

4.1 Vector spaces and subspaces

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1

DEF A Vector space - a nonempty set V , objects - "vectors", with two operators

- addition $\textcircled{1} \vec{u} + \vec{v} \in V$ for $\vec{u}, \vec{v} \in V$
- ~~scalar~~ multiplication by scalars $\textcircled{2} c\vec{u} \in V$ for $\vec{u} \in V, c \in \mathbb{R}$.

such that:

- $\textcircled{3} (\vec{u} + \vec{v}) + \vec{w} = \vec{u} + (\vec{v} + \vec{w})$, $\textcircled{4} \vec{u} + \vec{v} = \vec{v} + \vec{u}$, $\textcircled{5} \exists$ zero vector $\vec{0} \in V$ s.t. $\vec{u} + \vec{0} = \vec{u} \quad \forall \vec{u}$.
- $\textcircled{6} c(\vec{u} + \vec{v}) = c\vec{u} + c\vec{v}$, $\textcircled{7} (c+d)\vec{u} = c\vec{u} + d\vec{u}$, $\textcircled{8} \forall \vec{u} \exists$ negative $-\vec{u}$ s.t. $\vec{u} + (-\vec{u}) = \vec{0}$
- $\textcircled{9} c(d\vec{u}) = (cd)\vec{u}$
- $\textcircled{10} 1 \cdot \vec{u} = \vec{u}$

Corollaries $\vec{0}$ is unique, $-\vec{u}$ is unique
 $0 \cdot \vec{u} = \vec{0}$, $c\vec{0} = \vec{0}$, $-\vec{u} = (-1)\vec{u}$.

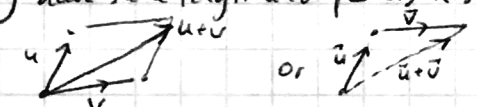
(Main example up to now)

Ex: spaces \mathbb{R}^n , $n \geq 1$

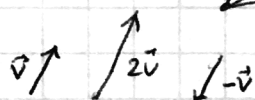
Ex: set of arrows (directed line segments) in \mathbb{R}^2 (or \mathbb{R}^3).

two arrows are considered equal if they have same length and point in same direction

addition: by parallelogram rule



scalar multiplication:



Ex \mathcal{S} - space of all doubly-infinite sequences of numbers $\{y_k\} = \{\dots, y_{-2}, y_{-1}, y_0, y_1, y_2, \dots\}$

$\{y_k\} + \{z_k\} = \{y_k + z_k\}$, $c \cdot \{y_k\} = \{cy_k\}$

- "discrete-time signals"

Ex for $n \geq 0$, \mathbb{P}_n - set of polynomials of degree $\leq n$, $\vec{p}(t) = a_0 + a_1 t + \dots + a_n t^n$ (*)

degree of \vec{p} - highest power of t whose coeff in (*) is $\neq 0$. ↑
real coeffs.

for $\vec{p}(t) = a_0 \neq 0$, degree = 0. If all $a_j = 0$, $\vec{p} \equiv 0$ is called the zero polynomial.
 (its degree is not defined)

sum: for $\vec{q}(t) = b_0 + b_1 t + \dots + b_n t^n$,

$(\vec{p} + \vec{q})$ is defined by $(\vec{p} + \vec{q})(t) = \vec{p}(t) + \vec{q}(t) = (a_0 + b_0) + (a_1 + b_1)t + \dots + (a_n + b_n)t^n$.

$(c \cdot \vec{p})$ is defined by $(c \cdot \vec{p})(t) = c \vec{p}(t) = c a_0 + (c a_1)t + \dots + (c a_n)t^n$

$\vec{0}$ = zero polynomial

$(-1)\vec{p} = -\vec{p}$ negative

Ex $V =$ set of all real-valued functions on a set D
 Rules: $(f+g)(t) = f(t) + g(t)$, $(cf)(t) = c f(t)$

E.g. $D = \mathbb{R}$, $f = 1 + \sin 3t$ $g = 2 + 7t$

Then: $(f+g)(t) = 3 + \sin 3t + 7t$, $(2g)(t) = 4 + 14t$.

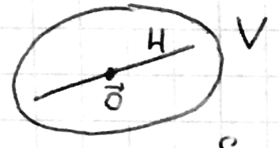
zero vector: $f(t) = 0 \forall t$.

• each function f is a "point" of V .

Def A subspace of a vector space V is a subset $H \subset V$ satisfying:

- (a) $\vec{0} \in H$
zero vector of V
- (b) for $\vec{u}, \vec{v} \in H$,
 $\vec{u} + \vec{v} \in H$
 H closed under addition
- (c) for $\vec{u} \in H$, $c \in \mathbb{R}$,
 $c\vec{u} \in H$
 H closed under scalar multiplication

• a subspace $H \subset V$ is automatically itself a vector space.



Ex $H = \{\vec{0}\} \subset V$ is a subspace - zero subspace of V .

Ex: Let $\mathbb{P} =$ all polynomials in t .
 • $\mathbb{P} \subset \{ \text{functions on } \mathbb{R} \}$ - subspace
 • $\mathbb{P}_n \subset \mathbb{P}$, $n \geq 0$ - subspace

Ex: \mathbb{R}^2 is not a subspace of \mathbb{R}^3 , (not even a subset).

But $H = \left\{ \begin{bmatrix} s \\ t \\ 0 \end{bmatrix} \mid s, t \in \mathbb{R} \right\}$ is a subspace of \mathbb{R}^3 which "looks and acts" like \mathbb{R}^2 .

Ex a line not through $\vec{0}$ in \mathbb{R}^2 - not a subspace

_____ a subspace spanned by a set _____

Ex: for $\vec{v}_1, \vec{v}_2 \in V$, let $H = \text{Span} \{ \vec{v}_1, \vec{v}_2 \}$. Then $H \subset V$ is a subspace.

Indeed, $\vec{0} = 0 \cdot \vec{v}_1 + 0 \cdot \vec{v}_2 \in H$; $\vec{u} = s_1 \vec{v}_1 + s_2 \vec{v}_2$, $\vec{v} = t_1 \vec{v}_1 + t_2 \vec{v}_2 \Rightarrow \vec{u} + \vec{v} = (s_1 + t_1) \vec{v}_1 + (s_2 + t_2) \vec{v}_2 \in H$; $c \cdot \vec{u} = (cs_1) \vec{v}_1 + (cs_2) \vec{v}_2 \in H$.

THM If $\vec{v}_1, \dots, \vec{v}_p$ are in V then $H = \text{Span} \{ \vec{v}_1, \dots, \vec{v}_p \}$ is a subspace of V .

H - subspace spanned/generated by $\{ \vec{v}_1, \dots, \vec{v}_p \}$
 $\{ \vec{v}_1, \dots, \vec{v}_p \}$ - spanning/generating set for H .

Ex: $H = \{ \text{vectors of form } (a-3b, b-a, a, b) \mid a, b \in \mathbb{R} \}$
 show that $H \subset \mathbb{R}^4$ subspace

Sol: $\begin{bmatrix} a-3b \\ b-a \\ a \\ b \end{bmatrix} = a \underbrace{\begin{bmatrix} 1 \\ -1 \\ 1 \\ 0 \end{bmatrix}}_{\vec{v}_1} + b \underbrace{\begin{bmatrix} -3 \\ 1 \\ 0 \\ 1 \end{bmatrix}}_{\vec{v}_2}$ Thus $H = \text{Span}\{\vec{v}_1, \vec{v}_2\}$ - subspace of \mathbb{R}^4

4.2 Null spaces, column spaces and lin. transformations

Recall: For A $m \times n$ mat., $\text{Nul } A = \{ \vec{x} \in \mathbb{R}^n \text{ s.t. } A\vec{x} = \vec{0} \}$ - subspace of \mathbb{R}^n
 $\text{Col } A = \text{Span}\{\vec{a}_1, \dots, \vec{a}_n\} = \{ \vec{b} \in \mathbb{R}^m \text{ s.t. } \vec{b} = A\vec{x} \text{ for some } \vec{x} \in \mathbb{R}^n \}$ - subspace of \mathbb{R}^m
 can describe as $\text{Span}\{\vec{v}_1, \dots, \vec{v}_p\}$
 with $\vec{v}_1, \dots, \vec{v}_p$ from the parametric vector solution of $A\vec{x} = \vec{0}$

3
02/21/2018
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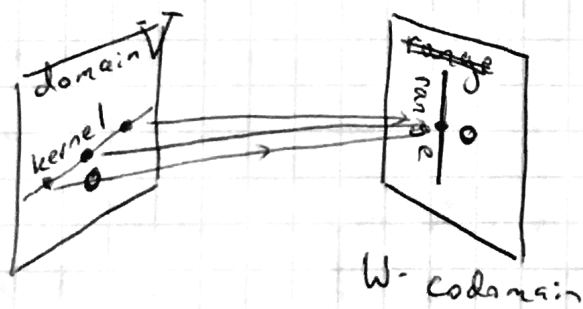
def A linear trans. T from a v.sp. V into a v.sp. W is a rule assigning to each vector \vec{x} in V a unique vector $T(\vec{x})$ in W , s.t.

- (i) $T(\vec{u} + \vec{v}) = T(\vec{u}) + T(\vec{v})$
 - (ii) $T(c\vec{u}) = cT(\vec{u})$
- any $\vec{u}, \vec{v} \in V$

5

kernel (or null space) of T = set of \vec{u} in V s.t. $T(\vec{u}) = \vec{0}$ ← subspace of V

range of T = all vectors of form $T(\vec{x})$ in W ← subspace of W



Ex: $T: V = \mathbb{R}^n \rightarrow W = \mathbb{R}^m$
 $\vec{x} \mapsto A\vec{x}$
 A is $m \times n$ matrix
 $\text{ker } T = \text{Nul } A$
 $\text{range } T = \text{Col } A$

Ex: $V =$ functions on $[a, b]$ which have continuous derivatives
 $W =$ continuous functions on $[a, b]$

$D: V \rightarrow W$ - linear trans., $\text{ker } D = \{ \text{constant functions on } [a, b] \}$
 $f \mapsto f'$ range = W .