

11 - Examples of curvatures

Note Title

10/20/2009

Recall! $M \subseteq \mathbb{R}^3$ (orientable)

$\vec{N}: M \rightarrow S^2 \subset \mathbb{R}^3$ Normal v.f

$x \in M$ $L: T_x M \rightarrow T_x M$ shape operator

$\stackrel{u}{-} D\vec{N}$

$f: U \rightarrow M$ parametrization
 \uparrow
 \mathbb{R}^2

$\nu = \vec{N} \circ f$

$L = -D\nu \circ (Df)^{-1}$

$I(-, -)$ on $T_x M$ local coordinates

$I(-, -) \sim [g_{ij}]$

$\mathbb{II}(X, Y) = I(LX, Y)$

$g_{ij} = \left\langle \frac{\partial f}{\partial x_i}, \frac{\partial f}{\partial x_j} \right\rangle$

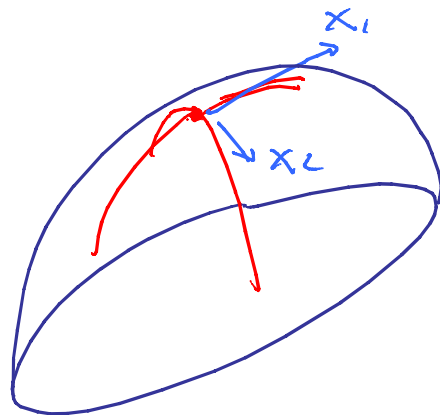
$\mathbb{II}(-, -) \sim [h_{ij}]$

$h_{ij} = \left\langle \frac{\partial \nu}{\partial x_i}, \frac{\partial \nu}{\partial x_j} \right\rangle$

Principal curvatures at x

$\kappa_1, \kappa_2 = \min \text{ and max of } \mathbb{II}(X, X) \text{ for } \{X \in T_x M \mid I(X, X) = 1\}$
 $= \text{eigenvalues of } L$

(Principle curvature directions = ^{unit} eigenvectors)



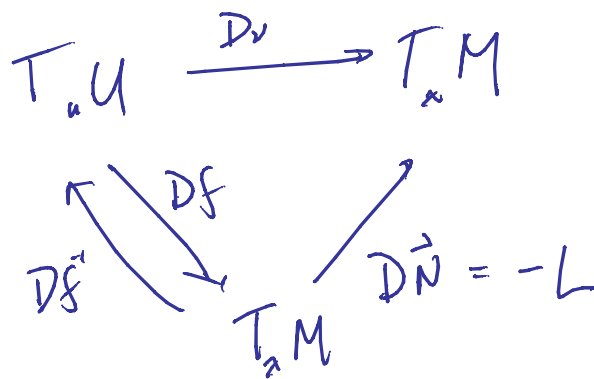
c_1, c_2 curves

$(c_i'') \perp TM$

$$K_i = K(c_i)$$

$$K = K_1 K_2 = \det L = \frac{\det(h_{ij})}{\det(g_{ij})}$$

Explanation of last equality



$$\det(-L) = \det(L) = \frac{\det(h_{ij})}{\det(g_{ij})}$$

e.g. $M = S_r^2 =$ sphere of radius r

Note Title

10/8/2009

$$\vec{N}: M \rightarrow S^2$$

$$x \mapsto \frac{x}{r}$$

$$\gamma(t) \mapsto \frac{\dot{\gamma}}{r}$$

$$\dot{\gamma} = X \mapsto \begin{pmatrix} \dot{X} \\ r \end{pmatrix} = \frac{\dot{\gamma}}{r}$$

S,

$$L: TM \rightarrow TM$$

$$\dot{v} \mapsto -\frac{1}{r} \dot{v}$$

$$L \sim \begin{bmatrix} \frac{1}{r} & \\ & -\frac{1}{r} \end{bmatrix}$$

$$\Rightarrow K = \frac{1}{r^2}$$

e.g. $M = \text{plane}$, \vec{N} constant

$$\Rightarrow L = 0$$

$$\Rightarrow K = 0$$

Thm Suppose $M \subseteq \mathbb{R}^3$ is a connected surface

(all points of M are umbilic)



(M is contained in a sphere or plane)

(pf) \Leftarrow already done

\Rightarrow Suppose $K_1 = K_2 = \lambda(u)$ at $u \in U$

$$f: U \subset \mathbb{R}^2 \rightarrow M$$

$$\Rightarrow L = \lambda \cdot I$$

$$= -Dv \cdot Df^{-1}$$

$$\Rightarrow Dv|_u = -\lambda(u) Df|_u$$

$$\Rightarrow \frac{\partial v}{\partial u_i} = -\lambda(u) \frac{\partial f}{\partial u_i}$$

$$\Rightarrow \frac{\partial^2 v}{\partial u_1 \partial u_2} = -\lambda(u) \frac{\partial^2 f}{\partial u_1 \partial u_2} - \frac{\partial \lambda}{\partial u_1} \frac{\partial f}{\partial u_2}$$

$$\text{So } \frac{\partial \lambda}{\partial u_1} \frac{\partial f}{\partial u_2} = \frac{\partial \lambda}{\partial u_2} \frac{\partial f}{\partial u_1}$$

Q: what does this mean?

but $\frac{\partial f}{\partial u_i} \perp \mathbb{R}^1$.

$$\Rightarrow \frac{\partial \lambda}{\partial u_1} = \frac{\partial \lambda}{\partial u_2} = 0$$

So λ is constant

$$\lambda \equiv 0 \Rightarrow Dv = 0 \Rightarrow v \text{ const}$$
$$\Rightarrow \text{plan}$$

o/w

$$D \left(\frac{1}{\lambda} v + f \right) = \frac{1}{\lambda} Dv + Df$$
$$= -Df + Df$$
$$= 0$$

$$\Rightarrow \frac{1}{\lambda} v + f \text{ const}$$

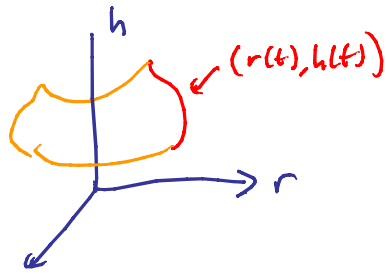
$$\Rightarrow f(u) = -\frac{1}{\lambda} v(u)$$

$$v(u) \in S^2$$

$$\Rightarrow -\frac{1}{\lambda} v(u) \in S_{\text{int}}^2$$

Examples

Surfaces of rotation



$$f(t, \varphi) = (r(t) \cos \varphi, r(t) \sin \varphi, h(t))$$

$$\frac{\partial f}{\partial t} = (\dot{r} \cos \varphi, \dot{r} \sin \varphi, \dot{h})$$

$$\frac{\partial f}{\partial \varphi} = (-r \sin \varphi, r \cos \varphi, 0)$$

$$B = [g_{ij}] \sim \begin{bmatrix} \dot{r}^2 + \dot{h}^2 & 0 \\ 0 & r^2 \end{bmatrix}$$

$$\det \begin{pmatrix} \hat{r} & \hat{\varphi} & \hat{h} \\ \dot{r} \cos \varphi & \dot{r} \sin \varphi & \dot{h} \\ -r \sin \varphi & r \cos \varphi & 0 \end{pmatrix} = (r \dot{h} \cos \varphi, -r \dot{h} \sin \varphi, r \dot{r})$$

$$v = \frac{1}{\sqrt{\dot{r}^2 + \dot{h}^2}} (-\dot{h} \cos \varphi, -\dot{h} \sin \varphi, \dot{r})$$

$$\frac{\partial^2 f}{\partial t^2} = (\ddot{r} \cos \varphi, \ddot{r} \sin \varphi, \ddot{L})$$

$$\frac{\partial^2 f}{\partial t \partial \varphi} = (-\dot{r} \sin \varphi, \dot{r} \cos \varphi, 0)$$

$$\frac{\partial^2 f}{\partial \varphi^2} = (-r \cos \varphi, -r \sin \varphi, 0)$$

$$\mathbb{H} = \langle \gamma, \rightarrow \rangle = \frac{1}{\sqrt{\dot{r}^2 + \dot{L}^2}} \begin{bmatrix} -\ddot{r}\dot{L} + \dot{r}\ddot{L} & 0 \\ 0 & r\dot{L} \end{bmatrix}$$

$$\Rightarrow \kappa_1 = \frac{1}{(\dot{r}^2 + \dot{L}^2)^{3/2}} (-\ddot{r}\dot{L} + \dot{r}\ddot{L})$$

$$\kappa_2 = \frac{1}{(\dot{r}^2 + \dot{L}^2)^{1/2}} \frac{\dot{L}}{r}$$

$$\mathbb{H}(x_i, x_i) = a_i$$

$$\mathbb{I}(x_i, x_i) = b_i$$

$$\tilde{x}_i = \frac{x_i}{\sqrt{b_i}}$$

$$\mathbb{H}(\tilde{x}_i, \tilde{x}_i) = \frac{1}{b_i} a_i$$

$$\underline{\underline{\mathbb{I}}} = \begin{pmatrix} 1 & \\ & r^2 \end{pmatrix}$$

$$\mathbb{H} = \begin{pmatrix} -r''\dot{L} + r'\dot{L}'' & \\ & r\dot{L}' \end{pmatrix}$$

$$K_1 = -r'' + r' h''$$

$$K_2 = \frac{h'}{r}$$

But $(r')^2 + (h')^2 = \text{constant}$

$$\Rightarrow r' r'' + h' h'' = 0$$

$$-r'' h' + r' h'' = \frac{h' h''}{r'} h' + r' h''$$

$$= \frac{h''}{r'} ((h')^2 + (r')^2)$$

$$= \frac{h''}{r'} = -\frac{r''}{h'}$$

$$\Rightarrow K_1 K_2 = -\frac{r''}{r}$$

$$\frac{r h'' + r' h'}{2 r r'} = \frac{(r h')'}{(r^2)'} \\ \text{" "}$$

$$H = \frac{1}{2} (K_1 + K_2) = \frac{1}{2} \left(\frac{h''}{r'} + \frac{h'}{r} \right)$$

$$h' = \sqrt{1 - (r')^2}$$

get O.D.E's for r

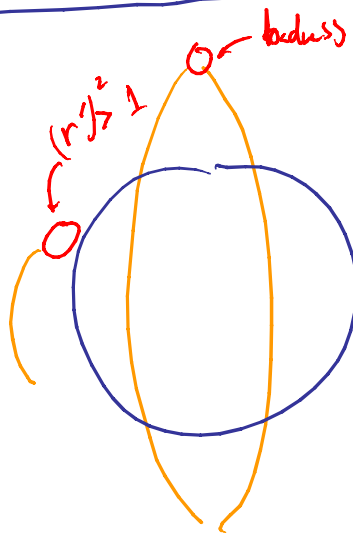
$$K = c \Leftrightarrow r'' + cr = 0$$

$$H = c \Leftrightarrow (rh')' = c(r^2)'$$

e.g.

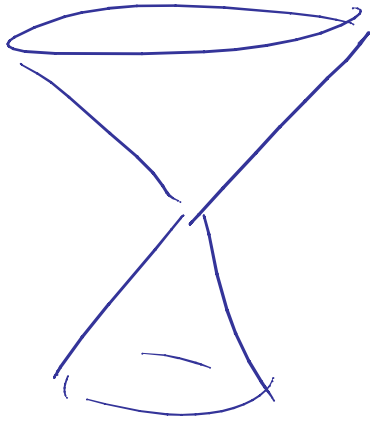
$$r(t) = \begin{cases} K > 0 & \left\{ \begin{array}{l} a \cos(\sqrt{K}t) + b \sin(\sqrt{K}t) \\ |a| \leq 1 \end{array} \right. \\ K = 0 & at + b \\ K < 0 & \left\{ \begin{array}{l} a \cosh(\sqrt{-K}t) + b \sinh(\sqrt{-K}t) \end{array} \right. \end{cases}$$

$$K = 1$$

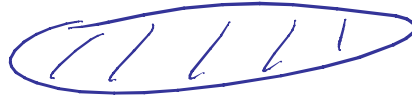


$$r'' = -r$$

e.g. $k=0$

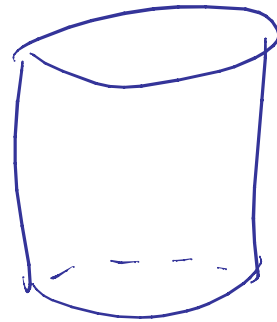


$$r'' = 0$$



r is
linear

r' const
 $\Rightarrow h'$ const



\Rightarrow linear!

Negative curvature

$$r'' - r = 0 \Leftrightarrow r'' = r$$

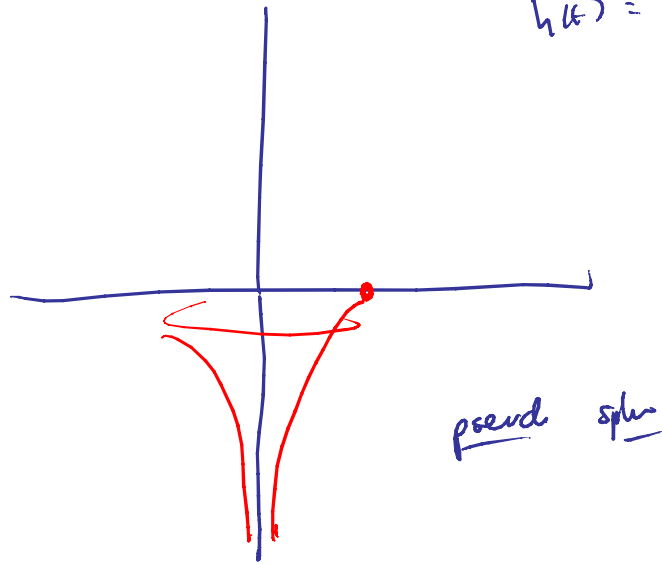
$r(t) = e^t$ works

except when $e^t = 1$

i.e. $t=0$

$$h'(t) = \sqrt{1 - (e^t)^2}$$

$$h(t) = \int \sqrt{1 - e^{2t}} dt$$



$$a = b, \quad K = -1$$

$$r(t) = a \exp(t)$$

Asymptote

curves

$$\mathbb{I}(\hat{c}, \hat{c}) = 0$$