

We say that $F: M \times [a, b] \rightarrow N$ is smooth if it is a restriction of $\tilde{F}: M \times (a-\epsilon, b+\epsilon) \rightarrow N$ for some $\epsilon > 0$.
a smooth

Theorem Let $F: M \times [0, 1] \rightarrow N$ be a smooth map. Set $F_t(x) = F(x, t)$ and consider the induced map on de Rham cohomology $F_t^*: H^p(N) \rightarrow H^p(M)$.

Then: $F_1^* = F_0^*$.

Proof Let $\alpha = [\alpha] \in H^p(N)$
closed form on N

$F^* \alpha \in \Omega^p(M \times [0, 1])$
in fact on $M \times (-\epsilon, 1+\epsilon)$
 (#) $F^* \alpha = \int + dt \wedge \gamma$ ← splitting
p-form on M depending on t (p-1)-form on M depending on t

splitting (#) is clear in a coord. system.

more invariantly:
 To get γ : let $\varphi_t: (x, s) \mapsto (x, s+t)$ be the flow on $M \times (a, b)$ - it generates a vector field $X = \frac{\partial}{\partial t}$
 then: $\gamma = \mathcal{L}_X F^* \alpha$

α closed $\Rightarrow F^* \alpha$ closed $\Rightarrow 0 = d(\beta + dt \wedge \gamma)$

$= d_M \beta + dt \wedge \frac{\partial \beta}{\partial t} - dt \wedge d_M \gamma$

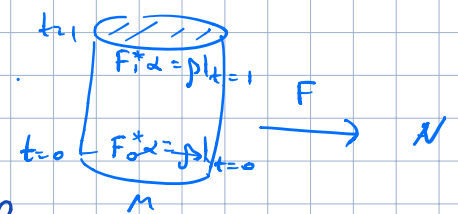
$d_M =$ exterior derivative \therefore the variables of M .

$\Rightarrow \frac{\partial \beta}{\partial t} = d_M \gamma$

$\Rightarrow F_1^* \alpha - F_0^* \alpha$

$\frac{\partial}{\partial t} F_t^* \alpha$

$= \int_0^1 dt \frac{\partial}{\partial t} F_t^* \alpha = d_M \int_0^1 dt \gamma$



\Rightarrow closed forms $F_1^* \alpha, F_0^* \alpha$ differ by an exact form

$\Rightarrow F_1^* \alpha = F_0^* \alpha$

□

Corollary: The de Rham cohomology groups of $M = \mathbb{R}^n$ are zero for $p > 0$.

Proof: set $F: \mathbb{R}^n \times [0,1] \rightarrow \mathbb{R}^n$
 $(x, t) \mapsto tx$

$F_1 = id$
 F_0 maps \mathbb{R}^n to $0 \in \mathbb{R}^n$
 - constant map

$F_1^*: H^p(\mathbb{R}^n) \rightarrow H^p(\mathbb{R}^n)$
 $= id$

$\Rightarrow DF_0$ vanishes \Rightarrow

for any $\alpha \in \Omega^{>0}(\mathbb{R}^n)$, $F_0^* \alpha = 0$

$\Rightarrow F_0^*: H^p(\mathbb{R}^n) \rightarrow H^p(\mathbb{R}^n)$, $p > 0$
 zero map

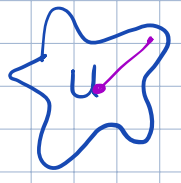
by Proposition, $F_1^* = F_0^* \Rightarrow H^p(\mathbb{R}^n) = 0$, $p > 0$

□

\mathbb{R}^n is connected $\Rightarrow H^0(\mathbb{R}^n) = \{ \text{locally constant functions on } \mathbb{R}^n \} \cong \mathbb{R}$

• By a similar argument:

- Poincaré lemma: if $U \subset \mathbb{R}^n$ a "star-shaped region" open
 $\forall x \in U, t \in [0,1], tx \in U$



then $H^p(U) = \begin{cases} \mathbb{R} & \text{if } p=0 \\ 0 & \text{if } p>0 \end{cases}$

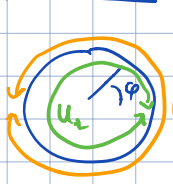
$H^p(M \times \mathbb{R}^n) \cong H^p(M)$

for any manifold M

$F_t(a, x) = (a, tx)$

\sim deformation retraction of $M \times \mathbb{R}^n$ onto M

* Example: $H^1(S^1)$



$S^1 = \{e^{i\varphi} \in \mathbb{C}\}$
 U_1 parameterize by the angle $\varphi \in \mathbb{R}/2\pi\mathbb{Z}$

$\mu = d\varphi$ is a nowhere-vanishing 1-form on S^1 .

μ defined by this f.l.s. in $U_1 = S^1 \setminus \{1\}$ where $\varphi \in (-\pi, \pi)$ and $U_2 = S^1 \setminus \{-1\}$ where $\varphi \in (0, 2\pi)$

$d\mu = 0$ obviously (e.g. for degree reason)
 $\Rightarrow \mu$ closed

assume $\mu = df$ S^1 compact $\Rightarrow f$ must have a min and a max global function on $S^1 \Rightarrow df$ must vanish somewhere but μ is nowhere-vanishing! $\Rightarrow \mu$ is not exact.

So: $H^1(S^1) \neq 0$
 and contains the nonzero class $[\mu]$

Let $\alpha \in \Omega^1(S^1)$ any form
 $\int \underbrace{g(\varphi) d\varphi}_{\text{periodic function of } \varphi}$

want $\alpha = dh \Rightarrow g(\varphi) = h'(\varphi)$
 solution $h(\varphi) = \int_0^\varphi g(s) ds (+C)$

this solution is periodic if $\int_0^{2\pi} g(s) ds = 0$

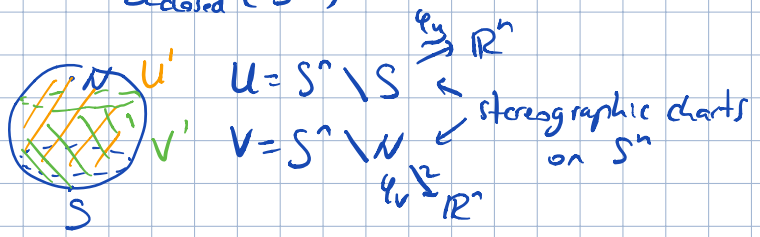
generally: $g(\varphi) = \underbrace{\frac{1}{2\pi} \int_0^{2\pi} ds g(s)}_{g_0 - \text{mean value of } g \text{ on } S^1} + \tilde{g}(\varphi)$ with $\tilde{g}(\varphi) = h'(\varphi)$
 $g(\varphi) - g_0, h(\varphi) = \int ds \tilde{g}(\varphi)$

So: $\alpha = g_0 \underbrace{\mu}_{d\varphi} + \underbrace{dh}_{\text{exact form}} \Rightarrow H^1(S^1) = \text{Span}[\mu] = \mathbb{R}$ ✓

Theorem: For $n > 0$, $H^p(S^n) \cong \begin{cases} \mathbb{R} & \text{if } p=0 \text{ or } n \\ 0 & \text{otherwise} \end{cases}$

Proof Let $n > 1$ (case $n=1$ was discussed above). Let $1 < p < n$.

Let $\alpha \in \Omega^p_{\text{closed}}(S^n)$



$d|_U = du \leftarrow \text{since } H^p(\mathbb{R}^n) = 0$
 $d|_V = dv \leftarrow \text{for some } u \in \mathbb{R}^n(U), v \in \mathbb{R}^n(V)$

on $U \cap V$: $0 = \alpha|_{U \cap V} - \alpha|_{U \cap V} = du - dv = d(u-v)$

$$\Rightarrow u-v \in \Omega_{\text{closed}}^{p-1}(UNV) \cong \mathbb{R} \times S^{n-1}$$

$$H^{p-1}(\mathbb{R} \times S^{n-1}) = H^{p-1}(S^{n-1}) = 0 \text{ for } 1 < p < n$$

by induction

$$\Rightarrow u-v = dW, W \in \Omega^{p-2}(UNV)$$

Let $U' = \varphi_u^{-1}(B_2(0))$
 $V' = \varphi_v^{-1}(B_2(0))$

Let $\psi =$ bump function on UNV with support s.t. $\psi = 1$ on $U' \cap V'$

$\psi \cdot W$ - global $(p-2)$ -form on S^n
 (extended by zero)

define $\beta = \begin{cases} u & \text{on } U' \\ v + d(\psi W) & \text{on } V' \end{cases}$ - global $(p-1)$ -form (restrictions to $U' \cap V'$ agree)

then $d\beta = \alpha \Rightarrow \alpha$ is exact! $\Rightarrow H^p(S^n) = 0$
 for $1 < p < n$

• If $p=1$, $u-v \in \Omega_{\text{closed}}^0(UNV) = \mathbb{C}$ - a constant function (using that UNV is connected, for $n > 1$)

$$\Rightarrow \beta = \begin{cases} u & \text{on } U \\ v+c & \text{on } V \end{cases}$$

- global function, $d\beta = 0$ (agree on overlap)

• If $p=n$, $u-v$ defines a class in $H^{n-1}(UNV) \cong H^{n-1}(S^{n-1}) \cong \mathbb{R}$
 induction

Let $H^{n-1}(S^{n-1}) = \text{Span}\{\omega\}$
 $\cong \Omega_{\text{closed}}^{n-1}(S^{n-1})$

$$UNV \xrightarrow{\cong} S^{n-1} \times \mathbb{R}$$

$$\begin{matrix} \pi \downarrow \\ S^{n-1} \end{matrix}$$

So: $u-v = \lambda \omega + dW$
 since $\lambda \in \mathbb{R}$

• If $\lambda=0$, then we do as above and find a global $(p-1)$ -form β s.t. $\alpha = d\beta$.

• λ is linear in α and independent of the choice of u, v (shifting them by an exact term can be absorbed into W)

$$\Rightarrow \dim H^n(S^n) \leq 1$$

- Need to find α with nonzero λ . Set $\alpha = \psi^+ \left(\int \psi(s) ds \right) \omega \in \Omega^n(S^n)$
 $\psi =$ bump function on \mathbb{R}

$u = \psi^+ \left(\int_{-\infty}^t \psi(s) ds \right) \omega \in \Omega^{p-1}(U)$
 extension by zero from UNV to U
 s.t. $du = \alpha$

extended by zero outside supp $\psi^+ \psi$

$v = \psi^+ \left(\int_t^{\infty} \psi(s) ds \right) \omega \in \Omega^{p-1}(V)$
 $u-v = \left(\int_{-\infty}^{\infty} \psi(s) ds \right) \omega$ on UNV \square

Integration of forms

Orientation Recall a change of variables formula in a multiple integral

$$\int f(y_1, \dots, y_n) dy_1 \dots dy_n = \int f(y_1(x) \dots y_n(x)) \left| \det \frac{\partial y_i}{\partial x_j} \right| dx_1 \dots dx_n \quad (*)$$

compare to: the change of coords for an n-form on an n-mfd:

$$\begin{aligned} \theta &= f(y_1, \dots, y_n) dy_1 \wedge \dots \wedge dy_n = f(y_1(x), \dots, y_n(x)) \left(\sum_{i_1} \frac{\partial y_{i_1}}{\partial x_{i_1}} dx_{i_1} \right) \wedge \dots \wedge \left(\sum_{i_n} \frac{\partial y_{i_n}}{\partial x_{i_n}} dx_{i_n} \right) \\ &= f(y_1(x), \dots, y_n(x)) \cdot \det \left(\frac{\partial y_i}{\partial x_j} \right) \cdot dx_1 \wedge \dots \wedge dx_n \end{aligned}$$

So: the difference is the absolute value $|\det|$ in (*). If we can deal with that, we

should be able to assign a coord-independent value to $\int_M \alpha$ \uparrow n-form.

... Dealing with $|\det|$ vs \det = orientation ...

def An n-mfd is orientable if it has an everywhere non-vanishing n-form ω .

def Let M be an orientable n-manifold. An orientation on M is an equiv. class of non-vanishing n-forms ω where $\omega \sim \omega'$ if $\omega' = f\omega$ with $f > 0$.

• A connected orientable mfd has two orientations $[\pm \omega]$.

Ex 1: $f: \mathbb{R}^{n+1} \rightarrow \mathbb{R}$ \cup regular value of f $M = f^{-1}(c) \subset \mathbb{R}^{n+1}$ submanifold (by regular value levelset thm)

if $\frac{\partial f}{\partial x_i} \Big|_a \neq 0$, then $x_1, \dots, \hat{x}_i, \dots, x_{n+1}$ are loc. coords on M near a.

On such a patch, consider $\omega = (-1)^i \frac{1}{\frac{\partial f}{\partial x_i}} dx_1 \wedge \dots \wedge \hat{dx}_i \wedge \dots \wedge dx_{n+1}$ (#) - non-vanishing n-form

if $\frac{\partial f}{\partial x_j} \Big|_a \neq 0$ also, then $\omega = (-1)^j \frac{1}{\frac{\partial f}{\partial x_j}} dx_1 \wedge \dots \wedge \hat{dx}_j \wedge \dots \wedge dx_{n+1}$ \leftarrow substitute $dx_j = \frac{-1}{\frac{\partial f}{\partial x_j}} \left(\frac{\partial f}{\partial x_i} dx_i + \dots \right)$

\Rightarrow (#) defines for all charts a non-vanishing n-form

\Rightarrow M is orientable

$$\sum_j \frac{\partial f}{\partial x_j} dx_j = 0 \text{ on } M$$

E.g. $M = S^n$ with $\omega = (-1)^i \frac{1}{x_i} dx_1 \wedge \dots \wedge \hat{dx}_i \wedge \dots \wedge dx_{n+1}$ (c)

Ex 2 Consider $\mathbb{R}P^n$, $p: S^n \rightarrow \mathbb{R}P^n$

\downarrow
with vector in \mathbb{R}^{n+1}
 $\rightarrow \text{Span}\{v\}$

~~if $x_i \neq 0$, use (x_2, \dots, x_{n+1}) coordinates on S^n , $(\frac{x_2}{x_1}, \dots, \frac{x_{n+1}}{x_1})$ coordr. on $\mathbb{R}P^n$~~

~~$p(x) = \frac{x}{\sqrt{1-\|x\|^2}}$ - smooth with smooth inverse $q(y) = \frac{y}{\sqrt{1+\|y\|^2}}$~~

Let $\sigma: S^n \rightarrow S^n$ be the diffeo $\sigma(x) = -x$. Then

$\sigma^* \omega = (-1)^i \frac{1}{-x_i} d(-x_1) \wedge \dots \wedge d(-x_i) \wedge \dots \wedge d(-x_{n+1}) = (-1)^{n+1} \omega$

Suppose $\mathbb{R}P^n$ is orientable. Then it has a nonvanishing n -form $\theta \Rightarrow p^* \theta$ is a nonvanishing n -form on S^n and so $p^* \theta = f \omega$, for f a nonvanishing function.

$p \circ \sigma = p \Rightarrow f \omega = p^* \theta = \sigma^* p^* \theta = \sigma^*(f \omega) = (\sigma^* f) \cdot (-1)^{n+1} \omega$

Thus, if $n=2m$ even, then $f = -\sigma^* f$, i.e. $f(a) = -f(-a)$

so, if $f(a) > 0$, then $f(-a) < 0$. But S^n is connected, so this means that f must vanish somewhere - contradiction!

$\Rightarrow \mathbb{R}P^{2m}$ is non-orientable!

Proposition A manifold is orientable iff it has a covering by coord. charts such that

$\det \left(\frac{\partial y_i}{\partial x_j} \right) > 0$ on the intersection.

Proof Assume M is orientable, ω a non-vanishing n -form. In a coord. chart, $\omega = f(x_1, \dots, x_n) dx_1 \wedge \dots \wedge dx_n$. After possibly making a coord. change $x_i \mapsto c - x_i$, we have coords. s.t. $f > 0$.

Look at two such overlapping charts:

$\omega = g(y_1, \dots, y_n) dy_1 \wedge \dots \wedge dy_n = g(y_1(x), \dots, y_n(x)) \left(\det \frac{\partial y_i}{\partial x_j} \right) dx_1 \wedge \dots \wedge dx_n = f(x_1, \dots, x_n) dx_1 \wedge \dots \wedge dx_n$

since $f > 0, g > 0$, we have $\det > 0$.

Conversely: suppose we have such coords. Let $\{p_\alpha\}$ be a partition of unity subordinate to $\{U_\alpha\}$ ^{the cover} on $\{U_\alpha\}$

Set $\omega = \sum \varphi_\alpha dy_1^\alpha \wedge \dots \wedge dy_n^\alpha$

On a chart U_β with coords x_1, \dots, x_n , we have

$\omega|_{U_\beta} = \sum \varphi_\alpha \underbrace{\det \left(\frac{\partial y_i^\alpha}{\partial x_j} \right)}_{\substack{\geq 0 \\ > 0}} dx_1 \wedge \dots \wedge dx_n$ - non-vanishing! \square

• Integration Suppose M is orientable and we have chosen an orientation. We will define the integral $\int_M \theta$ of any n -form θ of compact support on M .

• choose $\{U_\alpha\}$ - coordinate covering $\theta|_{U_\alpha} = f_\alpha(x_1, \dots, x_n) dx_1 \wedge \dots \wedge dx_n$
let $\{\varphi_i\}$ - partition of unity subordinate to $\{U_\alpha\}$ $\varphi_i \theta|_{U_\alpha} = \underbrace{g_i(x_1, \dots, x_n)}_{\substack{\text{smooth function with compact} \\ \text{support on the entire } \mathbb{R}^n}}$

Define $\int_M \theta := \left(\sum_i \int_M \varphi_i \theta \right) = \sum_i \int_{\mathbb{R}^n} g_i(x_1, \dots, x_n) dx_1 \wedge \dots \wedge dx_n$

• $\text{supp } \theta$ compact $\Rightarrow \varphi_i \theta \neq 0$ for finitely many i 's \Rightarrow finitely many terms are nonzero
* $\{\text{supp } \varphi_\alpha\}$ are locally finite (finitely many $\text{supp } \varphi_i$'s intersect $\text{supp } \theta$)

$\int_M \theta$ is well-defined because of the change of variables f-ls for integration + consistent choice of sign of det Jac from orientation.