2 \pi \kappa_{m}}} \int_{\mathbb{R}} \sqrt{r_{m}} \rho_{m+1,1}\left(\sqrt{r_{m}} \lambda\right) e^{-\frac{r_{m}}{4} \lambda^{2}} e^{-\frac{r_{m} \beta_{m}}{2}(\lambda-y)^{2}} d \lambda \\
& \stackrel{(D .6)}{=} 2^{\frac{m+3}{2}} \Gamma\left(\frac{m+3}{2}\right) \frac{1}{\sqrt{\kappa_{m} r_{m} \beta_{m}}} \int_{\mathbb{R}} \rho_{m+1,1 / r_{m}}(\lambda) e^{-\frac{r_{m}}{4} \lambda^{2}} d \gamma_{\frac{1}{\beta_{m} r_{m}}}(y-\lambda) d \lambda
\end{aligned}
$$

$$
\left(\kappa_{m} r_{m} \beta_{m}=\frac{1}{2}\right)
$$

$$
=2^{\frac{m+4}{2}} \Gamma\left(\frac{m+3}{2}\right) \int_{\mathbb{R}} \rho_{m+1,1 / r_{m}}(\lambda) e^{-\frac{r_{m}}{4} \lambda^{2}} d \gamma_{\frac{1}{\beta_{m} r_{m}}}(y-\lambda) d \lambda
$$

$$
=2^{\frac{m+4}{2}} \Gamma\left(\frac{m+3}{2}\right) \int_{\mathbb{R}} \rho_{m+1,1 / r_{m}}(\lambda) e^{-\frac{r_{m}}{4} \lambda^{2}} d \gamma_{\frac{r_{m}-1}{r_{m}}}(y-\lambda) d \lambda
$$

Using the last equality in (2.13) we obtain the case $r_{m}>1$ (1.13b) of Theorem 1.2.
Case 2. $r_{m}=1$. The proof of Theorem 1.2 in this case follows a similar pattern. Note first that in this case $\kappa_{m}=0$ so invoking Lemma D. 1 we obtain the following counterpart of (2.16)

$$
\boldsymbol{E}_{\mathrm{GOE}_{m}^{1}}\left(\left|\operatorname{det}\left(A-y \mathbb{1}_{m}\right)\right|\right)=2^{\frac{m+4}{2}} \Gamma\left(\frac{m+3}{2}\right) e^{\frac{y^{2}}{4}} \rho_{m+1,1}(y)
$$

Using this in (2.15) we deduce

$$
\frac{d \mu_{m}}{d y}=2^{\frac{m+4}{2}} \Gamma\left(\frac{m+3}{2}\right) e^{\frac{-y^{2}}{4}} \rho_{m+1,1}(y)
$$

which is (1.13b) in the case $r_{m}=1$. This completes the proof of Theorem 1.2.
2.3. Proof of Corollary 1.3. According to (1.10) we have

$$
\gamma_{\boldsymbol{\omega}_{m} \varepsilon^{-m}} * \boldsymbol{\sigma}^{\varepsilon}=\check{\boldsymbol{\sigma}}^{\varepsilon} .
$$

Thus

$$
\gamma \frac{\omega_{m}}{\omega_{m}} *\left(\mathcal{R}_{\sqrt{\sqrt{s} m \varepsilon^{-m}}}\right)_{*} \sigma^{\varepsilon}=\left(\mathcal{R} \frac{1}{\sqrt{\bar{s}_{m} \varepsilon^{-m}}}\right)_{*} \check{\sigma}^{\varepsilon} .
$$

Hence

$$
\lim _{\varepsilon \rightarrow 0} \frac{1}{\boldsymbol{N}^{\varepsilon}} \gamma \frac{\omega_{m}}{\bar{s}_{m}} *\left(\mathcal{R} \frac{1}{\sqrt{\bar{s}_{m} \varepsilon^{-m}}}\right)_{*} \boldsymbol{\sigma}^{\varepsilon}=\check{\boldsymbol{\sigma}}_{m}
$$

We can now conclude by invoking Lévy's continuity theorem [23, Thm. 15.23(ii)] or [32, Thm. 2.4].

### 2.4. Proof of Theorem 1.4. We have

$$
\begin{equation*}
\check{\boldsymbol{\sigma}}_{m}=\frac{1}{K_{m}} \theta_{m+1, \frac{1}{r_{m}}}^{-} * \gamma_{\frac{r_{m}-1}{r_{m}}} d y \tag{2.17}
\end{equation*}
$$

where

$$
\theta_{m+1, \frac{1}{r_{m}}}^{-}(\lambda)=\rho_{m+1, \frac{1}{r_{m}}}(\lambda) e^{-\frac{r_{m} \lambda^{2}}{4}},
$$

and

$$
K_{m}=\int_{\mathbb{R}} \theta_{m+1, \frac{1}{r_{m}}}^{-} * \gamma_{\frac{r_{m-1}}{r_{m}}}(y) d y=\int_{\mathbb{R}} \theta_{m+1, \frac{1}{r_{m}}}^{-}(\lambda) d \lambda=\int_{\mathbb{R}} \rho_{m+1, \frac{1}{r_{m}}}(\lambda) e^{-\frac{r_{m} \lambda^{2}}{4}} d \lambda .
$$

We set

$$
R_{m}(\lambda):=\rho_{m+1, \frac{1}{m}}(\lambda), \quad R_{\infty}(x)=\frac{1}{2 \pi} \boldsymbol{I}_{\{|x| \leq 2\}} \sqrt{4-x^{2}}
$$

Fix $c \in(0,2)$. In $[26, \S 4.2]$ we proved that

$$
\begin{gather*}
\lim _{m \rightarrow \infty} \sup _{|x| \leq c}\left|\bar{R}_{m}(x)-R_{\infty}(x)\right|=0,  \tag{2.18a}\\
\sup _{|x| \geq c}\left|\bar{R}_{m}(x)-R_{\infty}(x)\right|=O(1) \text { as } m \rightarrow \infty . \tag{2.18b}
\end{gather*}
$$

Then

$$
\rho_{m+1, \frac{1}{r_{m}}}(\lambda)=\sqrt{\frac{r_{m}}{m}} R_{m}\left(\sqrt{\frac{r_{m}}{m}} \lambda\right), \theta_{m+1, \frac{1}{r_{m}}}^{-}(\lambda)=\sqrt{\frac{r_{m}}{m}} R_{m}\left(\sqrt{\frac{r_{m}}{m}} \lambda\right) e^{-\frac{r_{m} \lambda^{2}}{4}} .
$$

We now distinguish two cases.

Case 1. $r=\lim _{m \rightarrow \infty} r_{m}<\infty$. In particular, $r \in[1, \infty)$. In this case we have

$$
K_{m}=\sqrt{\frac{r_{m}}{m}} \int_{\mathbb{R}} R_{m}\left(\sqrt{\frac{r_{m}}{m}} \lambda\right) e^{-\frac{r_{m} \lambda^{2}}{4}} d \lambda,
$$

and using (2.18a)-(2.18b) we deduce

$$
\lim _{m \rightarrow \infty} \int_{\mathbb{R}} R_{m}\left(\sqrt{\frac{r_{m}}{m}} \lambda\right) e^{-\frac{r_{m} \lambda^{2}}{4}} d \lambda=R_{\infty}(0) \int_{\mathbb{R}} e^{-\frac{r \lambda^{2}}{4}} d r=R_{\infty}(0) \sqrt{\frac{4 \pi}{r}}
$$

Hence

$$
\begin{equation*}
K_{m} \sim K_{m}^{\prime}=R_{\infty}(0) \sqrt{\frac{4 \pi}{m}} \text { as } m \rightarrow \infty . \tag{2.19}
\end{equation*}
$$

Now observe that

$$
\begin{gathered}
\frac{1}{K_{m}^{\prime}} \theta_{m+1, \frac{1}{r_{m}}}^{-}(\lambda) d \lambda=\frac{1}{R_{\infty}(0)} R_{m}\left(\sqrt{\frac{r_{m}}{m}} \lambda\right) \frac{r_{m}}{\sqrt{4 \pi}} e^{-\frac{r_{m} \lambda^{2}}{4}} d \lambda \\
=\frac{1}{R_{\infty}(0)} R_{m}\left(\sqrt{\frac{r_{m}}{m}} \lambda\right) \gamma_{\frac{2}{r_{m}}}(d \lambda)
\end{gathered}
$$

Using (2.18a) and (2.18b) we conclude that the sequence of measures

$$
\frac{1}{K_{m}^{\prime}} \theta_{m+1, \frac{1}{r_{m}}}^{-}(\lambda) d \lambda
$$

converges weakly to the Gaussian measure $\gamma_{\frac{2}{r}}$. Using this and the asymptotic equality (2.19) in (2.17) we deduce

$$
\lim _{m \rightarrow \infty} \check{\sigma}_{m}=\gamma_{\frac{2}{r}} * \gamma_{\frac{r-1}{r}}=\gamma_{\frac{r+1}{r}}^{r} .
$$

This proves Theorem 1.4 in the case $r<\infty$ since

$$
\gamma_{\bar{s}_{m}} * \boldsymbol{\sigma}_{m}=\check{\boldsymbol{\sigma}}_{m} \text { and } \lim _{m \rightarrow \infty} \frac{\boldsymbol{\omega}_{m}}{\check{s}_{m}} \stackrel{(1.9)}{=} 0
$$

Case 2. $\lim _{m \rightarrow \infty} r_{m}=\infty$. In this case we write

$$
\theta_{m+1, \frac{1}{r_{m}}}^{-}(\lambda) d \lambda=\sqrt{\frac{4 \pi}{m}} R_{m}\left(\sqrt{\frac{r_{m}}{m}} \lambda\right) \gamma_{\frac{2}{r_{m}}}(\lambda) d \lambda
$$

Lemma 2.3. The sequence of measures

$$
R_{m}\left(\sqrt{\frac{r_{m}}{m}} \lambda\right) \gamma_{\frac{2}{r_{m}}}(\lambda) d \lambda
$$

converges weakly to the measure $R_{\infty}(0) \delta_{0}$.
Proof. Fix a bounded continuous function $f: \mathbb{R} \rightarrow \mathbb{R}$. Observe first that

$$
\begin{equation*}
\lim _{m \rightarrow \infty} \underbrace{\int_{\mathbb{R}}\left(R_{m}\left(\sqrt{\frac{r_{m}}{m}} \lambda\right)-R_{\infty}\left(\sqrt{\frac{r_{m}}{m}} \lambda\right)\right) f(\lambda) \gamma_{\frac{2}{r_{m}}}(\lambda) d \lambda}_{=D_{m}}=0 . \tag{2.20}
\end{equation*}
$$

Indeed, we have

$$
D_{m}=\underbrace{\int_{|\lambda|<c \frac{\sqrt{m}}{\sqrt{r_{m}}}}\left(R_{m}\left(\sqrt{\frac{r_{m}}{m}} \lambda\right)-R_{\infty}\left(\sqrt{\frac{r_{m}}{m}} \lambda\right)\right) f(\lambda) \gamma_{\frac{2}{r_{m}}}(\lambda) d \lambda}_{=: D_{m}^{\prime}}
$$

$$
+\underbrace{\int_{|\lambda|>c \frac{\sqrt{m}}{\sqrt{r_{m}}}}\left(R_{m}\left(\sqrt{\frac{r_{m}}{m}} \lambda\right)-R_{\infty}\left(\sqrt{\frac{r_{m}}{m}} \lambda\right)\right) f(\lambda) \gamma_{\frac{2}{r_{m}}}(\lambda) d \lambda}_{=: D_{m}^{\prime \prime}}
$$

Observe that

$$
D_{m}^{\prime} \leq \sup _{|x| \leq c}\left|R_{m}(x)-R_{\infty}(x)\right| \int_{|\lambda|<c \frac{\sqrt{m}}{\sqrt{r_{m}}}} f(\lambda) \gamma_{\frac{2}{r_{m}}}(\lambda) d \lambda
$$

and invoking (2.18a) we deduce

$$
\lim _{m \rightarrow \infty} D_{m}^{\prime}=0
$$

Using (2.18b) we deduce that there exists a constant $S>0$ such that

$$
D_{m}^{\prime} \leq S \int_{|\lambda|>c \frac{\sqrt{m}}{\sqrt{r_{m}}}} \gamma_{\frac{2}{r_{m}}}(\lambda) d \lambda
$$

On the other hand, Chebyshev's inequality shows that

$$
\int_{|\lambda|>c \frac{\sqrt{m}}{\sqrt{r_{m}}}} \gamma_{\frac{2}{r_{m}}}(\lambda) d \lambda \leq \frac{2}{c^{2} m} .
$$

Hence

$$
\lim _{m \rightarrow \infty} D_{m}^{\prime \prime}=0
$$

This proves (2.20).
The sequence of measures $\gamma_{\frac{2}{r_{m}}}(\lambda) d \lambda$ converges to $\delta_{0}$ so that

$$
R_{\infty}(0) f(0)=\lim _{m \rightarrow \infty} \int_{\mathbb{R}} R_{\infty}(0) f(\lambda) \gamma_{\frac{2}{r_{m}}}(\lambda) d \lambda
$$

Using (2.20) and the above equality we deduce that the conclusion of the lemma is equivalent to

$$
\begin{equation*}
\lim _{m \rightarrow \infty} \underbrace{\int_{\mathbb{R}}\left(R_{\infty}(0)-R_{\infty}\left(\sqrt{\frac{r_{m}}{m}} \lambda\right)\right) f(\lambda) \gamma_{\frac{2}{r_{m}}}(\lambda) d \lambda}_{=F_{m}}=0 \tag{2.21}
\end{equation*}
$$

To prove this we decompose $F_{m}$ as follows.

$$
\begin{aligned}
& F_{m}=\underbrace{\int_{|\lambda|<m^{-\frac{1}{4}} \frac{\sqrt{m}}{\sqrt{r_{m}}}}\left(R_{\infty}(0)-R_{\infty}\left(\sqrt{\frac{r_{m}}{m}} \lambda\right)\right) f(\lambda) \gamma_{\frac{2}{r_{m}}}(\lambda) d \lambda}_{=: F_{m}^{\prime}} \\
&+\underbrace{\int_{|\lambda|>m^{-\frac{1}{4}} \frac{\sqrt{m}}{\sqrt{r_{m}}}}\left(R_{\infty}(0)-R_{\infty}\left(\sqrt{\frac{r_{m}}{m}} \lambda\right)\right) f(\lambda) \gamma_{\frac{2}{r_{m}}}(\lambda) d \lambda}_{=: F_{m}^{\prime \prime}} .
\end{aligned}
$$

Observe that

$$
F_{m}^{\prime} \leq \sup _{|x| \leq m^{-\frac{1}{4}}}\left|R_{\infty}(0)-R_{\infty}(x)\right| \int_{|\lambda|<m^{-\frac{1}{4}} \frac{\sqrt{m}}{\sqrt{T_{m}}}} f(\lambda) \gamma_{\frac{2}{r_{m}}}(\lambda) d \lambda
$$

and since $R_{\infty}$ is continuous at 0 we deduce

$$
\lim _{m \rightarrow \infty} F_{m}^{\prime}=0
$$

Since $R_{\infty}$ and $f$ are bounded we deduce that there exists a constant $S>0$ such that

$$
F_{m}^{\prime \prime} \leq S \int_{|\lambda|>m^{-\frac{1}{4}} \frac{\sqrt{m}}{\sqrt{r_{m}}}} \gamma_{\frac{2}{r_{m}}}(\lambda) d \lambda
$$

On the other hand, Chebyshev's inequality shows that

$$
\int_{|\lambda|>m^{-\frac{1}{4}} \frac{\sqrt{m}}{\sqrt{r_{m}}}} \gamma_{\frac{2}{r_{m}}}(\lambda) d \lambda \leq \frac{2}{\sqrt{m}}
$$

Hence

$$
\lim _{m \rightarrow \infty} F_{m}^{\prime \prime}=0
$$

This proves (2.21) and the lemma.
Lemma 2.3 shows that

$$
K_{m} \sim K_{m}^{\prime}=\sqrt{\frac{4 \pi}{m}} R_{\infty}(0)
$$

and

$$
\lim _{m \rightarrow \infty} \frac{1}{K_{m}} \theta_{m+1, \frac{1}{r_{m}}}^{-}(\lambda) d \lambda=\delta_{0}
$$

On the other hand

$$
\lim _{m \rightarrow \infty} \gamma_{\frac{r_{m-1}}{r_{m}}}(\lambda) d \lambda=\gamma_{1}(\lambda) d \lambda
$$

so that

$$
\lim _{m \rightarrow \infty} \check{\sigma}_{m}=\delta_{0} * \gamma_{1}=\gamma_{1}
$$

This completes the proof of Theorem 1.4.
2.5. Proof of Corollary 1.5. Using (2.14) we deduce

$$
\begin{gathered}
\varepsilon^{m} \boldsymbol{N}^{\varepsilon}=\left(\frac{h_{m}}{2 \pi d_{m}}\right)^{\frac{m}{2}} \mu_{m}(\mathbb{R})+O(\varepsilon) \\
=2^{\frac{m+4}{2}} \Gamma\left(\frac{m+3}{2}\right)\left(\frac{h_{m}}{2 \pi d_{m}}\right)^{\frac{m}{2}} \int_{\mathbb{R}} \theta_{m+1, \frac{1}{r_{m}}}^{-} * \gamma_{\frac{r_{m}-1}{r_{m}}}(y) d y+O(\varepsilon) \\
=2^{\frac{m+4}{2}} \Gamma\left(\frac{m+3}{2}\right)\left(\frac{h_{m}}{2 \pi d_{m}}\right)^{\frac{m}{2}} \int_{\mathbb{R}} \theta_{m+1, \frac{1}{r_{m}}}^{-}(\lambda) d \lambda+O(\varepsilon) \\
=\underbrace{2^{\frac{m+4}{2}} \Gamma\left(\frac{m+3}{2}\right)\left(\frac{h_{m}}{2 \pi d_{m}}\right)^{\frac{m}{2}} K_{m}}_{=C_{m}(w)}+O(\varepsilon) .
\end{gathered}
$$

Lemma 2.3 implies that as $m \rightarrow \infty$ we have

$$
K_{m} \sim \sqrt{\frac{4 \pi}{m}} R_{\infty}(0)=\frac{2}{\sqrt{\pi m}}
$$

We deduce that

$$
C_{m}(w) \sim \frac{2^{\frac{m+6}{2}}}{\sqrt{\pi m}} \Gamma\left(\frac{m+3}{2}\right)\left(\frac{h_{m}}{2 \pi d_{m}}\right)^{\frac{m}{2}} \quad \text { as } m \rightarrow \infty
$$

2.6. Proof of Theorem 1.6. Fix a point $\boldsymbol{p} \in M$ and normal coordinates $\left(x^{i}\right)$ near $\boldsymbol{p}$. The equality (2.2b) shows that as $\varepsilon \rightarrow 0$ we have the following estimate, uniform in $\boldsymbol{p}$.

$$
\left.\boldsymbol{E}\left(\partial_{x^{i}} \check{\boldsymbol{u}}_{\varepsilon}(\boldsymbol{p}) \partial_{x^{j}} \check{\boldsymbol{u}}_{\varepsilon}(\boldsymbol{p})\right)=d_{m} \varepsilon^{-(m+2)}\left(\delta_{i j}+O(\varepsilon)^{2}\right)\right)
$$

Hence

$$
\begin{equation*}
h^{\varepsilon}\left(\partial_{x^{i}}, \partial_{x^{j}}\right)=\delta_{i j}+O\left(\varepsilon^{2}\right)=g_{\boldsymbol{p}}\left(\partial_{x^{i}}, \partial_{x^{j}}\right)+O\left(\varepsilon^{2}\right) . \tag{2.22}
\end{equation*}
$$

This proves (a) and (b) of Theorem 1.2.
With $\boldsymbol{p}$ and $\left(x^{i}\right)$ as above we set

$$
\begin{array}{r}
\mathscr{E}_{i_{1}, \ldots, i_{a} ; j_{1}, \ldots, j_{b}}^{\varepsilon}:=\left.\frac{\partial^{a+b} \mathscr{E}^{\varepsilon}(x, y)}{\partial x^{i_{1}} \cdots \partial x^{i_{a}} \partial y^{j_{1}} \cdots \partial y^{j_{b}}}\right|_{x=y=0}, \\
h_{i j}^{\varepsilon}:=h_{\boldsymbol{p}}^{\varepsilon}\left(\partial_{x^{i}}, \partial_{x^{j}}\right), \quad 1 \leq i, j \leq m .
\end{array}
$$

We denote by $K_{i j}^{\varepsilon}$ the sectional curvature of $h^{\varepsilon}$ along the plane spanned by $\partial_{x^{i}}, \partial_{x^{j}}$. Using [1, Lemma 12.2.1] and that the sectional curvatures of a metric are inverse proportional to the metric we deduce as in $[26, \S 3.3]$ that

$$
K_{i j}^{\varepsilon}=\frac{d_{m}}{\varepsilon^{m+2}} \times \frac{\mathscr{E}_{i i ; j j}^{\varepsilon}-\mathscr{E}_{i j ; i j}^{\varepsilon}}{\mathscr{E}_{i ; i}^{\varepsilon} \mathscr{E}_{j, j}^{\varepsilon}-\left(\mathscr{E}_{i, j}^{\varepsilon}\right)^{2}}
$$

Using Theorem B. 5 we deduce that there exists a universal constant $z_{m}$ that depends only on $m$ and $w$ such that

$$
\left.\mathscr{E}_{i i ; j j}^{\varepsilon}-\mathscr{E}_{i j ; i j}^{\varepsilon}=\varepsilon^{-(m+2)}\right) \mathcal{Z}_{m} K_{i j}(\boldsymbol{p})\left(1+O\left(\varepsilon^{2}\right)\right),
$$

where $K_{i j}(\boldsymbol{p})$ denotes the sectional curvature of $g$ at $\boldsymbol{p}$. The estimate (2.2b) implies that

$$
\mathscr{E}_{i, i}^{\varepsilon} \mathscr{E}_{j, j}^{\varepsilon}-\left(\mathscr{E}_{i ; j}^{\varepsilon}\right)^{2}=d_{m}^{2} \varepsilon^{-2(m+2)}\left(1+O\left(\varepsilon^{2}\right)\right)
$$

Thus

$$
K_{i j}^{\varepsilon}=\frac{z_{m}}{d_{m}} K_{i j}(\boldsymbol{p})\left(1+O\left(\varepsilon^{2}\right)\right) .
$$

To determine the constant $\frac{z_{m}}{d_{m}}$ it suffices to compute it on a special manifold. Assume that $M$ is the unit sphere $S^{m}$ equipped with the round metric. This is is a homogeneous space equipped with an invariant metric $g$ with positive sectional curvatures. The metrics $h^{\varepsilon}$ are also invariant so there exists a constant $C_{\varepsilon}>0$ such that $h^{\varepsilon}=C_{\varepsilon} g$. The estimate (2.22) implies that $C_{\varepsilon}=1$ and thus $K_{i j}^{\varepsilon}=K_{i j}(\boldsymbol{p})$ so that $\frac{z_{m}}{d_{m}}=1$.

## 3. Some examples

We want to discuss several examples of weights $w$ satisfying the assumptions of the central limit theorem, Theorem 1.4. Observe first that

$$
r_{n}(w) \sim R_{m}(w)=\frac{I_{m-1}(w) I_{m+3}(w)}{I_{m+1}(w)} \text { as } m \rightarrow \infty .
$$

Moreover

$$
R_{n}\left(w_{\varepsilon}\right)=R_{n}(w) .
$$

Example 3.1. Suppose that $w(t)=e^{-t^{2}}$. In this case $\mathscr{E}^{\varepsilon}$ is the Schwartz kernel of the heat operator $e^{-\varepsilon \Delta}$ whose asymptotics as $\varepsilon \rightarrow 0$ have been thoroughly investigated. The momenta (1.4) are

$$
I_{k}(w)=\int_{0}^{\infty} t^{k} e^{-t^{2}} d t=\frac{1}{2} \int_{0}^{\infty} s^{\frac{k-1}{2}} e^{-s} d s=\frac{1}{2} \Gamma\left(\frac{k+1}{2}\right) .
$$

Hence

$$
R_{m}(w)=\frac{\Gamma\left(\frac{m}{2}\right) \Gamma\left(\frac{m}{2}+2\right)}{\Gamma\left(\frac{m}{2}+1\right)^{2}}=\frac{m+4}{m+2} \geq 1, \quad q_{m}=\frac{m(m+4)}{(m+2)^{2}}<1, \quad \forall m
$$

so that $r_{m}=1$ for all $m$. Moreover, in this case we have

$$
\frac{I_{m+3}(w)}{I_{m+1}(w)}=m+2,
$$

so that

$$
C_{m}(w) \sim \frac{2^{\frac{m+6}{2}}}{\sqrt{m} \pi^{\frac{m+1}{2}}} \Gamma\left(\frac{m+3}{2}\right) \quad \text { as } m \rightarrow \infty
$$

and Stirling's formula implies

$$
\begin{equation*}
\log C_{m}(w) \sim \frac{m}{2} \log m \text { as } m \rightarrow \infty \tag{3.1}
\end{equation*}
$$

Example 3.2. Suppose that

$$
w(t)=\exp (-(\log t) \log (\log t)), \quad \forall t \geq 1
$$

Observe that

$$
I_{k}(w)=\int_{0}^{1} r^{k} w(r) d r+\int_{1}^{\infty} r^{k} \exp (-(\log r) \log (\log r)) d r
$$

This proves that

$$
I_{k}(w) \sim J_{k}:=\int_{1}^{\infty} r^{k} \exp (-(\log r) \log (\log r)) d r \text { as } k \rightarrow \infty
$$

Using the substitution $r=e^{t}$ we deduce

$$
J_{k}=\int_{0}^{\infty} e^{(k+1) t-t \log t} d t
$$

We want to investigate the large $\lambda$ asymptotics of the integral

$$
\begin{equation*}
T_{\lambda}=\int_{0}^{\infty} e^{-\phi_{\lambda}(t)} d t, \quad \phi_{\lambda}(t)=\lambda t-t \log t \tag{3.2}
\end{equation*}
$$

We will achieve this by relying on the Laplace method [9, Chap. 4]. Note that

$$
\phi_{\lambda}^{\prime}(t)=\lambda-\log t-1, \quad \phi_{\lambda}^{\prime \prime}(t)=-\frac{1}{t} .
$$

Thus $\phi_{\lambda}(t)$ has a unique critical point

$$
\tau=\tau(\lambda):=e^{\lambda-1}
$$

We make the change in variables $t=\tau s$ in (3.2). Observe that

$$
\lambda e^{\lambda-1} s-e^{\lambda-1} s \log \left(e^{\lambda-1} s\right)=e^{\lambda-1} s-(\lambda-1) e^{\lambda-1} s-e^{\lambda-1} \log s=e^{\lambda-1} s(1-\log s)
$$

and we deduce

$$
T_{\lambda}=\tau \int_{0}^{\infty} e^{-\tau h(s)} d s, \quad h(s)=s(\log s-1)
$$

The asymptotics of the last integral can be determined using the Laplace method and we have, [9, §4.1]

$$
T_{\lambda} \sim \tau e^{-\tau h(1)} \sqrt{\frac{2 \pi}{\tau h^{\prime \prime}(1)}}=\sqrt{2 \pi \tau} e^{\tau}
$$

Hence

$$
J_{k}=T_{k+1} \sim \sqrt{2 \pi \tau(k+1)} e^{\tau(k+1)}=\sqrt{2 \pi e^{k}} e^{e^{k}} \text { as } k \rightarrow \infty .
$$

In this case

$$
R_{m}(w) \rightarrow \infty \text { as } m \rightarrow \infty
$$

Note that

$$
\frac{h_{m}}{d_{m}}=\frac{2 I_{m+3}(w)}{(m+2) I_{m+1}(w)} .
$$

We deduce that

$$
\log \left(\frac{h_{m}}{d_{m}}\right) \sim e^{m+4}-e^{m+2} \text { as } m \rightarrow \infty
$$

Hence

$$
\log C_{m}(w) \sim \frac{m}{2} e^{m+2}\left(e^{2}-1\right) \text { as } m \rightarrow \infty
$$

Example 3.3. Suppose that

$$
w(r)=\exp \left(-C(\log r)^{\alpha}\right), \quad C>0, \quad r>1, \quad \alpha>1
$$

Arguing as in Example 3.2 we deduce that as $k \rightarrow \infty$

$$
I_{k}(w) \sim \int_{1}^{\infty} r^{k} \exp \left(-C(\log r)^{\alpha}\right) d r=\int_{0}^{\infty} e^{(k+1) t-C t^{\alpha}} d t
$$

Again, set

$$
T_{\lambda}:=\int_{0}^{\infty} e^{-\phi_{\lambda}(t)} d t, \quad \phi_{\lambda}(t):=C t^{\alpha}-\lambda t
$$

We determine the asymptotics of $T_{\lambda}$ as $\lambda \rightarrow \infty$ using the Laplace method. Note that

$$
\phi_{\lambda}^{\prime}(t)=\alpha C t^{\alpha-1}-\lambda
$$

The function $\phi_{\lambda}$ has a unique critical point

$$
\tau=\tau(\lambda)=\left(\frac{\lambda}{\alpha C}\right)^{\frac{1}{\alpha-1}}
$$

Observe that

$$
\begin{gathered}
\phi_{\lambda}(\tau s)=a\left(s^{\alpha}-b s\right), \quad a:=\left(\frac{\lambda}{C^{1 / \alpha} \alpha}\right)^{\frac{\alpha}{\alpha-1}}, \quad b:=\alpha^{\frac{1}{\alpha-1}} \\
T_{\lambda}=\tau(\lambda) \int_{0}^{\infty} e^{-a\left(s^{\alpha}-b s\right)} d s
\end{gathered}
$$

We set $g(s):=s^{\alpha}-b s$. Using the Laplace method [9, §4.2] we deduce

$$
T_{\lambda} \sim \tau(\lambda) e^{-a g(1)} \sqrt{\frac{2 \pi}{a g^{\prime \prime}(1)}}=\sqrt{\frac{2 \pi}{a \alpha(\alpha-1)}} e^{a(b-1)}
$$

Hence

$$
\log T_{\lambda} \sim\left(\frac{\lambda^{\alpha}}{C}\right)^{\frac{1}{\alpha-1}} \frac{\alpha^{\frac{1}{\alpha-1}}-1}{\alpha^{\frac{\alpha}{\alpha-1}}}=: Z(\alpha, C) \lambda^{\frac{\alpha}{\alpha-1}}
$$

Hence

$$
\begin{aligned}
& \log R_{m}(w) \sim \log T_{m}+\log T_{m+4}-2 \log T_{m+2} \\
\sim & Z(\alpha, C)\left(m^{\frac{\alpha}{\alpha-1}}+(m+4)^{\frac{\alpha}{\alpha-1}}-2(m+2)^{\frac{\alpha}{\alpha-1}}\right)
\end{aligned}
$$

$$
\begin{gathered}
\quad=Z(\alpha, C) m^{\frac{\alpha}{\alpha-1}}\left(1+\left(1+\frac{4}{m}\right)^{\frac{\alpha}{\alpha-1}}-2\left(1+\frac{2}{m}\right)^{\frac{\alpha}{\alpha-1}}\right) \\
\sim Z(\alpha, C) m^{\frac{\alpha}{\alpha-1}} \times \frac{8}{m^{2}} \times \frac{\alpha}{\alpha-1}\left(\frac{\alpha}{\alpha-1}-1\right)=\frac{8 \alpha Z(\alpha)}{(\alpha-1)^{2}} m^{\frac{2-\alpha}{\alpha-1}} .
\end{gathered}
$$

Hence

$$
r=\lim _{m \rightarrow \infty} r_{m}=\times \begin{cases}\infty, & \alpha<2, \\ e^{16 Z(2, C)}, & \alpha=2, \\ 1, & \alpha>2\end{cases}
$$

which shows that $r$ can have any value in $[1, \infty]$. Note that in this case

$$
\begin{gathered}
\log I_{m+3}(w)-\log I_{m+1}(w) \sim Z(\alpha, C) m^{\frac{\alpha}{\alpha-1}}\left(\left(1+\frac{4}{m}\right)^{\frac{\alpha}{\alpha-1}}-\left(1+\frac{2}{m}\right)^{\frac{\alpha}{\alpha-1}}\right) \\
\sim \frac{2 Z(\alpha, C)}{\alpha-1} m^{\frac{1}{\alpha-1}}, m \rightarrow \infty,
\end{gathered}
$$

so that

$$
\log C_{m}(w) \sim \frac{Z(\alpha, C)}{\alpha-1} m^{\frac{\alpha}{\alpha-1}}, \quad m \rightarrow \infty .
$$

Example 3.4. Suppose now that $w$ is a weight with compact support disjoint from the origin. For example, assume that on the positive semi-axis it is given by

$$
w(x)=\left\{\begin{array}{ll}
e^{-\frac{1}{1-(x-c)^{2}},} & |x-c| \leq 1 \\
0, & |x-c|>1,
\end{array}, c>1 .\right.
$$

Then

$$
\begin{gathered}
I_{k}(w)=\int_{c-1}^{c+1} t^{k} e^{-\frac{1}{1-(t-c)^{2}}} d t=\int_{-1}^{1}(t+c)^{k} e^{-\frac{1}{1-t^{2}}} d t \\
=\underbrace{\int_{-1}^{0}(t+c)^{k} e^{-\frac{1}{1-t^{2}}} d t}_{I_{k}^{-}}+\underbrace{\int_{0}^{1}(t+c)^{k} e^{-\frac{1}{1-t^{2}}} d t}_{I_{k}^{+}} .
\end{gathered}
$$

Observe that

$$
\lim _{k \rightarrow \infty} c^{-k} I_{k}^{-}=0
$$

On the other hand

$$
I_{k}^{+}=\int_{0}^{1}(c+1-t)^{k} e^{-\frac{1}{t^{2}}} d t
$$

and we deduce

$$
c^{k} \int_{0}^{1} e^{-\frac{1}{t^{2}}} d t \leq I_{k}^{+} \leq(c+1)^{k} \int_{0}^{1} e^{-\frac{1}{t^{2}}} d t .
$$

Hence the asymptotic behavior of $I_{k}(w)$ is determined by $I_{k}^{+}$. We will determine the asymptotic behavior of $I_{k}^{+}$by relying again on the Laplace method. Set $a:=(c+1)$ so that

$$
I_{k}^{+}=\int_{0}^{1}(a-t)^{k} e^{-\frac{1}{t^{2}}} d t=a^{k} \int_{0}^{\frac{1}{a}}(1-s)^{k} e^{-\frac{1}{a^{2} s^{2}}} d s=a^{k} \int_{a}^{\infty}(u-1)^{k} u^{-(k+2)} e^{-\frac{u^{2}}{a^{2}}} d u .
$$

Consider the phase

$$
\phi_{\hbar}(s)=\frac{1}{\hbar} \log (1-s)-\frac{1}{a^{2} s^{2}}, \quad \hbar \searrow 0,
$$

and set

$$
P_{\hbar}=a^{\frac{1}{\hbar}} \int_{0}^{\frac{1}{a}} e^{\phi_{\hbar}(s)}
$$

so that

$$
I_{k}^{+}=P_{1 / k}
$$

We have

$$
\phi_{\hbar}^{\prime}(s)=-\frac{1}{\hbar(1-s)}+\frac{2}{a^{2} s^{3}}, \quad \phi_{\hbar}^{\prime \prime}(t)=-\frac{1}{\hbar(1-s)^{2}}-\frac{6}{a^{2} s^{4}} .
$$

The phase $\phi_{\hbar}$ as a unique critical point $\tau=\tau(\hbar) \in(0,1 / a)$ satisfying

$$
\hbar=\frac{a^{2} \tau^{3}}{2(1-\tau)}=\frac{a^{2} \tau^{3}}{2}(1+O(\tau))
$$

so that

$$
\begin{equation*}
\tau=\left(\frac{2 \hbar}{a^{2}}\right)^{\frac{1}{3}}\left(1+O\left(\hbar^{\frac{1}{3}}\right)\right) \text { as } \hbar \searrow 0 \tag{3.3}
\end{equation*}
$$

Set

$$
\begin{equation*}
v:=v(\hbar):=-\frac{1}{\phi_{k}^{\prime \prime}(\tau)} \sim \frac{a^{2} \tau^{4}}{6} \sim \frac{\left(2 \hbar \hbar^{\frac{4}{3}}\right.}{6 a^{\frac{2}{3}}}=\frac{1}{6}\left(\frac{2 \hbar^{2}}{a}\right)^{\frac{2}{3}} . \tag{3.4}
\end{equation*}
$$

We make the change in variables $s=\tau+\sqrt{v} x$ and we deduce

$$
P_{\hbar}=e^{\phi_{\hbar}(\tau)} a^{\frac{1}{\hbar}} \sqrt{v} \int_{J(\hbar)} e^{\phi_{\hbar}(\tau+\sqrt{v} x)-\phi_{\hbar}(\tau)} d x, \quad J(\hbar)=\left[-\frac{\tau}{\sqrt{v}}, \frac{1 / a-\tau}{\sqrt{v}}\right] .
$$

We claim that

$$
\begin{equation*}
\lim _{\hbar \rightarrow 0} \int_{J(\hbar)} e^{\phi_{\hbar}(\tau+\sqrt{v} x)-\phi_{\hbar}(\tau)} d x=\int_{\mathbb{R}} e^{-\frac{x^{2}}{2}} d x=\sqrt{2 \pi} . \tag{3.5}
\end{equation*}
$$

It is convenient to think of $\tau$ as the small parameter and then redefine

$$
\hbar=\hbar(\tau)=\frac{a^{2} \tau^{3}}{2(1-\tau)}
$$

and think of $v$ as a function of $\tau$. Finally set $\sigma:=\sqrt{v}$ and

$$
\begin{gathered}
\varphi_{\tau}(x):=\phi_{\hbar(\tau)}(\tau+\sigma x)-\phi_{\hbar(\tau)}(\tau)=\frac{2(1-\tau)}{a^{2} \tau^{3}} \log (1-s)-\frac{1}{a^{2} s^{2}} \\
=\frac{2(1-\tau)}{a^{2} \tau^{3}}(\log (1-\tau-\sigma x)-\log (1-\tau))-\frac{1}{a^{2}}\left(\frac{1}{(\tau+\sigma x)^{2}}-\frac{1}{\tau^{2}}\right) \\
=\frac{2(1-\tau)}{a^{2} \tau^{3}} \log \left(1-\frac{\sigma}{1-\tau} x\right)-\frac{1}{a^{2} \tau^{2}}\left(\frac{1}{\left(1+\frac{\sigma}{\tau} x\right)^{2}}-1\right) \\
=\frac{1}{a^{2} \tau^{2}}\left(\frac{2(1-\tau)}{\tau} \log \left(1-\frac{\sigma}{1-\tau} x\right)-\left(\frac{1}{\left(1+\frac{\sigma}{\tau} x\right)^{2}}-1\right)\right) .
\end{gathered}
$$

The equality (3.5) is equivalent to

$$
\begin{equation*}
\lim _{\tau \rightarrow \infty} \int_{J(\hbar)} e^{\varphi_{\tau}(x)}=\int_{\mathbb{R}} e^{-\frac{x^{2}}{2}} d x . \tag{3.6}
\end{equation*}
$$

By construction, we have

$$
\varphi_{\tau}(0)=\varphi_{\tau}^{\prime}(0)=0, \quad \varphi_{\tau}^{\prime \prime}(0)=-1, \quad \varphi_{\tau}(x) \leq 0, \quad \forall x \in J(\hbar)
$$

Let us observe that

$$
\begin{equation*}
\lim _{\tau \rightarrow 0} \varphi_{\tau}(x)=\frac{1}{2} \varphi_{\tau}^{\prime \prime}(0) x^{2}=-\frac{x^{2}}{2}, \quad \forall x \in \mathbb{R} \tag{3.7}
\end{equation*}
$$

Indeed, fix $x \in \mathbb{R}$ and assume $\tau$ is small enough so that

$$
\begin{equation*}
\tau|x|<\frac{1}{2} \tag{3.8}
\end{equation*}
$$

Observe that

$$
\begin{gathered}
\varphi_{\tau}^{(j)}(0)=\frac{1}{a^{2} \tau^{2}}\left(\left.\frac{2(1-\tau)}{\tau} \frac{d^{j}}{d x^{j}}\right|_{x=0} \log \left(1-\frac{\sigma}{1-\tau} x\right)-\left.\frac{d^{j}}{d x^{j}}\right|_{x=0}\left(\frac{1}{\left(1+\frac{\sigma}{\tau} x\right)^{2}}-1\right)\right) \\
=\frac{1}{a^{2} \tau^{2}}\left(-\frac{2(1-\tau)}{\tau}\left(\frac{\sigma}{1-\tau}\right)^{j}+(-1)^{j+1}(j+1)!\left(\frac{\sigma}{\tau}\right)^{j}\right)
\end{gathered}
$$

Using the estimate $\sigma=O\left(\tau^{2}\right)$ as $\tau \rightarrow 0$ we deduce that there exists $C>0$ such that, for any $j \geq 0$ we have

$$
\left|\varphi_{\tau}^{(j)}(0)\right| \leq C(j+1)!\tau^{j-2}
$$

Hence

$$
\frac{1}{j!}\left|\varphi_{\tau}^{(j)}(0) x^{j}\right| \leq C j|\tau x|^{j-2} x^{2}, \quad \forall j \geq 2
$$

Thus if $\tau$ satisfies (3.8), we have

$$
\varphi_{\tau}(x)+\frac{x^{2}}{2}=\varphi_{\tau}(x)-\varphi_{\tau}^{\prime}(0) x-\frac{1}{2} \varphi_{\tau}^{\prime \prime}(0) x^{2}=\sum_{j \geq 3} \frac{1}{j!} \varphi_{\tau}^{(j)}(0) x^{j},
$$

where the series in the right-hand side is absolutely convergent. Hence

$$
\left|\varphi_{\tau}(x)+\frac{x^{2}}{2}\right| \leq C x^{2}|\tau x| \sum_{j \geq 3} j|\tau x|^{j-3} \leq C|\tau x| x^{2} \sum_{j \geq 3} j 2^{j-3} .
$$

This proves (3.7).
Next we want to prove that there exists a constant $A>0$ such that

$$
\begin{equation*}
\varphi_{\tau}(x) \leq A(1-|x|), \quad \forall x \in J(\hbar), \quad \forall \tau \ll 1 \tag{3.9}
\end{equation*}
$$

We will achieve this by relying on the concavity of $\varphi_{\tau}$ over the interval $J(\hbar)$. The graph of $\varphi_{\tau}$ is situated below either of the lines tangent to the graph at $x= \pm 1$. Thus

$$
\begin{gathered}
\varphi_{\tau}(x) \leq \varphi_{\tau}(1)+\varphi_{\tau}^{\prime}(1)(x-1) \leq-\varphi_{\tau}^{\prime}(1)+\varphi_{\tau}^{\prime}(1) x \\
\varphi_{\tau}(x) \leq \varphi_{\tau}(-1)+\varphi_{\tau}^{\prime}(-1)(x+1) \leq \varphi_{\tau}^{\prime}(-1)+\varphi_{\tau}^{\prime}(-1)
\end{gathered}
$$

Now observe that

$$
\frac{d}{d x} \varphi_{\tau}(x)=\frac{1}{a^{2} \tau^{2}}\left(-\frac{2 \sigma}{\tau} \frac{1}{1-\frac{\sigma}{1-\tau} x}+\frac{2 \sigma}{\tau} \frac{1}{\left(1+\frac{\sigma}{\tau} x\right)^{3}}\right)=\frac{2 \sigma}{a^{2} \tau^{3}}\left(\frac{1}{\left(1+\frac{\sigma}{\tau} x\right)^{3}}-\frac{1}{1-\frac{\sigma}{1-\tau} x}\right) .
$$

Using the fact that $\sigma=O\left(\tau^{2}\right)$ we deduce from the above equality that

$$
\left|\varphi_{\tau}^{\prime}( \pm 1)\right|=O(1), \text { as } \tau \rightarrow 0
$$

This proves (3.9). Using (3.7), (3.9) and the dominated convergence theorem we deduce

$$
\lim _{\tau \rightarrow \infty} \int_{J(\hbar)} e^{\varphi_{\tau}(x)} d x=\int_{\mathbb{R}} e^{-\frac{x^{2}}{2}} d x=\sqrt{2 \pi}
$$

We conclude that

$$
\begin{equation*}
P_{\hbar} \sim e^{\phi_{\hbar}(\tau)} a^{\frac{1}{\hbar}} \sqrt{2 \pi v} \text { as } \hbar \rightarrow 0 \tag{3.10}
\end{equation*}
$$

Now observe that

$$
\phi_{\hbar}(\tau)=\frac{1}{\hbar} \log (1-\tau)-\frac{1}{a^{2} \tau^{2}}=\frac{2(1-\tau)}{a^{2} \tau^{2}} \frac{\log (1-\tau)}{\tau}-\frac{1}{a^{2} \tau^{2}} \sim-\frac{3}{a^{2} \tau^{2}}
$$

Using (3.3) we deduce

$$
\phi_{\hbar}(\tau) \sim-\frac{3}{a^{2}}\left(\frac{a^{2}}{2 \hbar}\right)^{\frac{2}{3}}=-\frac{3}{(2 a \hbar)^{\frac{2}{3}}}=-3\left(\frac{k}{2 a}\right)^{\frac{2}{3}}, \quad k=\frac{1}{\hbar}
$$

Also

$$
e^{\phi_{\hbar}(\tau)}=(1-\tau)^{\frac{2(1-\tau)}{a^{2} \tau^{3}}} e^{-\frac{1}{a^{2} \tau^{2}}}
$$

In any case, using (3.3), (3.4) and (3.10) we deduce that

$$
\begin{equation*}
\log I_{k}(w) \sim k \log a=k \log (c+1) \text { as } k \rightarrow \infty \tag{3.11}
\end{equation*}
$$

Thus

$$
\log r_{m}(w)=\log \left(\frac{I_{m-1}(w) I_{m+3}(w)}{I_{m+1}(w)}\right)=0
$$

so that

$$
\lim _{m \rightarrow \infty} q_{m}=\lim _{m \rightarrow \infty} r_{m}=1
$$

Example 3.5. If we let $c=0$ in the above example, then we deduce that

$$
I_{k}(w)=\int_{0}^{1} t^{k} e^{-\frac{1}{1-t^{2}}} d t \sim e^{\phi_{\hbar}(\tau)} \sqrt{2 \pi v(\hbar)}
$$

where

$$
\phi_{\hbar}(\tau) \sim-3\left(\frac{k}{2}\right)^{\frac{2}{3}}, \quad v(\hbar) \sim \frac{1}{6}\left(\frac{2}{k^{2}}\right)^{\frac{2}{3}}
$$

Hence

$$
\begin{gathered}
\log I_{k}(w) \sim-3\left(\frac{k}{2}\right)^{\frac{2}{3}} \\
\log r_{m}(w) \sim-\frac{3}{2^{\frac{2}{3}}}\left((m-1)^{\frac{2}{3}}+(m+3)^{\frac{2}{3}}-(m+1)^{\frac{2}{3}}\right) \rightarrow 0
\end{gathered}
$$

so that

$$
\lim _{m \rightarrow \infty} q_{m}=\lim _{m \rightarrow \infty} r_{m}=1
$$

## 4. A PROBABILISTIC PROOF OF THE GAUSS-BONNET THEOREM

Suppose that $M$ is a smooth, compact, connected oriented manifold of even dimension $m$. For any Riemann metric $g$ we can view the Riemann curvature tensor $R_{g}$ as a symmetric bundle morphism $R_{g}: \Lambda^{2} T M \rightarrow \Lambda^{2} T M$. Equivalently, using the metric identification $T^{*} M \cong T M$ we can view $R_{g}$ as a section of $\Lambda^{2} T^{*} M \otimes \Lambda^{2} T^{*} M$.

We will denote by $\Omega^{p, q}(M)$ the sections of $\Lambda^{p} T^{*} M \otimes \Lambda^{q} T^{*} M$ and we will refer to them of double forms of type $(p, q)$. Thus $R_{g} \in \Omega^{2,2}(M)$. We have a natural product

$$
\bullet: \Omega^{p, q}(M) \times \Omega^{p^{\prime}, q^{\prime}}(M) \rightarrow \Omega^{p+p^{\prime}, q+q^{\prime}}(M)
$$

defined in a natural way; see [1, Eq. (7.2.3)] for a precise definition.
Using the metric $g$ we can identify a double-form in $\Omega^{k, k}(M)$ with a section of $\Lambda^{k} T^{*} M \otimes \Lambda^{k} T M$, i.e., with a bundle morphism $\Lambda^{k} T M \rightarrow \Lambda^{k} T M$ and thus we have a linear map

$$
\operatorname{tr}: \Omega^{k, k}(M) \rightarrow C^{\infty}(M)
$$

For $1 \leq k \leq \frac{m}{2}$ we have a double form

$$
R_{g}^{\bullet k}=\underbrace{R_{g} \bullet \cdots \bullet R_{g}}_{k} \in \Omega^{2 k, 2 k}(M)
$$

We denote by $d V_{g} \in \Omega^{m}(M)$ the volume form on $M$ defined by the metric $g$ and the orientation on $M$. We set

$$
\boldsymbol{e}_{g}(M):=\frac{1}{(2 \pi)^{\frac{m}{2}}\left(\frac{m}{2}\right)!} \operatorname{tr}\left(-R_{g}^{\bullet \frac{m}{2}}\right) d V_{g} \in \Omega^{m}(M)
$$

The form $\boldsymbol{e}_{g}(M)$ is called the Euler form of the metric $g$ and the classical Gauss-Bonnet theorem states that

$$
\begin{equation*}
\int_{M} \boldsymbol{e}_{g}(M)=\chi(M)=: \text { the Euler characteristic of } M \tag{4.1}
\end{equation*}
$$

In this section we will show that the Gauss-Bonnet theorem for any metric $g$ is an immediate consequence of the Kac-Rice formula coupled with the approximation theorem Thm. 1.6.

Fix a metric $g$. For simplicity we assume that $\operatorname{vol}_{g}(M)=1$. This does not affect the generality since $\boldsymbol{e}_{c g}(M)=\boldsymbol{e}_{g}(M)$ for any constant $c>0$. Consider the random function $\boldsymbol{u}^{\varepsilon}$ on $M$ defined by (1.1, 1.2). Set

$$
\boldsymbol{v}^{\varepsilon}=\left(\frac{\varepsilon^{m+2}}{d_{m}}\right)^{\frac{1}{2}} \boldsymbol{u}^{\varepsilon}
$$

Observe that for $\varepsilon>0$ sufficiently small, any $X, Y \in \operatorname{Vect}(M)$ and any $\boldsymbol{p} \in M$ we have

$$
h^{\varepsilon}(X(\boldsymbol{p}), Y(\boldsymbol{p}))=\boldsymbol{E}\left(X \boldsymbol{v}^{\varepsilon}(\boldsymbol{p}), Y \boldsymbol{v}^{\varepsilon}(\boldsymbol{p})\right)
$$

where $h^{\varepsilon}$ is the metric on $M$ that appears in the approximation theorem, Theorem 1.6.
For any smooth function $f: M \rightarrow \mathbb{R}$ and any $\boldsymbol{p} \in M$ we denote by $\operatorname{Hess}_{\boldsymbol{p}}^{\varepsilon}(f)$ the Hessian of $f$ at $\boldsymbol{p}$ defined in terms of the metric $h^{\varepsilon}$. More precisely

$$
\operatorname{Hess}_{\boldsymbol{p}}^{\varepsilon}(f)=X Y f(\boldsymbol{p})-\left(\nabla_{X}^{\varepsilon} Y\right) f(\boldsymbol{p}), \forall X, Y \in \operatorname{Vect}(M),
$$

where $\nabla^{\varepsilon}$ denotes the Levi-Civita connection of the metric $h^{\varepsilon}$. Using the metric $h^{\varepsilon}$ we can identify this Hessian with a symmetric linear operator

$$
\operatorname{Hess}_{\boldsymbol{p}}^{\varepsilon}(f):\left(T_{\boldsymbol{p}} M, h^{\varepsilon}\right) \rightarrow\left(T_{\boldsymbol{p}} M, h^{\varepsilon}\right)
$$

For any $\boldsymbol{p} \in M$ we have a random vector $d \boldsymbol{v}^{\varepsilon}(\boldsymbol{p}) \in T_{\boldsymbol{p}}^{*} M$. Its covariance form $S\left(d \boldsymbol{v}^{\varepsilon}(\boldsymbol{p})\right)$ is precisely the metric $h^{\varepsilon}$, and if we use the metric $h^{\varepsilon}$ to identify this form with an operator we deduce that $S\left(d \boldsymbol{v}^{\varepsilon}(\boldsymbol{p})\right)$ is identified with the identity operator.

For every smooth Morse function $f$ on $M$ and any integer $0 \leq k \leq m$ we have a measure $\nu_{f, k}$ on M

$$
\nu_{f, k}=\sum_{d f(\boldsymbol{p})=0, \operatorname{ind}(f, \boldsymbol{p})=k} \delta_{\boldsymbol{p}},
$$

where $\operatorname{ind}(f, \boldsymbol{p})$ denotes the Morse index of the critical point $\boldsymbol{p}$ of the Morse function $f$. We set

$$
\nu_{f}=\sum_{k=0}^{m}(-1)^{k} \nu_{f, k}
$$

The Poincaré-Hopf theorem implies that for any Morse function we have

$$
\begin{equation*}
\int_{M} \nu_{f}(d \boldsymbol{p})=\chi(M) \tag{4.2}
\end{equation*}
$$

Using the random Morse function $\boldsymbol{v}^{\varepsilon}$ we obtain the random measures $\nu_{\boldsymbol{v}^{\varepsilon}, \boldsymbol{p}}, \nu_{\boldsymbol{v}^{\varepsilon}}$. We denote by $\nu_{k}^{\varepsilon}$ and respectively $\nu^{\varepsilon}$ their expectations. The Kac-Rice formula implies that

$$
\nu_{k}=\frac{1}{(2 \pi)^{\frac{m}{2}}} \rho_{k}^{\varepsilon}(\boldsymbol{p})\left|d V_{h^{\varepsilon}}(\boldsymbol{p})\right|,
$$

where

$$
\begin{aligned}
\rho_{k}^{\varepsilon}(\boldsymbol{p})= & \frac{1}{\sqrt{\operatorname{det} S\left(\boldsymbol{v}^{\varepsilon}(\boldsymbol{p})\right)}} \boldsymbol{E}\left(\left|\operatorname{det} \operatorname{Hess}_{\boldsymbol{p}}^{\varepsilon}\left(\boldsymbol{v}^{\varepsilon}\right)\right| \mid d \boldsymbol{v}^{\varepsilon}(\boldsymbol{p})=0, \quad \operatorname{ind} \operatorname{Hess}_{\boldsymbol{p}}^{\varepsilon}\left(\boldsymbol{v}^{\varepsilon}\right)=k\right) \\
& =(-1)^{k} \boldsymbol{E}\left(\operatorname{det} \operatorname{Hess}_{\boldsymbol{p}}^{\varepsilon}\left(\boldsymbol{v}^{\varepsilon}\right) \mid d \boldsymbol{v}^{\varepsilon}(\boldsymbol{p})=0, \quad \text { ind } \operatorname{Hess}_{\boldsymbol{p}}^{\varepsilon}\left(\boldsymbol{v}^{\varepsilon}\right)=k\right)
\end{aligned}
$$

As shown in [1, Eq. (12. 2.11)], the Gaussian random variables $\operatorname{Hess}_{\boldsymbol{p}}^{\varepsilon}\left(\boldsymbol{v}^{\varepsilon}\right)$ and $d \boldsymbol{v}^{\varepsilon}(\boldsymbol{p})$ are independent so that

$$
\rho_{k}^{\varepsilon}(\boldsymbol{p})=(-1)^{k} \boldsymbol{E}\left(\operatorname{det} \operatorname{Hess}_{\boldsymbol{p}}^{\varepsilon}\left(\boldsymbol{v}^{\varepsilon}\right) \mid \operatorname{ind} \operatorname{Hess}_{\boldsymbol{p}}^{\varepsilon}\left(\boldsymbol{v}^{\varepsilon}\right)=k\right) .
$$

Thus

$$
\begin{gathered}
\nu^{\varepsilon}=\frac{1}{(2 \pi)^{\frac{m}{2}}} \sum_{k=0}^{m}(-1)^{k} \rho_{k}^{\varepsilon}(\boldsymbol{p})\left|d V_{h^{\varepsilon}}(\boldsymbol{p})\right|, \\
=\frac{1}{(2 \pi)^{\frac{m}{2}}} \sum_{k=0}^{m} \boldsymbol{E}\left(\operatorname{det} \operatorname{Hess}_{\boldsymbol{p}}^{\varepsilon}\left(\boldsymbol{v}^{\varepsilon}\right) \mid \operatorname{ind} \operatorname{Hess}_{\boldsymbol{p}}^{\varepsilon}\left(\boldsymbol{v}^{\varepsilon}\right)=k\right)\left|d V_{h^{\varepsilon}}(\boldsymbol{p})\right| \\
=\frac{1}{(2 \pi)^{\frac{m}{2}}} \boldsymbol{E}\left(\operatorname{det} \operatorname{Hess}_{\boldsymbol{p}}^{\varepsilon}\left(\boldsymbol{v}^{\varepsilon}\right)\right)\left|d V_{h^{\varepsilon}}(\boldsymbol{p})\right|
\end{gathered}
$$

From the Poincaré-Hopf equality (4.2) we deduce

$$
\begin{equation*}
\chi(M)=\int_{M} \nu^{\varepsilon}(d \boldsymbol{p})=\frac{1}{(2 \pi)^{\frac{m}{2}}} \int_{M} \boldsymbol{E}\left(\operatorname{det} \operatorname{Hess}_{\boldsymbol{p}}^{\varepsilon}\left(\boldsymbol{v}^{\varepsilon}\right)\right)\left|d V_{h^{\varepsilon}}(\boldsymbol{p})\right| . \tag{4.3}
\end{equation*}
$$

Observe that Hessian $\operatorname{Hess}^{\varepsilon}(f)$ of a function $f$ can also be viewed as a double form

$$
\operatorname{Hess}^{\varepsilon}(f) \in \Omega^{1,1}(M) .
$$

In particular, $\operatorname{Hess}^{\varepsilon}\left(\boldsymbol{v}^{\varepsilon}\right)$ is a random $(1,1)$ double form and we have the following equality, $[1$, Lemma 12.2.1]

$$
\begin{equation*}
-2 R_{h^{\varepsilon}}=\boldsymbol{E}\left(\operatorname{Hess}^{\varepsilon}\left(\boldsymbol{v}^{\varepsilon}\right)^{\bullet 2}\right), \tag{4.4}
\end{equation*}
$$

where $R_{h^{\varepsilon}}$ denotes the Riemann curvature tensor of the metric $h^{\varepsilon}$. On the other hand we have the equality [1, Eq. (12.3.1)]

$$
\begin{equation*}
\operatorname{det} \operatorname{Hess}^{\varepsilon}\left(\boldsymbol{v}^{\varepsilon}\right)=\frac{1}{m!} \operatorname{tr}^{\operatorname{Hess}}{ }^{\varepsilon}\left(\boldsymbol{v}^{\varepsilon}\right)^{\bullet m} \tag{4.5}
\end{equation*}
$$

Using (4.4), (4.5) and the algebraic identities in [1, Lemma 12.3.1] we conclude that

$$
\frac{1}{(2 \pi)^{\frac{m}{2}}} \boldsymbol{E}\left(\operatorname{det} \operatorname{Hess}_{\boldsymbol{p}}^{\varepsilon}\left(\boldsymbol{v}^{\varepsilon}\right)\right)=\frac{1}{(2 \pi)^{\frac{m}{2}}\left(\frac{m}{2}\right)!} \operatorname{tr}\left(-R_{h^{\varepsilon}}^{\bullet \frac{m}{2}}\right) .
$$

This proves (1.19). Using this equality in (4.3) we deduce

$$
\chi(M)=\int_{M} e_{h^{\varepsilon}}(M),
$$

i.e., we have proved the Gauss-Bonnet theorem for the metric $h^{\varepsilon}$. Now let $\varepsilon \rightarrow 0$. As we have mentioned, Theorem 1.6 implies that $h^{\varepsilon} \rightarrow g$ so in the limit, the above equality reduced to the GaussBonnet theorem for the original metric $g$.

## Appendix A. Jets of the distance function

Suppose that $(M, g)$ is a smooth, $m$-dimensional manifold, $\boldsymbol{p}_{0} \in M, U$ is an open, geodesically convex neighborhood of $\boldsymbol{p}_{0}$ and $\left(x^{1}, \ldots, x^{m}\right)$ are normal coordinates on $U$ centered at $\boldsymbol{p}_{0}$. We have a smooth function

$$
\eta: U \times U \rightarrow[0, \infty), \quad \eta(\boldsymbol{p}, \boldsymbol{q})=\operatorname{dist}_{g}(\boldsymbol{p}, \boldsymbol{q})^{2} .
$$

We want to investigate the partial derivatives of $r$ at $\left(\boldsymbol{p}_{0}, \boldsymbol{p}_{0}\right)$. Using the above normal coordinates we regard $\eta$ as a function $\eta=\eta(x, y)$ defined in an open neighborhood of $(0,0) \in \mathbb{R}^{m} \times \mathbb{R}^{m}$.

If $f=f\left(t^{1}, \ldots, t^{N}\right)$ is a smooth function defined in a neighborhood of $0 \in \mathbb{R}^{N}$ and $k$ is a nonnegative integer, then we denote by $[f]_{k}$ the degree $k$-homogeneous part in the Taylor expansion of $f$ at 0 , i.e.,

$$
[f]_{k}=\left.\frac{1}{k!} \sum_{|\alpha|=k} \partial_{t}^{\alpha} f\right|_{t=0} t^{\alpha} \in \mathbb{R}\left[t^{1}, \ldots, t^{N}\right] .
$$

In the coordinates $\left(x^{i}\right)$ the metric $g$ has the form (using Einstein's summation convention throughout)

$$
g=g_{i j} d x^{i} d x^{j},
$$

where $g_{i j}$ satisfy the estimates [18, Cor. 9.8]

$$
\begin{equation*}
g_{k \ell}=\delta_{k \ell}-\frac{1}{3} R_{i k j \ell}(0) x^{i} x^{j}+O\left(|x|^{3}\right) . \tag{A.1}
\end{equation*}
$$

We deduce that

$$
\begin{equation*}
g^{k \ell}=\delta_{k \ell}+\frac{1}{3} R_{i k j \ell}(0) x^{i} x^{j}+O\left(|x|^{3}\right) . \tag{A.2}
\end{equation*}
$$

The function $\eta$ satisfies a Hamilton-Jacobi equation, [29, p. 171],

$$
\begin{equation*}
g^{k \ell} \frac{\partial \eta(x, y)}{\partial x^{k}} \frac{\partial \eta(x, y)}{\partial x^{\ell}}=4 \eta(x, y), \quad \forall x, y \tag{A.3}
\end{equation*}
$$

Moreover, $\eta$ satisfies the obvious symmetry conditions

$$
\begin{equation*}
\eta(x, y)=\eta(y, x), \quad \eta(0, x)=\eta(x, 0)=|x|^{2}:=\sum_{i=1}^{m}\left(x^{i}\right)^{2} . \tag{A.4}
\end{equation*}
$$

As shown in [7, Lemma 2.2] we have

$$
\begin{equation*}
[\eta]_{2}=|x-y|^{2}=\sum_{i=1}^{m}\left(x^{i}-y^{i}\right)^{2} \tag{A.5}
\end{equation*}
$$

The symmetries (A.4) suggest the introduction of new coordinates $(u, v)$ on $U \times U$,

$$
u_{i}=x^{i}-y^{i}, \quad v_{j}=x^{j}+y^{j} .
$$

Then

$$
x^{i}=\frac{1}{2}\left(u_{i}+v_{i}\right), \quad y^{j}=\frac{1}{2}\left(v_{j}-u_{j}\right), \quad \partial_{x^{i}}=\partial_{u_{i}}+\partial_{v_{i}} .
$$

The equality (A.2) can be rewritten as

$$
\begin{equation*}
g^{k \ell}(x)=\delta^{k \ell}+\frac{1}{12} \sum_{i, j} R_{i k j \ell}\left(u_{i}+v_{i}\right)\left(u_{j}+v_{j}\right)+O(3) \tag{A.6}
\end{equation*}
$$

The symmetry relations (A.4) become

$$
\begin{equation*}
\eta(u, v)=\eta(-u, v), \quad \eta(u, u)=|u|^{2}, \tag{A.7}
\end{equation*}
$$

while (A.5) changes to

$$
\begin{equation*}
[\eta]_{1}=0, \quad[\eta]_{2}=|u|^{2} \tag{A.8}
\end{equation*}
$$

The equality (A.3) can be rewritten

$$
\begin{equation*}
\sum_{k, l} g^{k l}(x) \underbrace{\left(\eta_{u_{k}}^{\prime}+\eta_{v_{k}}^{\prime}\right)}_{=: A_{k}} \underbrace{\left(\eta_{u_{\ell}}^{\prime}+\eta_{v_{\ell}}^{\prime}\right)}_{=: A_{\ell}}=4 \eta \tag{A.9}
\end{equation*}
$$

Note that

$$
\begin{equation*}
\left[A_{k}\right]_{0}=\left[A_{\ell}\right]_{0}=\left[g^{k, \ell}\right]_{1}=0 \tag{A.10}
\end{equation*}
$$

while (A.8) implies that

$$
\left[A_{k}\right]_{1}=2 u^{k}
$$

We deduce

$$
4[\eta]_{3}=\sum_{k, \ell}\left[g^{k l}\right]_{0}\left(\left[A_{k}\right]_{1}\left[A_{\ell}\right]_{2}+\left[A_{k}\right]_{2}\left[B_{\ell}\right]_{1}\right)=\sum_{k} 2\left[A_{k}\right]_{2}\left[A_{k}\right]_{1}=4 \sum_{k} u_{k}\left[A_{k}\right]_{2}
$$

We can rewrite this last equality as a differential equation for $[\eta]_{3}$ namely

$$
[\eta]_{3}=\sum_{k} u_{k}\left(\partial_{u_{k}}+\partial_{v_{k}}\right)[\eta]_{3}
$$

We set $P=[\eta]_{3}$ so that $P$ is a homogeneous polynomial of degree 3 in the variables $u, v$. Moreover, according to (A.7) the polynomial $P$ is even in $u$ and $P(u, u)=0$. Thus $P$ has the form

$$
P=\underbrace{\sum_{i} C_{i}(u) v_{i}}_{=: P_{2}}+P_{0}(v)
$$

where $C_{i}(u)$ is a homogeneous polynomial of degree 2 in the variables $u$, and $P_{0}(v)$ is homogeneous of degree 3 in the variables $v$.

We have

$$
\sum_{k} u_{k} \partial_{v_{k}} P_{2}=\underbrace{\sum_{k} C_{k}(u) u_{k}}_{=: Q_{3}}, \quad Q_{1}:=\sum_{k} u_{k} \partial_{v_{k}} P_{0}, \quad \sum_{k} u_{k} \partial_{u_{k}} P_{0}=0
$$

and the classical Euler equations imply

$$
\sum_{k} u_{k} \partial_{u_{k}} P_{2}=2 P_{2}
$$

We deduce

$$
P=2 P_{2}+Q_{3}+Q_{1}
$$

where the polynomials $Q_{3}$ and $Q_{1}$ are odd in the variable $u$. Since $P$ is even in the variable $u$ we deduce

$$
Q_{3}+Q_{1}=0
$$

so that $P_{2}+P_{0}=P=2 P_{2}$. Hence $P_{2}=P_{0}=0$ and thus

$$
\begin{equation*}
[\eta]_{3}=0 \tag{A.11}
\end{equation*}
$$

In particular

$$
\begin{equation*}
\left[A_{k}\right]_{2}=0, \quad \forall k \tag{A.12}
\end{equation*}
$$

Going back to (A.9) and using (A.10) and (A.12) we deduce

$$
\begin{align*}
4[\eta]_{4}=\sum_{k, \ell}\left[g^{k \ell}\right]_{2}\left[A_{k}\right]_{1}\left[A_{\ell}\right]_{1}+ & \sum_{k, \ell}\left[g^{k \ell}\right]_{0}\left(\left[A_{k}\right]_{1}\left[A_{\ell}\right]_{3}+\left[A_{k}\right]_{3}\left[A_{\ell}\right]_{1}\right) \\
& =4 \sum_{k, \ell}\left[g^{k \ell}\right]_{2} u_{k} u_{\ell}+2 \sum_{k} u_{k}\left[A_{k}\right]_{3} \tag{A.13}
\end{align*}
$$

We set $P=[\eta]_{4}$. The polynomial $P$ is homogeneous of degree 4 in the variables $u, v$, and it is even in the variable $u$. We can write $P=P_{0}+P_{2}+P_{4}$, where

$$
P_{4}=\sum_{k} c_{i j k l} u_{i} u_{j} u_{k} u_{\ell}, \quad P_{2}=\sum_{i, j} Q_{i j}(u) v_{i} v_{j}
$$

and $P_{0}$ is homogeneous of degree 4 in the variables $v, Q_{i j}(u)$ is a homogeneous quadratic polynomial in the variables $u$. We have

$$
\sum_{k} u_{k}\left[A_{k}\right]_{3}=\sum_{k} u_{k}\left(\partial_{u_{k}}+\partial_{v_{k}}\right) P
$$

We have

$$
\begin{gathered}
\sum_{k} u_{k} \partial_{u_{k}} P_{2 \nu}=2 \nu P_{2 \nu}, \quad \nu=0,1,2 . \\
\sum_{k} u_{k} \partial_{v_{k}} P_{4}=0 \\
\sum_{k} u_{k} \partial_{v_{k}} P_{2}=\sum_{k, i, j} u_{k} Q_{i j}\left(\delta_{k i} v_{j}+\delta_{k j} v_{i}\right)=\sum_{k, j}\left(Q_{k j} u_{k} v_{j}+Q_{j k} v_{j} u_{k}\right)
\end{gathered}
$$

Using these equalities in (A.13) we deduce

$$
\begin{aligned}
4 P_{4}+4 P_{2}+4 P_{0}= & 4 \sum_{k, \ell}\left[g^{k \ell}\right]_{2} u_{k} u_{\ell}+4 P_{4}+2 P_{2}+\sum_{k} u_{k} \partial_{v_{k}} P_{0} \\
& +\sum_{k, j}\left(Q_{j k}+Q_{k j}\right) u_{k} v_{j}
\end{aligned}
$$

This implies $P_{0}=0$ so that $P=P_{4}+P_{2}$, and we can then rewrite the above equality as

$$
\begin{equation*}
P_{2}=2 \sum_{k, \ell}\left[g^{k \ell}\right]_{2} u_{k} u_{\ell}+\sum_{k, j}\left(Q_{j k}+Q_{k j}\right) u_{k} v_{j} . \tag{A.14}
\end{equation*}
$$

Note that the equality $r(u, u)=|u|^{2}$ implies $P(u, u)=0$ so that

$$
P_{4}(u)=P_{4}(u, u)=-P_{2}(u, u) .
$$

There fore it suffices to determine $P_{2}$. This can be achieved using the equality (A.6) in (A.14). We have

$$
\begin{gathered}
2 \sum_{k, \ell}\left[g^{k \ell}\right]_{2} u_{k} u_{\ell}=\frac{1}{6} \sum_{i, j, k, \ell} R_{i k j \ell}\left(u_{i}+v_{i}\right)\left(u_{j}+v_{j}\right) u_{k} u_{\ell} \\
\quad=\frac{1}{6} \sum_{i, j} \underbrace{\left(\sum_{k, \ell} R_{i k j \ell} u_{k} u_{\ell}\right)}_{\widehat{Q}_{i j}(u)} v_{i} v_{j}+\sum_{j} S_{j}(u) v_{j},
\end{gathered}
$$

where $S_{j}(u)$ denotes a homogeneous polynomial of degree 3 in $u$. The equality (A.14) can now be rewritten as

$$
\sum_{i, j} Q_{i j}(u) v_{i} v_{j}=\frac{1}{6} \sum_{i, j} \widehat{Q}_{i j}(u) v_{i} v_{j}+\sum_{j} S_{j}(u) v_{j}+\frac{1}{2} \sum_{k, j}\left(Q_{j k}+Q_{k j}\right) u_{k} v_{j}
$$

From this we read easily

$$
Q_{i j}(u)=\frac{1}{6} \widehat{Q}_{i j}(u)=\frac{1}{6} \sum_{k, \ell} R_{i k j \ell} u_{k} u_{\ell}
$$

This determines $P_{2}$.

$$
\begin{equation*}
P_{2}(u, v)=\frac{1}{6} \sum_{i, j} \widehat{Q}_{i j}(u) v_{i} v_{j} \tag{A.15}
\end{equation*}
$$

As we have indicated above $P_{2}$ determines $P_{4}$.

$$
\begin{equation*}
P_{4}(u)=-P_{2}(u, u)=-\frac{1}{6} \sum_{i, j, k, \ell} R_{i k j \ell} u_{i} u_{j} u_{k} u_{\ell} \tag{A.16}
\end{equation*}
$$

The skew symmetries of the Riemann tensor imply that $P_{4}=0$ so that

$$
\begin{equation*}
[\eta]_{4}(u, v)=\frac{1}{6} \sum_{i, j} \widehat{Q}_{i j}(u) v_{i} v_{j}, \quad \widehat{Q}_{i j}(u)=\sum_{k, \ell} R_{i k j \ell} u_{k} u_{\ell} \tag{A.17}
\end{equation*}
$$

Example A.1. Suppose that $M$ is a surface, i.e., $m=2$. Set

$$
K=R_{1212}=R_{2121}=-R_{1221}
$$

Note that $K$ is the Gaussian curvature of the surface. Then

$$
\begin{gathered}
\widehat{Q}_{11}=\sum_{k, \ell} R_{1 k 1 \ell} u_{k} u_{\ell}=K u_{2}^{2}, \quad \widehat{Q}_{22}=\sum_{k, \ell} R_{2 k 2 \ell} u_{k} u_{\ell}=K u_{1}^{2} \\
\widehat{Q}_{12}=\sum_{k, \ell} R_{1 k 2 \ell} u_{k} u_{\ell}=-K u_{1} u_{2}=\widehat{Q}_{21}
\end{gathered}
$$

Hence

$$
P_{2}(u, v)=\frac{K}{6}\left(u_{2}^{2} v_{1}^{2}+u_{1}^{2} v_{2}^{2}-2 u_{1} u_{2} v_{1} v_{2}\right)=\frac{K}{6}\left(u_{1} v_{2}-u_{2} v_{1}\right)^{2}
$$

## Appendix B. Spectral estimates

As we have already mentioned, the correlation function

$$
\mathscr{E}^{\varepsilon}(\boldsymbol{p}, \boldsymbol{q})=\sum_{k \geq 0} w_{\varepsilon}\left(\sqrt{\lambda_{k}}\right) \Psi_{k}(\boldsymbol{p}) \Psi_{k}(\boldsymbol{q})
$$

is the Schwartz kernel of the smoothing operator $w_{\varepsilon}(\sqrt{\Delta})$. In this appendix we present in some detail information about the behavior along the diagonal of this kernel as $\varepsilon \rightarrow 0$. We will achieve this by relying on the wave kernel technique pioneered by L. Hörmander, [20].

The fact that such asymptotics exist and can be obtained in this fashion is well known to experts; see e.g [11] or [31, Chap.XII]. However, we could not find any reference describing these asymptotics with the level of specificity needed for the considerations in this paper.

Theorem B.1. Suppose that $w \in \mathcal{S}(\mathbb{R})$ is an even, nonnegative Schwartz function, and $(M, g)$ is a smooth, compact, connected m-dimensional Riemann manifold. We define

$$
\mathscr{E}^{\varepsilon}: M \times M \rightarrow \mathbb{R}, \quad \mathscr{E}^{\varepsilon}(\boldsymbol{p}, \boldsymbol{q})=\sum_{k \geq 0} w\left(\varepsilon \sqrt{\lambda_{k}}\right) \Psi_{k}(\boldsymbol{p}) \Psi_{k}(\boldsymbol{q}),
$$

where $\left(\Psi_{k}\right)_{k \geq 1}$ is an orthonormal basis of $L^{2}(M, g)$ consisting of eigenfunctions of $\Delta_{g}$.
Fix a point $\boldsymbol{p}_{0} \in M$ and normal coordinates at $\boldsymbol{p}_{0}$ defined in an open neighborhood $\mathcal{O}_{0}$ of $\boldsymbol{p}_{0}$. The restriction of $\mathscr{E}^{\varepsilon}$ to $\mathscr{E}^{\varepsilon}$ to $\mathcal{O}_{0} \times \mathcal{O}_{0}$ can be viewed as a function $\mathscr{E}^{\varepsilon}(x, y)$ defined in an open neighborhood of $(0,0)$ in $\mathbb{R}^{m} \times \mathbb{R}^{m}$. Fix multi-indices $\alpha, \beta \in\left(\mathbb{Z}_{\geq 0}\right)^{m}$. Then

$$
\begin{equation*}
\left.\partial_{x}^{\alpha} \partial_{y}^{\beta} \mathscr{E}^{\varepsilon}(x, y)\right|_{x=y=0}=\varepsilon^{-m-2 d(\alpha, \beta)} \frac{i^{|\alpha|-|\beta|}}{(2 \pi)^{m}}\left(\int_{\mathbb{R}^{m}} w(|x|) x^{\alpha+\beta} d x+O\left(\varepsilon^{2}\right)\right), \quad \varepsilon \rightarrow 0, \tag{B.1}
\end{equation*}
$$

where

$$
d(\alpha, \beta):=\left\lfloor\frac{|\alpha+\beta|}{2}\right\rfloor .
$$

Moreover, the constant implied by the symbol $O(\varepsilon)$ in (B.1) uniformly bounded with respect to $\boldsymbol{p}_{0}$.
Proof. For the reader's convenience and for later use, we go in some detail through the process of obtaining these asymptotics. We skip many analytical steps that are well covered in [22, Chap. 17] or [28].

Observe that for any smooth $f: M \rightarrow \mathbb{R}$ we have

$$
\begin{equation*}
w_{\varepsilon}(\sqrt{\Delta}) f=\frac{1}{2 \pi} \int_{\mathbb{R}} \widehat{w_{\varepsilon}}(t) e^{i t \sqrt{\Delta}} f d t=\frac{1}{2 \pi \varepsilon} \int_{\mathbb{R}} \widehat{w}\left(\frac{t}{\varepsilon}\right) e^{i t \sqrt{\Delta}} f d t . \tag{B.2}
\end{equation*}
$$

The Fourier transform $\widehat{w}(t)$ is a Schwartz function so $\widehat{w}(t / \varepsilon)$ is really small for $t$ outside a small interval around 0 and $\varepsilon$ sufficiently small. Thus a good understanding of the kernel of $e^{i t \sqrt{\Delta}}$ for $t$ sufficiently small could potentially lead to a good understanding of the Schwartz kernel of $w_{\varepsilon}(\sqrt{\Delta})$.

Fortunately, good short time asymptotics for the wave kernel are available. We will describe one such method going back to Hadamard, [19, 29]. Our presentation follows closely [22, §14.4] but we also refer to [28] where we have substantially expanded the often dense presentation in [22].

To describe these asymptotics we need to introduce some important families homogeneous generalized functions (or distributions) on $\mathbb{R}$. We will denote by $C^{-\infty}(\Omega)$ the space of generalized functions on the smooth manifold $\Omega$, defined as the dual of the space compactly supported 1-densities, [17, Chap. VI].

For any $a \in \mathbb{C}, \operatorname{Re} a>1$ we define $\chi_{+}^{a}: \mathbb{R} \rightarrow \mathbb{R}$ by

$$
\chi_{+}^{a}(x)=\frac{1}{\Gamma(a+1)} x_{+}^{a}, \quad x_{+}=\max (x, 0) .
$$

Observe that we have the following equality in the sense of distributions

$$
\frac{d}{d x} \chi_{+}^{a+1}=\chi_{+}^{a}(x), \quad \boldsymbol{\operatorname { R e }} a>1 .
$$

We can use this to define for any $a \in \mathbb{C}$

$$
\chi_{+}^{a}:=\frac{d^{k}}{d x^{k}} \chi_{+}^{a+k} \in C^{-\infty}(\mathbb{R}), \quad k>1-\boldsymbol{\operatorname { R e }} a .
$$

For $\operatorname{Re} a>0$ we denote by $|\chi|^{a}$ the generalized function defined by the locally integrable function

$$
|\chi|^{a}(x)=\frac{1}{\Gamma\left(\frac{a+1}{2}\right)}|x|^{a}
$$

The correspondence $a \mapsto|\chi|^{a}$ is a holomorphic map $\{\boldsymbol{\operatorname { R e }} z>0\} \rightarrow C^{-\infty}(\mathbb{R})$ which admits a holomorphic extension to the whole complex plane, [15, Chap. 1], [28]. This is a temperate generalized function, and its Fourier transform is given by, [15, 28],

$$
\begin{equation*}
\widehat{|\chi|^{a}}(\xi)=\sqrt{\pi} 2^{a+1}|\chi|^{-(a+1)}(\xi), \quad \forall a \in \mathbb{C} . \tag{B.3}
\end{equation*}
$$

Denote by $K_{t}(x, y)$ the Schwartz kernel of $e^{i t \sqrt{\Delta}}$. We then have the following result [22, §17.4] or [28].

Theorem B.2. Set $n:=m+1$, and let

$$
\eta(x, y)=\operatorname{dist}_{g}(x, y)^{2}, \quad x, y \in M .
$$

There exists a positive constant $c>0$, smaller than the injectivity radius of $(M, g)$, such that for $\operatorname{dist}_{g}(x, y)<c$ we have the following asymptotic expansion as $t \rightarrow 0$

$$
\begin{equation*}
K_{t}(\boldsymbol{p}, \boldsymbol{q}) \sim \sum_{k=1}^{\infty} U_{k}(\boldsymbol{p}, \boldsymbol{q}) d_{m}(2 k) \mathcal{H}_{k}(t, \boldsymbol{p}, \boldsymbol{q}), \quad|t|<c \tag{B.4}
\end{equation*}
$$

where for $\operatorname{Re} a>0$ we have

$$
\begin{gathered}
\mathcal{H}_{a}(t, \boldsymbol{p}, \boldsymbol{q})=\partial_{t}\left(\chi_{+}^{a-\frac{n}{2}}\left(t_{+}^{2}-\eta(\boldsymbol{p}, \boldsymbol{q})\right)-\chi_{+}^{a-\frac{n}{2}}\left(t_{-}^{2}-\eta(\boldsymbol{p}, \boldsymbol{q})\right)\right), \\
d_{m}(2 a)=\frac{\Gamma\left(\frac{2 a+1}{2}\right)}{\pi^{\frac{m}{2}} \Gamma(2 a)} .
\end{gathered}
$$

Let us explain in more detail the meaning of the above result. The functions $U_{k}$ are smooth functions defined in the neighborhood $\operatorname{dist}_{g}(\boldsymbol{p}, \boldsymbol{q})<c$ of the diagonal in $M \times M$. For fixed $\boldsymbol{q}$, the functions $\boldsymbol{p} \mapsto V_{k}(\boldsymbol{p}):=U_{k}(\boldsymbol{p}, \boldsymbol{q})$ are determined as follows.

Fix normal coordinates $x$ at $\boldsymbol{q}$, set $|g|:=\operatorname{det}\left(g_{i j}\right)$, and

$$
h(x):=-\frac{1}{2} g(\nabla \log |g|, x)=-\frac{1}{2} \sum_{j, k} g^{j k} x^{j} \partial_{x^{k}} \log |g| .
$$

Then $V_{k}(x)$ are the unique solutions of the differential recurrences

$$
\begin{gather*}
V_{1}(0)=1, \quad 2 x \cdot \nabla V_{1}=h V_{1}, \quad|x|<c,  \tag{B.5}\\
\frac{1}{k} x \cdot \nabla V_{k+1}+\left(1-\frac{1}{2 k} h\right) V_{k+1}=-\Delta_{g} V_{k}, \quad V_{k+1}(0)=0, \quad|x|<c, \quad k \geq 1 . \tag{B.6}
\end{gather*}
$$

We have the following important equality

$$
\begin{equation*}
\lim _{\operatorname{dist}_{g}(\boldsymbol{p}, \boldsymbol{q}) \rightarrow 0} \mathcal{H}_{a}(t, \boldsymbol{p}, \boldsymbol{q})=|\chi|^{2 a-2-m}(t), \quad \forall a \in \mathbb{C} . \tag{B.7}
\end{equation*}
$$

The asymptotic estimate (B.4) signifies that for any positive integer $\mu$ there exists a positive integer $N(\mu)$ so that for any $N \geq N(\mu)$ the tail

$$
\widetilde{\mathfrak{T}}_{N}(t, \boldsymbol{p}, \boldsymbol{q}):=K_{t}(\boldsymbol{p}, \boldsymbol{q})-\sum_{k=1}^{N} U_{k}(\boldsymbol{p}, \boldsymbol{q}) d_{m}(2 k) \mathcal{H}_{k}(t, \boldsymbol{p}, \boldsymbol{q})
$$

belongs to $C^{\mu}((-c, c) \times M \times M)$ and satisfies the estimates

$$
\begin{equation*}
\left\|\partial_{t}^{j} \widetilde{\mathcal{T}}_{N}(t,-,-)\right\|_{C^{\mu-j}(M \times M)} \leq C|t|^{2 N-n-1-\mu}, \quad|t| \leq c, \quad, j \leq \mu, \quad N \geq N(\mu) \tag{B.8}
\end{equation*}
$$

Fix a point $\boldsymbol{p}_{0} \in M$ and normal coordinates at $\boldsymbol{p}_{0}$ defined in a neighborhood $\mathcal{O}_{0}$ of $\boldsymbol{p}_{0}$. Then we can identify a point $(\boldsymbol{p}, \boldsymbol{q}) \in \mathcal{O}_{0} \times \mathcal{O}_{0}$ with a point $(x, y)$ in a neighborhood of $(0,0)$ in $\mathbb{R}^{m} \times \mathbb{R}^{m}$.

Using (B.2) we deduce

$$
\begin{equation*}
\left.\partial_{x}^{\alpha} \partial_{y}^{\beta} \mathscr{E}^{\varepsilon}(x, y)\right|_{x=y}=\frac{1}{\varepsilon}\langle\underbrace{\left.\partial_{x}^{\alpha} \partial_{y}^{\beta} K_{t}(x, y)\right|_{x=y}}_{=: K_{t}^{\alpha, \beta}}, \widehat{w}\left(\frac{t}{\varepsilon}\right)\rangle . \tag{B.9}
\end{equation*}
$$

Choose an even, nonnegative cutoff function $\rho \in C_{0}^{\infty}(\mathbb{R})$ such that

$$
\rho(t)= \begin{cases}1, & |t| \leq \frac{c}{4}, \\ 0, & |t| \geq \frac{c}{2}\end{cases}
$$

where $c>0$ is the constant in Theorem B.2. Then

$$
\left.\partial_{x}^{\alpha} \partial_{y}^{\beta} \mathscr{E}^{\varepsilon}(x, y)\right|_{x=y}=\frac{1}{\varepsilon}\left\langle K_{t}^{\alpha, \beta}, \rho(t) \widehat{w}\left(\frac{t}{\varepsilon}\right)\right\rangle+\frac{1}{\varepsilon}\left\langle K_{t}^{\alpha, \beta},(1-\rho(t)) \widehat{w}\left(\frac{t}{\varepsilon}\right)\right\rangle .
$$

Let us observe that that for any $N>0$

$$
\frac{1}{\varepsilon}\left\langle K_{t}^{\alpha, \beta},(1-\rho(t)) \widehat{w}\left(\frac{t}{\varepsilon}\right)\right\rangle=O\left(\varepsilon^{N}\right) \text { as } \varepsilon \rightarrow 0
$$

Thus

$$
\begin{equation*}
\forall N>\left.0 \quad \partial_{x}^{\alpha} \partial_{y}^{\beta} \mathscr{E}^{\varepsilon}(x, y)\right|_{x=y} \sim \frac{1}{\varepsilon}\left\langle K_{t}^{\alpha, \beta}, \rho(t) \widehat{w}\left(\frac{t}{\varepsilon}\right)\right\rangle+O\left(\varepsilon^{N}\right), \quad \varepsilon \rightarrow 0 . \tag{B.10}
\end{equation*}
$$

On the other hand

$$
\begin{equation*}
\partial_{x}^{\alpha} \partial_{y}^{\beta} K_{t}(x, y) \sim \sum_{k=1}^{\infty} d_{m}(2 k) \partial_{x}^{\alpha} \partial_{y}^{\beta}\left\{U_{k}(x, y) \mathcal{H}_{k}(t, x, y)\right\} . \tag{B.11}
\end{equation*}
$$

Recall that

$$
d(\alpha, \beta)=\left\lfloor\frac{1}{2}|\alpha+\beta|\right\rfloor .
$$

One can show (see [7, 28])

$$
\begin{equation*}
\left.\partial_{x}^{\alpha} \partial_{y}^{\beta} K_{t}(x, y)\right|_{x=y=0} \sim \sum_{k=0}^{\infty} A_{m, \alpha, \beta, k}|\chi|^{-m-2 d(\alpha, \beta)+2 k}(t), \tag{B.12}
\end{equation*}
$$

where $A_{m, \alpha, \beta, 0}$ is a universal constant depending only on $m, \alpha, \beta$, which is equal to 0 if $|\alpha+\beta|$ is odd.

Lemma B.3. (a) For any $r \in \mathbb{Z}$ and any $N>0$ we have

$$
\left.\left.\left.\frac{1}{\varepsilon}\langle | \chi\right|^{r}, \rho \widehat{w_{\varepsilon}}\right\rangle=\varepsilon^{r}\left(\left.\langle | \chi\right|^{r}, \widehat{w}\right\rangle+O\left(\varepsilon^{N}\right)\right) \text { as } \varepsilon \rightarrow 0 .
$$

(b) For every positive integer $r$ we have

$$
\left.\left.\langle | \chi\right|^{-r}, \widehat{w}\right\rangle=\frac{\sqrt{\pi} 2^{1-r}}{\Gamma\left(\frac{r}{2}\right)} \int_{\mathbb{R}}|\tau|^{r-1} w(\tau) d \tau .
$$

Proof. (a) For transparency we will use the integral notation for the pairing between a generalized function and a test function. We have

$$
\begin{gathered}
\left.\left.\langle | \chi\right|^{r}, \eta \widehat{w_{\varepsilon}}\right\rangle=\frac{1}{\varepsilon} \int_{\mathbb{R}}|\chi|^{r}(t) \rho(t) \widehat{w}(t / \varepsilon) d t=\int_{\mathbb{R}}|\chi|^{r}(\varepsilon t) \rho(\varepsilon t) \widehat{w}(t) d t \\
\left.=\varepsilon^{r} \int_{\mathbb{R}}|\chi|^{r}(t) \rho(\varepsilon t) \widehat{w}(t) d t=\left.\varepsilon^{r}\langle | \chi\right|^{r}, \rho_{\varepsilon} \widehat{w}\right\rangle, \quad \rho_{\varepsilon}(t)=\rho(\varepsilon t) .
\end{gathered}
$$

Now observe that $\rho_{\varepsilon} \widehat{w}-\widehat{w}=\widehat{w}\left(\rho_{\varepsilon}-1\right) \rightarrow 0$ in $\mathcal{S}(\mathbb{R})$. More precisely for $k \geq 0$ we have

$$
\frac{\partial^{k}}{\partial k}\left(\rho_{\varepsilon}-1\right)=O\left(\varepsilon^{N} t^{N}\right) \text { as } \varepsilon \rightarrow 0
$$

This implies that

$$
\left.\left.\langle | \chi\right|^{r}, \widehat{w}\left(\rho_{\varepsilon}-1\right)\right\rangle=O\left(\varepsilon^{N}\right) \text { as } \varepsilon \rightarrow 0,
$$

so that

$$
\left.\left.\left.\left.\left.\langle | \chi\right|^{r}, \rho_{\varepsilon} \widehat{w}\right\rangle=\left.\langle | \chi\right|^{r}, \widehat{w}\right\rangle+\left.\langle | \chi\right|^{r}, \widehat{w}\left(\rho_{\varepsilon}-1\right)\right\rangle=\left.\langle | \chi\right|^{r}, \widehat{w}\right\rangle+O\left(\varepsilon^{N}\right) \text { as } \varepsilon \rightarrow 0 .
$$

(b) We have

$$
\begin{aligned}
\left.\left.\langle | \chi\right|^{-r}, \widehat{w}\right\rangle= & \left.\left.\left\langle\widehat{|\chi|^{-r}}, w\right\rangle \stackrel{(B .3)}{=} \sqrt{\pi} 2^{1-r}\langle | \chi\right|^{r-1}(\tau), w(\tau)\right\rangle \\
& =\frac{\sqrt{\pi} 2^{1-r}}{\Gamma\left(\frac{r}{2}\right)} \int_{\mathbb{R}}|\tau|^{r-1} w(\tau) d \tau .
\end{aligned}
$$

Using (B.10) and the above lemma we deduce

$$
\begin{equation*}
\left.\partial_{x}^{\alpha} \partial_{y}^{\beta} \mathscr{E}^{\varepsilon}(x, y)\right|_{x=y}=D_{m, \alpha, \beta} \varepsilon^{-m-2 d(\alpha, \beta)}+O\left(\varepsilon^{-m-2 d(\alpha, \beta)+2}\right) \quad \text { as } \varepsilon \rightarrow 0 \tag{B.13}
\end{equation*}
$$

where $D_{m, \alpha, \beta}$ is a universal constant that depends only on $m, \alpha, \beta$ which is $=0$ if $|\alpha+\beta|$ is odd,

$$
\begin{equation*}
D_{m, \alpha, \beta}=A_{m, \alpha, \beta, 0} \frac{\sqrt{\pi} 2^{1-r}}{\Gamma\left(\frac{r}{2}\right)} \int_{\mathbb{R}}|\tau|^{r-1} w(\tau) d \tau, \quad r=m+2 d(\alpha, \beta) . \tag{B.14}
\end{equation*}
$$

To determine the constant $D_{m, \alpha, \beta}$ it suffices to compute it for one particular $m$-dimensional Riemann manifold. Assume that $(M, g)$ is the torus $T^{m}$ equipped with the flat metric

$$
g=\sum_{i=1}^{m}\left(d \theta^{i}\right)^{2}, \quad 0 \leq \theta^{i} \leq 2 \pi .
$$

The eigenvalues of the corresponding Laplacian $\Delta_{m}$ are

$$
|\vec{k}|^{2}, \quad \vec{k}=\left(k_{1}, \ldots, k_{m}\right) \in \mathbb{Z}^{m} .
$$

Denote by $\prec$ the lexicographic order on $\mathbb{Z}^{m}$. For $\vec{\theta}=\left(\theta^{1}, \ldots, \theta^{m}\right) \in \mathbb{R}$ and $\vec{k} \in \mathbb{Z}^{m}$ we set

$$
\langle\vec{k}, \vec{\theta}\rangle:=\sum_{j=1}^{m} k_{j} \theta^{j} .
$$

A real orthornormal basis of $L^{2}\left(\mathbb{T}^{m}\right)$ is given by the functions

$$
\Psi_{\vec{k}}(\vec{\theta})=\frac{1}{(2 \pi)^{\frac{m}{2}}} \begin{cases}1, & \vec{k}=\overrightarrow{0} \\ 2^{\frac{1}{2}} \sin \langle\vec{k}, \vec{\theta}\rangle, & \vec{k} \succ \overrightarrow{0}, \\ 2^{\frac{1}{2}} \cos \langle\vec{k}, \vec{\theta}\rangle, & \vec{k} \prec \overrightarrow{0} .\end{cases}
$$

Then

$$
\mathscr{E}^{\varepsilon}(\vec{\theta}, \vec{\varphi})=\frac{1}{(2 \pi)^{m}} \sum_{\vec{k} \in \mathbb{Z}^{m}} w(\varepsilon|\vec{k}|) e^{i\langle\vec{k}, \vec{\theta}-\vec{\varphi}\rangle},
$$

so that

$$
\partial_{\vec{\theta}}^{\alpha} \partial_{\vec{\varphi}}^{\beta} \mathscr{E}^{\varepsilon}(\vec{\theta}, 0)=\frac{i^{|\alpha|-|\beta|}}{(2 \pi)^{m}} \sum_{\vec{k} \in \mathbb{Z}^{m}} w_{\varepsilon}(|\vec{k}|) \vec{k}^{\alpha+\beta} e^{i\langle\vec{k}, \vec{\theta}\rangle} .
$$

Define

$$
W_{m}, u_{\varepsilon}: \mathbb{R}^{m} \rightarrow \mathbb{R}, \quad W_{m}(x)=w(|x|), \quad u_{\varepsilon}(x)=W_{m}(\varepsilon x) x^{\alpha+\beta} .
$$

Using the Poisson summation formula [21, §7.2] we deduce

$$
\partial_{\vec{\theta}}^{\alpha} \partial_{\vec{\varphi}}^{\beta} \mathscr{E}^{\varepsilon}(0,0)=\frac{\boldsymbol{i}^{|\alpha|-|\beta|}}{(2 \pi)^{m}} \sum_{\vec{\nu} \in \mathbb{Z}^{m}} \widehat{u}_{\varepsilon}(2 \pi \vec{\nu}) .
$$

Observe that

$$
\begin{aligned}
& \widehat{u}_{\varepsilon}(\xi)=\int_{\mathbb{R}^{m}} e^{-\boldsymbol{i}\langle\xi, x\rangle} w(\varepsilon|x|) x^{\alpha+\beta} d x=\left(\boldsymbol{i} \partial_{\xi}\right)^{\alpha+\beta}\left(\int_{\mathbb{R}^{m}} e^{-\boldsymbol{i}\langle\xi, x\rangle} W_{m}(\varepsilon x) d x\right) \\
& =\varepsilon^{-m}\left(\boldsymbol{i} \partial_{\xi}\right)^{\alpha+\beta}\left(\int_{\mathbb{R}^{m}} e^{-i\left\langle\frac{1}{\varepsilon} \xi, y\right\rangle} W_{m}(y) d y\right)=\varepsilon^{-m}\left(\boldsymbol{i} \partial_{\xi}\right)^{\alpha+\beta} \widehat{W}_{m}\left(\frac{1}{\varepsilon} \xi\right) .
\end{aligned}
$$

Hence

$$
\partial_{\vec{\theta}}^{\alpha} \partial_{\vec{\varphi}}^{\beta} \mathscr{E}^{\varepsilon}(\vec{\theta}, 0)=\frac{\boldsymbol{i}^{|\alpha|-|\beta|}}{(2 \pi \varepsilon)^{m}} \sum_{\vec{\nu} \in \mathbb{Z}^{m}}\left\{\left(\boldsymbol{i} \partial_{\xi}\right)^{\alpha+\beta} \widehat{W}_{m}\left(\frac{1}{\varepsilon} \xi\right)\right\}_{\xi=2 \pi \vec{\nu}}
$$

As $\varepsilon \rightarrow 0$ we have

$$
\partial_{\vec{\theta}}^{\alpha} \partial_{\vec{\varphi}}^{\beta} \mathscr{E}^{\varepsilon}(0,0)=\varepsilon^{-m-|\alpha+\beta|} \frac{\boldsymbol{i}^{|\alpha|-|\beta|}}{(2 \pi)^{m}}\left(\left(i \partial_{\xi}\right)^{\alpha+\beta} \widehat{W}_{m}(0)+O\left(\varepsilon^{N}\right)\right), \quad \forall N
$$

Now observe that

$$
\left(\boldsymbol{i} \partial_{\xi}\right)^{\alpha+\beta} \widehat{W}_{m}(0)=\int_{\mathbb{R}^{m}} w(|x|) x^{\alpha+\beta} d x
$$

so that

$$
\begin{equation*}
\partial_{\vec{\theta}}^{\alpha} \partial_{\vec{\varphi}^{\beta}}^{\beta} \mathscr{E}^{\varepsilon}(0,0)=\varepsilon^{-m-|\alpha+\beta|} \frac{\left.\right|^{|\alpha|-|\beta|}}{(2 \pi)^{m}}\left(\int_{\mathbb{R}^{m}} w(|x|) x^{\alpha+\beta} d x+O\left(\varepsilon^{N}\right)\right), \quad \forall N \tag{B.15}
\end{equation*}
$$

This shows that

$$
\begin{equation*}
D_{m, \alpha, \beta}=\frac{\boldsymbol{i}^{|\alpha|-|\beta|}}{(2 \pi)^{m}} \int_{\mathbb{R}^{m}} w(|x|) x^{\alpha+\beta} d x \tag{B.16}
\end{equation*}
$$

This completes the proof of Theorem B.1.
Remark B.4. Note that

$$
\int_{\mathbb{R}^{m}} w(|x|) x^{\alpha+\beta} d x=\left(\int_{|x|=1} x^{\alpha+\beta} d A(x)\right) \underbrace{\left(\int_{0}^{\infty} w(r) r^{m+|\alpha+\beta|-1} d r\right)}_{=: I_{m, \alpha, \beta}(w)}
$$

On the other hand, according to [25, Lemma 9.3.10] we have

$$
\int_{|x|=1} x^{\alpha+\beta} d A(x)=Z_{m, \alpha, \beta}:= \begin{cases}\frac{2 \prod_{i=1}^{k} \Gamma\left(\frac{\alpha_{i}+\beta_{i}+1}{2}\right)}{\Gamma\left(\frac{m+\alpha+\beta)}{2}\right)}, & \alpha+\beta \in\left(2 \mathbb{Z}_{\geq 0}\right)^{m}  \tag{B.17}\\ 0, & \text { otherwise }\end{cases}
$$

We can now rewrite (B.16) as

$$
\begin{equation*}
D_{m, \alpha, \beta}=\varepsilon^{-m-|\alpha+\beta|} \frac{\boldsymbol{i}^{|\alpha|-|\beta|} Z_{m, \alpha, \beta}}{(2 \pi)^{m}} I_{m, \alpha, \beta}(w) . \tag{B.18}
\end{equation*}
$$

Theorem B.5. Fix a point $\boldsymbol{p} \in M$ and normal coordinates $\left(x^{i}\right)$ near $\boldsymbol{p}$. For $i \neq j$ we denote by $K_{i j}(\boldsymbol{p})$ the sectional curvature of $g$ at $\boldsymbol{p}$ along the plane spanned by $\partial_{x^{i}}, \partial_{x^{j}}$. For any multi-induces $\alpha, \beta \in\left(\mathbb{Z}_{\geq 0}\right)^{m}$ we set

$$
\mathscr{E}_{\alpha ; \beta}^{\varepsilon}:=\left.\partial_{x}^{\alpha} \partial_{y}^{\beta} \mathscr{E}^{\varepsilon}(x, y)\right|_{x=y=0}
$$

Then there exists a universal constant $z_{m}$ that depends only on the dimension of $M$ and the weight w such that

$$
\begin{equation*}
\mathscr{E}_{i i ; j j}^{\varepsilon}-\mathscr{E}_{i j ; i j}^{\varepsilon}=z_{m} K_{i j}(\boldsymbol{p}) \varepsilon^{-m-2}\left(1+O\left(\varepsilon^{2}\right)\right) \text { as } \varepsilon \rightarrow 0 . \tag{B.19}
\end{equation*}
$$

Proof. Using (B.12) we deduce

$$
\begin{equation*}
\mathscr{E}_{i i i j j j}^{\varepsilon}-\mathscr{E}_{i j ; i j}^{\varepsilon} \sim \frac{1}{\varepsilon}\left\langle K_{t}^{i i, j j}-K_{t}^{i j, i j}, \eta(t) \widehat{w}\left(\frac{t}{\varepsilon}\right)\right\rangle+O\left(\varepsilon^{N}\right), \quad \varepsilon \rightarrow 0 \tag{B.20}
\end{equation*}
$$

On the other hand from (B.9) we conclue

$$
\begin{equation*}
K_{t}^{i i, j j}-\left.K_{t}^{i j, i j} \sim \sum_{k=1}^{\infty} d_{m}(2 k)\left(\partial_{x^{i}}^{2} \partial_{y^{j}}^{2}-\partial_{x^{i} x^{j}}^{2} \partial_{y^{i} y^{j}}^{2}\right)\left\{U_{k}(x, y) \mathcal{H}_{k}(t, x, y)\right\}\right|_{x=y=0} \tag{B.21}
\end{equation*}
$$

To investigate the above asymptotics we use the technology in [28].
Let us introduce some notations. For a positive integer $k$ we denote by $\partial^{k}$ a generic mixed-partial derivative of order $k$ in the variables $x^{i}, y^{j}$. We denote by $\partial^{k} \eta$ the collection of $k$-th order derivatives of $\eta(x, y) . \mathcal{P}_{i}(X)$ will denote a homogeneous polynomial of degree $i$ in the variables $X$, while $\mathcal{P}_{k}(X) \mathcal{P}_{\ell}(Y)$ will denote a polynomial which is homogeneous of degree $k$ in the variables $X$ and of degree $\ell$ in the variables $Y$. We then have the equalities

$$
\begin{gather*}
\mathcal{H}_{a}=\mathcal{P}_{1}(\partial \eta) \mathcal{H}_{a-1},  \tag{B.22}\\
\partial^{2} \mathcal{H}_{a}=\mathcal{P}_{2}(\partial \eta) \mathcal{H}_{a-2}+\mathcal{P}_{1}\left(\partial^{2} \eta\right) \mathcal{H}_{a-1},  \tag{B.23}\\
\partial^{3} \mathcal{H}_{a}=\mathcal{P}_{3}(\partial \eta) \mathcal{H}_{a-3}+\mathcal{P}_{1}(\partial \eta) \mathcal{P}_{1}\left(\partial^{2} \eta\right) \mathcal{H}_{a-2}+\mathcal{P}_{1}\left(\partial^{3} \eta\right) \mathcal{H}_{a-1},  \tag{B.24}\\
\partial^{4} \mathcal{H}_{a}=\mathcal{P}_{4}(\partial \eta) \mathcal{H}_{a-4}+\left(\mathcal{P}_{2}(\partial \eta) \mathcal{P}_{1}\left(\partial^{2} \eta\right)\right) \mathcal{H}_{a-3} \\
+\left(\mathcal{P}_{2}\left(\partial^{2} \eta\right)+\mathcal{P}_{1}(\partial \eta) \mathcal{P}_{1}\left(\partial^{3} \eta\right)\right) \mathcal{H}_{a-2}+\mathcal{P}_{1}\left(\partial^{4} \eta\right) \mathcal{H}_{a-1} . \tag{B.25}
\end{gather*}
$$

To simplify the presentation we will assume that in (B.19) we have $i=1, j=2$. Also, we will denote by $O(1)$ a function $f(x, y)$ such that $\left.f(x, y)\right|_{x=y=0}=0$. The computations in Section A show that for $x=0$ terms of the form $\mathcal{P}_{j}(\partial \eta)$ and $\mathcal{P}_{k}\left(\partial^{3} \eta\right)$ are $O(1)$. In particular, the above equalities show that the 1st and 3rd order derivatives of $\mathcal{H}^{a}$ are $O(1)$. We have

$$
\begin{array}{r}
\partial_{x^{1}}^{2} \partial_{y^{2}}^{2}\left(U_{k} \mathcal{H}_{k}\right)=\partial_{x^{1}}^{2}\left(\left(\partial_{y^{2}}^{2} U_{k}\right) \mathcal{H}_{k}+2 \partial_{y^{2}} U_{k} \partial_{y^{2}} \mathcal{H}_{k}+U_{k} \partial_{y^{2}}^{2} \mathcal{H}_{k}\right) \\
=\left(\partial_{x^{1}}^{2} \partial_{y^{2}}^{2} U_{k}\right) \mathcal{H}_{k}+\left(\partial_{y^{2}}^{2} U_{k}\right)\left(\partial_{x^{1}}^{2} \mathcal{H}_{k}\right)+\left(\partial_{x^{1}}^{2} U_{k}\right)\left(\partial_{y^{2}}^{2} \mathcal{H}_{k}\right) \\
+4\left(\partial_{x^{1} y^{2}}^{2} U_{k}\right)\left(\partial_{x^{1} y^{2}}^{2} \mathcal{H}_{k}\right)+U_{k} \partial_{x^{1}}^{2} \partial_{y^{2}}^{2} \mathcal{H}_{k}+O(1), \\
\partial_{x^{1} x^{2}}^{2} \partial_{y^{1} y^{2}}^{2}\left(U_{k} \mathcal{H}_{k}\right)=\partial_{x^{1} x^{2}}^{2}\left(\left(\partial_{y^{1} y^{2}}^{2} U_{k}\right) \mathcal{H}_{k}+\partial_{y^{1}} U_{k} \partial_{y^{2}} \mathcal{H}_{k}+\partial_{y^{2}} U_{k} \partial_{y^{1}} \mathcal{H}_{k}+U_{k} \partial_{y^{1} y^{2}}^{2} \mathcal{H}_{k}\right) \\
=\left(\partial_{x^{1} x^{2}}^{2} \partial_{y^{1} y^{2}}^{2} U_{k}\right) \mathcal{H}_{k}+\left(\partial_{y^{1} y^{2}}^{2} U_{k}\right)\left(\partial_{x^{1} x^{2}}^{2} \mathcal{H}_{k}\right) \\
+\partial_{x^{2} y^{1}}^{2} U_{k} \partial_{x^{1} y^{2}}^{2} \mathcal{H}_{k}+\partial_{x^{1} y^{1}}^{2} U_{k} \partial_{x^{2} y^{2}}^{2} \mathcal{H}_{k}+\partial_{x^{2} 2^{2}}^{2} U_{k} \partial_{x^{1} y^{1}} \mathcal{H}_{k}+\partial_{x^{1}{ }^{2}}^{2} U_{k} \partial_{x^{2} y^{1}}^{2} \mathcal{H}_{k} \\
+\partial_{x^{1} x^{2}}^{2} U_{k} \partial_{y^{1} y^{2}} \mathcal{H}_{k}+U_{k} \partial_{x^{1} x^{2}}^{2} \partial_{y^{1} y^{2}}^{2} \mathcal{H}_{k}+O(1) \tag{B.27}
\end{array}
$$

He deduce that

$$
\left(\partial_{x^{1}}^{2} \partial_{y^{2}}^{2}-\partial_{x^{1} x^{2}}^{2} \partial_{y^{1} y^{2}}^{2}\right)\left(U_{k} \mathcal{H}_{k}\right)_{x=y=0}=\left.\sum_{j=0}^{4} T_{k}^{j} \mathcal{H}^{k-j}\right|_{x=y=0}
$$

where the coefficients $T_{k}^{j}$ are polynomials in the derivatives of $U_{k}$ and $\eta$ at $(x, y)=(0,0)$. Using (B.22)-(B.25) we deduce

$$
T_{k}^{4}=T_{k}^{3}=0
$$

Moreover, the terms that appear in $T_{k}^{2}$ appear only when we take forth order derivatives of $\mathcal{H}_{k}$. Upon inspecting (B.26) and (B.27) we see that the 4th order derivatives of $\mathcal{H}_{k}$ are multiplied by $U_{k}$. According to (B.6) the function $U_{k}$ is $O(1)$ if $k>1$. Hence $T_{k}^{2}=0$ for $k>1$. We deduce

$$
\begin{gathered}
K_{t}^{i i, j j}-\left.K_{t}^{i j, i j} \sim \sum_{k=1}^{\infty} d_{m}(2 k)\left(T_{k}^{0} \mathcal{H}_{k}+T_{k}^{1} \mathcal{H}_{k-1}+T_{k}^{2} \mathcal{H}_{k-2}\right)\right|_{x=y=0} \\
\quad=\left.B_{-1} \mathcal{H}_{-1}\right|_{x=y=0}+\left.B_{0} \mathcal{H}_{0}\right|_{x=y=0}+\left.B_{1} \mathcal{H}_{1}\right|_{x=y=0}+\cdots
\end{gathered}
$$

where

$$
B_{-1}=d_{m}(2) T_{1}^{2}, \quad B_{0}=d_{m}(2) T_{1}^{1}, \quad B_{1}=d_{m}(2) T_{1}^{0}+d_{m}(4) T_{2}^{1}, \ldots
$$

The term $B_{-1}$ can be alternatively described as

$$
B_{-1}=A_{m, i i ; j j, 0}-A_{m, i j ; i j, 0},
$$

where the coefficients $A_{m, \alpha, \beta, 0}$ are defined as in (B.12). Using (B.14) and (B.16) we deduce

$$
B_{-1}=0 .
$$

To compute $T_{1}^{1}$ we observe first that

$$
\begin{equation*}
\eta(x-y)=\sum_{i}\left(x^{i}-y^{i}\right)^{2}+\text { higer order terms } \tag{B.28}
\end{equation*}
$$

Using (B.23) we can simplify (B.26) and (B.27) in the case $k=1$ as follows.

$$
\begin{align*}
\partial_{x^{1}}^{2} \partial_{y^{2}}^{2}\left(U_{1} \mathcal{H}_{1}\right)=\left(\partial_{x^{1}}^{2} \partial_{y^{2}}^{2} U_{1}\right) \mathcal{H}_{1}+U_{1} \partial_{x^{1}}^{2} \partial_{y^{2}}^{2} \mathcal{H}_{1}+O(1),  \tag{B.29}\\
\partial_{x^{1} x^{2}}^{2} \partial_{y^{1} y^{2}}^{2}\left(U_{1} \mathcal{H}_{1}\right)=\left(\partial_{x^{1} x^{2}}^{2} \partial_{y^{1} y^{2}}^{2} U_{1}\right) \mathcal{H}_{1}+\partial_{x^{1} y^{1}}^{2} U_{1} \partial_{x^{2} y^{2}}^{2} \mathcal{H}_{1} \\
+\partial_{x^{2} y^{2}}^{2} U_{1} \partial_{x^{1} y^{1}} \mathcal{H}_{1}+U_{1} \partial_{x^{1} x^{2}}^{2} \partial_{y^{1} y^{2}}^{2} \mathcal{H}_{1}+O(1) . \tag{B.30}
\end{align*}
$$

Using (B.23), (B.25) and (B.28) we deduce that

$$
\begin{array}{r}
T_{1}^{1}=\left.\left(\partial_{x^{1}}^{2} \partial_{y^{2}}^{2}-\partial_{x^{1} x^{2}}^{2} \partial_{y^{1} y^{2}}^{2}\right) \eta\right|_{(0,0)} \\
+\left.2\left(\partial_{x^{1}}^{2} U_{1}+\partial_{y^{2}}^{2} U_{1}\right)\right|_{(0,0)}+\left.2\left(\partial_{x^{1} y^{1}}^{2} U_{1}+\partial_{x^{2} y^{2}}^{2} U_{1}\right)\right|_{(0,0)}
\end{array}
$$

Using the transport equation (B.5) we obtain as in [10, VI.3] that $U_{1}$ coincides with the function $\varphi(x, y)$ in [10, VI.3 Eq.(33)] or the function $u_{0}(x, y)$ in [6, p. 380]. For our purposes an explicit description of $U_{1}$ is not needed. All we care is that

$$
U_{1}(x, y)=U_{1}(y, x), \quad U_{1}(x, x) \equiv 1
$$

These conditions imply that the Hessian of $U_{1}(x, y)$ at $(0,0)$ is a quadratic form in the variables $u_{i}=\left(x^{i}-y^{i}\right)$ so that

$$
\partial_{x^{1}}^{2} U_{1}(0,0)+\partial_{x^{1} y^{1}}^{2} U_{1}(0,0)=\partial_{y^{2}}^{2} U_{1}(0,0)+\partial_{x^{2} y^{2}}^{2} U_{1}(0,0)=0
$$

Hence

$$
T_{1}^{1}=\left.\left(\partial_{x^{1}}^{2} \partial_{y^{2}}^{2}-\partial_{x^{1} x^{2}}^{2} \partial_{y^{1} y^{2}}^{2}\right) \eta\right|_{(0,0)} .
$$

Using (A.17) we conclude that

$$
T_{1}^{1}=Z R_{1212}=Z K_{12}(\boldsymbol{p})
$$

where $Z$ is a universal constant, independent of $(M, g)$. Hence

$$
K_{t}^{i i, j j}-\left.K_{t}^{i j, i j} \sim d_{m}(2) Z K_{12}(\boldsymbol{p}) \mathcal{H}^{0}\right|_{x=y=0}+\left.\sum_{k \geq 1} B_{k} \mathcal{H}_{k}\right|_{x=y=0}
$$

The equality (B.19) now follows from the above equality by using (B.20), (B.7) and Lemma B.3.

## Appendix C. Gaussian measures and Gaussian vectors

For the reader's convenience we survey here a few basic facts about Gaussian measures. For more details we refer to [8]. A Gaussian measure on $\mathbb{R}$ is a Borel measure $\gamma_{\mu, v}, v \geq 0, m \in \mathbb{R}$, of the form

$$
\gamma_{\mu, v}(x)=\frac{1}{\sqrt{2 \pi v}} e^{-\frac{(x-\mu)^{2}}{2 v}} d x
$$

The scalar $\mu$ is called the mean, while $v$ is called the variance. We allow $v$ to be zero in which case

$$
\gamma_{\mu, 0}=\delta_{\mu}=\text { the Dirac measure on } \mathbb{R} \text { concentrated at } \mu
$$

For a real valued random variable $X$ we write

$$
\begin{equation*}
X \in \boldsymbol{N}(\mu, v) \tag{C.1}
\end{equation*}
$$

if the probability measure of $X$ is $\gamma_{\mu, v}$.
Suppose that $\boldsymbol{V}$ is a finite dimensional vector space. A Gaussian measure on $\boldsymbol{V}$ is a Borel measure $\gamma$ on $\boldsymbol{V}$ such that, for any $\xi \in \boldsymbol{V}^{\vee}$, the pushforward $\xi_{*}(\gamma)$ is a Gaussian measure on $\mathbb{R}$,

$$
\xi_{*}(\gamma)=\gamma_{\mu(\xi), v(\xi)}
$$

One can show that the map $\boldsymbol{V}^{\vee} \ni \xi \mapsto \mu(\xi) \in \mathbb{R}$ is linear, and thus can be identified with a vector $\boldsymbol{\mu}_{\gamma} \in \boldsymbol{V}$ called the barycenter or expectation of $\gamma$ that can be alternatively defined by the equality

$$
\boldsymbol{\mu}_{\gamma}=\int_{\boldsymbol{V}} \boldsymbol{v} d \gamma(\boldsymbol{v})
$$

Moreover, there exists a nonnegative definite, symmetric bilinear map

$$
\boldsymbol{\Sigma}: \boldsymbol{V}^{\vee} \times \boldsymbol{V}^{\vee} \rightarrow \mathbb{R} \text { such that } v(\xi)=\boldsymbol{\Sigma}(\xi, \xi), \quad \forall \xi \in \boldsymbol{V}^{\vee}
$$

The form $\boldsymbol{\Sigma}$ is called the covariance form and can be identified with a linear operator $\boldsymbol{S}: \boldsymbol{V}^{\vee} \rightarrow \boldsymbol{V}$ such that

$$
\boldsymbol{\Sigma}(\xi, \eta)=\langle\xi, \boldsymbol{S} \eta\rangle, \quad \forall \xi, \eta \in \boldsymbol{V}^{\vee}
$$

where $\langle-,-\rangle: V^{\vee} \times \boldsymbol{V} \rightarrow \mathbb{R}$ denotes the natural bilinear pairing between a vector space and its dual. The operator $S$ is called the covariance operator and it is explicitly described by the integral formula

$$
\langle\xi, \boldsymbol{S} \eta\rangle=\boldsymbol{\Sigma}(\xi, \eta)=\int_{\boldsymbol{V}}\left\langle\xi, \boldsymbol{v}-\boldsymbol{\mu}_{\gamma}\right\rangle\left\langle\eta, \boldsymbol{v}-\boldsymbol{\mu}_{\gamma}\right\rangle d \gamma(\boldsymbol{v})
$$

The Gaussian measure is said to be nondegenerate if $\boldsymbol{\Sigma}$ is nondegenerate, and it is called centered if $\boldsymbol{\mu}=0$. A Gaussian measure on $\boldsymbol{V}$ is uniquely determined by its covariance form and its expectation.

Example C.1. Suppose that $\boldsymbol{U}$ is an $n$-dimensional Euclidean space with inner product $(-,-)$. We use the inner product to identify $\boldsymbol{U}$ with its dual $\boldsymbol{U}^{\vee}$. If $A: \boldsymbol{U} \rightarrow \boldsymbol{U}$ is a symmetric, positive definite operator, then

$$
\begin{equation*}
\boldsymbol{\gamma}_{A}(d \boldsymbol{u})=\frac{1}{(2 \pi)^{\frac{n}{2}} \sqrt{\operatorname{det} A}} e^{-\frac{1}{2}\left(A^{-1} \boldsymbol{u}, \boldsymbol{u}\right)}|d \boldsymbol{u}| \tag{C.2}
\end{equation*}
$$

is a centered Gaussian measure on $\boldsymbol{U}$ with covariance form described by the operator $A$.
If $\boldsymbol{V}$ is a finite dimensional vector space equipped with a Gaussian measure $\gamma$ and $\boldsymbol{L}: \boldsymbol{V} \rightarrow \boldsymbol{U}$ is a linear map, then the pushforward $\boldsymbol{L}_{*} \gamma$ is a Gaussian measure on $\boldsymbol{U}$ with expectation $\boldsymbol{\mu}_{\boldsymbol{L}_{*} \gamma}=\boldsymbol{L}\left(\boldsymbol{\mu}_{\gamma}\right)$ and covariance form

$$
\boldsymbol{\Sigma}_{\boldsymbol{L}_{* \gamma}}: \boldsymbol{U}^{\vee} \times \boldsymbol{U}^{\vee} \rightarrow \mathbb{R}, \quad \boldsymbol{\Sigma}_{\boldsymbol{L}_{*} \gamma}(\eta, \eta)=\boldsymbol{\Sigma}_{\gamma}\left(\boldsymbol{L}^{\vee} \eta, \boldsymbol{L}^{\vee} \eta\right), \quad \forall \eta \in \boldsymbol{U}^{\vee},
$$

where $\boldsymbol{L}^{\vee}: \boldsymbol{U}^{\vee} \rightarrow \boldsymbol{V}^{\vee}$ is the dual (transpose) of the linear map $\boldsymbol{L}$. Observe that if $\gamma$ is nondegenerate and $\boldsymbol{L}$ is surjective, then $\boldsymbol{L}_{*} \gamma$ is also nondegenerate.

Suppose $(\mathcal{S}, \mu)$ is a probability space. A Gaussian random vector on $(\mathcal{S}, \mu)$ is a (Borel) measurable map

$$
X: \mathcal{S} \rightarrow \boldsymbol{V}, \quad \boldsymbol{V} \text { finite dimensional vector space }
$$

such that $X_{*} \mu$ is a Gaussian measure on $\boldsymbol{V}$. We will refer to this measure as the associated Gaussian measure, we denote it by $\gamma_{X}$ and we denote by $\boldsymbol{\Sigma}_{X}$ (respectively $\boldsymbol{S}(X)$ ) its covariance form (respectively operator),

$$
\boldsymbol{\Sigma}_{X}\left(\xi_{1}, \xi_{2}\right)=\boldsymbol{E}\left(\left\langle\xi_{1}, X-\boldsymbol{E}(X)\right\rangle\left\langle\xi_{2}, X-\boldsymbol{E}(X)\right\rangle\right)
$$

Note that the expectation of $\gamma_{X}$ is precisely the expectation of $X$. The random vector is called nondegenerate, respectively centered, if the Gaussian measure $\gamma_{X}$ is such.

Let us point out that if $X: \mathcal{S} \rightarrow \boldsymbol{U}$ is a Gaussian random vector and $\boldsymbol{L}: \boldsymbol{U} \rightarrow \boldsymbol{V}$ is a linear map, then the random vector $\boldsymbol{L} X: \mathcal{S} \rightarrow \boldsymbol{V}$ is also Gaussian. Moreover

$$
\boldsymbol{E}(\boldsymbol{L} X)=\boldsymbol{L} \boldsymbol{E}(X), \quad \boldsymbol{\Sigma}_{\boldsymbol{L} X}(\xi, \xi)=\boldsymbol{\Sigma}_{X}\left(\boldsymbol{L}^{\vee} \xi, \boldsymbol{L}^{\vee} \xi\right), \quad \forall \xi \in \boldsymbol{V}^{\vee}
$$

where $\boldsymbol{L}^{\vee}: \boldsymbol{V}^{\vee} \rightarrow \boldsymbol{U}^{\vee}$ is the linear map dual to $\boldsymbol{L}$. Equivalently, $\boldsymbol{S}(\boldsymbol{L} X)=\boldsymbol{L} \boldsymbol{S}(X) \boldsymbol{L}^{\vee}$.
Suppose that $X_{j}: \mathcal{S} \rightarrow \boldsymbol{V}_{1}, j=1,2$, are two centered Gaussian random vectors such that the direct sum $X_{1} \oplus X_{2}: \mathcal{S} \rightarrow \boldsymbol{V}_{1} \oplus \boldsymbol{V}_{2}$ is also a centered Gaussian random vector with associated Gaussian measure

$$
\gamma_{X_{1} \oplus X_{2}}=p_{X_{1} \oplus X_{2}}\left(\boldsymbol{x}_{1}, \boldsymbol{x}_{2}\right)\left|d \boldsymbol{x}_{1} d \boldsymbol{x}_{2}\right| .
$$

We obtain a bilinear form

$$
\operatorname{cov}\left(X_{1}, X_{2}\right): \boldsymbol{V}_{1}^{\vee} \times \boldsymbol{V}_{2}^{\vee} \rightarrow \mathbb{R}, \quad \operatorname{cov}\left(X_{1}, X_{2}\right)\left(\xi_{1}, \xi_{2}\right)=\boldsymbol{\Sigma}\left(\xi_{1}, \xi_{2}\right),
$$

called the covariance form. The random vectors $X_{1}$ and $X_{2}$ are independent if and only if they are uncorrelated, i.e.,

$$
\boldsymbol{\operatorname { c o v }}\left(X_{1}, X_{2}\right)=0 .
$$

We can then identify $\boldsymbol{\operatorname { c o v }}\left(X_{1}, X_{2}\right)$ with a linear operator $\boldsymbol{\operatorname { C o v }}\left(X_{1}, X_{2}\right): \boldsymbol{V}_{2} \rightarrow \boldsymbol{V}_{1}$, via the equality

$$
\begin{aligned}
\boldsymbol{E}\left(\left\langle\xi_{1}, X_{1}\right\rangle\left\langle\xi_{2}, X_{2}\right\rangle\right) & =\boldsymbol{\operatorname { c o v }}\left(X_{1}, X_{2}\right)\left(\xi_{1}, \xi_{2}\right) \\
& =\left\langle\xi_{1}, \boldsymbol{\operatorname { C o v }}\left(X_{1}, X_{2}\right) \xi_{2}^{\dagger}\right\rangle, \quad \forall \xi_{1} \in \boldsymbol{V}_{1}^{\vee}, \quad \xi_{2} \in \boldsymbol{V}_{2}^{\vee},
\end{aligned}
$$

where $\xi_{2}^{\dagger} \in \boldsymbol{V}_{2}$ denotes the vector metric dual to $\xi_{2}$. The operator $\boldsymbol{\operatorname { C o v }}\left(X_{1}, X_{2}\right)$ is called the covariance operator of $X_{1}, X_{2}$.

The conditional random variable ( $X_{1} \mid X_{2}=x_{2}$ ) has probability density

$$
p_{\left(X_{1} \mid X_{2}=\boldsymbol{x}_{2}\right)}\left(\boldsymbol{x}_{1}\right)=\frac{p_{X_{1} \oplus X_{2}}\left(\boldsymbol{x}_{1}, \boldsymbol{x}_{2}\right)}{\int_{\boldsymbol{V}_{1}} p_{X_{1} \oplus X_{2}}\left(\boldsymbol{x}_{1}, \boldsymbol{x}_{2}\right)\left|d \boldsymbol{x}_{1}\right|} .
$$

For a measurable function $f: \boldsymbol{V}_{1} \rightarrow \mathbb{R}$ the conditional expectation $\boldsymbol{E}\left(f\left(X_{1}\right) \mid X_{2}=\boldsymbol{x}_{2}\right)$ is the (deterministic) scalar

$$
\boldsymbol{E}\left(f\left(X_{1}\right) \mid X_{2}=\boldsymbol{x}_{2}\right)=\int_{\boldsymbol{V}_{1}} f\left(\boldsymbol{x}_{1}\right) p_{\left(X_{1} \mid X_{2}=\boldsymbol{x}_{2}\right)}\left(\boldsymbol{x}_{1}\right)\left|d \boldsymbol{x}_{1}\right| .
$$

If $X_{2}$ is nondegenerate, the regression formula, [5], implies that the random vector $\left(X_{1} \mid X_{2}=x_{2}\right)$ is a Gausian vector with covariance operator

$$
\begin{equation*}
\boldsymbol{S}(Y)=\boldsymbol{S}\left(X_{1}\right)-\boldsymbol{\operatorname { C o v }}\left(X_{1}, X_{2}\right) \boldsymbol{S}\left(X_{2}\right)^{-1} \boldsymbol{\operatorname { C o v }}\left(X_{2}, X_{1}\right), \tag{C.3}
\end{equation*}
$$

and mean

$$
\begin{equation*}
\boldsymbol{E}\left(X_{1} \mid X_{2}=x_{2}\right)=C x_{2}, \tag{C.4}
\end{equation*}
$$

where $C$ is given by

$$
\begin{equation*}
C=\boldsymbol{C o v}\left(X_{1}, X_{2}\right) \boldsymbol{S}\left(X_{2}\right)^{-1} . \tag{C.5}
\end{equation*}
$$

## Appendix D. A class of random symmetric matrices

We denote by $\mathrm{Sym}_{m}$ the space of real symmetric $m \times m$ matrices. This is an Euclidean space with respect to the inner product

$$
(A, B):=\operatorname{tr}(A B) .
$$

This inner product is invariant with respect to the action of $\mathrm{SO}(m)$ on $\mathrm{Sym}_{m}$. We set

$$
\widehat{\boldsymbol{E}}_{i j}:=\left\{\begin{array}{ll}
\boldsymbol{E}_{i j}, & i=j \\
\frac{1}{\sqrt{2}} E_{i j}, & i<j .
\end{array} .\right.
$$

The collection $\left(\widehat{\boldsymbol{E}}_{i j}\right)_{i \leq j}$ is a basis of $\mathrm{Sym}_{m}$ orthonormal with respect to the above inner product. We set

$$
\hat{a}_{i j}:= \begin{cases}a_{i j}, & i=j \\ \sqrt{2} a_{i j}, & i<j .\end{cases}
$$

The collection $\left(\hat{a}_{i j}\right)_{i \leq j}$ the orthonormal basis of $\operatorname{Sym}_{m}^{\vee}$ dual to $\left(\widehat{\boldsymbol{E}}_{i j}\right)$. The volume density induced by this metric is

$$
|d A|:=\prod_{i \leq j} d \widehat{a}_{i j}=2^{\frac{1}{2}\binom{m}{2}} \prod_{i \leq j} d a_{i j} .
$$

Throughout the paper we encountered a 2 -parameter family of Gaussian probability measures on $\mathrm{Sym}_{m}$. More precisely for any real numbers $u, v$ such that

$$
v>0, m u+2 v>0,
$$

we denote by $\operatorname{Sym}_{m}^{u, v}$ the space $\operatorname{Sym}_{m}$ equipped with the centered Gaussian measure $d \boldsymbol{\Gamma}_{u, v}(A)$ uniquely determined by the covariance equalities

$$
\boldsymbol{E}\left(a_{i j} a_{k \ell}\right)=u \delta_{i j} \delta_{k \ell}+v\left(\delta_{i k} \delta_{j \ell}+\delta_{i \ell} \delta_{j k}\right), \quad \forall 1 \leq i, j, . k, \ell \leq m .
$$

In particular we have

$$
\boldsymbol{E}\left(a_{i i}^{2}\right)=u+2 v, \quad \boldsymbol{E}\left(a_{i i} a_{j j}\right)=u, \quad \boldsymbol{E}\left(a_{i j}^{2}\right)=v, \quad \forall 1 \leq i \neq j \leq m,
$$

while all other covariances are trivial. The ensemble $\operatorname{Sym}_{m}^{0, v}$ is a rescaled version of of the Gaussian Orthogonal Ensemble (GOE) and we will refer to it as $\mathrm{GOE}_{m}^{v}$.

For $u>0$ the ensemble $\operatorname{Sym}_{m}^{u, v}$ can be given an alternate description. More precisely a random $A \in \operatorname{Sym}_{m}^{u, v}$ can be described as a sum

$$
A=B+X \mathbb{1}_{m}, \quad B \in \operatorname{GOE}_{m}^{v}, \quad X \in \boldsymbol{N}(0, u), \quad B \text { and } X \text { independent } .
$$

We write this

$$
\begin{equation*}
\operatorname{Sym}_{m}^{u, v}=\operatorname{GOE}_{m}^{v} \hat{+} \boldsymbol{N}(0, u) \mathbb{1}_{m}, \tag{D.1}
\end{equation*}
$$

where $\hat{+}$ indicates a sum of independent variables.
The Gaussian measure $d \boldsymbol{\Gamma}_{u, v}$ coincides with the Gaussian measure $d \boldsymbol{\Gamma}_{u+2 v, u, v}$ defined in [26, App. B]. We recall a few facts from [26, App. B].

The probability density $d \boldsymbol{\Gamma}_{u, v}$ has the explicit description

$$
d \boldsymbol{\Gamma}_{u, v}(A)=\frac{1}{(2 \pi)^{\frac{m(m+1)}{4}} \sqrt{D(u, v)}} e^{-\frac{1}{4 v} \operatorname{tr} A^{2}-\frac{u^{\prime}}{2}(\operatorname{tr} A)^{2}}|d A|,
$$

where

$$
D(u, v)=(2 v)^{(m-1)+\binom{m}{2}}(m u+2 v)
$$

and

$$
u^{\prime}=\frac{1}{m}\left(\frac{1}{m u+2 v}-\frac{1}{2 v}\right)=-\frac{u}{2 v(m u+2 v)} .
$$

In the special case $\operatorname{GOE}_{m}^{v}$ we have $u=u^{\prime}=0$ and

$$
\begin{equation*}
d \boldsymbol{\Gamma}_{0, v}(A)=\frac{1}{(2 \pi v)^{\frac{m(m+1)}{4}}} e^{-\frac{1}{4 v} \operatorname{tr} A^{2}}|d A| . \tag{D.2}
\end{equation*}
$$

We have a Weyl integration formula [3] which states that if $f: \operatorname{Sym}_{m} \rightarrow \mathbb{R}$ is a measurable function which is invariant under conjugation, then the the value $f(A)$ at $A \in \operatorname{Sym}_{m}$ depends only on the eigenvalues $\lambda_{1}(A) \leq \cdots \leq \lambda_{n}(A)$ of $A$ and we have

$$
\begin{equation*}
\boldsymbol{E}_{\mathrm{GOE}_{m}^{v}}(f(X))=\frac{1}{\boldsymbol{Z}_{m}(v)} \int_{\mathbb{R}^{m}} f\left(\lambda_{1}, \ldots, \lambda_{m}\right) \underbrace{\left(\prod_{1 \leq i<j \leq m}\left|\lambda_{i}-\lambda_{j}\right|\right) \prod_{i=1}^{m} e^{-\frac{\lambda_{i}^{2}}{4 v}}}_{=: Q_{m, v}(\lambda)}\left|d \lambda_{1} \cdots d \lambda_{m}\right|, \tag{D.3}
\end{equation*}
$$

where the normalization constant $\boldsymbol{Z}_{m}(v)$ is defined by

$$
\begin{aligned}
& \boldsymbol{Z}_{m}(v)=\int_{\mathbb{R}^{m}} \prod_{1 \leq i<j \leq m}\left|\lambda_{i}-\lambda_{j}\right| \prod_{i=1}^{m} e^{-\frac{\lambda_{i}^{2}}{4 v}}\left|d \lambda_{1} \cdots d \lambda_{m}\right| \\
&=(2 v)^{\frac{m(m+1)}{4}} \\
& \underbrace{\int_{\mathbb{R}^{m}} \prod_{1 \leq i<j \leq m}\left|\lambda_{i}-\lambda_{j}\right| \prod_{i=1}^{m} e^{-\frac{\lambda_{i}^{2}}{2}}\left|d \lambda_{1} \cdots d \lambda_{m}\right|}_{=: \boldsymbol{Z}_{m}}
\end{aligned}
$$

The precise value of $\boldsymbol{Z}_{m}$ can be computed via Selberg integrals, [3, Eq. (2.5.11)], and we have

$$
\begin{equation*}
\boldsymbol{Z}_{m}=(2 \pi)^{\frac{m}{2}} m!\prod_{j=1}^{m} \frac{\Gamma\left(\frac{j}{2}\right)}{\Gamma\left(\frac{1}{2}\right)}=2^{\frac{m}{2}} m!\prod_{j=1}^{m} \Gamma\left(\frac{j}{2}\right) . \tag{D.4}
\end{equation*}
$$

For any positive integer $n$ we define the normalized 1-point corelation function $\rho_{n, v}(x)$ of $\mathrm{GOE}_{n}^{v}$ to be

$$
\rho_{n, v}(x)=\frac{1}{Z_{n}(v)} \int_{\mathbb{R}^{n-1}} Q_{n, v}\left(x, \lambda_{2}, \ldots, \lambda_{n}\right) d \lambda_{1} \cdots d \lambda_{n}
$$

For any Borel measurable function $f: \mathbb{R} \rightarrow \mathbb{R}$ we have $[11, \S 4.4]$

$$
\begin{equation*}
\frac{1}{n} \boldsymbol{E}_{\mathrm{GOE}_{n}^{v}}(\operatorname{tr} f(X))=\int_{\mathbb{R}} f(\lambda) \rho_{n, v}(\lambda) d \lambda \tag{D.5}
\end{equation*}
$$

The equality (D.5) characterizes $\rho_{n, v}$. Let us observe that for any constant $c>0$, if

$$
A \in \operatorname{GOE}_{n}^{v} \Longleftrightarrow c A \in \operatorname{GOE}_{n}^{c^{2} v}
$$

Hence for any Borel set $B \subset \mathbb{R}$ we have

$$
\int_{c B} \rho_{n, c^{2} v}(x) d x=\int_{B} \rho_{n, v}(y) d y
$$

We conclude that

$$
\begin{equation*}
c \rho_{n, c^{2} v}(c y)=\rho_{n, v}(y), \quad \forall n, c, y . \tag{D.6}
\end{equation*}
$$

The behavior of the 1-point correlation function $\rho_{n, v}(x)$ for $n$ large is described by Wigner semicircle theorem [3, Thm.2.1.1] which states that for any $v>0$ the sequence of probability measures on $\mathbb{R}$

$$
\rho_{n, v n^{-1}}(x) d x=n^{\frac{1}{2}} \rho_{n, v}\left(n^{\frac{1}{2}} x\right) d x
$$

converges weakly as $n \rightarrow \infty$ to the semicircle distribution

$$
\rho_{\infty, v}(x)|d x|=\boldsymbol{I}_{\{|x| \leq 2 \sqrt{v}\}} \frac{1}{2 \pi v} \sqrt{4 v-x^{2}}|d x| .
$$

The expected value of the absolute value of the determinant of of a random $A \in \mathrm{GOE}_{m}^{v}$ can be expressed neatly in terms of the correlation function $\rho_{m+1, v}$. More precisely, we have the following result first observed by Y.V. Fyodorov [14] in a context related to ours.
Lemma D.1. Suppose $v>0$. Then for any $c \in \mathbb{R}$ we have

$$
\boldsymbol{E}_{\mathrm{GOE}_{m}^{v}}\left(\left|\operatorname{det}\left(A-c \mathbb{1}_{m}\right)\right|\right)=2^{\frac{3}{2}}(2 v)^{\frac{m+1}{2}} \Gamma\left(\frac{m+3}{2}\right) e^{\frac{c^{2}}{4 v}} \rho_{m+1, v}(c) .
$$

Proof. Using the Weyl integration formula we deduce

$$
\begin{gathered}
\boldsymbol{E}_{\mathrm{GOE}_{m}^{v}}\left(\left|\operatorname{det}\left(A-c \mathbb{1}_{m}\right)\right|\right)=\frac{1}{\boldsymbol{Z}_{m}(v)} \int_{\mathbb{R}^{m}} \prod_{i=1}^{m} e^{-\frac{\lambda_{i}^{2}}{4 v}}\left|c-\lambda_{i}\right| \prod_{i \leq j}\left|\lambda_{i}-\lambda_{j}\right| d \lambda_{1} \cdots d \lambda_{m} \\
=\frac{e^{\frac{c^{2}}{4 v}}}{\boldsymbol{Z}_{m}(v)} \int_{\mathbb{R}^{m}} e^{-\frac{c^{2}}{4 v}} \prod_{i=1}^{m} e^{-\frac{\lambda_{i}^{2}}{4 v}}\left|c-\lambda_{i}\right| \prod_{i \leq j}\left|\lambda_{i}-\lambda_{j}\right| d \lambda_{1} \cdots d \lambda_{m} \\
=\frac{e^{\frac{c^{2}}{4 v}} \boldsymbol{Z}_{m+1}(v)}{\boldsymbol{Z}_{m}(v)} \frac{1}{\boldsymbol{Z}_{m+1}(v)} \int_{\mathbb{R}^{m}} Q_{m+1, v}\left(c, \lambda_{1}, \ldots, \lambda_{m}\right) d \lambda_{1} \cdots d \lambda_{m} \\
=\frac{e^{\frac{c^{2}}{4 v}} \boldsymbol{Z}_{m+1}(v)}{\boldsymbol{Z}_{m}(v)} \rho_{m+1, v}(c)=v^{\frac{m+1}{2}} \frac{e^{\frac{c^{2}}{4 v}} \boldsymbol{Z}_{m+1}}{\boldsymbol{Z}_{m}} \rho_{m+1, v}(c) \\
=(m+1) \sqrt{2}(2 v)^{\frac{m+1}{2}} e^{\frac{c^{2}}{4 v}} \Gamma\left(\frac{m+1}{2}\right) \rho_{m+1, v}(c)=2^{\frac{3}{2}}(2 v)^{\frac{m+1}{2}} \Gamma\left(\frac{m+3}{2}\right) e^{\frac{c^{2}}{4 v}} \rho_{m+1, v}(c) .
\end{gathered}
$$

The above result admits the following generalization, [4, Lemma 3.2.3].
Lemma D.2. Let $u, v>0$. Set

$$
\theta_{m, v}^{+}(x):=\rho_{m+1, v}(x) e^{\frac{x^{2}}{4 v}} .
$$

Then

$$
\begin{gather*}
\boldsymbol{E}_{\mathrm{Sym}_{m}^{u, v}}\left(\left|\operatorname{det}\left(A-c \mathbb{1}_{m}\right)\right|\right)=2^{\frac{3}{2}}(2 v)^{\frac{m+1}{2}} \Gamma\left(\frac{m+3}{2}\right) \frac{1}{\sqrt{2 \pi u}} \int_{\mathbb{R}} \rho_{m+1, v}(c-x) e^{\frac{(c-x)^{2}}{4 v}-\frac{x^{2}}{2 u}} d x \\
=2^{\frac{3}{2}}(2 v)^{\frac{m+1}{2}} \Gamma\left(\frac{m+3}{2}\right)\left(\gamma_{u} * \theta_{m+1, v}^{+}\right)(c) . \tag{D.7a}
\end{gather*}
$$

In particular, if $u=2 k v, k<1$ we have
$\boldsymbol{E}_{\mathrm{Sym}_{m}^{2 k v, v}}\left(\left|\operatorname{det}\left(A-c \mathbb{1}_{m}\right)\right|\right)=2^{\frac{3}{2}}(2 v)^{\frac{m}{2}} \Gamma\left(\frac{m+3}{2}\right) \frac{1}{\sqrt{2 \pi k}} \int_{\mathbb{R}} \rho_{m+1, v}(c-x) e^{-\frac{1}{4 v t_{k}^{2}}\left(x+t_{k}^{2} c\right)^{2}+\frac{\left(t_{k}^{2}+1\right) c^{2}}{4 v}} d x$,
$(\lambda:=c-x)$

$$
=2^{\frac{3}{2}}(2 v)^{\frac{m}{2}} \Gamma\left(\frac{m+3}{2}\right) \frac{1}{\sqrt{2 \pi k}} \int_{\mathbb{R}} \rho_{m+1, v}(\lambda) e^{-\frac{1}{4 v t_{k}^{2}}\left(\lambda-\left(t_{k}^{2}+1\right) c\right)^{2}+\frac{\left(t_{k}^{2}-1\right) c^{2}}{4 v}} d \lambda
$$

where

$$
t_{k}^{2}:=\frac{1}{\frac{1}{k}-1}=\frac{k}{1-k}
$$

Proof. Recall the equality (D.1)

$$
\operatorname{Sym}_{m}^{u, v}=\operatorname{GOE}_{m}^{v} \hat{+} \boldsymbol{N}(0, u) \mathbb{1}_{m}
$$

We deduce that

$$
\begin{gathered}
\boldsymbol{E}_{\mathrm{Sym}_{m}^{u, v}}\left(\left|\operatorname{det}\left(A-c \mathbb{1}_{m}\right)\right|\right)=\boldsymbol{E}(\operatorname{det}(B+(X-c) \mathbb{1}) \mid) \\
=\frac{1}{\sqrt{2 \pi u}} \int_{\mathbb{R}} \boldsymbol{E}_{\mathrm{GOE}_{m}^{v}}\left(\left|\operatorname{det}\left(B-(c-X) \mathbb{1}_{m}\right)\right| \mid X=x\right) e^{-\frac{x^{2}}{2 u}} d x \\
=\frac{1}{\sqrt{2 \pi u}} \int_{\mathbb{R}} \boldsymbol{E}_{\mathrm{GOE}_{m}^{v}}\left(\left|\operatorname{det}\left(B-(c-x) \mathbb{1}_{m}\right)\right|\right) e^{-\frac{x^{2}}{2 u}} d x \\
=2^{\frac{3}{2}}(2 v)^{\frac{m+1}{2}} \Gamma\left(\frac{m+3}{2}\right) \frac{1}{\sqrt{2 \pi u}} \int_{\mathbb{R}} \rho_{m+1, v}(c-x) e^{\frac{(c-x)^{2}}{4 v}-\frac{x^{2}}{2 u}} d x .
\end{gathered}
$$

Now observe that if $u=2 k v$ then

$$
\begin{gathered}
\frac{(c-x)^{2}}{4 v}-\frac{x^{2}}{2 u}=-\frac{x^{2}}{4 k v}+\frac{1}{4 v}\left(x^{2}-2 c x+c^{2}\right) \\
=\frac{1}{4 v}\left(-\frac{1}{t_{k}^{2}} x^{2}-2 c x-c^{2} t_{k}^{2}\right)+\frac{c^{2}\left(1+t_{k}^{2}\right)}{4 v}=-\frac{1}{4 v t_{k}^{2}}\left(x+t_{k}^{2} c\right)^{2}+\frac{c^{2}\left(1+t_{k}^{2}\right)}{4 v}
\end{gathered}
$$

## Appendix E. Notations

(i) For any set $S$ we denote by $|S| \in \mathbb{Z}_{\geq 0} \cup\{\infty\}$ its cardinality. For any subset $A$ of a set $S$ we denote by $\boldsymbol{I}_{A}$ its characteristic function

$$
\boldsymbol{I}_{A}: S \rightarrow\{0,1\}, \quad \boldsymbol{I}_{A}(s)= \begin{cases}1, & s \in A \\ 0, & s \in S \backslash A\end{cases}
$$

(ii) For any point $x$ in a smooth manifold $X$ we denote by $\delta_{x}$ the Dirac measure on $X$ concentrated at $x$.
(iii) For any smooth manifold $M$ we denote by $\operatorname{Vect}(M)$ the vector space of smooth vector fields on $M$.
(iv) For any random variable $\xi$ we denote by $\boldsymbol{E}(\xi)$ and respectively $\boldsymbol{\operatorname { v a r }}(\xi)$ its expectation and respectively its variance.
(v) For any finite dimensional real vector space $\boldsymbol{V}$ we denote by $\boldsymbol{V}^{\vee}$ its dual, $\boldsymbol{V}^{\vee}:=\operatorname{Hom}(\boldsymbol{V}, \mathbb{R})$.
(vi) For any Euclidean space $\boldsymbol{V}$ we denote $\operatorname{by} \operatorname{Sym}(\boldsymbol{V})$ the space of symmetric linear operators $\boldsymbol{V} \rightarrow \boldsymbol{V}$. When $\boldsymbol{V}$ is the Euclidean space $\mathbb{R}^{m}$ we set $\operatorname{Sym}_{m}:=\operatorname{Sym}\left(\mathbb{R}^{m}\right)$. We denote by $\mathbb{1}_{m}$ the identity map $\mathbb{R}^{m} \rightarrow \mathbb{R}^{m}$.
(vii) We denote by $\mathcal{S}\left(\mathbb{R}^{m}\right)$ the space of Schwartz functions on $\mathbb{R}^{m}$.
(viii) For $v>0$ we denote by $\gamma_{v}$ the centered Gaussian measure on $\mathbb{R}$ with variance $v$,

$$
\gamma_{v}(x) d x=\frac{1}{\sqrt{2 \pi v}} e^{-\frac{x^{2}}{2 v}}|d x|
$$

Since $\lim _{v \searrow 0} \gamma_{v}=\delta_{0}$, we set $\gamma_{0}:=\delta_{0}$. For a real valued random variable $X$ we write $X \in \boldsymbol{N}(0, v)$ if the probability distribution of $X$ is $\gamma_{v}$.
(ix) If $\mu$ and $\nu$ are two finite measures on a common space $X$, then the notation $\mu \propto \nu$ means that

$$
\frac{1}{\mu(X)} \mu=\frac{1}{\nu(X)} \nu
$$

## References

[1] R. Adler, R.J.E. Taylor: Random Fields and Geometry, Springer Monographs in Mathematics, Springer Verlag, 2007.
[2] M.T. Anderson, J. Cheeger: $C^{\alpha}$-compactness for manifolds with Ricci curvature and injectivity radius bounded below, J. Diff. Geom., 35(1992), 265-281.
[3] G. W. Anderson, A. Guionnet, O. Zeitouni: An Introduction to Random Matrices, Cambridge University Press, 2010.
[4] A. Auffinger: Random matrices, complexity of spin glasses and heavy tailed processes, 2011 NYU PhD Dissertation.
[5] J.-M. Azaïs, M. Wschebor: Level Sets and Extrema of Random Processes, John Wiley \& Sons, 2009.
[6] P. Bérard, G. Besson, S. Gallot: Embedding Riemannian manifolds by their heat kernel, Geom. Gunct. Anal., 4(1994), 373-398.
[7] X. Bin: Derivatives of the spectral function and Sobolev norms of eigenfunctions on a closed Riemannian manifold, Ann. Global. Analysis an Geometry, 26(2004), 231-252.
[8] V. I. Bogachev: Gaussian Measures, Mathematical Surveys and Monographs, vol. 62, American Mathematical Society, 1998.
[9] N.G. De Brujin: Asymptotic Methods in Analysis, Dover Publications, 1981.
[10] I. Chavel: Eigenvalues in Riemannian Geometry, Academic Press, 1984.
[11] P. Deift, D. Gioev: Random Matrix Theory: Invariant Ensembles and Universality, Courant Lecture Notes, vol. 18, Amer. Math. Soc., 2009.
[12] B. DeWitt: The Global Approach to Quantum Field Theory, Oxford University Press, 2003.
[13] J.J. Duistermaat, V.W. Guillemin: The spectrum of positive elliptic operators and periodic bicharacteristics, Invent. Math., 29(1975), 39-79.
[14] Y. V. Fyodorov: Complexity of random energy landscapes, glass transition, and absolute value of the spectral determinant of random matrices, Phys. Rev. Lett, 92(2004), 240601; Erratum: 93(2004), 149901.
[15] I.M. Gelfand, G.E. Shilov: Generalized Functions, vol. 1, Academic Press, New York, 1964.
[16] I.M. Gelfand, N.Ya. Vilenkin: Generalized Functions, vol. 4, Academic Press, New York, 1964.
[17] V. Guillemin, S, Sternberg: Geometric Asymptotics, Amer. Math, Soc. 1990.
[18] A. Gray: Tubes, 2nd Edition, Birhäuser, 2004.
[19] J. Hadamard: Lectureson Cauchy's Problem in Linear Partial Differential Equations, Yale University Press, 1923.
[20] L. Hörmander: On the spectral function of an elliptic operator, Acta Math. 121(1968), 193-218.
[21] L. Hörmander: The Analysis of Linear Partial Differential Operators I, Springer Verlag, 1990.
[22] L. Hörmander: The Analysis of Linear Partial Differential Operators III, Springer Verlag, 1994.
[23] A. Klenke: Probability Theory. A Comprehensive Course. Springer Verlag, 2006.
[24] M. L. Mehta: Random Matrices, 3rd Edition, Elsevier, 2004.
[25] L.I. Nicolaescu: Lectures on the Geometry of Manifolds 2nd Edition, World Scientific, 2007.
[26] L.I. Nicolaescu: Critical sets of random smooth functions on compact manifolds., arXiv: 1101.5990
[27] L.I. Nicolaescu: Complexity of random smooth functions con compact manifolds, arXiv: 1201.4972, to appear in Indiana Univ. Math. J.
[28] L.I. Nicolaescu: The wave group and the spectral geometry of compact manifolds, http://www.nd.edu/~lnicolae/Wave.pdf
[29] M. Riesz: L'intégrale de Riemann-Liouville et le problème de Cauchy, Acta Math. 81(1949), 1-223.
[30] S. Peters: Convergence of Riemannian manifolds, Compositio Math., 62(1987), 3-16.
[31] M. Taylor: Pseudodifferential Operators, Princeton University Press, 1981.
[32] S.R.S. Varadhan: Probability Theory, Courant Lect. Notes in Math., vol. 7, Amer. Math. Soc., 2001.
[33] S. Zelditch: Real and complex zeros of Riemannian random waves, Spectral analysis in geometry and number theory, 321342, Contemp. Math., 484, Amer. Math. Soc., Providence, RI, 2009. arXiv:0803.433v1

Department of Mathematics, University of Notre Dame, Notre Dame, IN 46556-4618.
E-mail address: nicolaescu.1@nd.edu
URL: http://www.nd.edu/~1nicolae/


[^0]:    1991 Mathematics Subject Classification. Primary 15B52, 42C10, 53C65, 58K05, 58J50, 60D05, 60G15, 60G60 .
    Key words and phrases. Morse functions, critical values, Kac-Price formula, gaussian random processes, random matrices, Laplacian, eigenfunctions.

    This work was partially supported by the NSF grant, DMS-1005745.

[^1]:    ${ }^{1}$ The set $\boldsymbol{D}(\boldsymbol{u})$ is sometime referred to as the discriminant set of $\boldsymbol{u}$.

