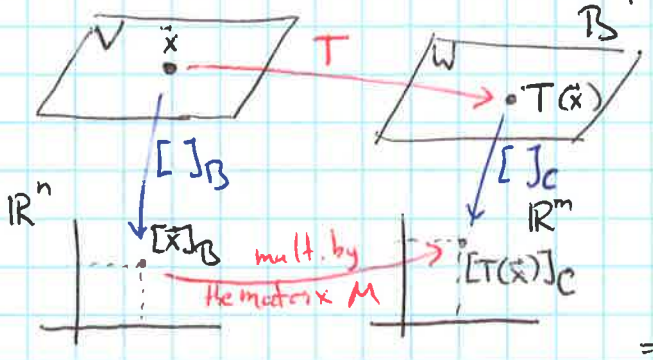


5.4 Eigenvectors and linear transformations

Idea: If $A = PDP^{-1}$, the lin. transf. $\vec{x} \mapsto A\vec{x}$ is "essentially the same" as a simple transformation $\vec{u} \mapsto D\vec{u}$.

Matrix of a lin. transf. $T: V \rightarrow W$
 v.sp. B v.sp. C - bases



how to connect $[\vec{x}]_B$ and $[T(\vec{x})]_C$?

$$\vec{x} = r_1 \vec{b}_1 + \dots + r_n \vec{b}_n \Rightarrow [\vec{x}]_B = \begin{bmatrix} r_1 \\ \vdots \\ r_n \end{bmatrix}$$

$$T(\vec{x}) = r_1 T(\vec{b}_1) + \dots + r_n T(\vec{b}_n)$$

$$\Rightarrow [T(\vec{x})]_C = r_1 [T(\vec{b}_1)]_C + \dots + r_n [T(\vec{b}_n)]_C$$

Thus: $[T(\vec{x})]_C = M [\vec{x}]_B$ with $M = [[T(\vec{b}_1)]_C \dots [T(\vec{b}_n)]_C]$ (*)

- matrix for T relative to the bases B, C
 = matrix representation of T

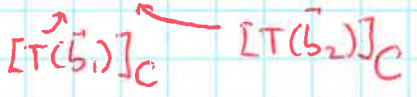
Ex: $B = \{\vec{b}_1, \vec{b}_2\}$ basis for V ,

$C = \{\vec{c}_1, \vec{c}_2, \vec{c}_3\}$ basis for W . Let $T: V \rightarrow W$ lin. transf. st.

$$T(\vec{b}_1) = 3\vec{c}_1 - 2\vec{c}_2 + 5\vec{c}_3, \quad T(\vec{b}_2) = 4\vec{c}_1 + 7\vec{c}_2 - \vec{c}_3$$

Q: Find the matrix for T rel. to B, C

Sol: $M = \begin{bmatrix} 3 & 4 \\ -2 & 7 \\ 5 & -1 \end{bmatrix}$

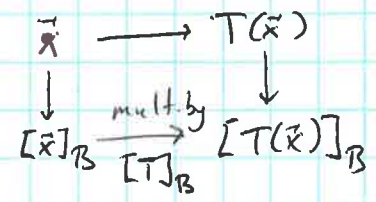


• If $V=W$ and $T(\vec{x})=\vec{x}$ the identity transf., then the matrix M is just $P_{C \leftarrow B}$ - change of coordinates matrix.

• Lin. transformations $T: V \rightarrow V$ same space
 $B \quad B$ - same basis

In this case $M = [T]_B$ - "matrix of T relative to B " or " B -matrix of T "

we have $[T(\vec{x})]_B = [T]_B [\vec{x}]_B$, for all $\vec{x} \in V$

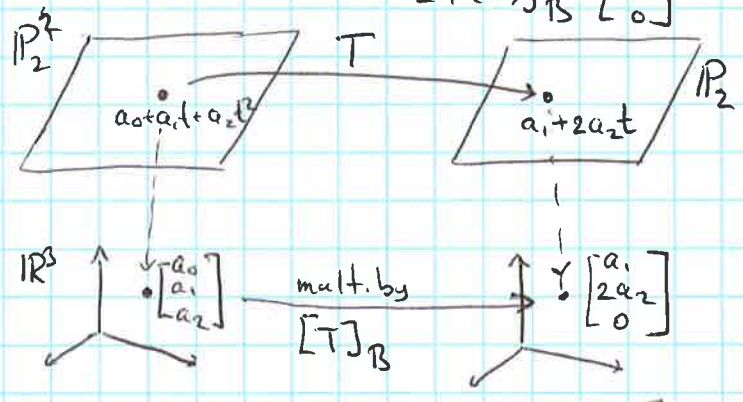


Ex: $T: \mathbb{P}_2 \rightarrow \mathbb{P}_2$ given by $T(a_0 + a_1 t + a_2 t^2) = a_1 + 2a_2 t$ (differentiation in t)

Q: Find the B -matrix for T , for $B = \{1, t, t^2\}$

Sol: $T(1) = 0 \quad [T(1)]_B = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$
 $T(t) = 1 \quad [T(t)]_B = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$
 $T(t^2) = 2t \quad [T(t^2)]_B = \begin{bmatrix} 0 \\ 2 \\ 0 \end{bmatrix}$

$\Rightarrow [T]_B = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 2 \\ 0 & 0 & 0 \end{bmatrix}$



Lin. transformations of \mathbb{R}^n

$T: \mathbb{R}^n \rightarrow \mathbb{R}^n$
 $\vec{x} \mapsto A\vec{x}$
 if A diagonalizable, B -matrix of A is diagonal, for B -basis of eigenvectors.

THM (Diagonal matrix representation)

Suppose $A = PDP^{-1}$ with D a diagonal $n \times n$ mat. If B is the basis of \mathbb{R}^n formed from the columns of P , then D is the D -matrix of the transf. $\vec{x} \mapsto A\vec{x}$.

Ex: $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$
 $\vec{x} \mapsto A\vec{x}$
 $A = \begin{bmatrix} 7 & 2 \\ -2 & 1 \end{bmatrix}$ find a basis B for \mathbb{R}^2 s.t. $[T]_B$ is diagonal.

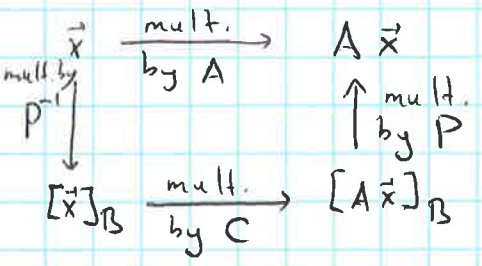
Sol: $A = PDP^{-1}$, $P = \begin{bmatrix} 1 & 1 \\ -1 & -2 \end{bmatrix}$, $D = \begin{bmatrix} 5 & 0 \\ 0 & 3 \end{bmatrix}$
 Thus for $B = \{\vec{b}_1, \vec{b}_2\}$, $[T]_B = D$

I.e. mappings $\vec{x} \mapsto A\vec{x}$ and $\vec{u} \mapsto D\vec{u}$ describe the same lin. transf. rel. to different bases.

Similarity of matrix representations

THM above does not in fact require D to be diagonal:

if $A \approx C$ similar, i.e. $A = PCP^{-1}$ and $T: \mathbb{R}^n \rightarrow \mathbb{R}^n$, then $[T]_B = C$
 basis of columns of P .



Conversely, matrix of T rel. to any basis B is similar to A .