# Lecture 8: Fast Linear Solvers (Part 2)

## Naive Parallel Backward Substitution Algorithm

After elimination, we obtain upper triangular  $Ux = b^{(n-1)}$ . Assume that U is stored by rows.

$$x_n = \frac{b_n^{(n-1)}}{u_{nn}}$$
 for  $i = n - 1$  to  $1$  
$$x_i = \frac{b_i^{(n-1)} - u_{i,i+1}x_{i+1} - u_{i,i+2}x_{i+2} - \dots - u_{i,n}x_n}{u_{ii}}$$

```
for k=n to 1 x_k=b_k for i=k+1 to n x_k=x_k-u_{ki}x_i end; x_k=x_k/u_{kk} broadcast x_k to all rows end;
```

#### Naive Parallel Forward Substitution Algorithm

Consider to solve lower triangular Lx = b.

for 
$$i = 1$$
 to  $n$ 

$$x_i = \frac{b_i - \sum_{j=1}^{i-1} l_{ij} x_j}{l_{ii}}$$

```
\begin{aligned} &\text{for } i = 1 \text{ to } n \\ &\text{for } j = 1 \text{ to } i - 1 \\ &b_i = b_i - l_{ij} x_j \\ &\text{end;} \\ &x_i = b_i / l_{ii} \\ &\text{broadcast } x_i \text{ to all rows} \\ &\text{end;} \end{aligned}
```

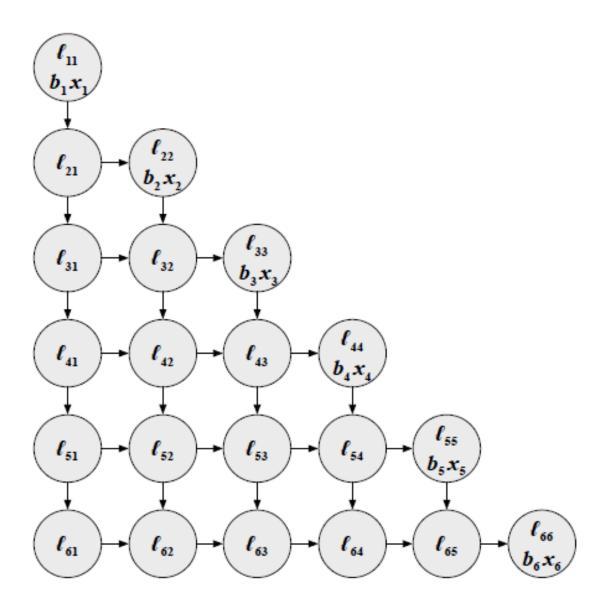
### **Revised Forward Substitution Algorithm**

```
// immediate-update of right hand side
for j = 1 to n
  x_i = b_i/l_{ii} // compute solution
  for i = j + 1 to n
    b_i = b_i - l_{ij}x_j //update right hand side
  end;
end;
```

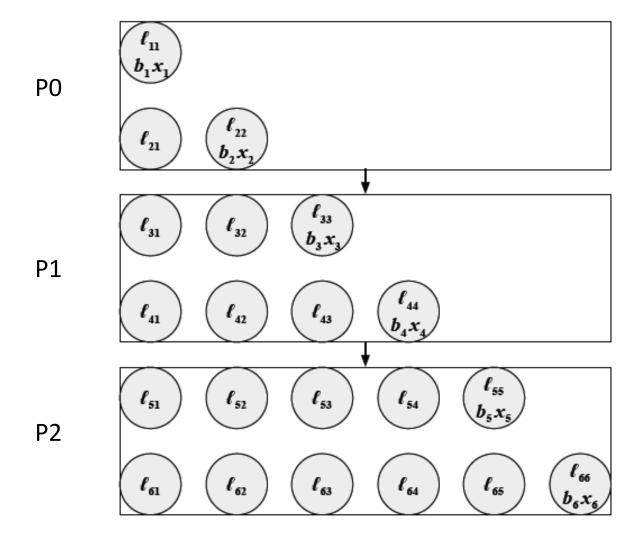
## Parallel Forward Substitution Algorithm

- Assume a fine-grained decomposition in which process  $p_{ij}$  stores  $l_{ij}$  and compute  $l_{ij}x_j$  for  $i=2,\ldots,n,j=1,\ldots,i-1$
- Assume  $p_{ii}$  stores  $l_{ii}$  and  $b_i$ , collects  $\sum_{j=1}^{i-1} l_{ij} x_j$  and computes  $x_i = \frac{b_i \sum_{j=1}^{i-1} l_{ij} x_j}{l_{ii}}$  for  $i=1,\ldots,n$

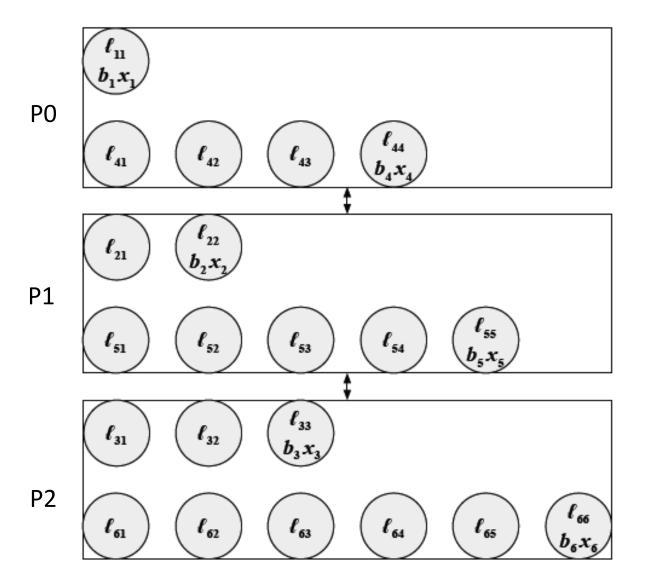
## **Primary Tasks and Communication**



## 1D Row Block Mapping



# 1D Row Cyclic Mapping



# Forward Substitution Parallel Algorithm Based on 1D Row Mapping

```
// immediate-update of right hand side
for j = 1 to n
  for process holding jth row
  x_i = b_i/l_{ii} // compute solution
  end;
  broadcast x_i to all processes
  for process holding ith row i > j
    b_i = b_i - l_{ij}x_i //update right hand side
  end;
end;
```

#### References

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### Gaussian Elimination and Sparse System

Consider to solve the tridiagonal system

```
a_ix_{i-1}+b_ix_i+c_ix_{i+1}=F_i, \qquad i=1,\dots,n for unknowns x_1,\dots,x_i,\dots,x_n (So x_0=x_{n+1}=0). Here a_i,b_i,c_i, and F_i are given.
```

Let m be the band width.

```
for k=1 to n-1
                                    // loop over columns
  for i = k + 1 to min(k + m, n)
    l_{ik} = a_{ik}/a_{ii}
                                    // multipliers for kth column
    b_i = b_i - l_{ik}b_k
  end;
  for j = k + 1 to min(k + m, n)
    for i = k + 1 to min(k + m, n)
       a_{ij} = a_{ij} - l_{ik} a_{ki}
                           // elimination step
    end;
   end;
end;
```

## Parallel Cyclic Reduction for Tridiagonal System

- When m < p, neither row-cyclic nor column-cyclic decomposition is efficient. Because only m processors are actively used.
- Assume that  $n=2^p-1$ , where p is the number of processors. If  $n \neq 2^p-1$ , then add a trivial equation  $x_i=0, i=n+1, ..., 2^p-1$ .

- Consider the case when  $n = 7 = 2^3 1$ .
- Key idea:
  - Combine linearly equations to eliminate the oddnumbered unknowns  $x_1, x_3, x_5, ...$  in the first stage.
    - Adding a multiple of (i-1)th equation and a multiple of (i+1)th equation to ith equation to eliminate  $x_{i-1}$  and  $x_{i+1}$  from the ith equation for i=2,4,...
  - Then renumber unknowns and repeat this process till there is a single equation with one unknown.
  - Solve backward to obtain the rest of the unknowns.

Remark: Cyclic Reduction is a divide-and-conquer method

• Multiply parameters  $\alpha_2$ ,  $\beta_2$ ,  $\gamma_2$  to the first three equations respectively to get:

$$\alpha_2 b_1 x_1 + \alpha_2 c_1 x_2 = \alpha_2 F_1$$

$$\beta_2 a_2 x_1 + \beta_2 b_2 x_2 + \beta_2 c_2 x_3 = \beta_2 F_2$$

$$\gamma_2 a_3 x_2 + \gamma_2 b_3 x_3 + \gamma_2 c_3 x_4 = \gamma_2 F_3$$

To eliminate  $x_1$  and  $x_3$ , add above three equations and let

$$\beta_{2} = 1$$

$$\alpha_{2}b_{1} + \beta_{2}a_{2} = 0$$

$$\beta_{2}c_{2} + \gamma_{2}b_{3} = 0$$

$$\Rightarrow \hat{b}_{2}x_{2} + \hat{c}_{2}x_{4} = \hat{F}_{2}$$

Where

$$\hat{b}_{2} = \alpha_{2}c_{1} + \beta_{2}b_{2} + \gamma_{2}a_{3}$$

$$\hat{c}_{2} = \gamma_{2}c_{3}$$

$$\hat{F}_{2} = \alpha_{2}F_{1} + \beta_{2}F_{2} + \gamma_{2}F_{3}$$

• Multiply parameters  $\alpha_4$ ,  $\beta_4$ ,  $\gamma_4$  to the third, fourth and fifth equations respectively and add to eliminate  $x_3$  and  $x_5$ :

$$\Rightarrow \hat{a}_4 x_2 + \hat{b}_4 x_4 + \hat{c}_4 x_6 = \hat{F}_4$$

Where

$$\hat{a}_{4} = \alpha_{4}a_{3}$$

$$\hat{b}_{4} = \alpha_{4}c_{3} + \beta_{4}b_{4} + \gamma_{4}a_{5}$$

$$\hat{c}_{4} = \gamma_{4}c_{5}$$

$$\hat{F}_{4} = \alpha_{4}F_{3} + \beta_{4}F_{4} + \gamma_{4}F_{5}$$

 $\alpha_4$ ,  $\beta_4$ ,  $\gamma_4$  are determined by :

$$\beta_4 = 1$$
 $\alpha_4 b_3 + \beta_4 a_4 = 0$ 
 $\beta_4 c_4 + \gamma_4 b_5 = 0$ 

• Finally, multiply parameters  $\alpha_6$ ,  $\beta_6$ ,  $\gamma_6$  to the fifth, sixth and seventh equations respectively and add to eliminate  $x_5$  and  $x_7$ :

$$\Rightarrow \hat{a}_6 x_4 + \hat{b}_6 x_6 = \hat{F}_6$$

Where

 $\alpha_6$ ,  $\beta_6$ ,  $\gamma_6$  are determined by :

$$\beta_6 = 1$$
 $\alpha_6 b_5 + \beta_6 a_6 = 0$ 
 $\beta_6 c_6 + \gamma_6 b_7 = 0$ 

In stage two:

$$\hat{b}_{2}x_{2} + \hat{c}_{2}x_{4} = \hat{F}_{2}$$

$$\hat{a}_{4}x_{2} + \hat{b}_{4}x_{4} + \hat{c}_{4}x_{6} = \hat{F}_{4}$$

$$\hat{a}_{6}x_{4} + \hat{b}_{6}x_{6} = \hat{F}_{6}$$

 Repeat the same elimination process, which leads to only one equation

$$\alpha_4^* x_4 = F_4^*$$

- Use backward substitution,  $x_2$  and  $x_6$  are solved by  $\hat{b}_2x_2+\hat{c}_2x_4=\hat{F}_2$  and  $\hat{a}_6x_4+\hat{b}_6x_6=\hat{F}_6$
- Use the original equations to solve for  $x_1, x_3, x_5, x_7$ .

### Cyclic Reduction Algorithm

```
for(i=0; i < log_2(size+1)-1;i++) // levels of reduction
  for(j=2^{i+1}-1; j < size; j=j+2^{i+1}) // rows that are reduced
      offset = 2^{i}:
       index1 = j - offset; // index of row before the jth row
       index2 = j + offset; // index of row after the jth row
       \alpha = A[i][index1]/A[index1][index1];
      \gamma = A[j][index2]/A[index2][index2];
      for(k=0; k < size; k++)
          A[j][k] = \alpha A[index1][k] + \gamma A[index2][k]; // do the reduction to have only
                                                         // jth row being active
       F[j] = \alpha F[index1] + \gamma F[index2];
```

#### **Backward Substitution**

```
int index = (size-1)/2;
x[index] = F[index]/A[index][index];
for(i=log_2(size+1)+2;i>=0;i--)
   for(j=2^{i+1}-1; j <size; j=j+2^{i+1})
      offset = 2^{i};
      index1 = j - offset;
      index2 = j + offset;
       x[index1] = F[index1];
       x[index2] = F[index2];
      for(k=0; k < size; k++)
         if(k! = index1)
            x[index1] -= A[index1]*x[k];
         if(k != index2)
            x[index2] = A[index2][k]*x[k];
      x[index1] = x[index1]/A[index1][index1];
      x[index2] = x[index2]/A[index2][index2];
```

#### Source of Parallelism

- Simultaneous reduction of equations in the system
- Simultaneous backward substitution to solve for the solution

#### **Row Decomposition**

For i = 1, ..., n of equations

Process *i* stores *ith* equation.

### Computation

when modulus(i, 2) = 0, do row reduction to yield updated ith equation

#### Communication

ith equation receive (i-1)th and (i+1)th equations for modulus(i,2)=0

#### Reference

- B. Buzbbe, G. Golub, and C. Nielsen.
   On direct methods for solving Poisson's equation. SIAM *J. Numer. Anal.*, 7:627-656, 1970
- J. Dongarra and S. Johnsson. Solving banded systems on a parallel processor, Parallel Computing 5:219-246, 1987
- M. Hegland. On the parallel solution of tridiagonal systems by wrap-around partitioning and incomplete LU factorization, Numer. Math. 59:453-472, 1991
- V. Mehrmann. Divide and conquer methods for block tridiagonal systems, Parallel Computing 19:257-280, 1993