

LAST TIME

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- $B = \{\vec{v}_1, \dots, \vec{v}_k\}$ is a basis for a subspace S in \mathbb{R}^n if
1) $S = \text{span}(B)$
2) B is lin. indep.

- basis for $\text{row}(A) = \{\text{nonzero rows of REF of } A\}$

$$A = \begin{bmatrix} 1 & 1 & 3 & 1 & 6 \\ 2 & -1 & 0 & 1 & -1 \\ -3 & 2 & 1 & -2 & 1 \\ 4 & 1 & 6 & 1 & 3 \end{bmatrix} \rightarrow R = \begin{bmatrix} 1 & 0 & 1 & 0 & -1 \\ 0 & 1 & 2 & 0 & 3 \\ 0 & 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\{[1 \ 0 \ 1 \ 0 \ -1], [0 \ 1 \ 2 \ 0 \ 3], [0 \ 0 \ 0 \ 1 \ -1]\} \text{ - basis for } \text{row}(A)$$

- basis for $\text{col}(A) = \{\text{pivot columns of } A\}$

$$\left\{ \begin{bmatrix} 1 \\ 2 \\ -3 \\ 4 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \\ 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ -2 \\ 1 \end{bmatrix} \right\} \text{ - basis for } \text{col}(A)$$

$$\text{null}(A) = \{ \text{solutions of } A\vec{x} = \vec{0} \} = \left\{ s \begin{bmatrix} -1 \\ -2 \\ 1 \\ 0 \\ 0 \end{bmatrix} + t \begin{bmatrix} 1 \\ -3 \\ 0 \\ 4 \\ 1 \end{bmatrix} \right\} = \text{Span}(\underbrace{\vec{u}, \vec{v}}_{\text{lin. indep.}})$$

Solve by row reduction

$$\Rightarrow \left\{ \begin{bmatrix} 1 \\ -2 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -3 \\ 0 \\ 4 \\ 1 \end{bmatrix} \right\} \text{ - basis for } \text{null}(A).$$

↑ RREF of A

- To find a basis for $\text{null}(A)$, solve $R\vec{x} = \vec{0}$ for leading vars in terms of free vars. Write the general sol. as a lin. comb. of (k) vectors $\vec{v}_1, \dots, \vec{v}_k$ with parameters $\# \text{ free vars}$ = free vars
These $\vec{v}_1, \dots, \vec{v}_k$ form a basis for $\text{null}(A)$.

Remark: Another way to construct a basis for $\text{col}(A)$: construct a basis for $\text{row}(A^T)$ and transpose row basis vectors back into columns.

Ex: $A^T = \begin{bmatrix} 1 & 2 & -3 & 4 \\ 1 & -1 & 2 & 1 \\ 3 & 0 & 1 & 6 \\ 1 & 1 & -2 & 1 \\ 6 & -1 & 1 & 3 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 6 \\ 0 & 0 & 1 & 3 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \Rightarrow \{ [1 \ 0 \ 0 \ 1], [0 \ 1 \ 0 \ 6], [0 \ 0 \ 1 \ 3] \}$
 - basis for $\text{row}(A^T)$

$\Rightarrow \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \\ 6 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \\ 3 \end{bmatrix} \right\}$ - basis for $\text{col}(A)$ (different from the one we constructed before!)

Dimension

Basis theorem Let S be a subspace of \mathbb{R}^n . Then any two bases for S have the same number of vectors.

def If S is a subspace of \mathbb{R}^n , the number of vectors in a basis for S is called the dimension of S . Notation: $\dim S$.

Ex: \mathbb{R}^n has a basis $\{ \underbrace{\vec{e}_1, \dots, \vec{e}_n}_n \} \Rightarrow \dim \mathbb{R}^n = n$.

For A $m \times n$ matrix,

$\dim \text{row}(A) = \# \text{ nonzero rows in REF of } A$	} rank(A)	in Example above
$\dim \text{col}(A) = \# \text{ pivotal columns} \Rightarrow \# \text{ pivots} = \text{rank}(A)$		
$\dim \text{null}(A) = \# \text{ free vars in } A\vec{x} = \vec{0}$		

def Nullity of A is the dimension of $\text{null}(A)$.

Thm: For any matrix A , $\dim \text{row}(A) = \dim \text{col}(A)$
(= rank(A))

So, $\text{rank}(A) = \# \text{lin. indep. rows in } A = \# \text{lin. indep. columns in } A$
surprisingly!

(2)

Corollary: $\text{rank}(A) = \text{rank}(A^T)$

$(\text{rank}(A) = \dim \text{row}(A) = \dim \text{col}(A^T) = \text{rank}(A^T))$

Rank thm: $\boxed{\text{rank}(A) + \text{nullity}(A) = n}$

pivotal columns in A # non-pivotal columns

Ex: for 4×5 matrix A above, $\dim \text{row}(A) = 3 = \dim \text{col}(A)$,
rank

$\dim \text{null}(A) = 2 \leftarrow \text{nullity}$

$3 + 2 = 5$
rank nullity # columns

• For a $m \times n$ matrix, $A\vec{x} = \vec{b}$ is consistent for any $\vec{b} \in \mathbb{R}^m$ iff RREF of A has a pivot in every row.

Fundamental Thm of invertible matrices, v.2

Let A be an $n \times n$ matrix. The following statements are equivalent:

- (a) A is invertible
- (b) $A\vec{x} = \vec{b}$ has a unique solution for any \vec{b} in \mathbb{R}^n
- (c) $A\vec{x} = \vec{0}$ has only the trivial solution
- (d) RREF of A is I_n
- (e) A is a product of elementary matrices ← we didn't discuss this
- (f) $\text{rank}(A) = n$
- (g) $\text{nullity}(A) = 0$
- (h) column vectors of A are lin. indep.
- (i) column vectors of A span \mathbb{R}^n
- (j) column vectors of A form a basis for \mathbb{R}^n
- (k) row vectors of A are lin. indep.
- (l) row vectors of A span \mathbb{R}^n
- (m) row vectors of A form a basis for \mathbb{R}^n

Ex: show that vectors $\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$, $\begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$, $\begin{bmatrix} 4 \\ 9 \\ 7 \end{bmatrix}$ form a basis for \mathbb{R}^3

Sol: $A = [\vec{u} \ \vec{v} \ \vec{w}] = \begin{bmatrix} 1 & -1 & 4 \\ 2 & 0 & 9 \\ 3 & 1 & 7 \end{bmatrix}$ $(i) \Leftrightarrow (j)$ implies $\{\vec{u}, \vec{v}, \vec{w}\}$ is a basis iff $\text{rank}(A) = 3$

$\rightarrow \begin{bmatrix} 1 & -1 & 4 \\ 0 & 2 & 1 \\ 0 & 0 & 7 \end{bmatrix}$ $\text{rank}(A) = 3 \quad \checkmark$
REF

Thm Let A be an $m \times n$ matrix, then

- a) $\text{rank}(A^T A) = \text{rank}(A)$
- b) the $n \times n$ matrix $A^T A$ is invertible iff $\text{rank}(A) = n$.

(a) $\text{null}(A^T A) = \text{null}(A)$ - because $A\vec{x} = \vec{0} \Rightarrow A^T A \vec{x} = \vec{0}$, so $\text{null}(A) \subset \text{null}(A^T A)$
and $A^T A \vec{x} = \vec{0} \Rightarrow \vec{x}^T A^T A \vec{x} = 0 \Rightarrow (A\vec{x}) \cdot (A\vec{x}) = 0 \Rightarrow A\vec{x} = \vec{0}$

Thus: $\text{nullity}(A^T A) = \text{nullity}(A)$

\Rightarrow rank-nullity Thm $\text{rank}(A^T A) = \text{rank}(A)$

(b) $A^T A$ invertible $\Leftrightarrow \text{rank}(A^T A) = n \Leftrightarrow \text{rank}(A) = n$.
 \uparrow
(a) \Leftrightarrow (b)

Ex: $A = \begin{bmatrix} 1 & 2 \end{bmatrix}$ $A^T A = \begin{bmatrix} 1 \\ 2 \end{bmatrix} \begin{bmatrix} 1 & 2 \end{bmatrix} = \begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix}$ $\text{rank} = 1$ non-invertible!

Ex: (for rank-nullity) A is 2×5 . What are the possible values of $\text{nullity}(A)$?

Sol: rank A can be $0, 1, 2 \Rightarrow \text{nullity}(A) = 5 - \text{rank}(A)$ can be 3, 4, 5.

Ex: find a basis for $S = \text{span}(\vec{u}, \vec{v}, \vec{w})$, $\vec{u} = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}$, $\vec{v} = \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix}$, $\vec{w} = \begin{bmatrix} -1 \\ 1 \\ 3 \\ 5 \end{bmatrix}$ (4)

Sol:

$$S = \text{col}(A),$$

$$A = \begin{bmatrix} 1 & 1 & -1 \\ 1 & 2 & 1 \\ 1 & 3 & 3 \\ 1 & 4 & 5 \\ \vec{u} & \vec{v} & \vec{w} \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & -1 \\ 0 & 1 & 2 \\ 0 & 2 & 4 \\ 0 & 3 & 6 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 1 & -1 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

pivots
REF

$\Rightarrow \{\vec{u}, \vec{v}\}$ - basis for S .
= pivot columns of A

Proof of Basis thm

Lemma Let $\vec{v}_1, \dots, \vec{v}_k$ be vectors in \mathbb{R}^n and $\vec{w}_1, \dots, \vec{w}_l$ a set of vectors in $\text{span}(\vec{v}_1, \dots, \vec{v}_k)$. Then, if $l > k$, the set $\vec{w}_1, \dots, \vec{w}_l$ is lin. dependent.

Γ We have $\vec{w}_i = \underbrace{a_{i1}\vec{v}_1 + \dots + a_{ik}\vec{v}_k}_{\text{some coefficients}}$, $i=1 \dots l$. Let $\vec{a}_i = \begin{bmatrix} a_{i1} \\ \vdots \\ a_{ik} \end{bmatrix}$.

Matrix $A = [\vec{a}_1, \dots, \vec{a}_l]$ has # columns $>$ # rows \Rightarrow columns of A are lin. dep.

$$\Rightarrow c_1 \vec{a}_1 + \dots + c_l \vec{a}_l = \vec{0} \quad \text{some lin. dep. rel.}$$

$$\Rightarrow c_1 \vec{w}_1 + \dots + c_l \vec{w}_l = \vec{0} \quad \text{- a lin. dep. rel. on } \vec{w}_i\text{'s}$$

Argument for basis theorem: Let $\mathcal{B} = \{\vec{v}_1, \dots, \vec{v}_k\}$, $\mathcal{C} = \{\vec{w}_1, \dots, \vec{w}_l\}$ two bases for S .

Assume $l > k$. Then by Lemma, \mathcal{C} is lin. dep. - contradiction!