

1. (3 points) Use undetermined coefficients to find a particular solution of the system  $\mathbf{x}' = A\mathbf{x} + \mathbf{f}$ , where

$$A = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}, \quad \mathbf{f} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}.$$

*Solution.* Since 0 is an eigenvalue of  $A$ , we cannot hope to find a particular solution  $\mathbf{x}_p = \mathbf{a}$ , i.e. a constant vector. We look for a particular solution of the form  $\mathbf{x}_p = \mathbf{a} + t\mathbf{b}$ . We get  $\mathbf{x}'_p = \mathbf{b}$ , so the equation  $\mathbf{x}'_p = A\mathbf{x}_p + \mathbf{f}$  becomes  $\mathbf{b} = A(\mathbf{a} + t\mathbf{b}) + \mathbf{f}$ , i.e.  $\mathbf{b} = A\mathbf{a} + \mathbf{f}$  and  $A\mathbf{b} = 0$ . Substituting  $\mathbf{b}$  in the second equation yields

$$A \cdot (A\mathbf{a} + \mathbf{f}) = 0.$$

If we write  $\mathbf{a} = \begin{bmatrix} a_1 \\ a_2 \end{bmatrix}$ , we get, using the fact that  $A^2 = A$ , that  $A\mathbf{a} = \begin{bmatrix} 0 \\ -1 \end{bmatrix}$ , i.e.  $a_2 = -1$  and  $a_1$  is arbitrary. We take  $a_1 = 0$  and compute  $\mathbf{b}$  using the formula  $\mathbf{b} = A\mathbf{a} + \mathbf{f}$ . This yields  $\mathbf{b} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ , so that a particular solution for  $\mathbf{x}' = A\mathbf{x} + \mathbf{f}$  is given by

$$\mathbf{x}_p = \begin{bmatrix} 0 \\ -1 \end{bmatrix} + t \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} t \\ -1 \end{bmatrix}.$$

□

2. (3 points) Use variation of parameters to find a general solution of the system  $\mathbf{x}' = A\mathbf{x} + \mathbf{f}$ , where

$$A = \begin{bmatrix} 2 & 1 \\ -3 & -2 \end{bmatrix}, \quad \mathbf{f} = \begin{bmatrix} 2e^t \\ 4e^t \end{bmatrix}.$$

Bonus (1 point): What is  $e^{At}$ ?

*Solution.* The eigenvalues of  $A = \begin{bmatrix} 2 & 1 \\ -3 & -2 \end{bmatrix}$  are  $\lambda_1 = -1$ ,  $\lambda_2 = 1$ , with corresponding eigenvectors  $u_1 = \begin{bmatrix} -1 \\ 3 \end{bmatrix}$ ,  $u_2 = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$ . A fundamental matrix is therefore

$$X(t) = \begin{bmatrix} -e^{-t} & -e^t \\ 3e^{-t} & e^t \end{bmatrix}, \quad \text{with } X^{-1}(t) = \frac{1}{2} \begin{bmatrix} e^t & e^t \\ -3e^{-t} & -e^{-t} \end{bmatrix}.$$

We get

$$X^{-1}(t) \cdot \mathbf{f}(t) = \begin{bmatrix} 3e^{2t} \\ -5 \end{bmatrix},$$

thus

$$\int X^{-1}(t) \cdot \mathbf{f}(t) dt = \begin{bmatrix} 3e^{2t}/2 \\ -5t \end{bmatrix},$$

and

$$X(t) \int X^{-1}(t) \cdot f(t) dt = \begin{bmatrix} -3e^t/2 + 5te^t \\ 9e^t/2 - 5te^t \end{bmatrix}.$$

It follows that the general solution is given by

$$c_1 \begin{bmatrix} -e^{-t} \\ 3e^{-t} \end{bmatrix} + c_2 \begin{bmatrix} -e^t \\ e^t \end{bmatrix} + \begin{bmatrix} -3e^t/2 + 5te^t \\ 9e^t/2 - 5te^t \end{bmatrix}.$$

Bonus:

$$e^{At} = X(t) \cdot X^{-1}(0) = \begin{bmatrix} -e^{-t} & -e^t \\ 3e^{-t} & e^t \end{bmatrix} \cdot \frac{1}{2} \begin{bmatrix} 1 & 1 \\ -3 & -1 \end{bmatrix} = \frac{1}{2} \cdot \begin{bmatrix} 3e^t - e^{-t} & e^t - e^{-t} \\ 3(e^{-t} - e^t) & 3e^{-t} - e^t \end{bmatrix}.$$

□