

16 - Thm Ergänzung

Note Title

11/3/2009

Q:

given h_{ij}, g_{ijj}

(Warning: poset \mathcal{J} may induce \mathcal{L})

is f determined?

$$\left\{ \begin{array}{l} D_X Y = \nabla_x Y + \mathbb{I}(x, Y) \nu \\ D_V = -L \circ Df \end{array} \right.$$

$$D_{\frac{\partial f}{\partial u_i}} \frac{\partial f}{\partial u_j} = \nabla_{\frac{\partial f}{\partial u_i}} \frac{\partial f}{\partial u_j} + \mathbb{I}\left(\frac{\partial f}{\partial u_i}, \frac{\partial f}{\partial u_j}\right) \nu$$

$$\frac{\partial^2 f}{\partial u_i \partial u_j} = \sum_k I_{ij}^k \frac{\partial f}{\partial u_k} + h_{ij} \nu$$

$$\frac{\partial \nu}{\partial u_i} = -L \frac{\partial f}{\partial u_i}$$

$$= - \sum_l h_i^k \frac{\partial f}{\partial u_k}$$

$$h_i^k = \sum_\ell g^{kl} h_{\ell i}$$

∇ denotes as f

Q: Can we use the above system of partial differential equations to "solve for f "

Existence of solns to $\underline{\underline{P.D.E}}$

gives functions

$$g_1 : \mathbb{R}^n \rightarrow \mathbb{R}^q$$

⋮

$$g_n : \mathbb{R}^q \rightarrow \mathbb{R}^n$$

when \Rightarrow there are $f : \mathbb{R}^n \rightarrow \mathbb{R}^n$

s.t. $\frac{\partial f}{\partial u_i} = g_i \quad \forall i$

$$\frac{\partial}{\partial u_j} \frac{\partial f}{\partial u_i} = \frac{\partial g_i}{\partial u_j}$$

$$\frac{\partial}{\partial u_i} \frac{\partial f}{\partial u_j} = \frac{\partial g_j}{\partial u_i}$$

"integrability conditions"

Turns out this is enough!

so $\frac{\partial^3 f}{\partial u_i \partial u_j \partial u_k} = \frac{\partial^3 f}{\partial u_i \partial u^k \partial u^j}$

$$v = \frac{\partial}{\partial u_n} \frac{\partial^2 f}{\partial u_i \partial u_j} - \frac{\partial}{\partial u_j} \frac{\partial^2 f}{\partial u_i \partial u_n}$$

$$\begin{aligned} &= \sum_l \left[\frac{\partial}{\partial u_n} \left(I_{ij}^l \frac{\partial f}{\partial u_e} \right) - \frac{\partial}{\partial u_j} \left(I_{ik}^l \frac{\partial f}{\partial u_n} \right) \right] \\ &\quad + \left(\frac{\partial}{\partial u_n} (h_{ij} v) - \frac{\partial}{\partial u_j} (h_{ik} v) \right) \end{aligned}$$

$$\begin{aligned} &= \sum_l \left[\frac{\partial}{\partial u_n} I_{ij}^l \frac{\partial f}{\partial u_e} - \frac{\partial}{\partial u_j} I_{ik}^l \frac{\partial f}{\partial u_e} + I_{ij}^l \frac{\partial^2 f}{\partial u_n \partial u_e} \right. \\ &\quad \left. - I_{ik}^l \frac{\partial^2 f}{\partial u_j \partial u_e} \right] + \left(\frac{\partial}{\partial u_n} h_{ij} - \frac{\partial}{\partial u_j} h_{ik} \right) v \\ &\quad + h_{ij} \frac{\partial v}{\partial u_n} - h_{ik} \frac{\partial v}{\partial u_j} \end{aligned}$$

$$= \sum_l \left[\left(\frac{\partial}{\partial u_n} \Gamma_{ij}^l - \frac{\partial}{\partial u_j} \Gamma_{ik}^l \right) \frac{\partial f}{\partial u_l} + \sum_m \left(\Gamma_{ij}^l \Gamma_{k,l}^m - \Gamma_{ik}^l \Gamma_{jl}^m \right) \frac{\partial f}{\partial u_m} \right]$$

$$+ \left(\Gamma_{ij}^l h_{ke} - \Gamma_{ik}^l h_{je} \right) v \Big]$$

$$+ \left(\frac{\partial}{\partial u_n} h_{ij} - \frac{\partial}{\partial u_j} h_{ik} \right) v$$

$$\sum_l \left(-h_{ij}^l h_k^l + h_{ik}^l h_j^l \right) \frac{\partial f}{\partial u_l}$$

iteration m, l

<u>So:</u>	$\frac{\partial f}{\partial u_n}$ term	Gauss Eqn
$\frac{\partial}{\partial u_n} \Gamma_{ij}^l - \frac{\partial}{\partial u_j} \Gamma_{ik}^l + \sum_m \Gamma_{ij}^m \Gamma_{k,m}^l - \Gamma_{ik}^m \Gamma_{j,m}^l$		
$= h_{ij}^l h_k^l - h_{ik}^l h_j^l$		

v term Codazzi-Mainardi Eqn

$\frac{\partial}{\partial u_n} h_{ij} - \frac{\partial}{\partial u_i} h_{jk} + \sum_l (\Gamma_{ij}^l h_{ke} - \Gamma_{ik}^l h_{je}) = 0$
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Curvature tensor:

$$R_{ikj}^s = \frac{\partial}{\partial u_k} \Gamma_{ij}^s - \frac{\partial}{\partial u_j} \Gamma_{ik}^s + \sum_r \left(\Gamma_{ij}^r \Gamma_{rk}^s - \Gamma_{ik}^r \Gamma_{rj}^s \right)$$

M surface

$$i=j=1 \quad k=2$$

$$\begin{aligned} & \frac{\partial}{\partial u_2} \Gamma_{11}^2 - \frac{\partial}{\partial u_1} \Gamma_{22}^2 + \sum_m \Gamma_{11}^m \Gamma_{22,m}^2 - \Gamma_{12}^m \Gamma_{11,m}^2 \\ &= h_{11} h_{22}^2 - h_{12} h_{11}^2 \end{aligned}$$

h_{it} w/ $g_{t,t}$

$$\begin{aligned} & \frac{\partial}{\partial u_2} \Gamma_{11}^2 - \frac{\partial}{\partial u_1} \Gamma_{22}^2 + \sum_m \Gamma_{11}^m \Gamma_{22,m,t}^2 - \Gamma_{12}^m \Gamma_{11,m,t}^2 \\ &= h_{11} h_{22,t}^2 - h_{12} h_{11,t}^2 = \det \mathbb{H}^2 ! \end{aligned}$$

Theorem

K only depends on $I(-, -)$

Coordinate free approach

$$D_x Y = \nabla_x Y + \langle Lx, Y \rangle N$$

$$L = -DN$$

$$\frac{\partial^3 f}{\partial u_i \partial u_j \partial u_k} = \frac{\partial^3}{\partial u_i \partial u_j \partial u_k} f$$
$$x = \frac{\partial f}{\partial u_i}, \quad y = \frac{\partial f}{\partial u_j}, \quad z = \frac{\partial f}{\partial u_k}$$

$$D_x D_y Z = D_y D_x Z$$

Lemma x, y, z vector fields

$$D_x D_y Z - D_y D_x Z = D_{[x, y]} Z$$

PF

φ

$$D_x D_y \varphi$$

wrtc: $X = \sum x^i \frac{\partial f}{\partial u_i}$

$$Y = \sum y^i \frac{\partial f}{\partial u_i}$$

$$D_x D_y \varphi = D_x \sum_i y^i \frac{\partial \varphi}{\partial u_i}$$

$$= \sum_j x^j \left(\frac{\partial Y^i}{\partial u_j} \frac{\partial \varphi}{\partial u_i} + y^i \frac{\partial^2 \varphi}{\partial u_i \partial u_j} \right)$$

$$D_x D_y Q - D_y D_x Q = \sum_j \left(x^j \frac{\partial y^i}{\partial u_i} - y^j \frac{\partial x^i}{\partial u_i} \right) \cancel{u_i}$$

$$= D_{[x,y]} Q$$

□

Gauss Eqn

$$0 = D_x D_y z - D_y D_x z - D_{[x,y]} z$$

$$= D_x \nabla_y z - D_y \nabla_x z - \nabla_{[x,y]} z$$

$$+ D_x (\langle L Y, z \rangle N) - D_y (\langle L X, z \rangle N)$$

$$- \langle L [x,y], z \rangle N$$

$$\left. \begin{aligned} L &= -DN \\ \Rightarrow Lx &= -D_x N \end{aligned} \right)$$

$$= \nabla_x \nabla_y z - \nabla_y \nabla_x z - \nabla_{[x,y]} z$$

$$+ \cancel{\langle L \nabla_y z, x \rangle N} - \cancel{\langle L \nabla_x z, y \rangle N}$$

$$+ \underline{\langle \nabla_x Ly, z \rangle N + \langle Ly, \nabla_x z \rangle N}$$

$$- \langle Ly, z \rangle Lx$$

$$- \underline{\langle \nabla_y Lx, z \rangle N} - \cancel{\langle Lx, \nabla_y z \rangle N}$$

$$+ \underline{\langle Lx, z \rangle Ly} - \cancel{\langle L[x,y], z \rangle N}$$

$$\nabla_x \nabla_y z - \nabla_y \nabla_x z - \nabla_{[x,y]} z =$$

$$\langle L Y, z \rangle L X - \langle L X, z \rangle L Y$$

$$= II(Y, z) L X - II(X, z) L Y$$

and

$$\nabla_x L Y - \nabla_y L X = L [X, Y]$$

Curvature tensor

$$R(X, Y) z = \nabla_x \nabla_y z - \nabla_y \nabla_x z - \nabla_{[x,y]} z$$

$$R(X, Y) z = II(Y, z) L X - II(X, z) L Y$$

Consequence $R(X, Y) z$ only depends on

$$(X(z_0), Y(z_0), z(z_0))$$

Aside What is a tensor?

$$A_{z_0} : \overbrace{T_{z_0} M \times \cdots \times T_{z_0} M}^n \longrightarrow T_{z_0} M \quad \text{deg } (1, s)$$

R ab (0, s)

$$A(x_1, \dots, x_n) \quad \text{bilinear in each variable}$$

e.g.

$$\begin{aligned} I(-, -) \\ II(-, -) \end{aligned} \quad \left. \begin{array}{l} \\ \end{array} \right\} \text{deg } (0, 2) \quad \begin{aligned} g_{ij} \\ h_{ij} \end{aligned}$$

whereas

$$R(-, -) - \quad \left. \begin{array}{l} \\ \end{array} \right\} \text{deg } (1, 3) \quad R_{ijkl}^e$$

$$\langle R(-, -) - , - \rangle . \quad \text{deg } (0, 4) \quad R_{ijkl}$$

Note: here

$$A_{z_0} : \underbrace{T_{z_0} M \otimes T_{z_0} M \otimes \cdots \otimes T_{z_0} M}_s \longrightarrow T_{z_0} M$$

given A (type $(1, \bar{s})$) $A_{i_1 \dots i_s}^{\bar{i}}$

B (type $(0, 1)$) B_i^j

get tensor of type $(0, s)$

$$B(A(x_1, \dots, x_s)) = C(x_1, \dots, x_s)$$

obtained by $C_{i_1 \dots i_s} = \sum_j A_{i_1 \dots i_s}^j B_j^i$

"contraction"

e.g. $R(x, y)z \sim R_{i j k}^l$

$$I(R(x, y)z, w) \sim R_{i j k}^l$$

$$I(-, -) \sim g_{ij}$$

$$R_{i j k l} = \sum_m g_{e,m} R_{i j k}^m$$

Then Esseen (take II) $M \subseteq \mathbb{R}^3$ surface

Suppose (X, Y) is an orthonormal basis of $T_{z_0} Y$

$$\langle R(X, Y)Y, X \rangle = \text{Det}(L) = K$$

$$LX \sim \begin{pmatrix} \langle Lx, x \rangle & \langle Ly, x \rangle \\ \langle Lx, y \rangle & \langle Ly, y \rangle \end{pmatrix}$$

$$\begin{aligned} \langle R(X, Y)Y, X \rangle &= \langle \langle Ly, Y \rangle LX - \langle Lx, Y \rangle LY, X \rangle \\ &= \langle Ly, Y \rangle \langle LX, X \rangle - \langle Lx, Y \rangle \langle LY, X \rangle \\ &= \det(L) \end{aligned}$$



Rank

M hyperplane

x_1, \dots, x_n principle curvatures
 $Lx_i = x_i$ (orthogonal basis)

$$\langle R(x_i, x_j) x_j, x_i \rangle$$

$$= \langle \langle Lx_j, x_i \rangle Lx_i - \langle Lx_i, x_j \rangle Lx_j, x_i \rangle$$

$$= K_{ij} K_{ji} \quad i \neq j \quad \text{" sectional curvature of } x_i x_j \text{ plane"}$$

Bst: x_1, \dots, x_n is any orthogonal basis of $T_p M$

$$\boxed{\frac{1}{\binom{n}{2}} \sum_{i \neq j} K_{ij} K_{ji} = \frac{1}{\binom{n}{2}} \sum \langle R(x_i, x_j) x_j, x_i \rangle}$$

K_L "scalar curvature"

only depends on $I(-, -)$

Note $n=1$
 does not
 give us anything

Consequence of Theorem 2, etc

As long as we have g_{ij}

get $I_{ij}^{\alpha\beta} \Rightarrow$ have $\nabla_x Y$

and have K ($n=2$)

(K_2 $n>2$)

Note: g_{ij} does not define surface (e.g. cylinder.)
or h_{ij}

Next idea: given h_{ij} , we can get back
the surface!

Thus $U \subset \mathbb{R}^n$ open

given: $g_{ij}: U \rightarrow \mathbb{R}$ $[g_{ij}]$ symm. + def

• $h_{ij}: U \rightarrow \mathbb{R}$ $[h_{ij}]$ symm.

• $\bar{u} \in U$

• $\bar{p} \in \mathbb{R}^{n+1}$

• $\bar{x}_1, \dots, \bar{x}_n \in \mathbb{R}^{n+1}$

s.t. $\langle \bar{x}_i, \bar{x}_j \rangle = g_{ij}(\bar{u})$
• $\bar{v} \perp \{\bar{x}_i\}$

define Γ_{ij}^k from g_{ij}

(+) assume Gauss and Codazzi-Mainardi eqns are satisfied.

$\exists V \subset U$
 ψ
 \bar{u}

and $f : V \rightarrow \mathbb{R}^{n+1}$

s.t. (1) $f(V) \subset \mathbb{R}^{n+1}$ is symmetric

(2) $f(\bar{u}) = \bar{p}$

(3) $\frac{\partial f}{\partial u_i} = \bar{X}_i$

(4) $\nu(\bar{u}) = \bar{\nu}$

(5) g_{ij} , h_{ij} are I, II of M .

(pf) existence of soln to linear PDE

given "integrability conditions"
