

## 5.6 Multistep Methods(cont'd)

**Example. Derive Adams-Bashforth two-step *explicit* method:** Solve the IVP:  $y' = f(t, y)$ ,  $a \leq t \leq b$ ,  $y(a) = \alpha$ .  
Integrate  $y' = f(t, y)$  over  $[y_i, y_{i+1}]$

$$y_{i+1} - y_i = \int_{t_i}^{t_{i+1}} y'(t) dt = \int_{t_i}^{t_{i+1}} f(t, y(t)) dt$$

Use  $(t_i, y_i)$  and  $(t_{i-1}, y_{i-1})$  to form interpolating polynomial  $P_1(t)$  (by Newton backward difference (Page 129)) to approximate  $f(t, y)$ .

$$\int_{t_i}^{t_{i+1}} f(t, y) dt = \int_{t_i}^{t_{i+1}} \left( f(t_i, y_i) + \nabla f(t_i, y_i) \frac{(t - t_i)}{h} + \text{error} \right) dt$$

$$y_{i+1} - y_i = h \left[ f(t_i, y_i) + \frac{1}{2} (f(t_i, y_i) - f(t_{i-1}, y_{i-1})) \right] + \text{Error}$$

where  $h = t_{i+1} - t_i$ , and the backward difference  $\nabla f(t_i, y_i) = hf[t_i, t_{i-1}] = (f(t_i, y_i) - f(t_{i-1}, y_{i-1}))$ .

Consequently, Adams-Bashforth two-step *explicit* method is:

$$w_0 = \alpha, \quad w_1 = \alpha_1$$

$$w_{i+1} = w_i + \frac{h}{2} [3f(t_i, w_i) - f(t_{i-1}, w_{i-1})] \quad \text{where } i = 1, 2, \dots, N - 1.$$

**Local Truncation Error.** If  $y(t)$  solves the IVP  $y' = f(t, y)$ ,  $a \leq t \leq b$ ,  $y(a) = \alpha$  and

$$\begin{aligned} w_{i+1} &= a_{m-1}w_i + a_{m-2}w_{i-1} + \dots + a_0w_{i+1-m} \\ &+ h[b_m f(t_{i+1}, w_{i+1}) + b_{m-1}f(t_i, w_i) + \dots \\ &+ b_0f(t_{i+1-m}, w_{i+1-m})], \end{aligned}$$

the local truncation error is

$$\tau_{i+1}(h) = \frac{y(t_{i+1}) - a_{m-1}y(t_i) + a_{m-2}y(t_{i-1}) + \dots + a_0y(t_{i+1-m})}{h} - [b_m f(t_{i+1}, y(t_{i+1})) + \dots + b_0f(t_{i+1-m}, y(t_i))]$$

NOTE: the local truncation error of a  $m$ -step *explicit* step is  $O(h^m)$ .

the local truncation error of a  $m$ -step *implicit* step is  $O(h^{m+1})$ .

## Predictor-Corrector Method

*Motivation:* (1) Solve the IVP  $y' = e^y$ ,  $0 \leq t \leq 0.25$ ,  $y(0) = 1$  by the three-step Adams-Moulton method.

Solution: The three-step Adams-Moulton method is

$$w_{i+1} = w_i + \frac{h}{24} [9e^{w_{i+1}} + 19e^{w_i} - 5e^{w_{i-1}} + e^{w_{i-2}}] \quad Eq. (1)$$

Eq. (1) can be solved by Newton's method. However, this can be quite computationally expensive.

(2) combine explicit and implicit methods.

## 4<sup>th</sup> order Predictor-Corrector Method

(we will combine 4<sup>th</sup> order Runge-Kutta method + 4<sup>th</sup> order 4-step explicit Adams-Bashforth method + 4<sup>th</sup> order three-step Adams-Moulton implicit method)

Step 1: Use 4<sup>th</sup> order Runge-Kutta method to compute  $w_0, w_1, w_2$  and  $w_3$ .

Step 2: For  $i = 3, 5, \dots, N$

(a) Predictor sub-step. Use 4<sup>th</sup> order 4-step explicit Adams-Bashforth method to compute a predicated value

$$w_{i+1,p} = w_i + \frac{h}{24} [55f(t_i, w_i) - 59f(t_{i-1}, w_{i-1}) + 37f(t_{i-2}, w_{i-2}) - 9f(t_{i-3}, w_{i-3})]$$

(b) Correction sub-step. Use 4<sup>th</sup> order three-step Adams-Moulton implicit method to compute a correction (the approximation at  $i + 1$  time step)

$$w_{i+1} = w_i + \frac{h}{24} [9f(t_{i+1}, w_{i+1,p}) + 19f(t_i, w_i) - 5f(t_{i-1}, w_{i-1}) + f(t_{i-2}, w_{i-2})]$$

## 5.10 Stability

### Consistency and Convergence

**Definition.** A one-step difference equation with local truncation error  $\tau_i(h)$  is said to be **consistent** if

$$\lim_{h \rightarrow 0} \max_{1 \leq i \leq N} |\tau_i(h)| = 0$$

**Definition.** A one-step difference equation is said to be **convergent** if

$$\lim_{h \rightarrow 0} \max_{1 \leq i \leq N} |w_i - y(t_i)| = 0$$

where  $y(t_i)$  is the exact solution and  $w_i$  is the approximate solution.

**Example.** To solve  $y' = f(t, y)$ ,  $a \leq t \leq b$ ,  $y(a) = \alpha$ . Let  $|y''(t)| \leq M$ , an  $f(t, y)$  be continuous and satisfy a Lipschitz condition with Lipschitz constant  $L$ . Show that Euler's method is consistent and convergent.

Solution:

$$\begin{aligned} |\tau_{i+1}(h)| &= \left| \frac{h}{2} y''(\xi_i) \right| \leq \frac{h}{2} M \\ \lim_{h \rightarrow 0} \max_{1 \leq i \leq N} |\tau_i(h)| &\leq \lim_{h \rightarrow 0} \frac{h}{2} M = 0 \end{aligned}$$

Thus Euler's method is consistent.

By Theorem 5.9,

$$\begin{aligned} \max_{1 \leq i \leq N} |w_i - y(t_i)| &\leq \frac{Mh}{2L} [e^{L(b-a)} - 1] \\ \lim_{h \rightarrow 0} \max_{1 \leq i \leq N} |w_i - y(t_i)| &\leq \lim_{h \rightarrow 0} \frac{Mh}{2L} [e^{L(b-a)} - 1] = 0 \end{aligned}$$

Thus Euler's method is convergent.

The rate of convergence of Euler's method is  $O(h)$ .

## Stability

*Motivation:* How does round-off error affect approximation? To solve IVP  $y' = f(t, y)$ ,  $a \leq t \leq b$ ,  $y(a) = \alpha$  by Euler's method. Suppose  $\delta_i$  is the round-off error associated with each step.

$$u_0 = \alpha + \delta_0$$

$$u_{i+1} = u_i + hf(t_i, u_i) + \delta_{i+1} \quad \text{for each } i = 0, 1, \dots, N-1.$$

Then  $|u_i - y(t_i)| \leq \frac{1}{L} \left( \frac{hM}{2} + \frac{\delta}{h} \right) [e^{L(t_i-a)} - 1] + |\delta_0| e^{L(t_i-a)}$ . Here  $|\delta_i| < \delta$ .

$$\lim_{h \rightarrow 0} \left( \frac{hM}{2} + \frac{\delta}{h} \right) = \infty.$$

**Stability:** small changes in the initial conditions produce correspondingly small changes in the subsequent approximations.

## Convergence of One-Step Methods

Theorem. Suppose the IVP  $y' = f(t, y)$ ,  $a \leq t \leq b$ ,  $y(a) = \alpha$  is approximated by a one-step difference method in the form

$$w_0 = \alpha,$$

$$w_{i+1} = w_i + h\phi(t_i, w_i, h) \quad \text{where } i = 0, 1, \dots, N-1.$$

Suppose also that  $h_0 > 0$  exists and  $\phi(t, w, h)$  is continuous with a Lipschitz condition in  $w$  with constant  $L$  on  $D$ , then

$$D = \{(t, w, h) \mid a \leq t \leq b, -\infty < w < \infty, 0 \leq h \leq h_0\}.$$

(1) The method is **stable**;

(2) The method is **convergent** if and only if it is **consistent**:

$$\phi(t, w, 0) = f(t, y), \quad \text{for all } a \leq t \leq b$$

(3) If  $\tau$  exists s.t.  $|\tau_i(h)| \leq \tau(h)$  when  $0 \leq h \leq h_0$ , then

$$|w_i - y(t_i)| \leq \frac{\tau(h)}{L} e^{L(t_i-a)}.$$