

Hamiltonian torus actions & convexity theorems

Thm (Atiyah-Guillemin-Sternberg)

Let (M, ω) be a compact connected symplectic manifold and let $\mathbb{T}^m = \mathbb{R}^m / \mathbb{Z}^m$ be an m -torus.

Let Ψ be a Hamiltonian action of \mathbb{T}^m on M with equivariant moment map $\mu: M \rightarrow \mathbb{R}^m$.

Then:

(1) $\text{Fix}_{\mathbb{T}^m}(M) = \bigsqcup_{j=1}^N C_j$ - finite union of symplectic submanifolds of M

(2) Level sets of μ are connected

(3) The image of μ is convex

(4) The image of μ is the convex hull of images of fixed points of \mathbb{T}^m -action.

- The image $\mu(M)$ of the moment map is called the "moment polytope"

polytope = convex hull of fin. many points in \mathbb{R}^n

convex polyhedron in \mathbb{R}^n = intersection of finitely many affine half-spaces

so: polytope = bounded convex polyhedron

Ex: $M = \mathbb{C}P^n$

ω = symplectic form arising from symplectic reduction
 $= \frac{i}{2} \partial \bar{\partial} \log(|z_0|^2 + \dots + |z_n|^2)$

$\mathbb{C}P^n = \mathbb{C}^{n+1} / S^1$
 with ω standard

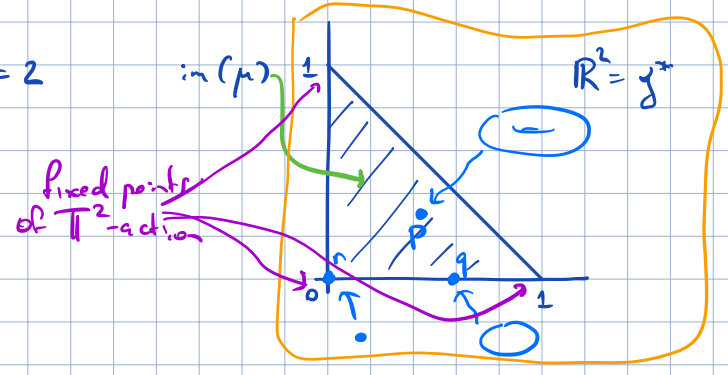
action $\mathbb{T}^n \curvearrowright \mathbb{C}P^n$ by $\Psi(e^{i\theta_1}, \dots, e^{i\theta_n}), (z_0:z_1:\dots:z_n)$
 $= (z_0:e^{i\theta_1}z_1:\dots:e^{i\theta_n}z_n)$

moment map:

$\mu: \mathbb{C}P^n \rightarrow \mathbb{R}^n$
 $(z_0:\dots:z_n) \mapsto \left(\frac{|z_1|^2}{\|z\|^2}, \dots, \frac{|z_n|^2}{\|z\|^2} \right)$

← scale the symplectic form by (-2) so as to avoid a factor $(-\frac{1}{2})$ here.

E.g. $n=2$



for p inside the triangle,
 $\mu^{-1}(p) = 2$ -torus $\{(1:e^{i\theta_1}\sqrt{x}:e^{i\theta_2}\sqrt{1-x})\}$

for q on the boundary (not corner),
 $\mu^{-1}(q) = S^1$ (e.g. $(1:e^{i\theta}\sqrt{x}:0)$ if $q=(x,0)$ or $(0:\sqrt{x}:e^{i\theta}\sqrt{1-x})$ if $q=(x,1-x)$)

for r a corner (vertex),
 $\mu^{-1}(r) = pt$

stabilizers $\subset \mathbb{T}^2$: $\text{Stab}(p) = \{1\}$, $\text{Stab}\{q\} = S^1$, $\text{Stab}\{r\} = \mathbb{T}^2$ (15)

Rem One can view this example like this:

$$\begin{array}{ccc} S^1 & \xrightarrow{\psi_1} & \mathbb{R} \\ \uparrow & & \uparrow \\ \mathbb{C}^{n+1} & \xrightarrow{\mu_1} & \mathbb{R} \\ \downarrow & & \downarrow \\ \mathbb{T}^n & \xrightarrow{\mu_2} & \mathbb{R}^n \end{array} \quad \text{commuting ham. actions}$$

$$\psi_1: e^{i\theta} \cdot (z_0, \dots, z_n) = (e^{i\theta} z_0, \dots, e^{i\theta} z_n), \quad \mu_1(z_0, \dots, z_n) = \|z\|^2 - 1$$

-diagonal action

$$\psi_2: (e^{i\theta_1}, \dots, e^{i\theta_n}) \cdot (z_0, \dots, z_n) = (z_0, e^{i\theta_1} z_1, \dots, e^{i\theta_n} z_n), \quad \mu_2(z_0, \dots, z_n) = (|z_1|^2, \dots, |z_n|^2)$$

Then: $\mathbb{C}P^n = \mathbb{C}^n // S^1$ - inherits the ham. action $\underline{\Psi}_2$ with moment map $\underline{\mu}_2$.

• A group action $G \curvearrowright M$ is called "effective" if each $g \in G$ moves at least one point in M (i.e. no elt. of G acts as identity)

Fact any effective torus action $T^m \curvearrowright M$ (not necessarily Hamiltonian) has orbits of dimension m .

Corollary (of AGS theorem) Under conditions of AGS thm., if the action $T^m \curvearrowright M$ is effective, then there must be at least $m+1$ fixed points.

Proof: T^m effective $\Rightarrow \exists$ a point $p \in M$ where μ is a submersion, i.e. $(d\mu_1)_p, \dots, (d\mu_m)_p$ are lin. indep.

$\Rightarrow \mu(p)$ is an interior point of $\text{im}(\mu) \Rightarrow \text{im}(\mu)$ is a non-degenerate convex polytope.

Any nondeg. convex polytope in \mathbb{R}^m has $\geq m+1$ vertices; vertices of $\text{im}(\mu)$ are images of fixed points \square

Prop. Let (M, ω, T^m, μ) be a Ham. T^m -space. If the T^m -action is effective, then $\dim M \geq 2m$.

Proof: (1) T^m -orbits are isotropic in M (see the proof of MWM thm.)

(2) since the action is effective, there are orbits of dimension $m = \dim G$.

(1) + (2) $\Rightarrow m \leq \frac{1}{2} \dim M \quad \square$

Def A (symplectic) toric manifold is a cpt connected symplectic mfd (M, ω) equipped with an effective Hamiltonian action of a torus T^m

with $m = \frac{1}{2} \dim M$ and with a choice of moment map μ .

Rem a toric manifold gives rise to an integrable system on M with (Poisson-commuting) Hamiltonians μ_1, \dots, μ_m .
with $\mu = (\mu_1, \dots, \mu_m)$

Classification of symplectic toric manifolds

def A Delzant polytope Δ in \mathbb{R}^n is a ^(compact) convex polytope that is:

- "simple" - there are ^{exactly} n edges meeting at each vertex ;
- "rational" - edges ^{meeting at p} have the form $p + t u_i$, $t \geq 0$ with $u_i \in \mathbb{Z}^n$;
- "smooth" - for each vertex p , corresponding u_i can be chosen to be a \mathbb{Z} -basis of \mathbb{Z}^n .

(positions of vertices don't have to be rational)

Examples:

$n=1$:

$n=2$:

$n=3$:

Non-examples

$n=2$: not smooth

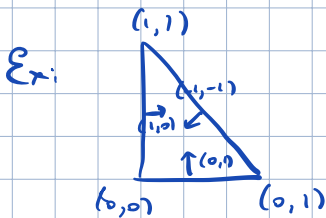
$n=3$: not simple

Another description of Delzant polytopes

Let Δ be a Delzant polytope in \mathbb{R}^n with d faces (of codim = 1).

Let $v_i \in \mathbb{Z}^n$, $i=1 \dots d$ the primitive inward-pointing normal vectors to faces
 \uparrow
 $v \neq k u$ for $u \in \mathbb{Z}^n$, $k \geq 2$, $k \in \mathbb{Z}$

Then: $\{x \in (\mathbb{R}^n)^* \mid \langle x, v_i \rangle \geq \lambda_i, i=1 \dots d\}$ for some $\lambda_i \in \mathbb{R}$.
 \uparrow
~~Euc. inner product on \mathbb{R}^n~~



$$\Delta = \{x \in (\mathbb{R}^2)^* \mid x_1 \geq 0, x_2 \geq 0, x_1 + x_2 \leq 1\}$$

$$= \{x \in (\mathbb{R}^2)^* \mid \langle x, (1,0) \rangle \geq 0, \langle x, (0,1) \rangle \geq 0, \langle x, (1,-1) \rangle \geq -1\}$$

Delzant theorem

Toric manifolds are classified by Delzant polytopes:

there is a bijection

$$\left\{ \begin{array}{l} \text{toric manifolds} \\ (M, \omega, \mathbb{T}^n, \mu) \end{array} \right\} \xleftrightarrow{\quad} \{ \text{Delzant polytopes} \}$$

$$(M, \omega, \mathbb{T}^n, \mu) \longmapsto \mu(M)$$

Sketch of proof of existence (surjectivity)

$$\Delta \subset (\mathbb{R}^n)^* \text{ Delzant with } d \text{ faces} \xrightarrow{?} (M_\Delta, \omega_\Delta, \mathbb{T}^n, \mu)$$

write $\Delta = \{x \in (\mathbb{R}^n)^* \mid \langle x, v_i \rangle \geq \lambda_i, i=1 \dots d\}$
 $v_i \in \mathbb{Z}^n$ primitive inward face vectors.

Let $\pi: \mathbb{R}^d \rightarrow \mathbb{R}^n$

$e_i \mapsto v_i$
 ↑
 stand. basis vectors

• Claim: π is onto and maps \mathbb{Z}^d onto \mathbb{Z}^n
 (at a vertex?, edge vectors $\{u_i\}$ form a basis of \mathbb{Z}^n ; $\{v_i\}$ form a dual basis of \mathbb{Z}^n)
 (for incident faces)

Thus π induces a surjective map of tori:

$$0 \rightarrow H \xrightarrow{i} \mathbb{T}^d \xrightarrow{\pi} \mathbb{T}^n \rightarrow 0 \quad \text{LES of Lie groups (tori)}$$

$\ker \pi \quad \mathbb{R}^d/\mathbb{Z}^d \quad \mathbb{R}^n/\mathbb{Z}^n$

$$0 \rightarrow \mathfrak{h} \xrightarrow{i} \mathbb{R}^d \xrightarrow{\pi} \mathbb{R}^n \rightarrow 0 \quad \text{LES of Lie alg.}$$

$$0 \leftarrow \mathfrak{h}^* \xleftarrow{i^*} (\mathbb{R}^d)^* \xleftarrow{\pi^*} (\mathbb{R}^n)^* \leftarrow 0 \quad \text{dual LES}$$

Consider $\mathbb{C}^d, \omega_0 = \frac{i}{2} \sum dz_k \wedge d\bar{z}_k$ with stand. ham action of \mathbb{T}^d

$$(e^{2\pi i \theta_1}, \dots, e^{2\pi i \theta_d}) \cdot (z_1, \dots, z_d) = (e^{2\pi i \theta_1} z_1, \dots, e^{2\pi i \theta_d} z_d)$$

moment map $\varphi(z_1, \dots, z_d) = (|z_1|^2, \dots, |z_d|^2) + C$ set $C = (\lambda_1, \dots, \lambda_d)$
 ↑
 constant

Q: What is the moment map for the action restricted to sub-torus H?

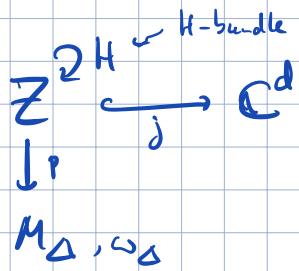
A: it is $\underbrace{i^* \circ \varphi}_{\mu_H}: \mathbb{C}^d \rightarrow \mathfrak{h}^*$

Let $Z = \mu_H^{-1}(0)$.

Claim: $0 \in \mathfrak{h}^*$ is a regular value of μ_H

• Z is a cpt subfld and H acts freely on Z .
 of $\dim Z = d - (d-n) = d+n$
 $\dim \mathfrak{h}$

Using MWN thm:
Symplectic quotient:



$$\mathbb{C}^d // H = \mathbb{Z} / H =: M_\Delta$$

orbit space

is $\hat{\omega}$ symplectic mfd, with sym form ω_Δ
 $\dim = (d+n) - (d-n) = 2n$

$$p^* \omega_\Delta = j^* \omega_0$$

• $\varphi: \mathbb{C}^d \rightarrow (\mathbb{R}^n)^*$ induces a moment map

$$\mu: M_\Delta \rightarrow \ker(i^*) = (\mathbb{R}^n)^*$$

Claim: $\mu(M_\Delta) = \Delta$.

