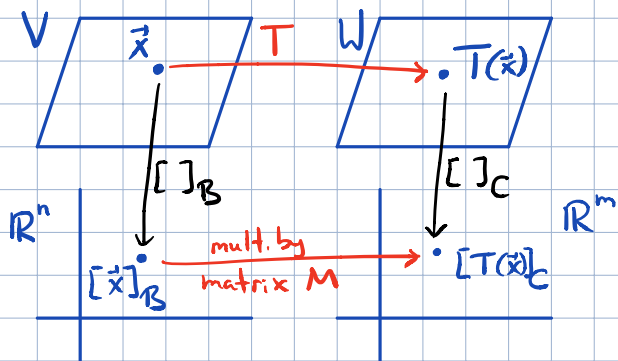


3/4/2020 | 5.4 Eigenvectors and linear transformations

Idea: if $A = PDP^{-1}$, the lin. transf. $\vec{x} \mapsto A\vec{x}$ is "essentially the same" as a simple lin. transf. $\vec{u} \mapsto D\vec{u}$.

• Matrix of a lin. transf. $T: V \rightarrow W$
 v.sp. \mathcal{B} v.sp. \mathcal{C} - bases



how to connect $[\vec{x}]_{\mathcal{B}}$ and $[T(\vec{x})]_{\mathcal{C}}$?

$$\vec{x} = r_1 \vec{b}_1 + \dots + r_n \vec{b}_n \Rightarrow [\vec{x}]_{\mathcal{B}} = \begin{bmatrix} r_1 \\ \vdots \\ r_n \end{bmatrix}$$

$$T(\vec{x}) = r_1 T(\vec{b}_1) + \dots + r_n T(\vec{b}_n)$$

$$\Rightarrow [T(\vec{x})]_{\mathcal{C}} = r_1 [T(\vec{b}_1)]_{\mathcal{C}} + \dots + r_n [T(\vec{b}_n)]_{\mathcal{C}}$$

Thus $[T(\vec{x})]_{\mathcal{C}} = M [\vec{x}]_{\mathcal{B}}$

with $M = [T(\vec{b}_1)_{\mathcal{C}} \dots T(\vec{b}_n)_{\mathcal{C}}]$

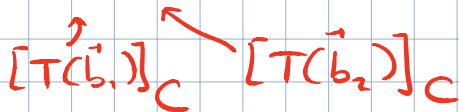
= matrix of T relative to bases \mathcal{B}, \mathcal{C}
 = matrix representation of T

Ex: $\mathcal{B} = \{\vec{b}_1, \vec{b}_2\}$ basis for V

$\mathcal{C} = \{\vec{c}_1, \vec{c}_2, \vec{c}_3\}$ basis for W . Let $T: V \rightarrow W$ be a lin. transf. s.t.

$$T(\vec{b}_1) = 3\vec{c}_1 - 2\vec{c}_2 + 5\vec{c}_3, \quad T(\vec{b}_2) = 4\vec{c}_1 + 7\vec{c}_2 - \vec{c}_3. \quad \underline{Q}: \text{find the matrix of } T \text{ rel. to } \mathcal{B}, \mathcal{C}$$

Sol: $M = \begin{bmatrix} 3 & 4 \\ -2 & 7 \\ 5 & -1 \end{bmatrix}$

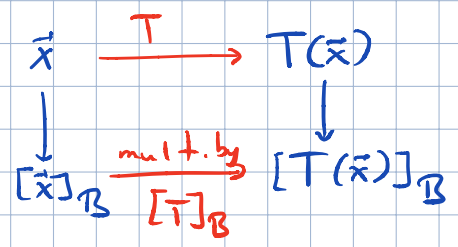


• If $V=W$ and $T(\vec{x})=\vec{x}$ the identity matrix, then the matrix M is just $\underset{\mathcal{C} \leftarrow \mathcal{B}}{P}$ - change-of-coordinates matrix

• Lin. transformations $T: V \rightarrow V$ same space
 $\mathcal{B} \quad \mathcal{B}$ - same basis

In this case, $M =: [T]_{\mathcal{B}}$ - "matrix of T relative to \mathcal{B} " or " \mathcal{B} -matrix of T "

We have $[T(\vec{x})]_{\mathcal{B}} = [T]_{\mathcal{B}} [\vec{x}]_{\mathcal{B}}$ for all $\vec{x} \in V$



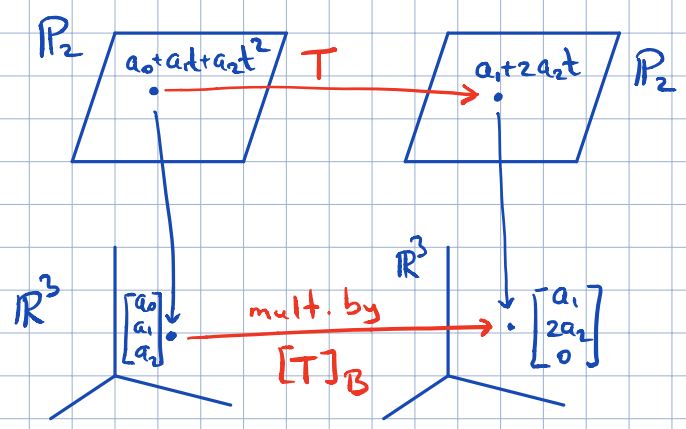
Ex: $T: \mathbb{P}_2 \rightarrow \mathbb{P}_2$ given by

$T(a_0 + a_1t + a_2t^2) = a_1 + 2a_2t$ (differentiation in t)

Q: find the \mathcal{B} -matrix for T , for $\mathcal{B} = \{1, t, t^2\}$

Sol: $T(1) = 0 \quad [T(1)]_{\mathcal{B}} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$
 $T(t) = 1 \quad [T(t)]_{\mathcal{B}} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$
 $T(t^2) = 2t \quad [T(t^2)]_{\mathcal{B}} = \begin{bmatrix} 0 \\ 2 \\ 0 \end{bmatrix}$

$\Rightarrow [T]_{\mathcal{B}} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 2 \\ 0 & 0 & 0 \end{bmatrix}$



Lin. transformations of \mathbb{R}^n

$T: \mathbb{R}^n \rightarrow \mathbb{R}^n$
 $\vec{x} \mapsto A\vec{x}$ if A diagonalizable, \mathcal{B} -matrix of A is diagonal, for \mathcal{B} -basis of eigenvectors

Thm (diagonal matrix representation)

Suppose $A = PDP^{-1}$ with D a diagonal $n \times n$ matrix. If \mathcal{B} is the basis of \mathbb{R}^n formed from the columns of P , then D is the \mathcal{B} -matrix of the transf $\vec{x} \mapsto A\vec{x}$.

Ex: $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ $A = \begin{bmatrix} 7 & 2 \\ -3 & 1 \end{bmatrix}$ find a basis \mathcal{B} for \mathbb{R}^2 s.t. $[T]_{\mathcal{B}}$ is diagonal.

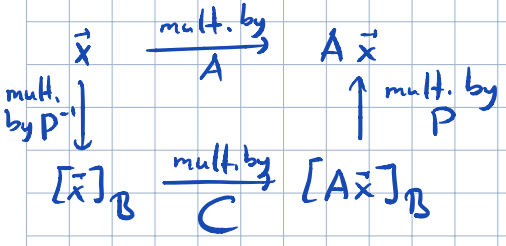
Sol: $A = PDP^{-1}$, $P = \begin{bmatrix} 1 & 1 \\ -1 & -2 \end{bmatrix}$, $D = \begin{bmatrix} 5 & 0 \\ 0 & 3 \end{bmatrix}$ Thus, for $\mathcal{B} = \{\vec{b}_1, \vec{b}_2\}$, $[T]_{\mathcal{B}} = D$

I.e. mappings $\vec{x} \mapsto A\vec{x}$ and $\vec{u} \mapsto D\vec{u}$ describe the same lin. transf. rel. to different bases.

Similarity of matrix representations

Thm above does not in fact require D to be diagonal:

if $A \sim C$, i.e. $A = P C P^{-1}$ and $T: \mathbb{R}^n \rightarrow \mathbb{R}^n$, $\vec{x} \mapsto A\vec{x}$, then $[T]_{\mathcal{B}} = C$
basis of columns of P.



conversely, matrix of T rel. to any basis B is similar to A.