

17 - Calculating Gaussian curvature

Note Title

11/5/2009

Sec 4E general formula

$$g_{ij} = \begin{pmatrix} E & F \\ F & G \end{pmatrix}$$

$$K = \left(\frac{\det \text{Hess} f}{\det g} \right)$$

Parameterization by lines of curvature (always center of curvature)

$f(u,v) : U \rightarrow \mathbb{R}^3$

$$[g_{ij}] = \begin{pmatrix} E & 0 \\ 0 & G \end{pmatrix} \quad [h_{ij}] \sim \begin{pmatrix} L & 0 \\ 0 & N \end{pmatrix}$$

Christoffel symbols

$$\Gamma_{ij,k} = \frac{1}{2} \left(-\frac{\partial}{\partial u_k} g_{ij} + \frac{\partial}{\partial u_i} g_{jk} + \frac{\partial}{\partial u_j} g_{ik} \right)$$

$$\Gamma_{u,u} = \frac{1}{2} (-E_u + E_u + E_u) = \frac{1}{2} E_u$$

$$\Gamma'_{u,u} = \frac{1}{2} \frac{E_u}{E}$$

$$\Gamma_{u,v} = \frac{1}{2} E_v$$

$$\Gamma_{v,v} = -\frac{1}{2} G_u$$

$$\Gamma'_{u,v} = \frac{1}{2} \frac{E_v}{E}$$

$$\Gamma_{11,2} = -\frac{1}{2} E_v$$

$$\Gamma_{12,2} = \frac{1}{2} G_u$$

$$\Gamma_{22,2} = \frac{1}{2} G_v$$

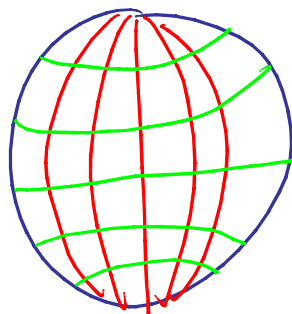
$$R_{1221} = \left(\cancel{\Gamma_{12}^s} \right)_v - \left(\cancel{\Gamma_{12}^s} \right)_v + \sum_r \Gamma_{12}^r \Gamma_{r2}^1 - \Gamma_{12}^r \Gamma_{r2}^1$$

$$= \dots$$

Werte der curv
tensor

$$K = \frac{1}{2\sqrt{EG}} \left(\left(\frac{E_v}{\sqrt{EG}} \right)_v + \left(\frac{G_u}{\sqrt{EG}} \right)_u \right)$$

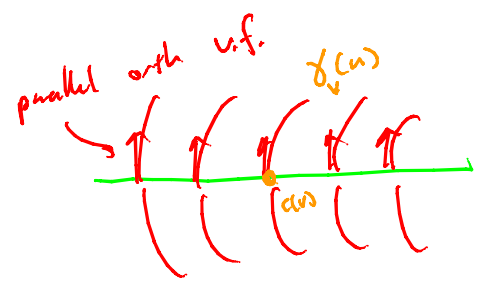
Großes parallel coordinates



a curv and
geodetic

Can always do this locally

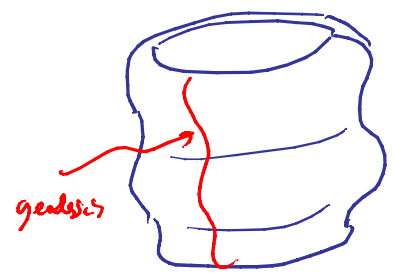
def $f(u,v) = \gamma_v(u)$



$$I \sim \begin{pmatrix} 1 & \\ & g \end{pmatrix}$$

$$K = - \frac{(\sqrt{g})_{uu}}{\sqrt{g}}$$

e.g. surface of rotation



$$I \sim \begin{pmatrix} 1 & \\ & r^2 \end{pmatrix}$$

$$K = - \frac{r''}{r}$$

Isometry

Suppose $M, N \subseteq \mathbb{R}^{n+1}$

a diffeomorphism is a smooth map

$$\varphi: M \rightarrow N$$

which is smoothly invertible

i.e. $\exists \varphi^{-1}: N \rightarrow M$

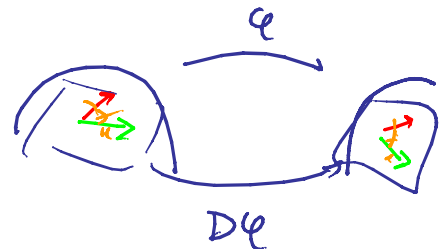
$$\text{s.t. } \varphi(\varphi^{-1}(z)) = z$$

$$\varphi^{-1}(\varphi(z)) = z$$

An isometry

$$\varphi: M \rightarrow N$$

is a diffeomorphism s.t.



$$D\varphi|_z: T_z M \rightarrow T_{\varphi(z)} N$$

$$\forall x, Y \in T_x M$$

$$\langle D\varphi(x), D\varphi(Y) \rangle = \langle x, Y \rangle$$

Locally:

$$\begin{array}{ccccc}
 & & \tilde{S} & & \\
 & & \curvearrowright & & \\
 U & \xrightarrow{S} & M & \xrightarrow{\varphi} & N \\
 \downarrow \eta & & & & \\
 \mathbb{R}^n & & & &
 \end{array}$$

$$g_{ij} = \left\langle \frac{\partial f}{\partial u_i}, \frac{\partial f}{\partial u_j} \right\rangle$$

$$\tilde{g}_{ij} = \left\langle \frac{\partial \tilde{f}}{\partial \tilde{u}_i}, \frac{\partial \tilde{f}}{\partial \tilde{u}_j} \right\rangle = \left\langle D\varphi \frac{\partial f}{\partial u_i}, D\varphi \frac{\partial f}{\partial u_j} \right\rangle$$

$$= \left\langle \frac{\partial f}{\partial u_i}, \frac{\partial f}{\partial u_j} \right\rangle$$

$$\Rightarrow \tilde{g}_{ij} = g_{ij} \quad \left(\begin{array}{l} \text{lemma } \varphi \text{ isometry} \\ \Leftrightarrow g_{ij} = \tilde{g}_{ij} \end{array} \right)$$

$$\Rightarrow \tilde{\Gamma}_{ij}^k = \Gamma_{ij}^k$$

$x \in T_x M$, Y vect. field.

$$\boxed{\nabla_{D\varphi(x)} D\varphi(Y) = \nabla_x Y}$$

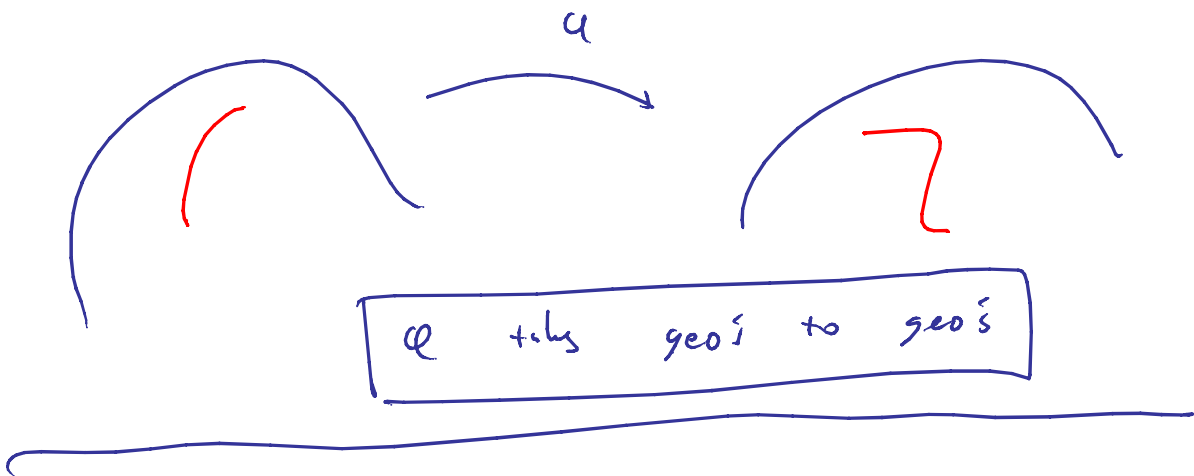
$$\Rightarrow c: I \rightarrow M \text{ geodesic}$$

$$\tilde{c} \\ \tilde{c} \\ \varphi \circ c : I \rightarrow N$$

$$\tilde{c}' = D\varphi \circ c'$$

$$\nabla_{\tilde{c}'} \tilde{c}' = \nabla_{c'} c' = 0$$

$\Rightarrow \tilde{c}$ is a geo



Thm Egregium

M, N surfaces

$$\Rightarrow K_z = K_{\varphi(z)}$$

e.g.

$$M = \{(x, y, 0) \in \mathbb{R}^3 \mid 0 < y < \pi, x \in \mathbb{R}\}$$

$N =$ half cylinder

parametrized by

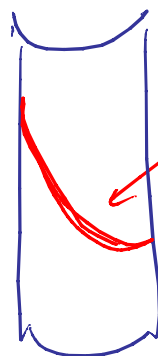
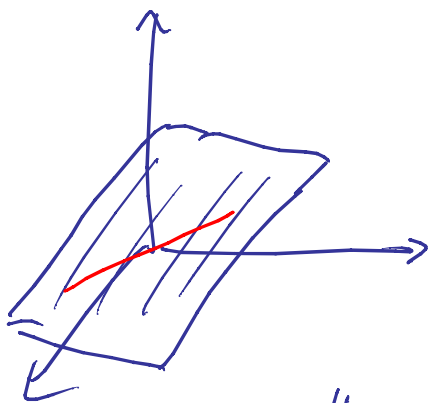
$$f(u, v) = \{(\cos u, \sin u, v) \mid \begin{array}{l} 0 < u < \pi \\ v \in \mathbb{R} \end{array}\}$$

$$\varphi: M \longrightarrow N$$

$$(x, y, 0) \longmapsto (\cos y, \sin y, x)$$

$$M: g_M = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$N: \tilde{g}_N = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$



geodesic helices

locally isometric:

$$\text{each } \textcircled{(\partial)_x^u} \longrightarrow \textcircled{(\partial)_v}$$

Aside on tensors

Note $X = \sum X^i \frac{\partial}{\partial u^i}$

$$D_x \varphi = \sum X^i \frac{\partial \varphi}{\partial u^i}$$

$A_{i_1 \dots i_m}^{j_1 \dots j_n}$ tensor of type (n, m)

$\left\{ \frac{\partial}{\partial u^i} \right\}$ basis of $TM \quad \frac{\partial}{\partial u^i}$

$\{du^i\}$ basis of $T^*M \leftarrow$ identifies $TM \rightarrow \mathbb{R}$

Write

$$du^i \left(\frac{\partial}{\partial u^j} \right) = \delta_{ij}$$

$$A = \sum_{\substack{i_1 \dots i_m \\ j_1 \dots j_n}} A_{i_1 \dots i_m}^{j_1 \dots j_n} \frac{\partial}{\partial u^{j_1}} \otimes \dots \otimes \frac{\partial}{\partial u^{j_n}} \otimes du^{i_1} \otimes \dots \otimes du^{i_m}$$

d.e. $X = \sum_i X^i \frac{\partial}{\partial u^i}$ vector field

$$I = \sum_{i,j} g_{ij} du^i \otimes du^j$$

" Short hand

Surfaces: $I = g_{11} du_1^2 + 2g_{12} du_1 du_2 + g_{22} du_2^2$

Warny

Note

2 freely two vectors

$$X = \sum X^i \frac{\partial}{\partial u^i}$$

$$Y = \sum Y^i \frac{\partial}{\partial u^i}$$

$$\left(\sum g_{ij} du^i \otimes du^j \right) (X, Y)$$

$$= \sum_{ij} g_{ij} du^i \left(\sum_k X^k \frac{\partial}{\partial u^k} \right) du^j \left(\sum_l Y^l \frac{\partial}{\partial u^l} \right)$$

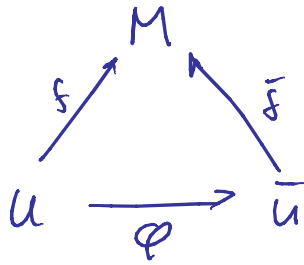
$$= \sum_{\substack{ij \\ kl}} g_{ij} X^k Y^l \delta_{ik} \delta_{jl}$$

$$= \sum_{ij} g_{ij} X^i Y^j$$

$$[X^1 \dots X^n] [g_{ij}] \begin{pmatrix} Y^1 \\ \vdots \\ Y^n \end{pmatrix}$$

$$= I(X, Y)$$

Convenient from POV of change of coordinates.



$$\bar{u}_i = \varphi_i(u_1, \dots, u_n)$$

$$\begin{aligned} \frac{\partial f}{\partial u_i} &= \frac{\partial}{\partial u_i} (\bar{f} \circ \varphi) = D\bar{f} \circ \varphi e_i \\ &= D\bar{f} \sum_j \frac{\partial \varphi_j}{\partial u_i} e_j \\ &= \sum_j \frac{\partial \varphi_j}{\partial u_i} \frac{\partial \bar{f}}{\partial \bar{u}_j} \\ &= \sum_j \frac{\partial \bar{u}_j}{\partial u_i} \frac{\partial}{\partial \bar{u}_j} \end{aligned}$$

$$\text{get } \frac{\partial}{\partial u_i} = \sum_j \frac{\partial \bar{u}_j}{\partial u_i} \frac{\partial}{\partial \bar{u}_j}$$

$$d\bar{u}^j = \sum_i \frac{\partial \bar{u}_i}{\partial u_j} du^i$$

e.g.

rule: scalar \otimes \otimes

$$I = \sum_{ij} \bar{g}_{ij} d\bar{u}^i \otimes d\bar{u}^j$$

$$= \sum_{\substack{ij \\ kl}} \bar{g}_{ij} \frac{\partial \bar{u}^i}{\partial u_k} du_k \otimes \frac{\partial \bar{u}^j}{\partial u_l} du_l$$

$$\text{So } g_{k,l} = \sum_{ij} \frac{\partial \bar{u}^i}{\partial u_k} \bar{g}_{ij} \frac{\partial \bar{u}^j}{\partial u_l}$$

Compu

$$\begin{bmatrix} g_{ij} \end{bmatrix} = \begin{bmatrix} \frac{\partial \bar{u}^i}{\partial u_j} \end{bmatrix}^T \begin{bmatrix} \bar{g}_{ij} \end{bmatrix} \begin{bmatrix} \frac{\partial \bar{u}^j}{\partial u_i} \end{bmatrix}$$

Q: to what degree does K determine
surface up to isometry

The problem #7 showed in general no!

$$f_1 = (u \cos v, u \sin v, \log u)$$

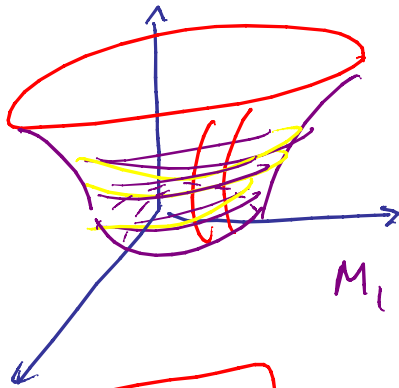
$$f_2 = (u \cos v, u \sin v, v) =$$

$$K_{f_1} = K_{f_2}$$

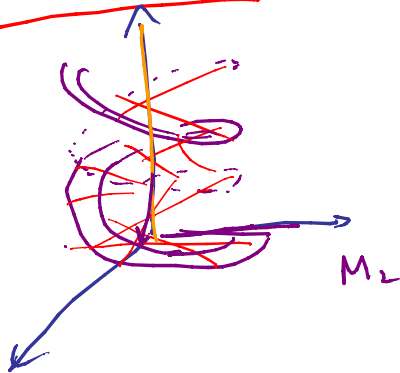
$$(0, 0, v) + u(\cos v, \sin v, 0)$$

per p curves are
straight

Curves when u varies
center is const



$$K = -\frac{1}{(1+u^2)^2}$$



Curves when v varies
line is const

= helix curves

per p curves

straight lines

Suppose these are ^{locally} isometric

$$\bar{u} = \bar{u}(u, v)$$

$$\bar{v} = \bar{v}(u, v)$$

$$\frac{1}{(1+\bar{u}^2)^2} = \bar{K}(\bar{u}, \bar{v}) = K(u, v) = -\frac{1}{(1+u^2)^2}$$

$$\Rightarrow (1+\bar{u}^2) = \pm(1+u^2)$$

$$\Rightarrow \bar{u} = \begin{cases} \pm u & \text{Case I} \\ \pm \sqrt{-2-u^2} & \text{Case II} \end{cases}$$

$$[g_{ij}] = \begin{bmatrix} 1 + \frac{1}{u^2} & \\ & u^2 \end{bmatrix}$$

$$[\bar{g}_{ij}] = \begin{bmatrix} 1 & \\ & 1 + \bar{u}^2 \end{bmatrix}$$

Isonetry Case I

$$d\bar{u}^2 + (1 + \bar{u}^2) d\bar{v}^2$$

$$= du^2 + (1 + u^2) (\bar{v}_u du + \bar{v}_v dv) \otimes (\bar{v}_u du + \bar{v}_v dv)$$

$$= \underbrace{1 + \bar{v}_u^2}_{(1 + u^2)} du^2 + 2 \overbrace{\bar{v}_u \bar{v}_v}^{(1 + u^2)} du dv + (1 + u^2) \bar{v}_v^2 dv^2$$

$$\stackrel{!}{=} \left(1 + \frac{1}{u^2}\right) du^2 + u^2 dv^2$$

$$\Rightarrow 1 + (1 + u^2) \bar{v}_u^2 = 1 + \frac{1}{u^2} \rightarrow \leftarrow$$

$$\bar{v}_u \bar{v}_v = 0 \Rightarrow \bar{v}_u = 0$$

$$(1 + u^2) \bar{v}_v^2 = u^2$$

etc...

Thus If M, \tilde{M} surfaces

$$K = \tilde{K} \equiv \text{constant}$$

$\Rightarrow M$ locally isometric to \tilde{M}

(pt)

Parameter both in Geodesic

Polar
coordinates

$$I \sim du^2 + G dv^2$$

$$I \sim d\bar{u}^2 + \bar{G} dv^2$$

$$K = - \frac{\frac{\partial^2}{\partial u^2} \sqrt{G}}{\sqrt{G}}$$

$$B = \sqrt{G}$$

$$\bar{B} = \sqrt{\bar{G}}$$

$$B_{uu} + k B = 0$$

$$\bar{B}_{uu} + k \bar{B} = 0$$

$$G(\sigma, v) = 0$$

$$G_{uu}(\sigma, v) = \underline{1}$$

} initial
conditions.

Thus

$$f, \tilde{f} : U \rightarrow M, \tilde{M} \subseteq \mathbb{R}^{n+1}$$

$$g_{ij} = \tilde{g}_{ij}$$

$$L : T_{z_0} M \rightarrow T_{z_0} \tilde{M}$$

has rank ≥ 3

$$f(u) = z_0$$

$$\Rightarrow h_{ij}(u) = \pm \tilde{h}_{ij}(u)$$

↑
up to orientation

ier surface defined by sig!

(pf) Assum:

$$z_0 = f(w) = \tilde{f}(w)$$

$$T_{z_0} M = T_{z_0} \tilde{M}$$

get $R, \tilde{R}, L, \tilde{L}$

Gauss eqs

$$\begin{aligned} \langle LY, z \rangle LX - \langle LX, z \rangle LY &= R(x, y)z \\ &= \tilde{R}(x, y)z \end{aligned}$$

$$= \langle \tilde{L}Y, z \rangle \tilde{L}X - \langle \tilde{L}X, z \rangle \tilde{L}Y$$

$$\tilde{L}X = 0$$

$$\Rightarrow \langle LY, LX \rangle LX - \langle LX, LX \rangle LY = 0 \quad \forall Y, z$$

Suppose $LX \neq 0$ pick LY l.i. from LX

using L has rank ≥ 2

$$\Rightarrow \langle LX, LX \rangle = 0 \quad \rightarrow \leftarrow$$

$$\text{So } Lx = 0$$

$$\Rightarrow \ker \tilde{L} \subseteq \ker L$$

$$\Rightarrow \text{rank } \tilde{L} \geq \text{rank } L$$

in particular, \tilde{L} rank ≥ 2

$$\text{Symmetry } \Rightarrow \text{rank } \tilde{L} = \text{rank } L$$

$$\ker \tilde{L} = \ker L$$

Fix x

$$\text{Span}(Lx) \subseteq \text{Span}(\text{Im } L)$$

$$\text{dim} \leq 1 \qquad \text{dim} \geq 3$$

$$\text{Span}(Lx) \cap \text{Span}(\tilde{L}x)^\perp \subseteq \text{Span}(Lx) \cap \text{Span}(\tilde{L}x)^\perp$$

$$\text{dim} \leq 1 \qquad \text{dim} \geq 2$$

$$\Rightarrow \text{can choose vector } y \quad \begin{array}{l} \bullet Lx \perp \tilde{L}x \\ \bullet Ly \perp Lx \end{array}$$

$$\text{Letting } z = Ly \neq 0 \quad \text{s.t. } Ly \perp \text{Span}(Lx, \tilde{L}x)$$

set

$$\langle Ly, Ly \rangle Lx - \langle Lx, Ly \rangle Ly = \langle \tilde{L}y, Ly \rangle \tilde{L}x$$

$$- \langle \tilde{L}x, Ly \rangle \tilde{L}y$$

$$\text{get } \langle \tilde{L}Y, LY \rangle \tilde{L}X = \langle LY, LY \rangle LX$$

$$LX \neq 0 \Leftrightarrow \tilde{L}X \neq 0$$

$$\text{get } \tilde{L}X = c_x LX \quad \left(\begin{array}{l} \text{set } c_x = 0 \\ \text{of } LX = 0 \\ \tilde{L}X = 0 \end{array} \right)$$

for any X

X eigenvector for $L \Leftrightarrow X$ eigenvector for \tilde{L}

X_i orthonormal basis of eigenvectors

$$LX_i = \lambda_i X_i$$

$$\tilde{L}X_i = \tilde{\lambda}_i X_i$$

$$\tilde{\lambda}_i = c_{X_i} \lambda_i$$

$$\underline{\underline{\text{but}}} \quad \tilde{L}(X_i + X_j) = c_{X_i + X_j} L(X_i + X_j)$$

$$\parallel \quad = c_{X_i + X_j} K_i X_i + c_{X_i + X_j} K_j X_j$$

$$c_{X_i} K_i X_i + c_{X_j} K_j X_j$$

$$K_i, K_j \neq 0 \quad \Rightarrow \quad c_{X_i} = c_{X_j}$$

call it c

$$\tilde{K}_i = c K_i \quad \forall i$$

$$\text{so } \tilde{L}X = c LX$$

$$\langle LY, Z \rangle LX - \langle LX, Z \rangle LY = c^2 \left(\text{---} \right)$$

$$\Rightarrow c^2 = 1 \Rightarrow c = \pm 1$$

□

