

Ex:  $W = \left\{ \begin{bmatrix} a & b \\ -b & a \end{bmatrix} \right\} \subset M_{22}$  is a subspace

(1)

$$a \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + b \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \Rightarrow W = \text{span} \left( \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \right)$$

• We also interested in sets that span the entire  $V$ .

Ex: polynomials  $1, x, x^2$  span  $P_2$ , since each  $p(x) \in P_2$   
in  $P_2$   $= a_0 + a_1x + a_2x^2$   
is a lin. comb. of  $1, x, x^2$ .

Likewise,  $1, x, \dots, x^n$  span  $P_n$   
in  $P_n$

$$\underline{\text{Ex:}} \quad M_{22} = \text{span} \left( \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right)$$

$E_{11} \quad E_{12} \quad E_{21} \quad E_{22}$

$$\text{since } \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} = a_{11}E_{11} + a_{12}E_{12} + a_{21}E_{21} + a_{22}E_{22}$$

$$M_{mn} = \text{span} \{ E_{ij} \}_{\substack{i=1 \dots m \\ j=1 \dots n}}$$

$E_{ij}$  = matrix where  $(i,j)$ -entry is 1  
all other entries are 0.

Ex:  $V = \mathbb{R}^2$  with operations  $\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \oplus \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \begin{bmatrix} x_1 + y_1 + 1 \\ x_2 + y_2 \end{bmatrix}$ ,  
 $c \odot \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} cx_1 + c - 1 \\ cx_2 \end{bmatrix}$

zero-vector:  $\begin{bmatrix} -1 \\ 0 \end{bmatrix}$

negative:  $\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \rightarrow \begin{bmatrix} -x_1 - 1 \\ -x_2 \end{bmatrix}$

- a vector space!

• Does a vector belong to a given span? (2)

Ex: In  $P_2$ , is  $r(x) = 1 - 4x + 6x^2$  in  $\text{span}(\underbrace{1 - x + x^2}_{p(x)}, \underbrace{2 + x - 3x^2}_{q(x)})$ ?

Sol: We want scalars  $c, d$  s.t.

$$c p(x) + d q(x) = r(x)$$

$$\text{i.e. } (c + 2d) + (-c + d)x + (c - 3d)x^2 = 1 - 4x + 6x^2$$

$$\text{i.e. } \begin{cases} c + 2d = 1 \\ -c + d = -4 \\ c - 3d = 6 \end{cases}$$

$$-c + d = -4$$

$$c - 3d = 6$$

$$\Rightarrow \begin{cases} c = 3 \\ d = -1 \end{cases} \Rightarrow r(x) = 3p(x) - q(x)$$

Ex: Does the set  $\{p(x), q(x)\}$  span  $P_2$ ?

Sol: it spans  $P_2$  iff eq.  $c p(x) + d q(x) = f(x)$  is consistent for any  $f(x) = s + tx + ux^2 \in P_2$

$$c + 2d = s$$

$$-c + d = t$$

$$c - 3d = u$$

$$\left[ \begin{array}{cc|c} 1 & 2 & s \\ -1 & 1 & t \\ 1 & -3 & u \end{array} \right] \rightarrow \left[ \begin{array}{cc|c} 1 & 2 & s \\ 0 & 3 & s+t \\ 0 & 0 & 2s+5t+3u \end{array} \right]$$

REF

- only consistent when variables

$\Rightarrow \{p(x), q(x)\}$  does not span  $P_2$ .

< another way: coeff. mat. is  $3 \times 2$ , so cannot have a pivot in every row,

so  $A\vec{x} = \vec{b}$  cannot be consistent for every  $\vec{b}$  >

Ex: In  $\mathcal{F} = \{\text{functions on } \mathbb{R}\}$ , determine whether  $\sin 2x$  is in  $W = \text{span}(\sin x, \cos x)$

Sol: assume  $\sin 2x = c \sin x + d \cos x$  - then it should be true for all values of  $x$ .

$$x = 0 \Rightarrow 0 = 0 \cdot c + 1 \cdot d \Rightarrow d = 0$$

$$x = \frac{\pi}{2} \Rightarrow 0 = 1 \cdot c + 0 \cdot d \Rightarrow c = 0$$

$$\Rightarrow \sin 2x = 0 \cdot \sin x + 0 \cdot \cos x \text{ which is wrong} \\ \Rightarrow \text{contradiction}$$

$\Rightarrow \sin 2x \notin \text{span}(\sin x, \cos x)$

# Linear independence, basis, dimension (Poole 6.2)

(3)

def A set of vectors  $\{\vec{v}_1, \dots, \vec{v}_k\}$  in a vector space  $V$  is linearly dependent if there exist scalars  $c_1, \dots, c_k$  (not all zero) s.t.

$$c_1 \vec{v}_1 + \dots + c_k \vec{v}_k = \vec{0}.$$

Otherwise,  $\{\vec{v}_1, \dots, \vec{v}_k\}$  is lin. independent

• A set  $\{\vec{v}_1, \dots, \vec{v}_k\}$  iff some  $\vec{v}_j$  can be expressed as a lin. comb. of the others.

Ex:  $\{1, x+x^2, 2+x+x^2\}$  is lin. dep. in  $P_2$  ( $r = 2p+q$ )

Ex:  $\{\sin^2 x, \cos^2 x, \cos 2x\}$  is lin. dep. in  $F$  ( $h = g - f$ )

Ex: Is the set  $S = \{1+x, x+x^2, 1+x^2\}$  lin. indep. in  $P_2$ ?

Sol:  $c_1(1+x) + c_2(x+x^2) + c_3(1+x^2) = 0$

$$\begin{aligned} \Leftrightarrow \quad c_1 + c_3 &= 0 & c_1 &= 0 \\ c_1 + c_2 &= 0 & \Rightarrow c_2 &= 0 \\ c_2 + c_3 &= 0 & c_3 &= 0 \end{aligned} \Rightarrow \text{the set } S \text{ is lin. indep.}$$

Ex:  $\{1, x, \dots, x^n\}$  is a lin. indep. set in  $P_n$ .

Basis def A subset  $B \subset V$  is a basis for  $V$  if

(1)  $B$  spans  $V$

(2)  $B$  is lin. indep.

Ex:  $\{\vec{e}_1, \dots, \vec{e}_n\}$  - stand. basis for  $\mathbb{R}^n$

Ex:  $\{1, x, \dots, x^n\}$  - stand. basis for  $P_n$

Ex:  $\{E_{11}, \dots, E_{1n}, E_{21}, \dots, E_{2n}, \dots, E_{m1}, \dots, E_{mn}\}$  - stand. basis for  $M_{mn}$

Ex:  $\mathcal{B} = \{1+x, x+x^2, 1+x^2\}$  is a basis for  $P_2$   
 $\underbrace{\qquad\qquad\qquad}_{P_1(x)} \quad \underbrace{\qquad\qquad\qquad}_{P_2(x)} \quad \underbrace{\qquad\qquad\qquad}_{P_3(x)}$

- we already know that it is lin. indep. Does it span  $P_2$ ?

$$c_1 p_1(x) + c_2 p_2(x) + c_3 p_3(x) = \underbrace{a+bx+cx^2}_{\text{arbitrary element of } P_2}$$

$$\Leftrightarrow \begin{cases} c_1 + c_3 = a \\ c_1 + c_2 = b \\ c_2 + c_3 = c \end{cases}$$

$$\begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} = \begin{bmatrix} a \\ b \\ c \end{bmatrix}$$

has rank 3  $\Rightarrow$  invertible  
 $\Rightarrow$  sys. is consistent for any  $a, b, c$

$\Rightarrow \mathcal{B}$  spans  $P_2 \Rightarrow \mathcal{B}$  is a basis for  $P_2$ .

Ex:  $W = \left\{ \underbrace{\begin{bmatrix} a & b \\ -b & a \end{bmatrix}}_{a \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + b \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}} \mid a, b \in \mathbb{R} \right\} \subset M_{22}$  has a basis

$$\mathcal{B} = \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \right\}$$

Dimension

Basis theorem: If a vector space  $V$  has a basis of  $n$  vectors, then every basis for  $V$  has exactly  $n$  vectors.

- A v. sp.  $V$  is called finite-dimensional if it has a basis consisting of finitely many vectors. Dimension of  $V$  ( $\dim V$ ) is the number of vectors in a basis for  $V$ .
- $\dim \{\vec{0}\} = 0$  (convention)
- A v. sp. that has no finite basis is called infinite-dimensional.

Ex:  $\mathbb{R}^n$  has a basis  $\{\vec{e}_1, \dots, \vec{e}_n\} \Rightarrow \dim \mathbb{R}^n = n$

Ex:  $P_n$  has a basis  $\{1, x, \dots, x^n\} \Rightarrow \dim P_n = n+1$

Ex:  $M_{mn}$  has a basis  $\{E_{ij}\}_{\substack{1 \leq i \leq m \\ 1 \leq j \leq n}} \Rightarrow \dim M_{mn} = mn$

Ex:  $\mathbb{P}$  and  $\mathbb{F}$  are  $\infty$ -dimensional (each contains an infinite lin. dep. set  $1, x, x^2, \dots$ )