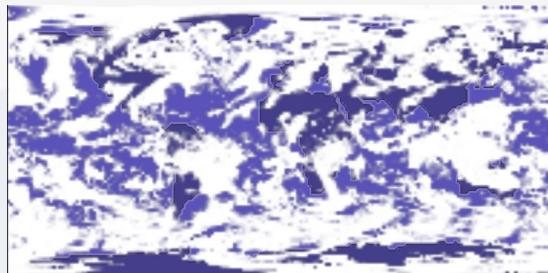




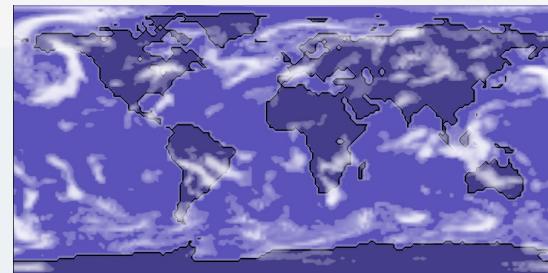
Information-theoretic Methods for the Visual Analysis of Climate and Flow Data

Heike Jänicke – Swansea University, UK

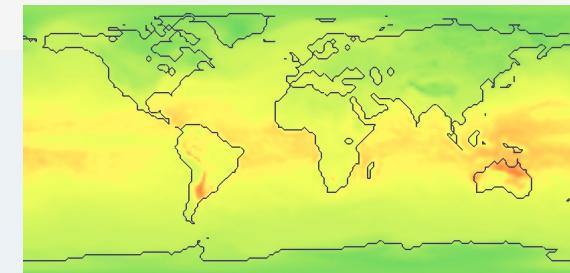
Weather simulation



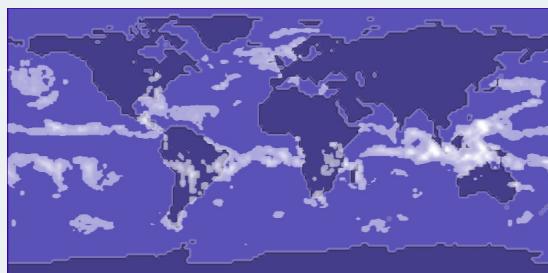
Cloud cover



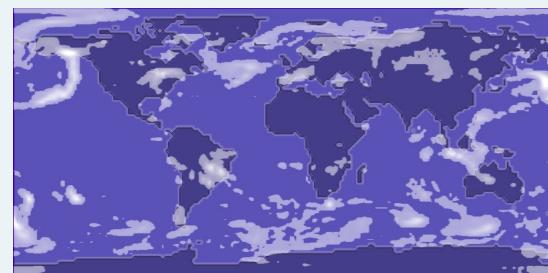
Cloud ice



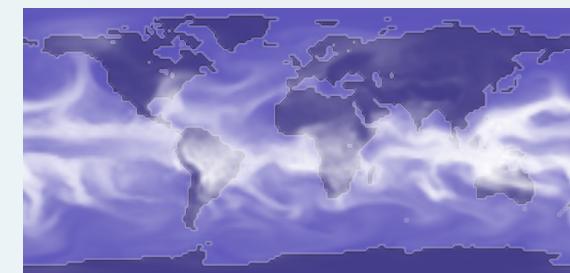
2m temperature



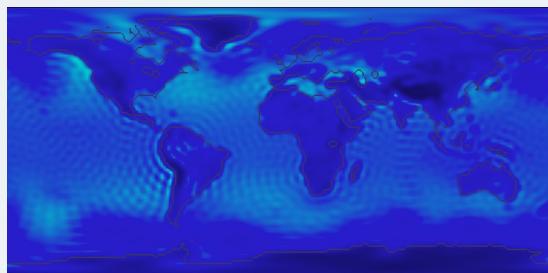
Convective precipitation



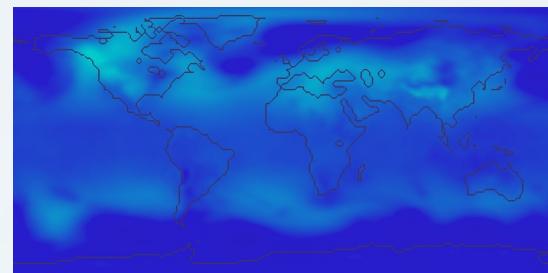
Precipitation



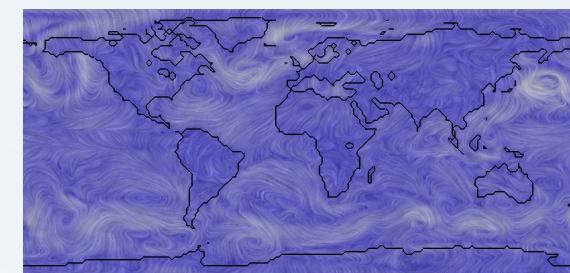
Evaporation



Surface pressure
 VisWeek 09
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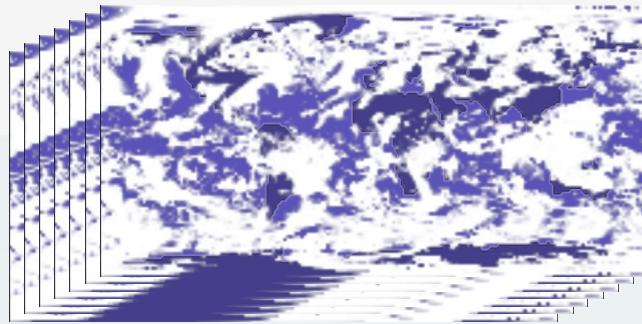


0m pressure

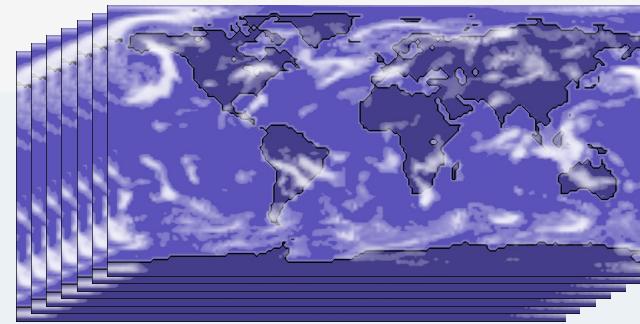


Wind

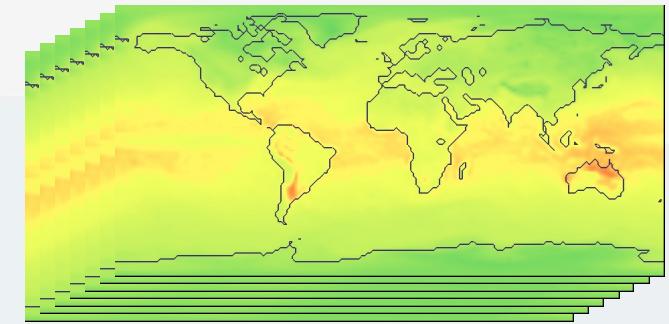
Weather simulation



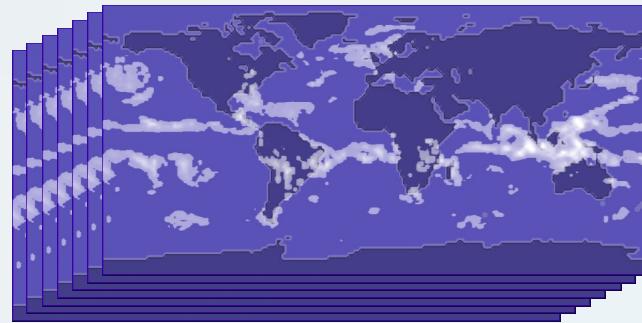
Cloud cover



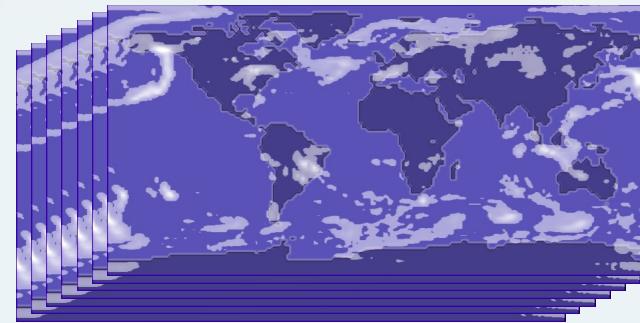
Cloud ice



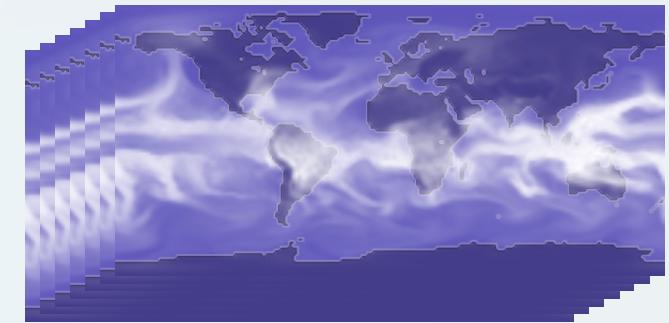
2m temperature



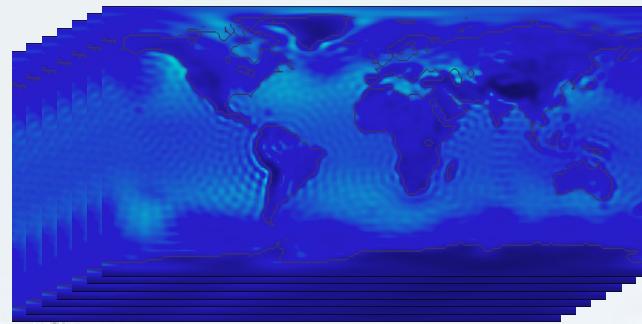
Convective precipitation



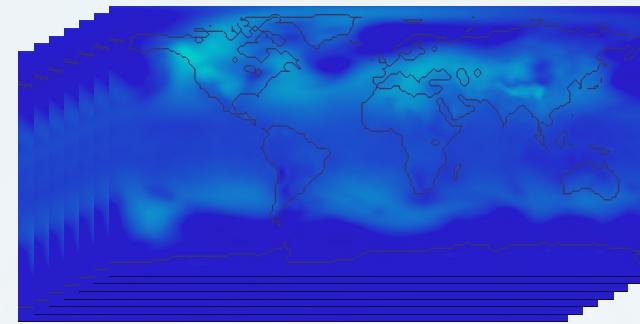
Precipitation



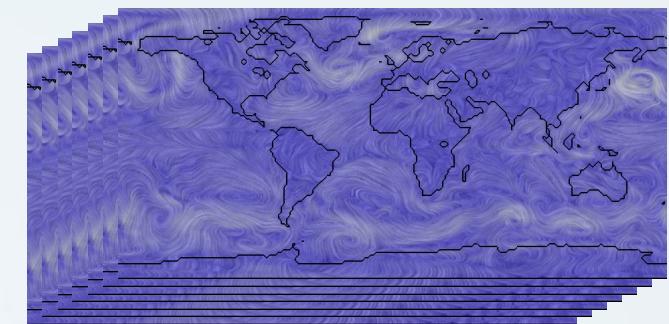
Evaporation



Surface pressure



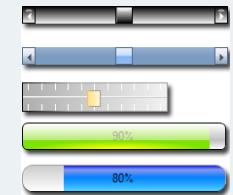
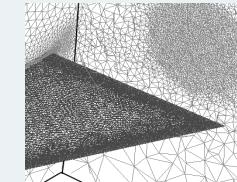
0m pressure



Wind

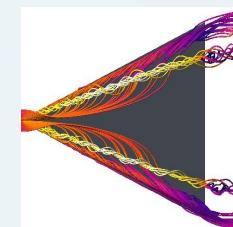
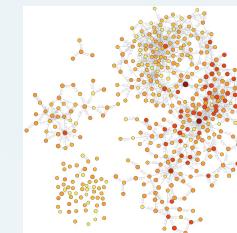
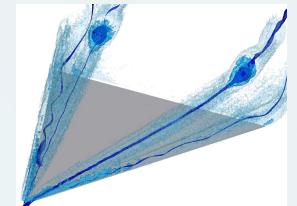
Outline

- Data representation
- Related work
- Information Theory
- Local Statistical Complexity
- Epsilon-machines
- Eulerian/ Lagrangian flow
- Conclusion/ future directions



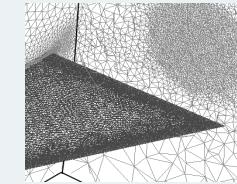
$$I(X;Y)$$

$$H(X) H(Y)$$

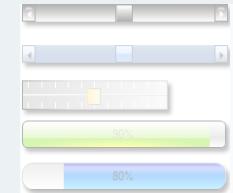


Outline

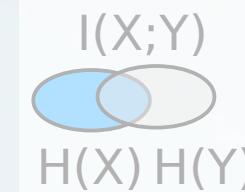
- Data representation



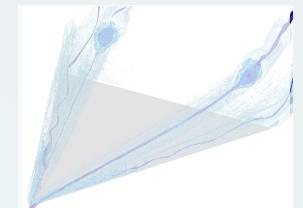
- Related work



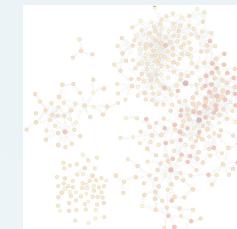
- Information Theory



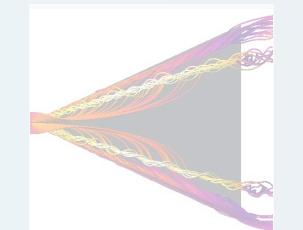
- Local Statistical Complexity



- Epsilon-machines



- Eulerian/ Lagrangian flow

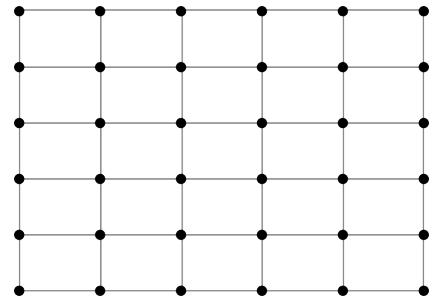
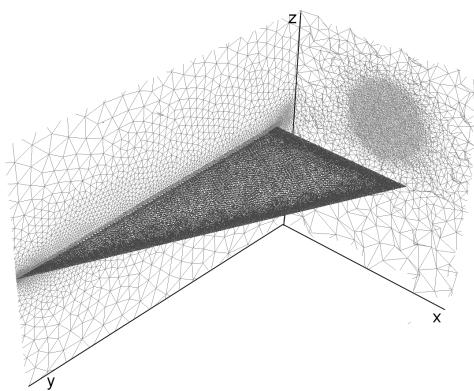


- Conclusion/ future directions



Computational Fluid Dynamics

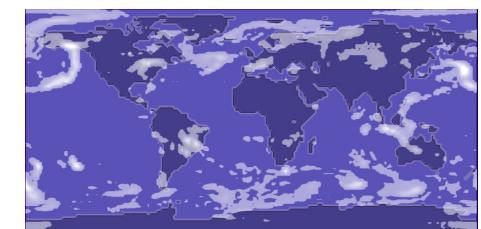
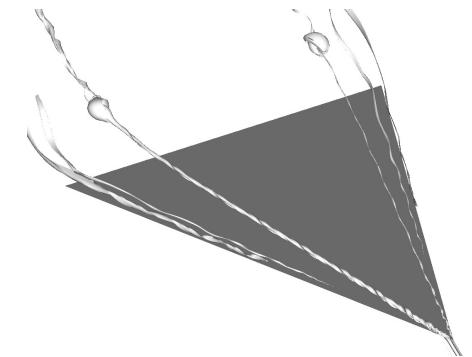
Preprocessing



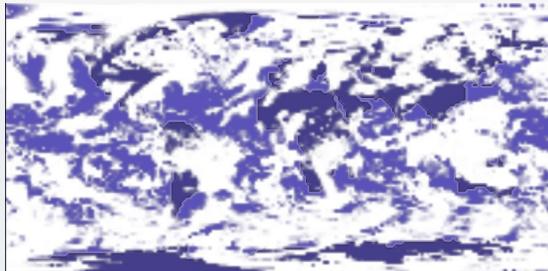
Problem solving



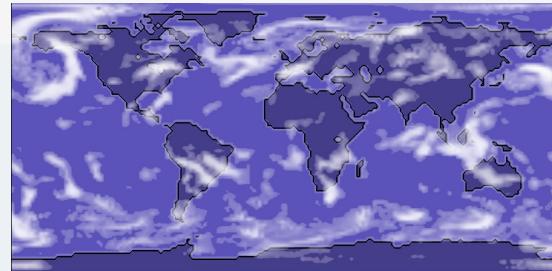
Postprocessing



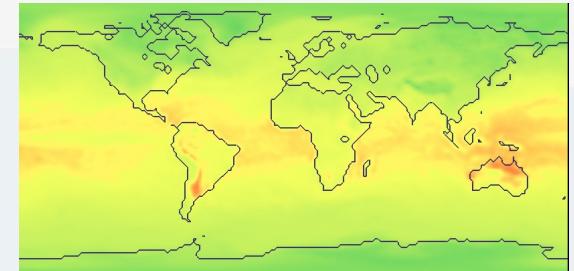
Data Sets – Weather Simulation



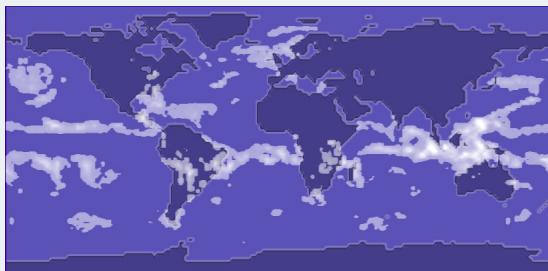
Cloud cover



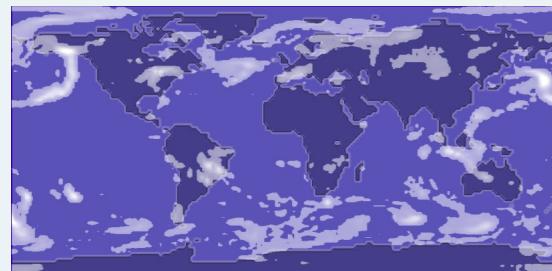
Cloud ice



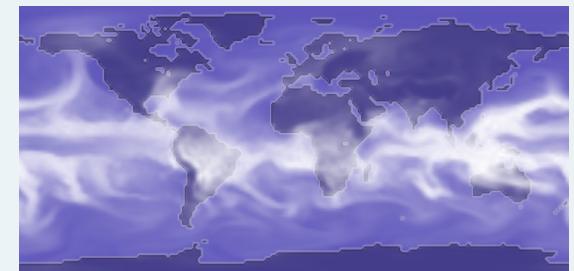
2m temperature



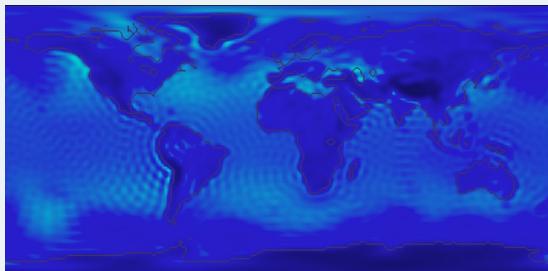
Convective precipitation



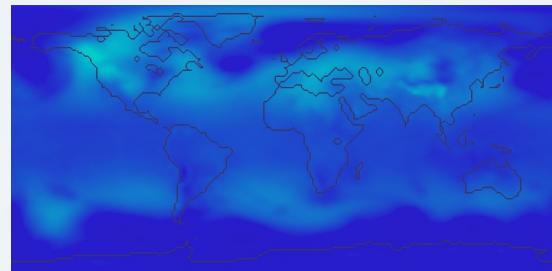
Precipitation



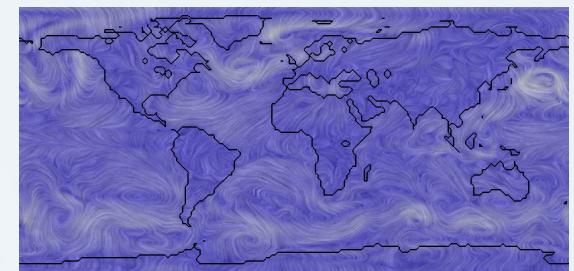
Evaporation



Surface pressure
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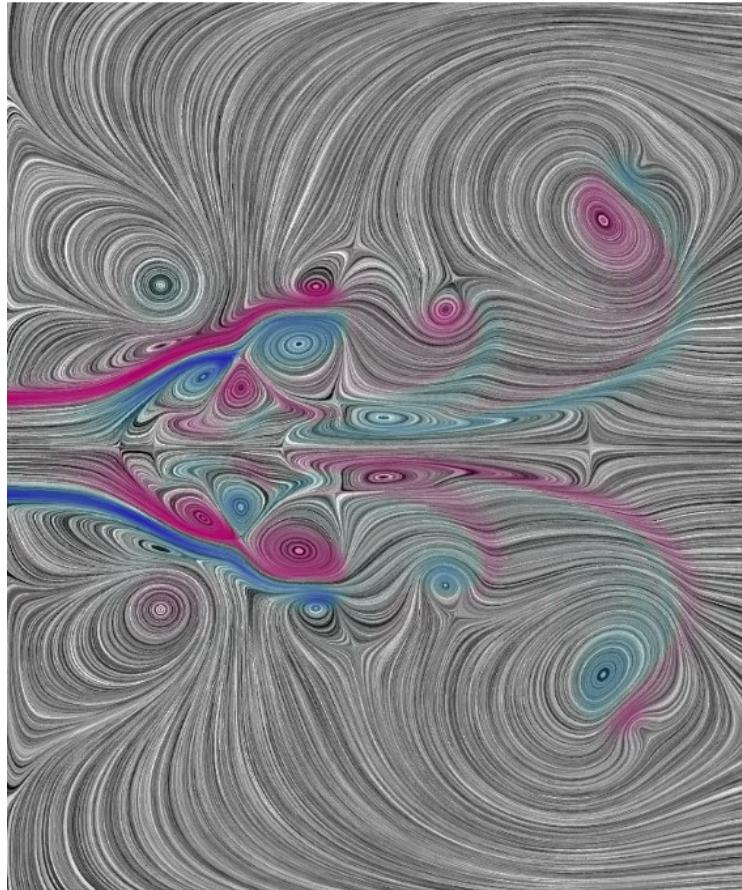


0m pressure



Wind

Data Sets – Flow Simulation I



Swirling flow
[Wolfgang Kollmann, UC Davis]

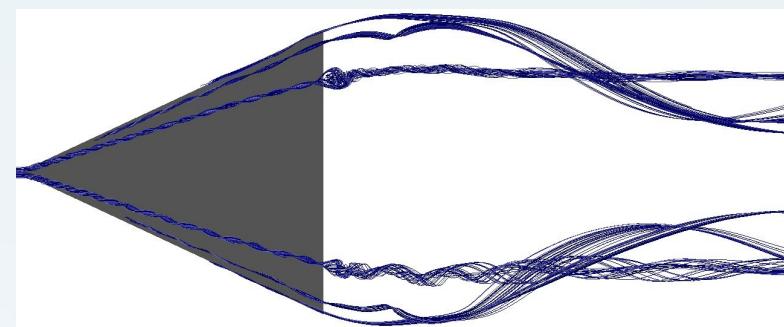
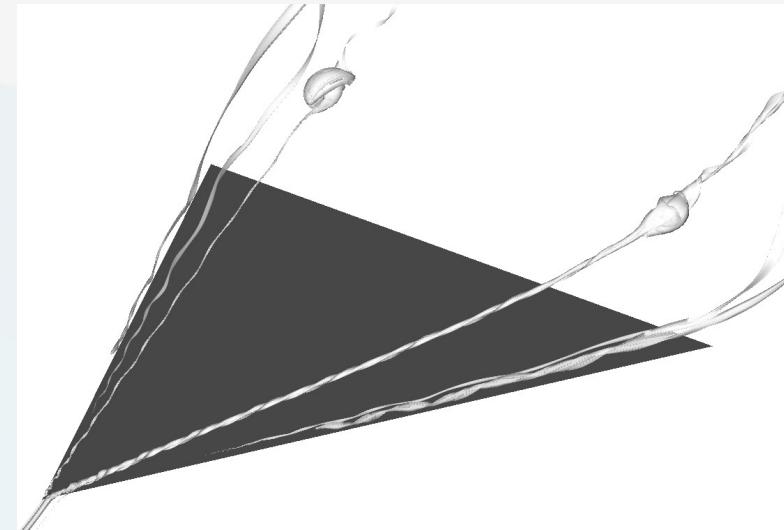


Flow around an obstacle
[NaSt2D/NaSt3D, Universität Bonn]

Data Sets – Flow Simulation II



Francis draft tube
[Ronny Peikert, ETH Zürich;
VA Tech Hydro]

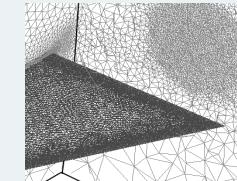


Delta wing
[Markus Rütten, DLR]

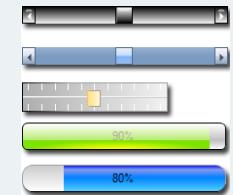


Outline

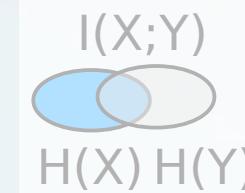
- Data representation



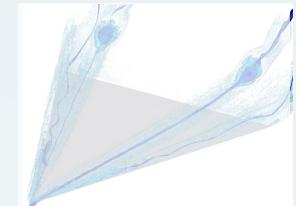
- Related work



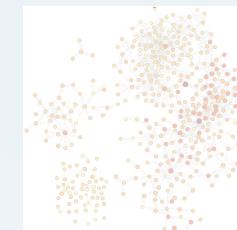
- Information Theory



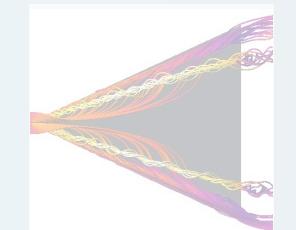
- Local Statistical Complexity



- Epsilon-machines



- Eulerian/ Lagrangian flow



- Conclusion/ future directions

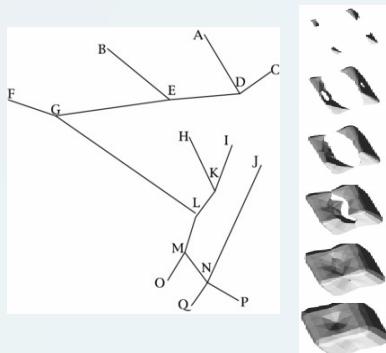


Related Work

Time-dependent data

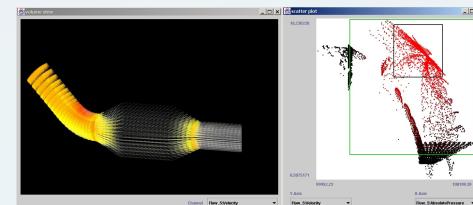


movie

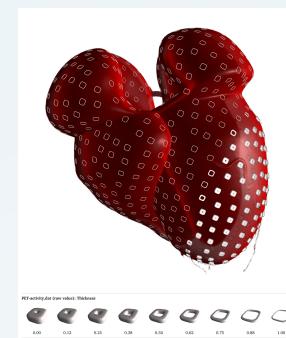


contour tree

Multivariate data

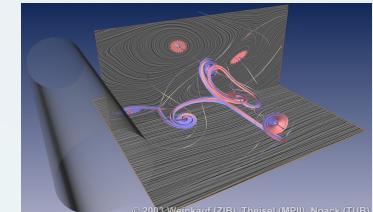


linking and brushing



glyphs

Feature extraction



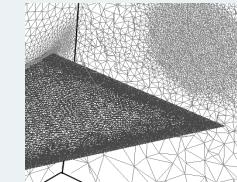
topology



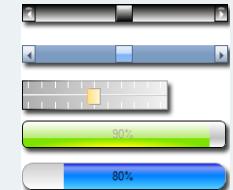
mathematical def.

Outline

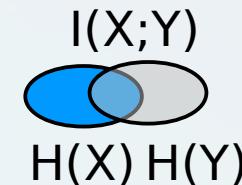
- Data representation



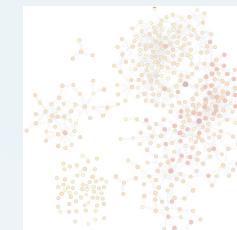
- Related work



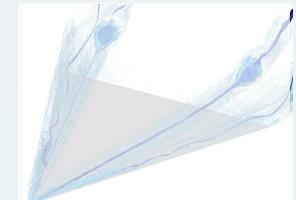
- Information Theory



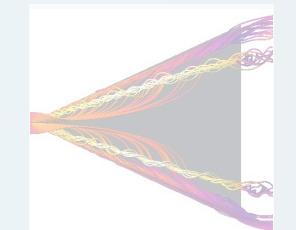
- Local Statistical Complexity



- Epsilon-machines



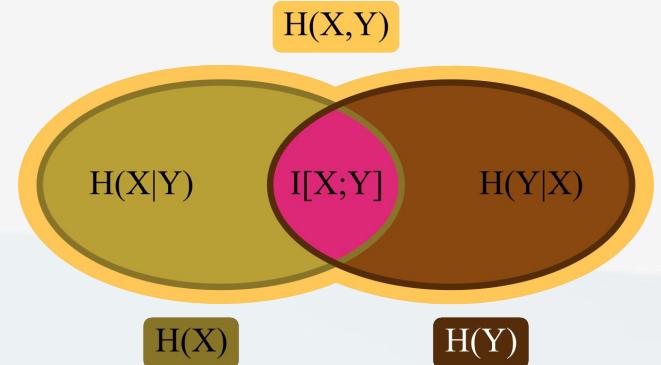
- Eulerian/ Lagrangian flow



- Conclusion/ future directions



Information Theory



- **Entropy** (uncertainty in X)

$$H(X) = - \sum_{x \in X} p(x) \log_2 p(x)$$

- **Conditional entropy** (Remaining uncertainty in X when Y is known)

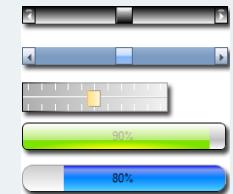
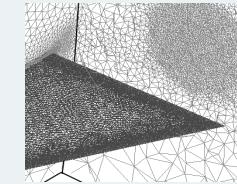
$$H(X|Y) = - \sum_{y \in Y} \sum_{x \in X} p(x, y) \log_2 p(y|x)$$

- **Mutual information** (Information X contains about Y and vice versa)

$$\begin{aligned} I(X;Y) &= H(X) - H(X|Y) \\ &= H(Y) - H(Y|X) = I(Y;X) \end{aligned}$$

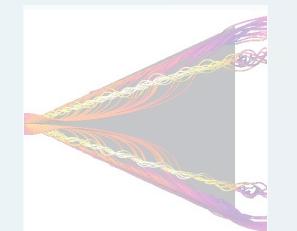
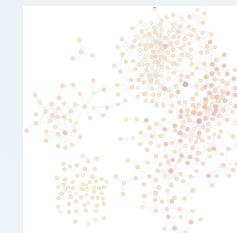
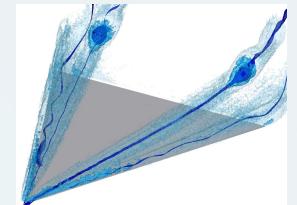
Outline

- Data representation
- Related work
- Information Theory
- Local Statistical Complexity
- Epsilon-machines
- Eulerian/ Lagrangian flow
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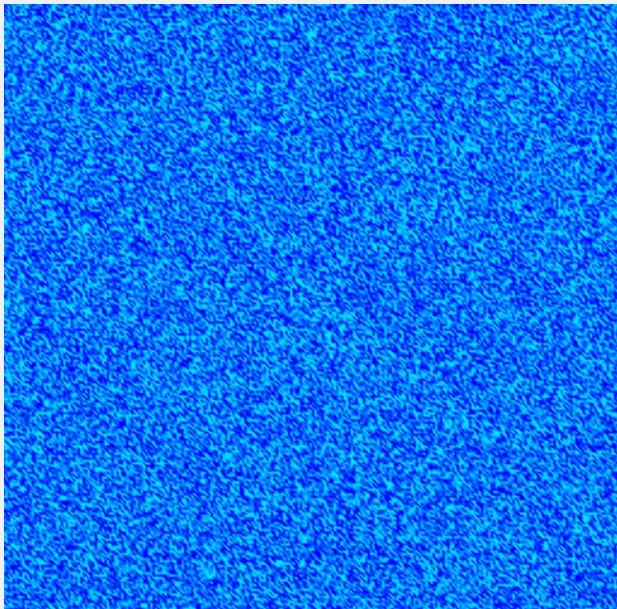
$$I(X;Y)$$

$$H(X) H(Y)$$

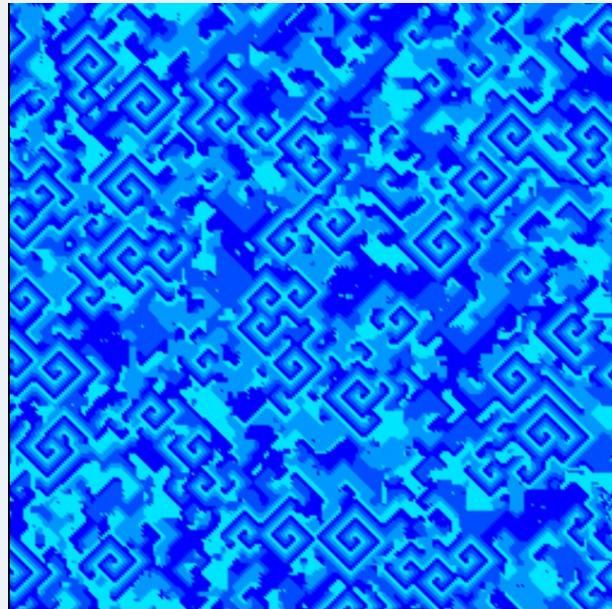


Cellular Automaton

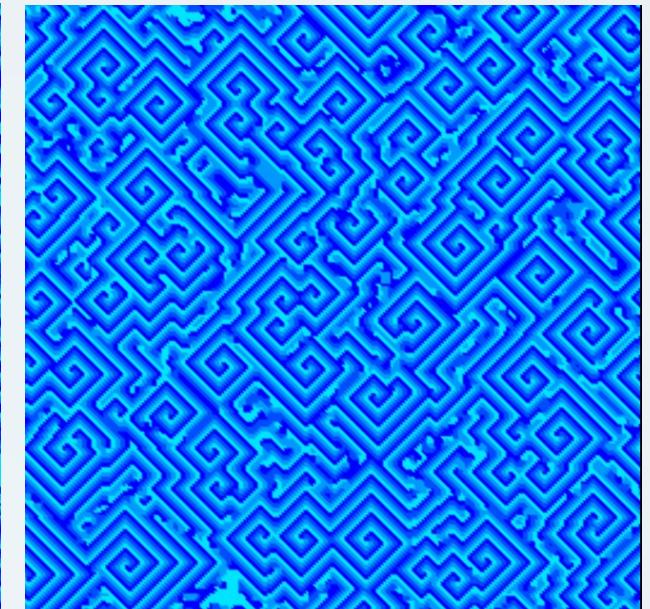
- Rule: cyclic cellular automaton (CCA) forming spirals



$t = 0$



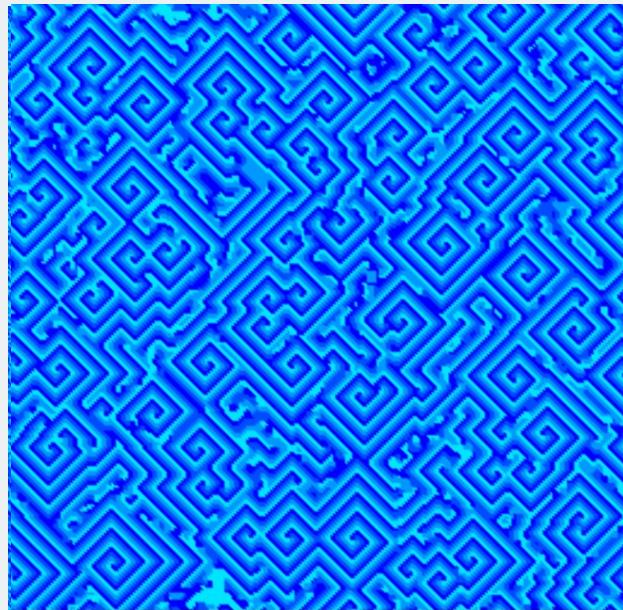
$t = 40$



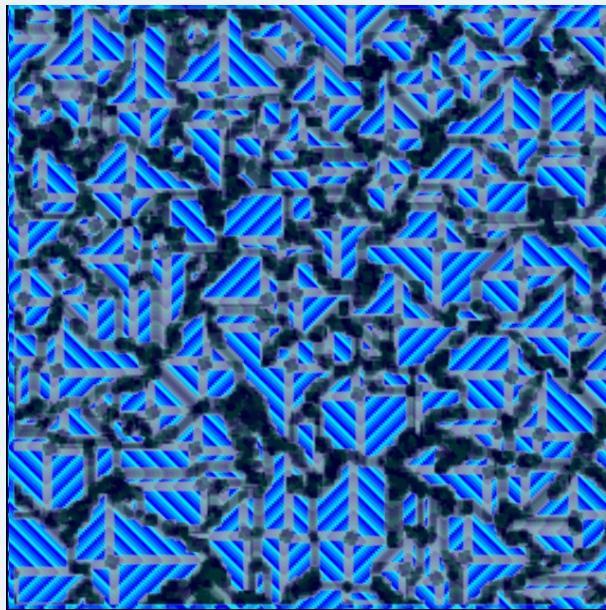
$t = 99$

Cellular Automaton

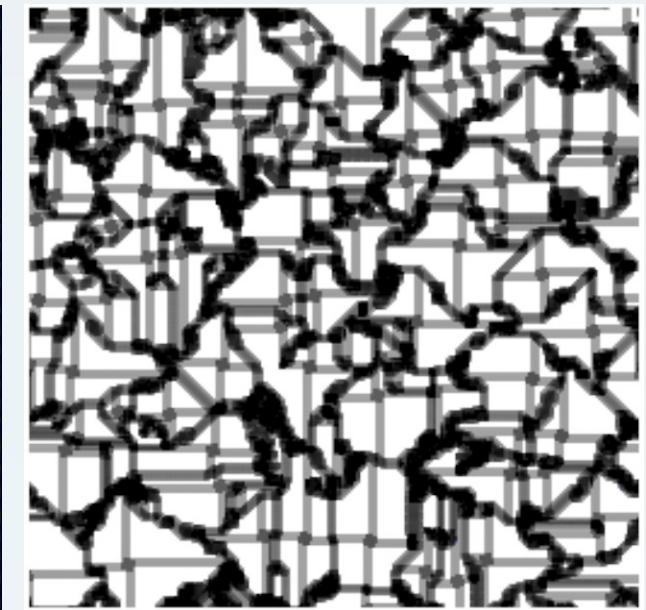
- Rule: cyclic cellular automaton (CCA) forming spirals



$t = 99$



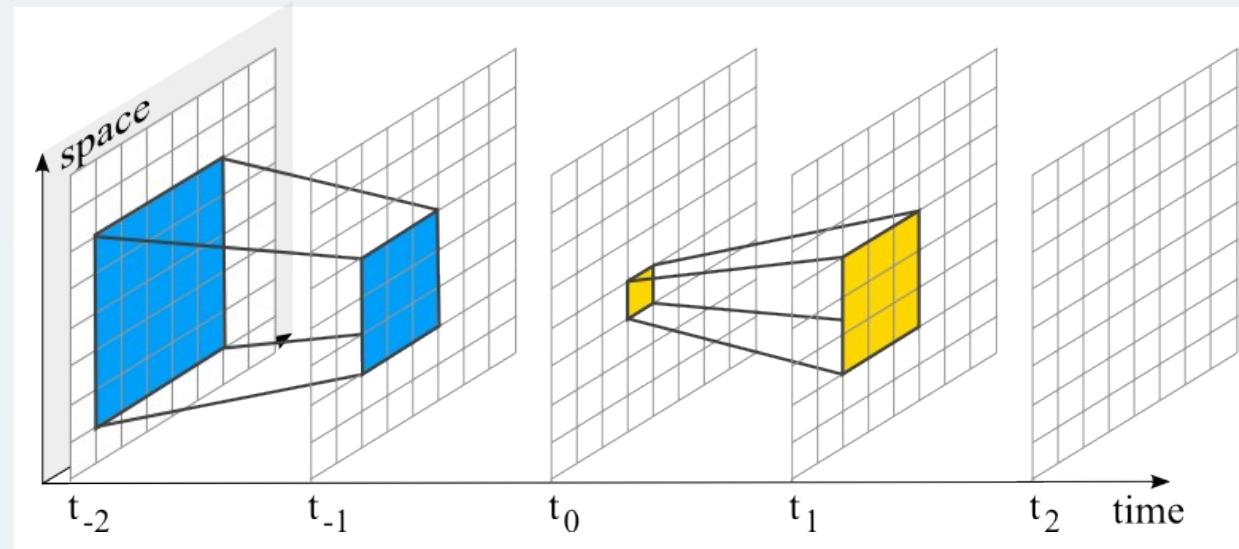
$t = 99 + \text{filter}$



filter

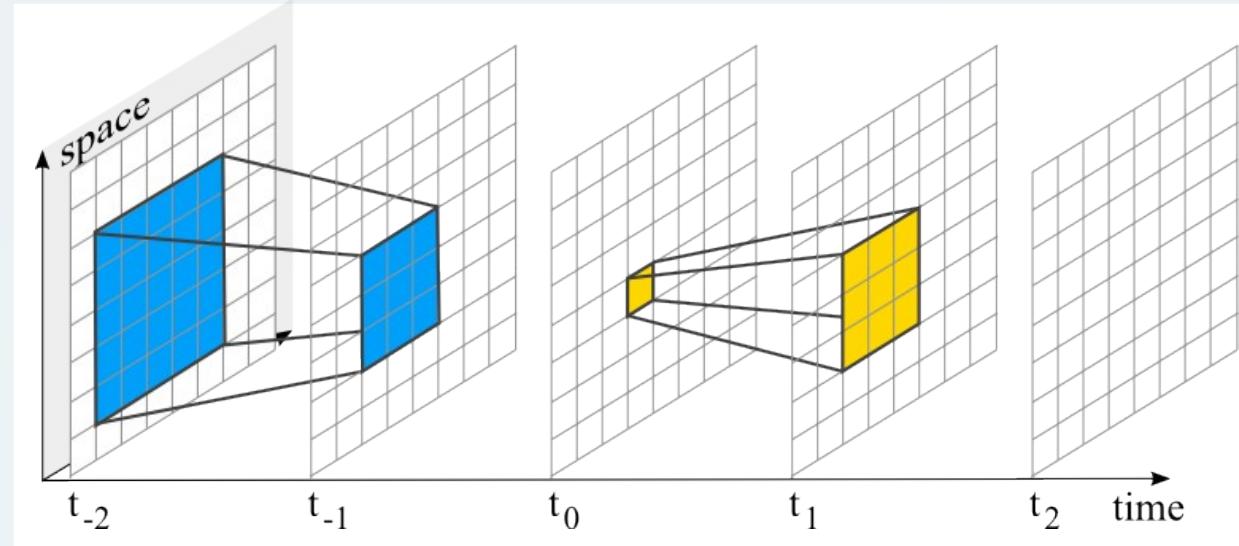
Local Statistical Complexity

- How much information from the **local past** do I need to predict the dynamics in the **local future**?



Local Statistical Complexity

- How much information from the **local past** do I need to predict the dynamics in the **local future**?

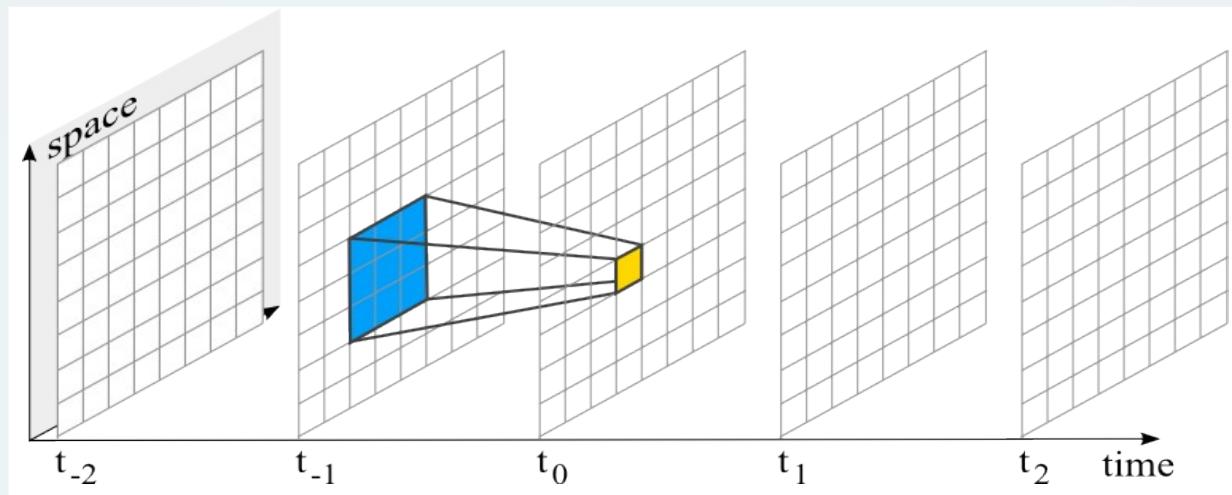


- Mutual information:

$$I[X ; Y] = \sum_{x, y} p(x, y) \log \frac{p(x, y)}{p(x) p(y)}$$

Specification

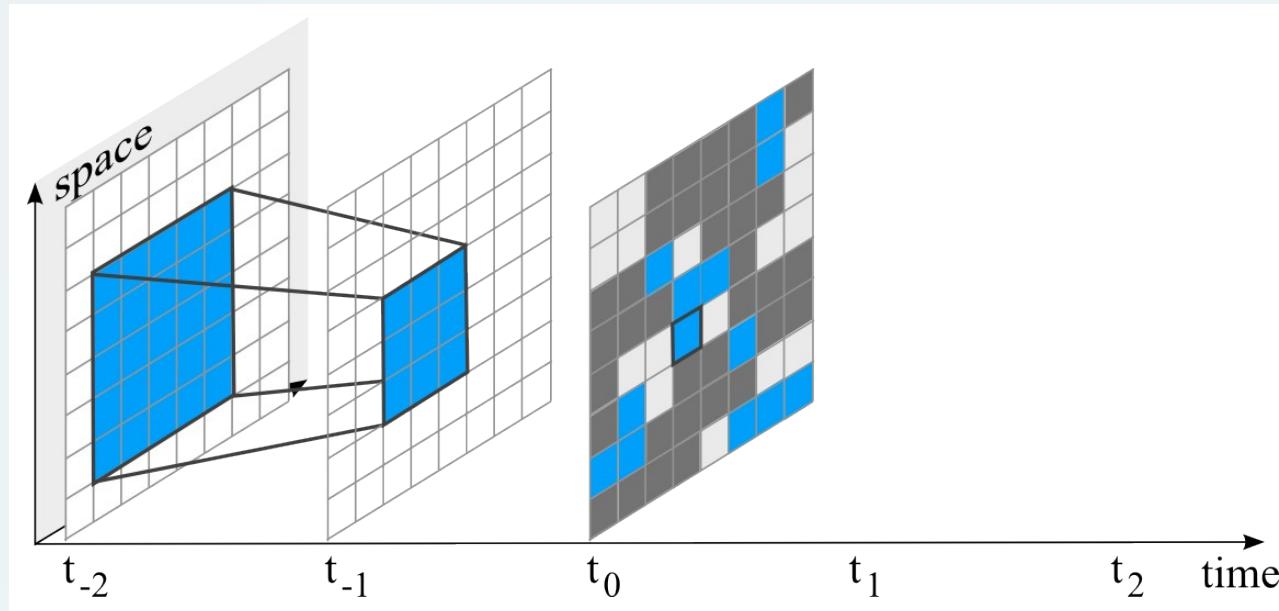
- PDE-simulation (e.g. engineering or natural sciences)
- Simulation using finite differences on a Cartesian grid
- Time-dependent data including all time steps



$$I[X;Y] = \sum_{x,y} p(x,y) \log \frac{p(x,y)}{p(x)p(y)}$$

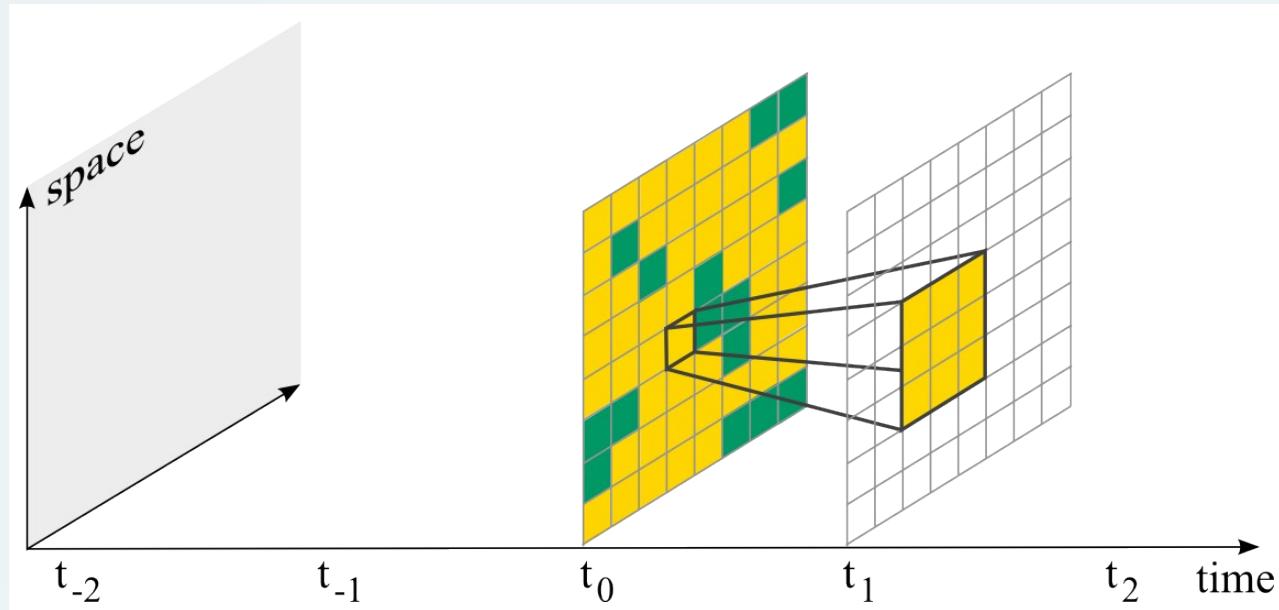
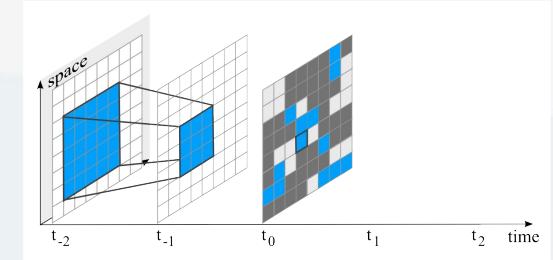
Local Statistical Complexity

- Identify pasts



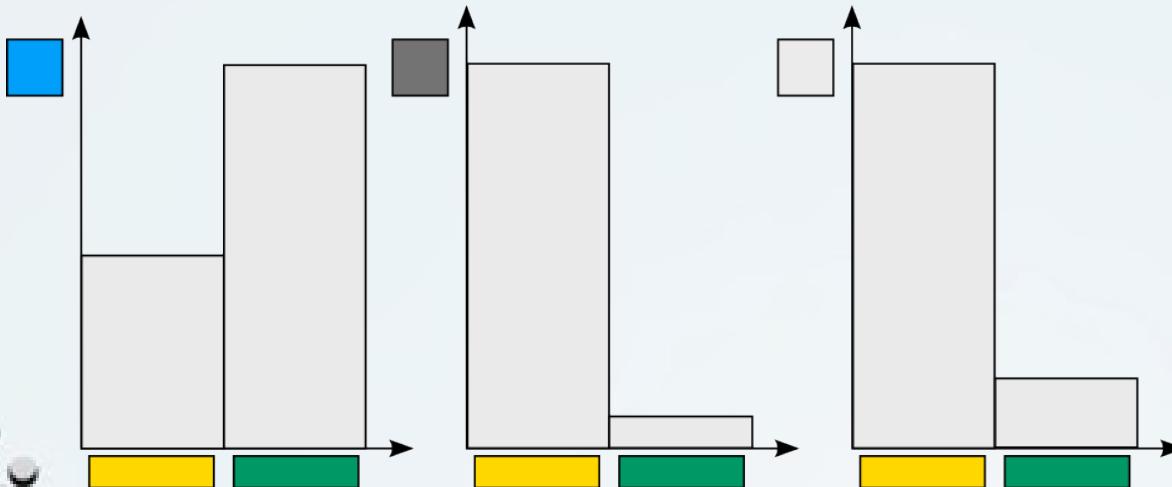
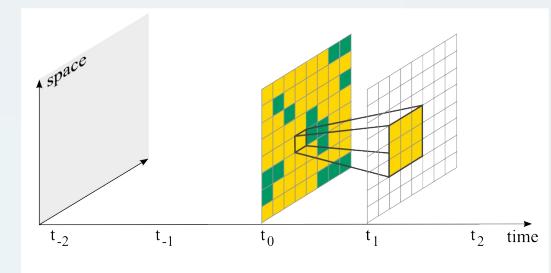
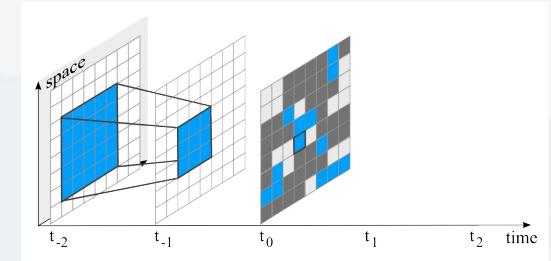
Local Statistical Complexity

- Identify pasts
- Identify futures



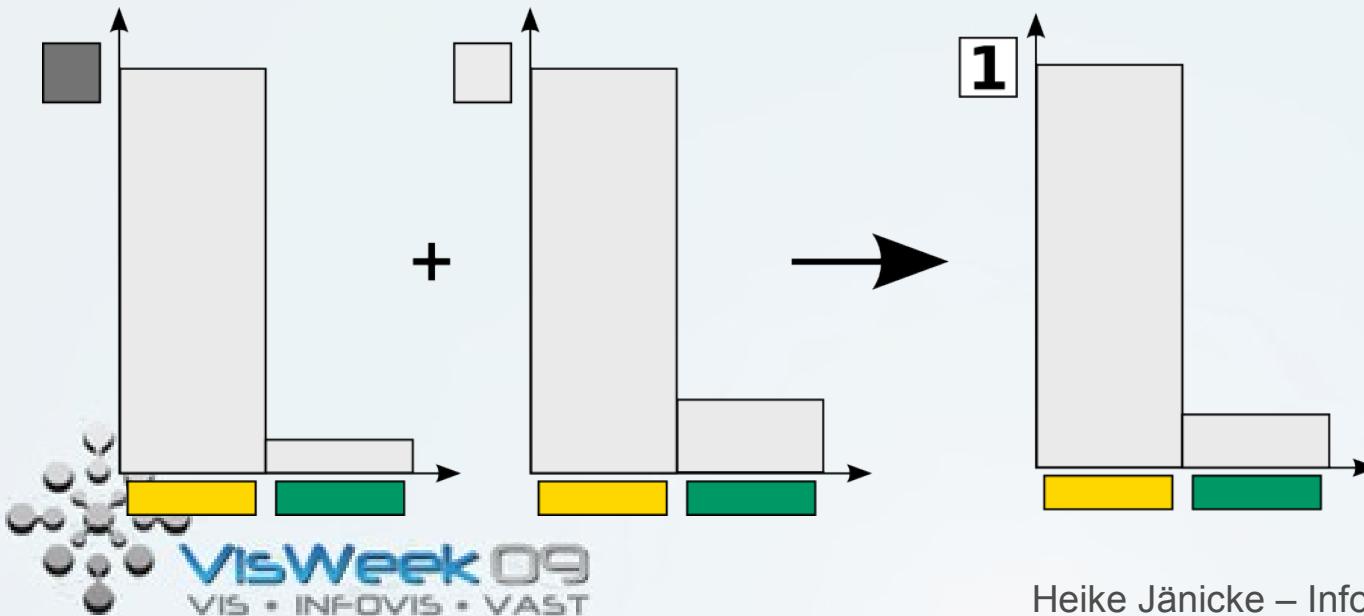
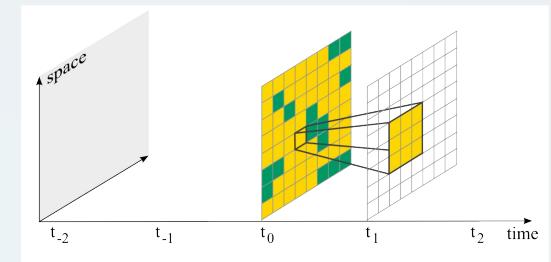
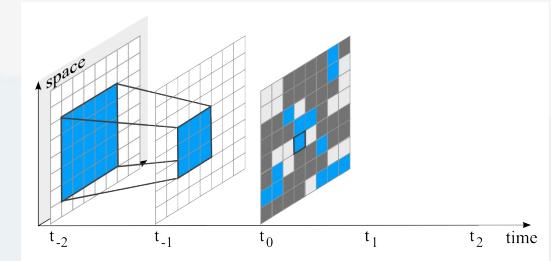
Local Statistical Complexity

- Identify pasts
- Identify futures
- Estimate distributions



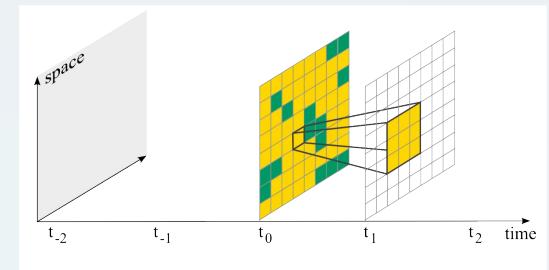
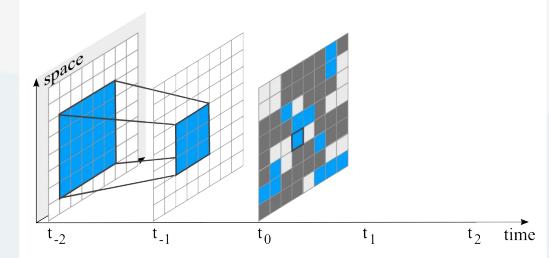
Local Statistical Complexity

- Identify pasts
 - Identify futures
 - Estimate distributions
 - Cluster similar patterns (χ^2 -Test)
- **causal states**



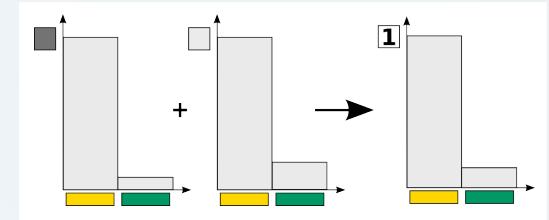
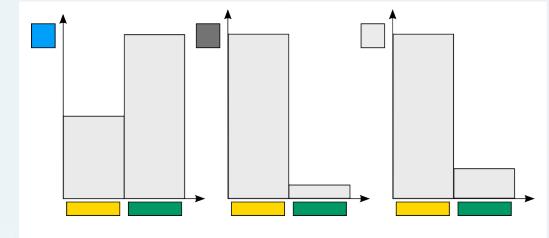
Local Statistical Complexity

- Identify pasts
- Identify futures
- Estimate distributions
- Cluster similar patterns (χ^2 -Test)
- **causal states**

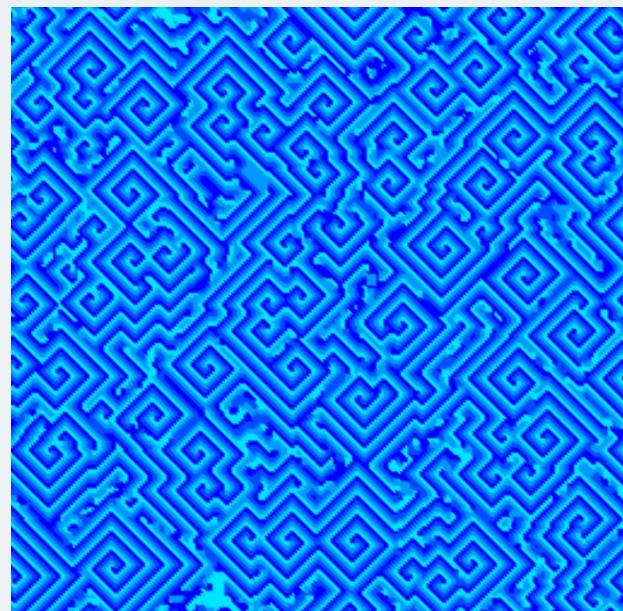


$$\text{causal state } \epsilon(l^-) = \{\lambda : P(l^+ | \lambda) = P(l^+ | l^-)\}$$

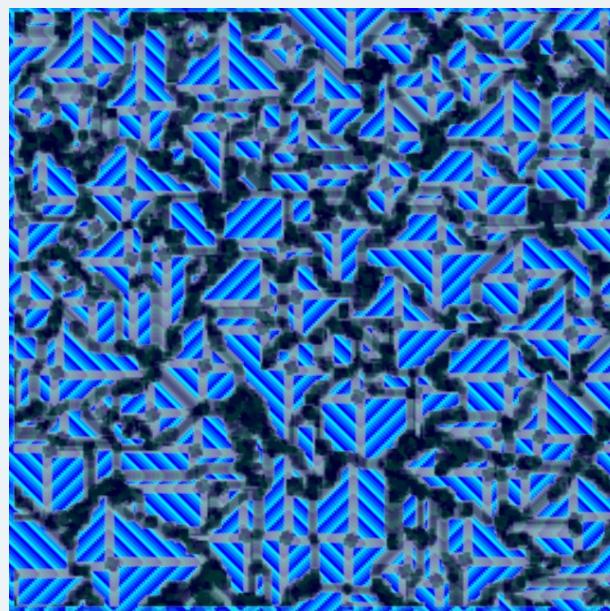
$$\begin{aligned} I[l^-(\vec{x}, t); S(l^-(\vec{x}, t))] &= \sum_{l^-, s} P(l^-, s) \log \frac{P(l^-, s)}{P(l^-) P(s)} \\ &= -\log P(s(l^-(\vec{x}, t))) \end{aligned}$$



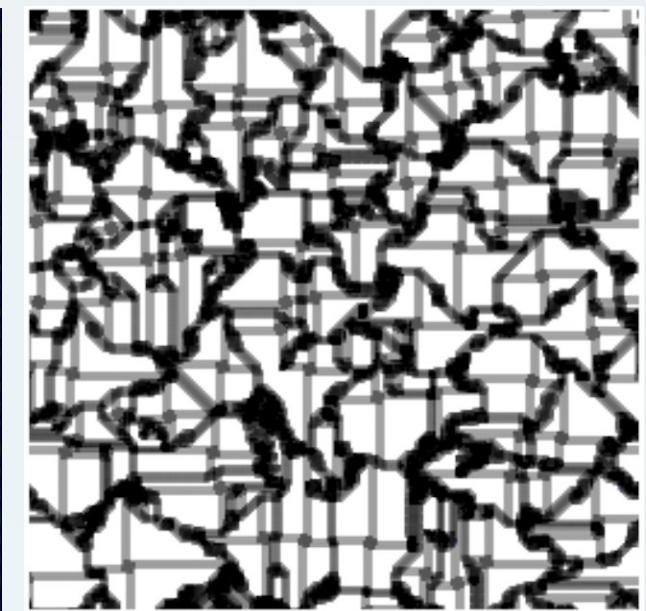
Local Statistical Complexity



$t = 99$

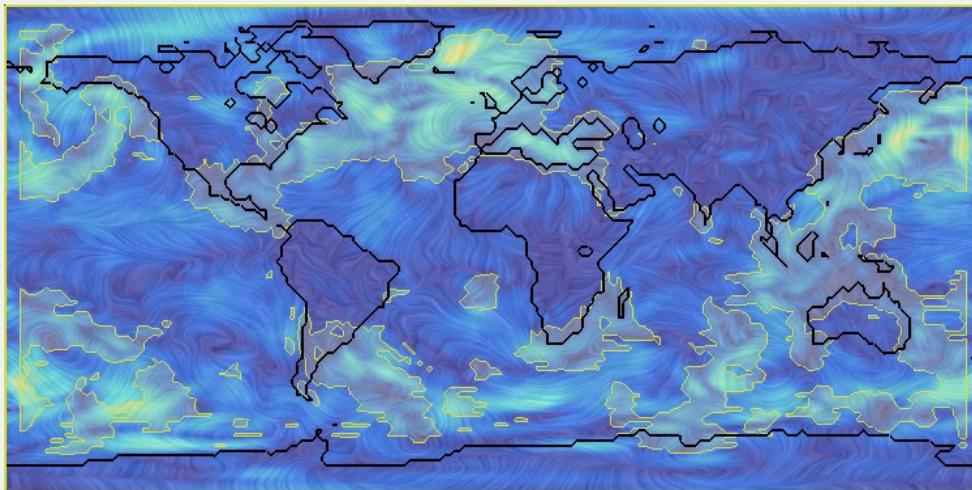


$t = 99 + \text{LSC}$

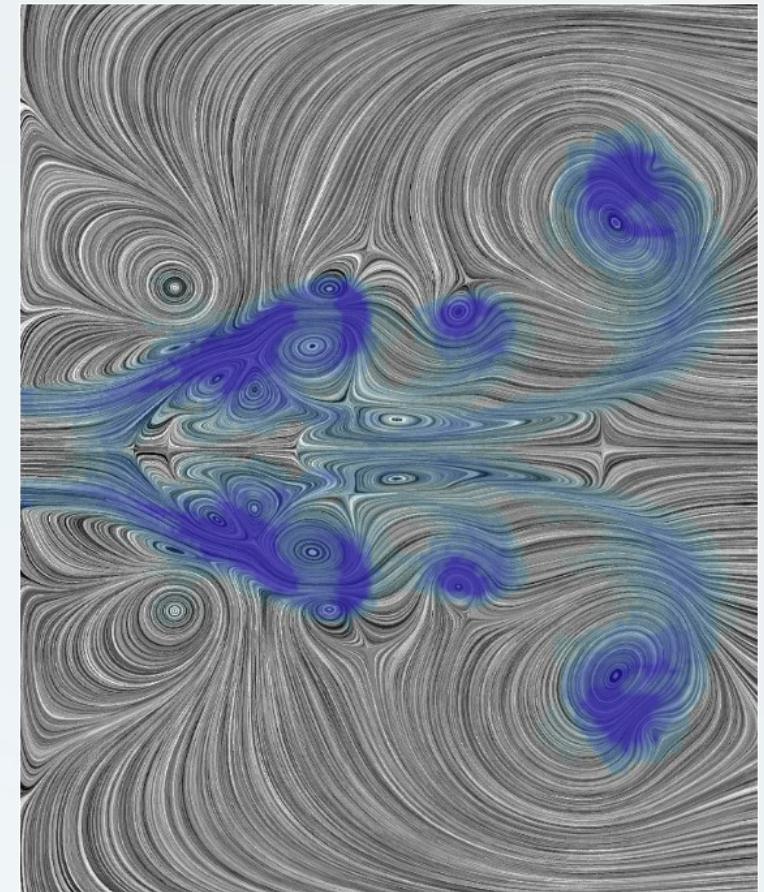


LSC

Results 2D



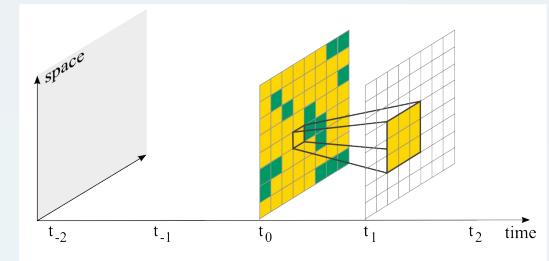
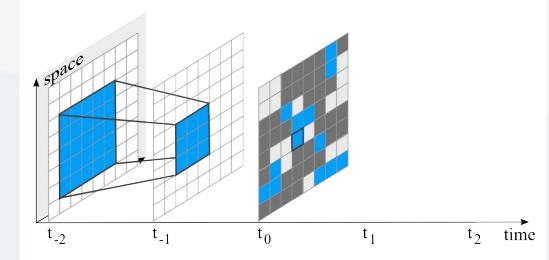
LSC wind and evaporation



LSC velocity and vorticity

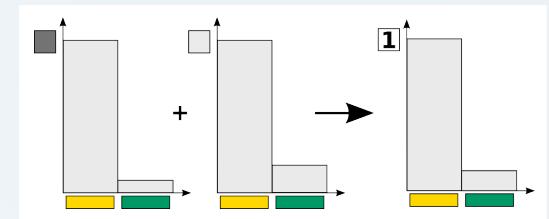
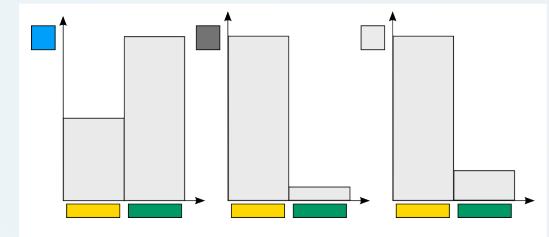
Difficult Part

- Identify pasts
- Identify futures
- Estimate distributions
- Cluster similar patterns (χ^2 -Test)
→ **causal states**

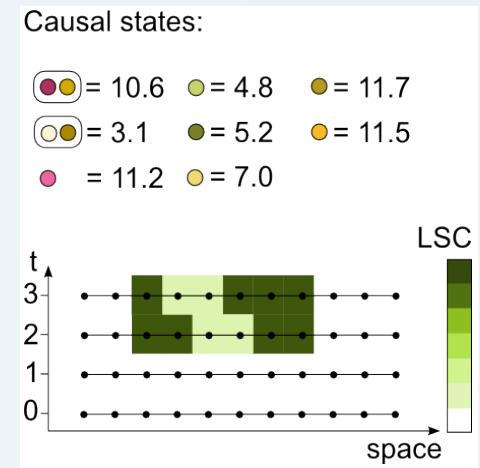
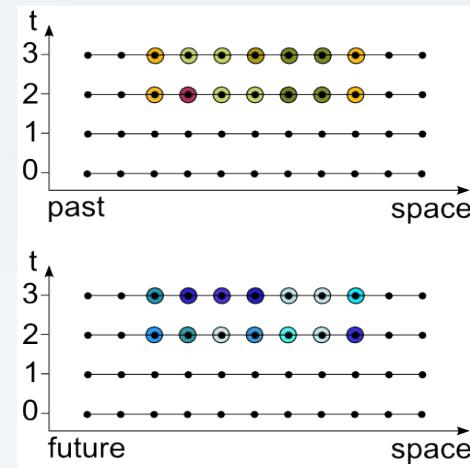
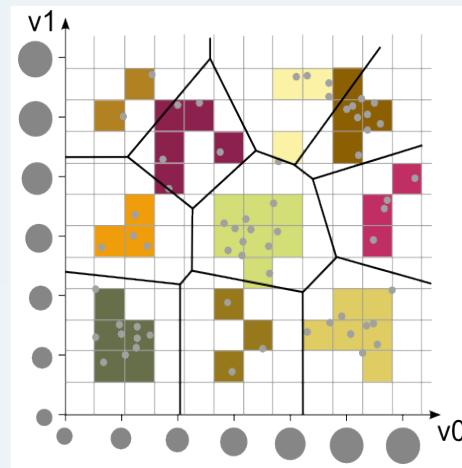
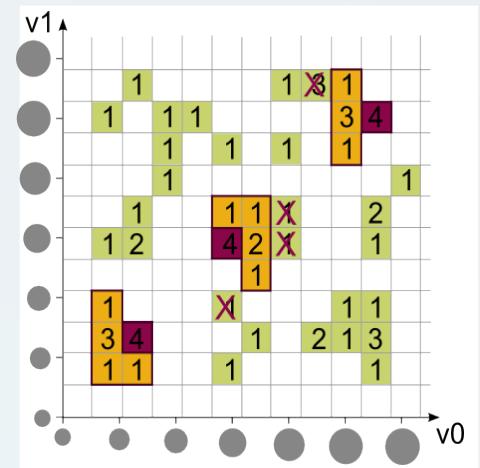
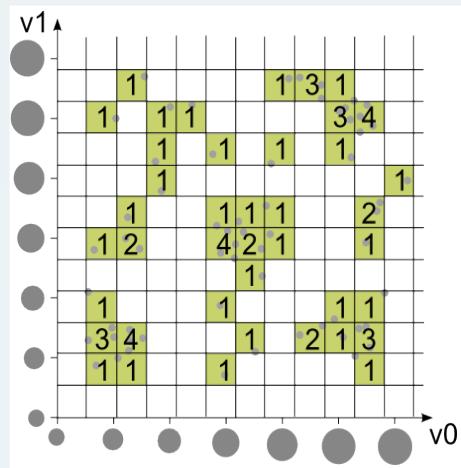
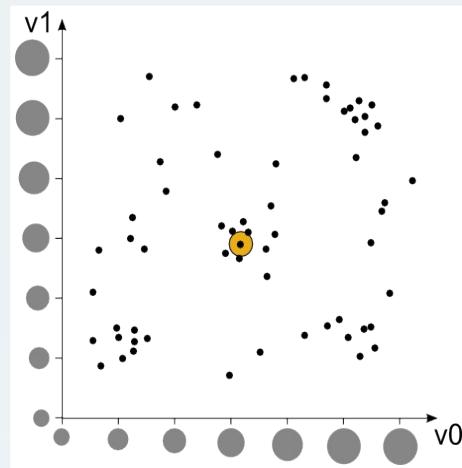
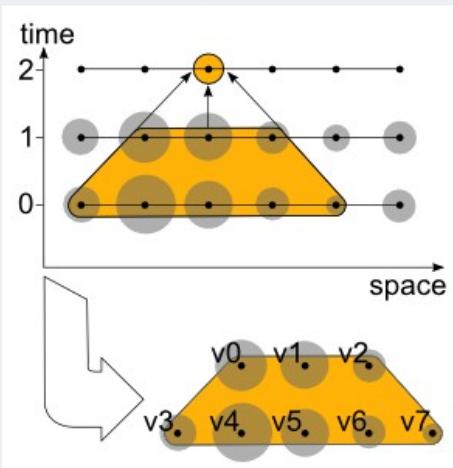


$$\text{causal state} = \epsilon(l) = \{\lambda : P(l^+ | \lambda) = P(l^+ | l)\}$$

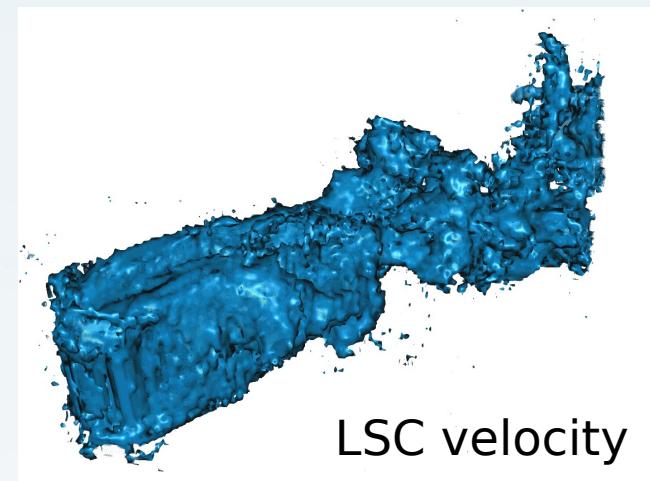
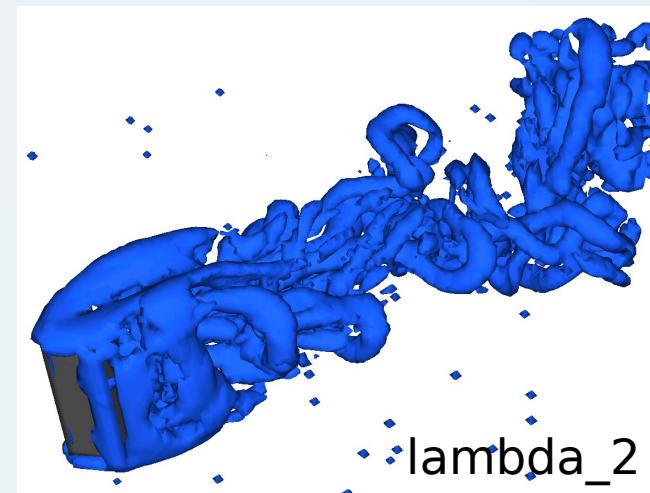
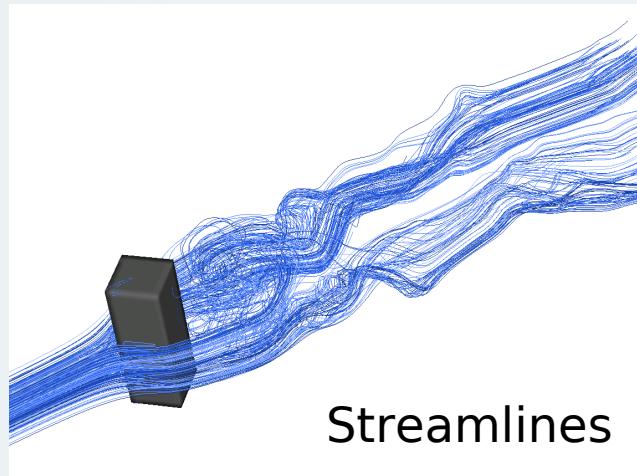
$$\begin{aligned} I[l(\vec{x}, t); S(l(\vec{x}, t))] &= \sum_{l, s} P(l, s) \log \frac{P(l, s)}{P(l) P(s)} \\ &= -\log P(s(l(\vec{x}, t))) \end{aligned}$$



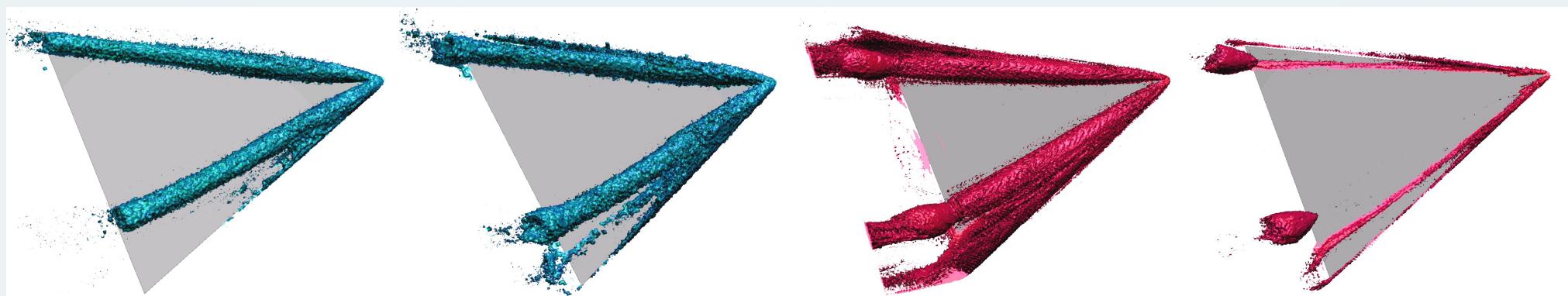
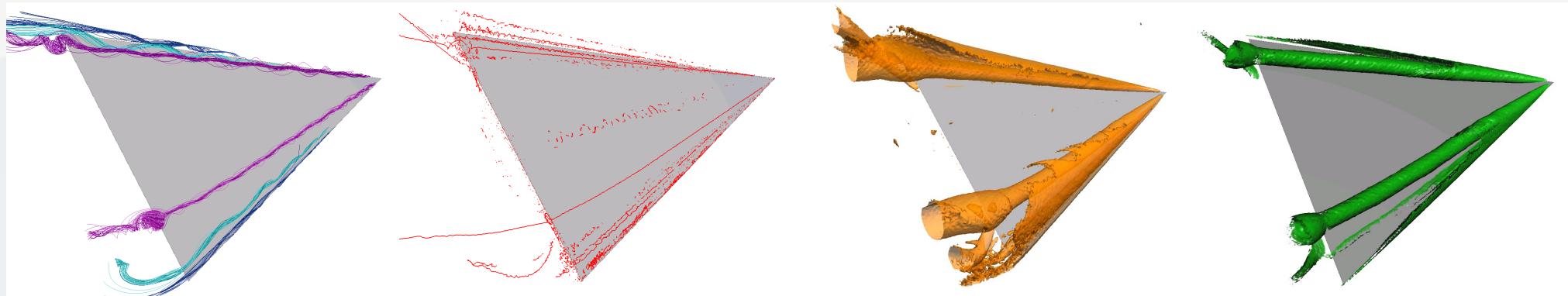
Density-driven Voronoi Tessellation



Flow Around an Obstacle

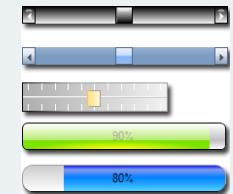
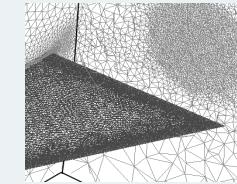


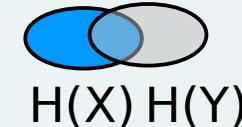
Delta Wing

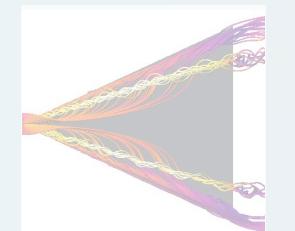
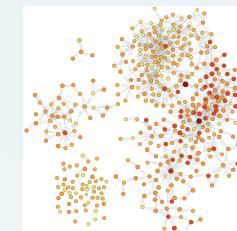
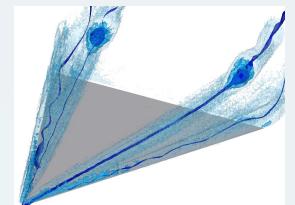


Outline

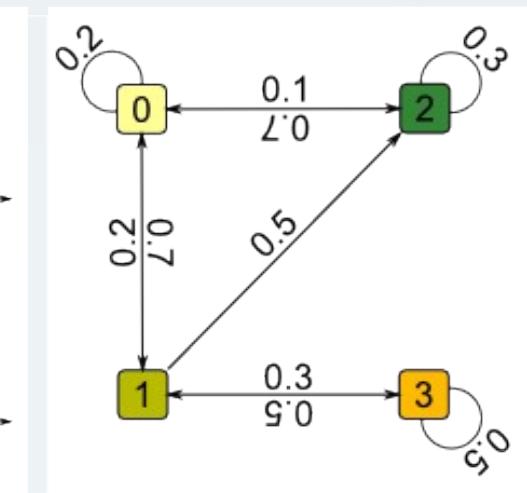
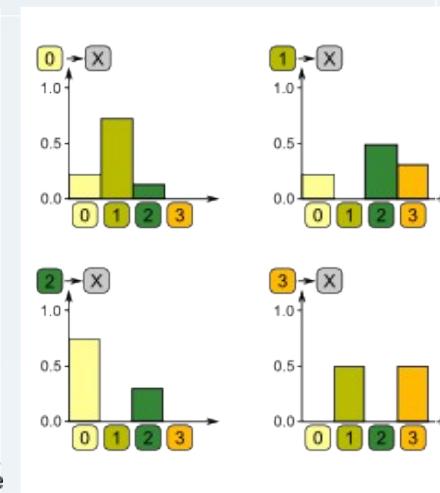
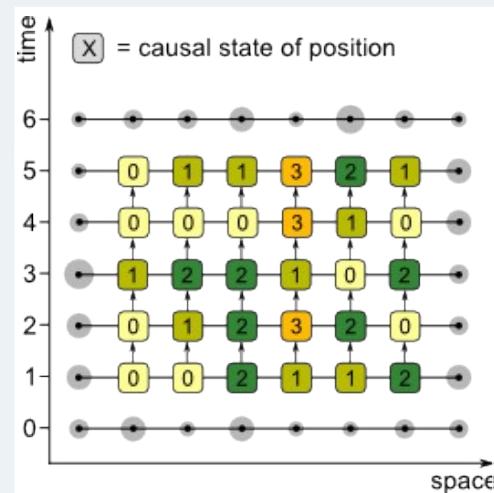
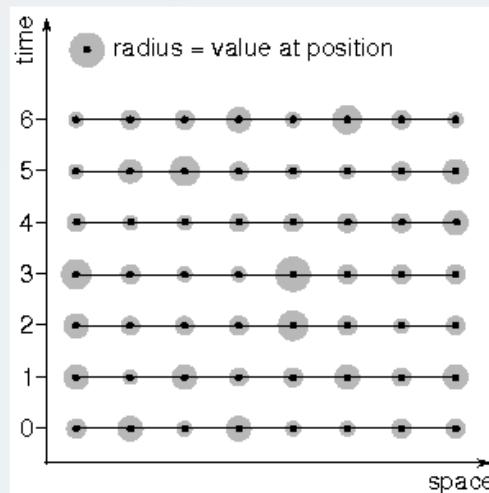
- Data representation
- Related work
- Information Theory
- Local Statistical Complexity
- Epsilon-machines
- Eulerian/ Lagrangian flow
- Conclusion/ future directions



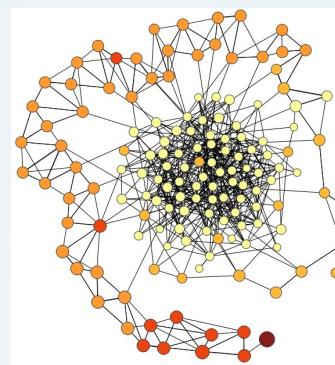
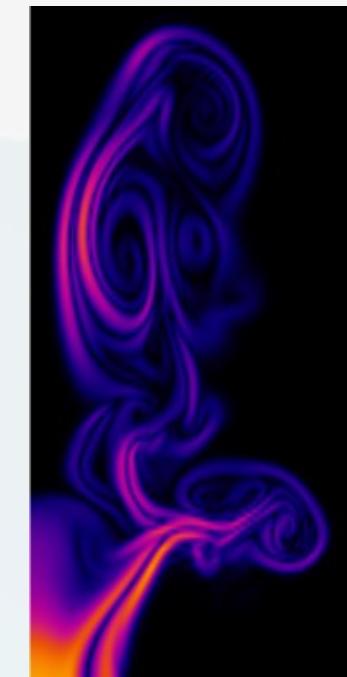
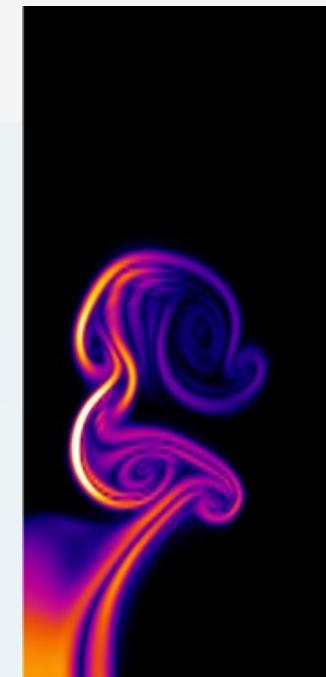
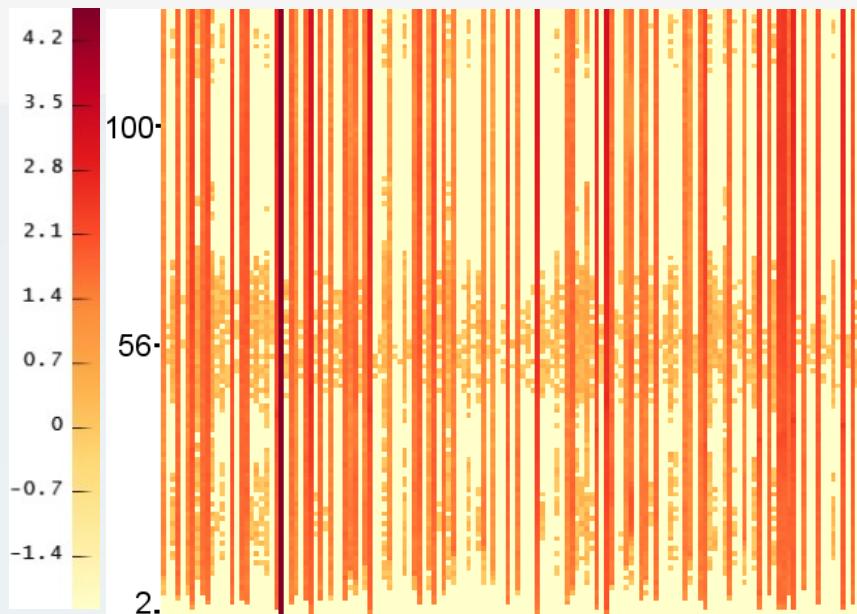
$$I(X;Y)$$

$$H(X) \ H(Y)$$



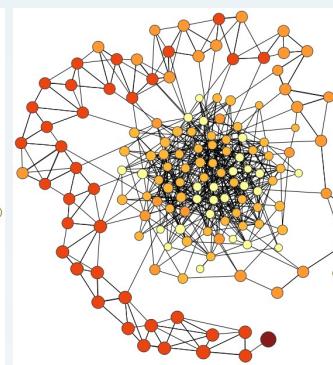
ε -Machine



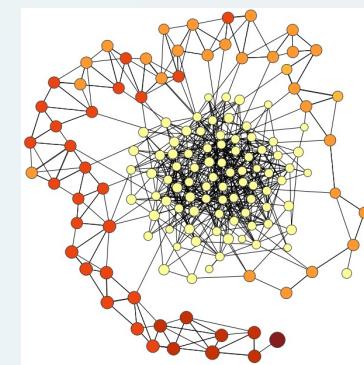
Swirling Flow



$t = 8$

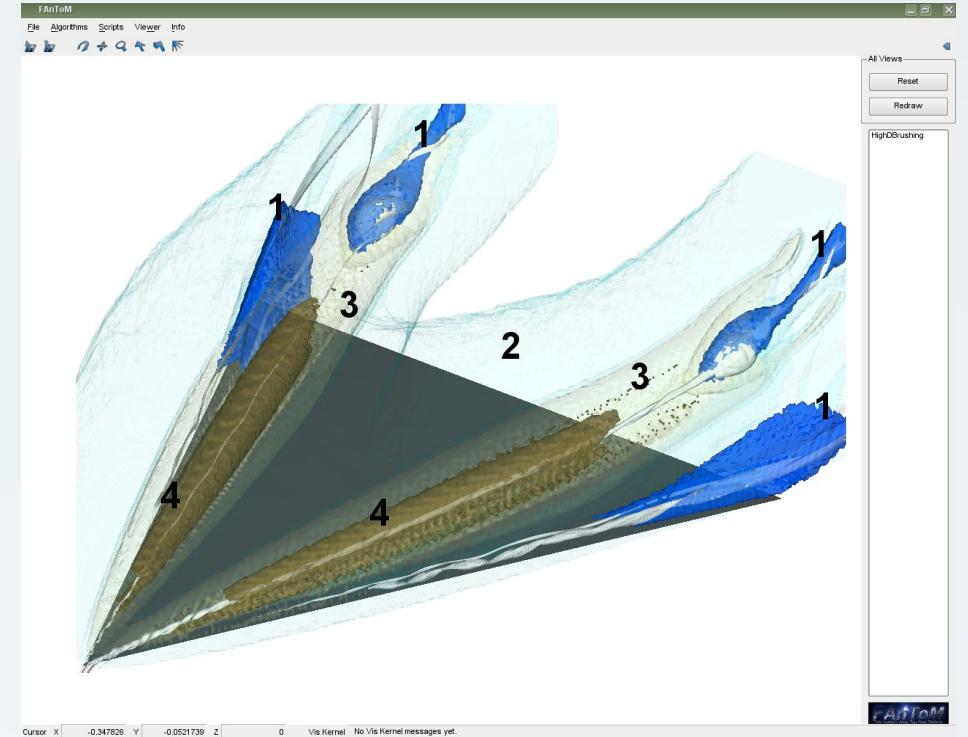
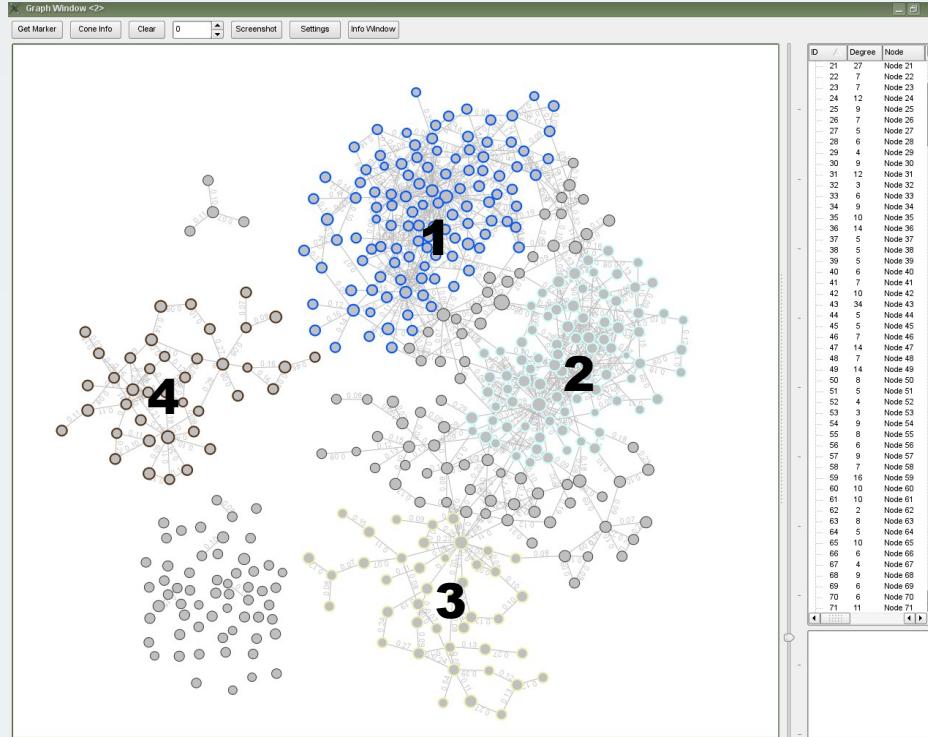


$t = 56$

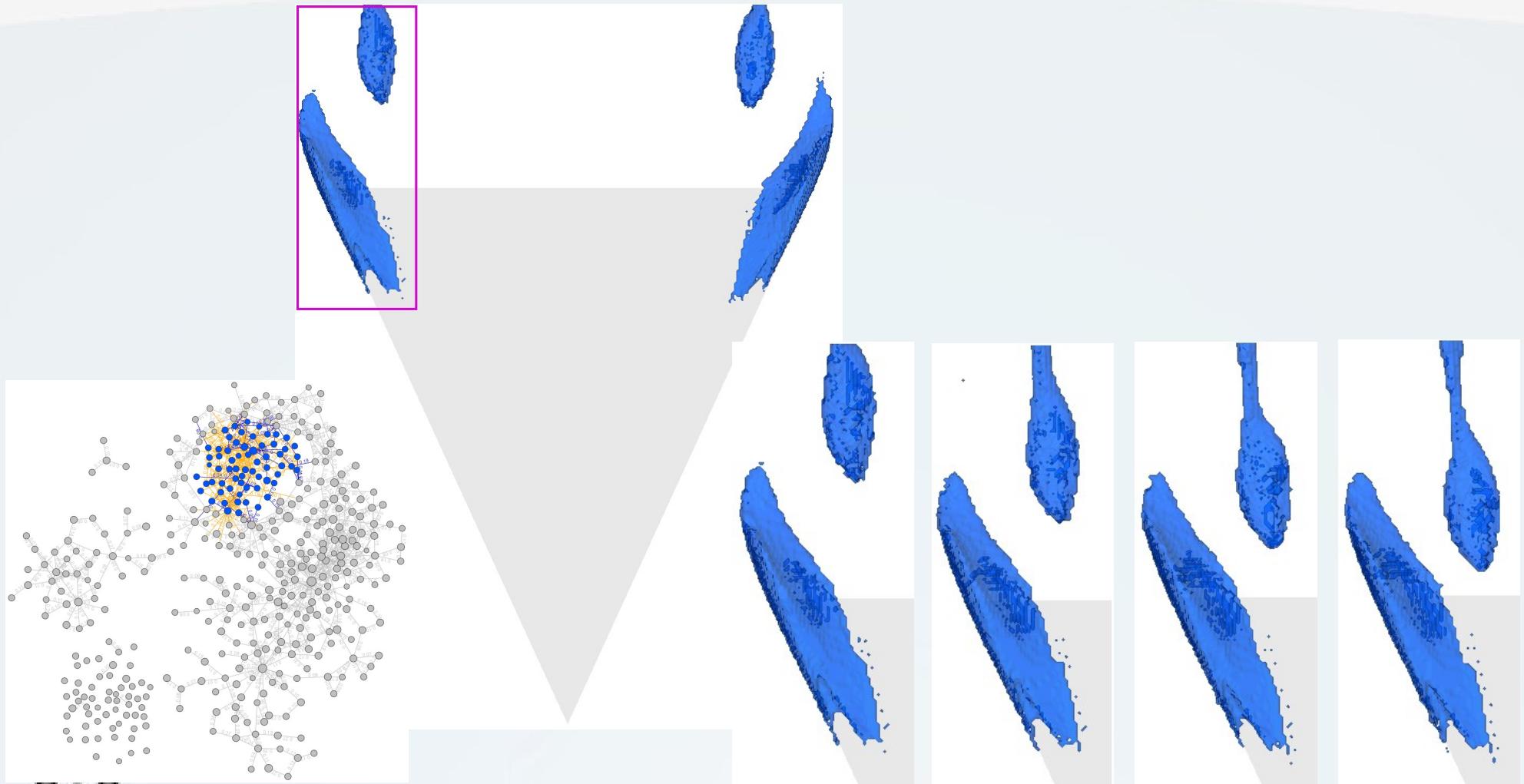


$t = 100$

ε -Machine of the Delta Wing

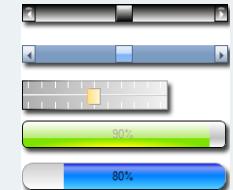
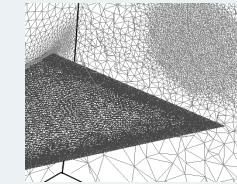


Delta Wing



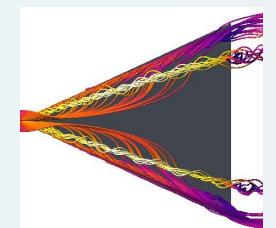
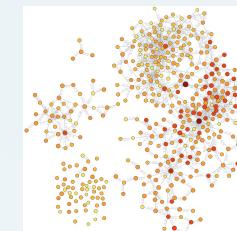
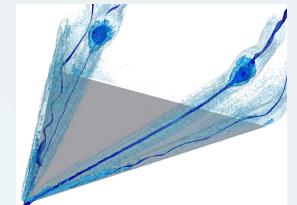
Outline

- Data representation
- Related work
- Information Theory
- Local Statistical Complexity
- Epsilon-machines
- Eulerian/ Lagrangian flow
- Conclusion/ future directions



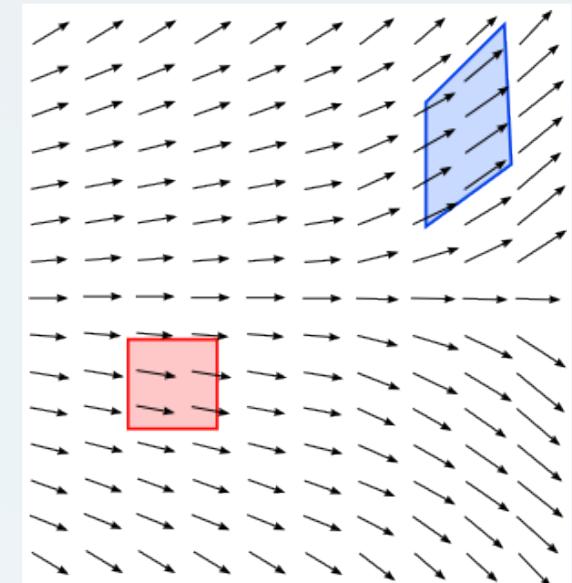
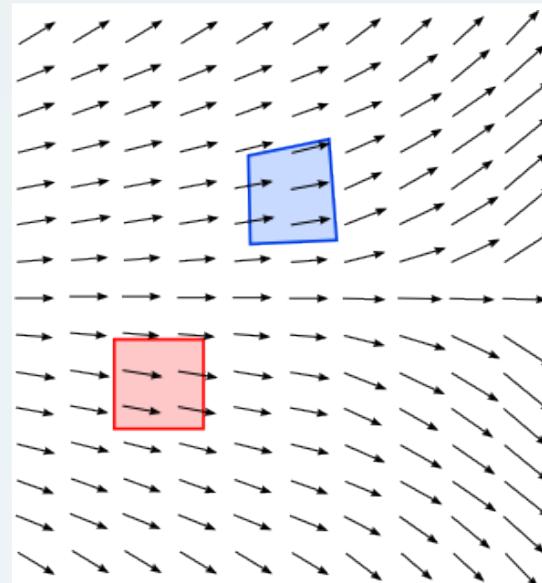
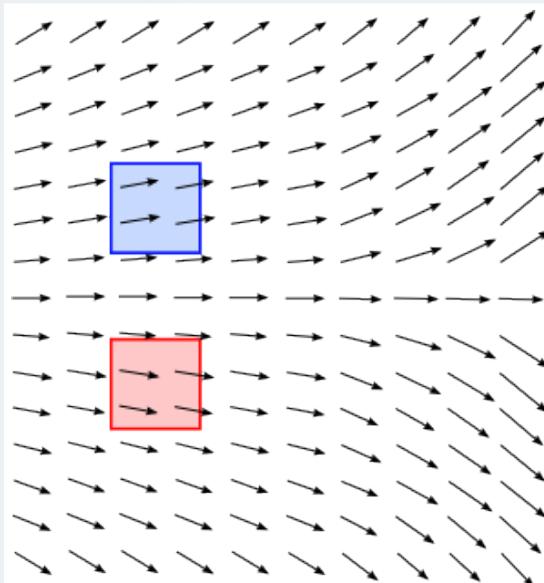
$$I(X;Y)$$

$$H(X) H(Y)$$



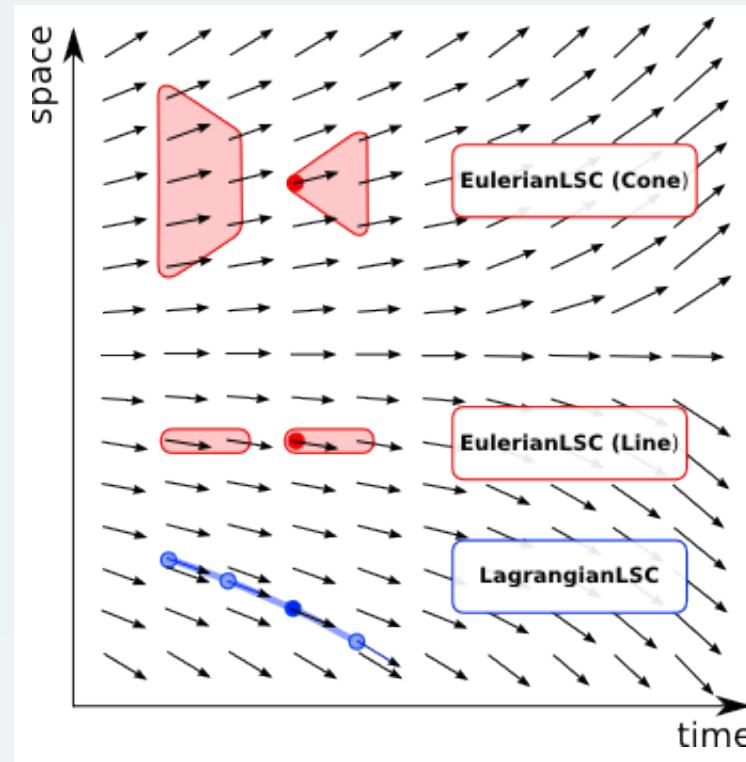
Flow Description

Lagrangian flow description



Eulerian flow description

Causal States in Different Flow Descriptions



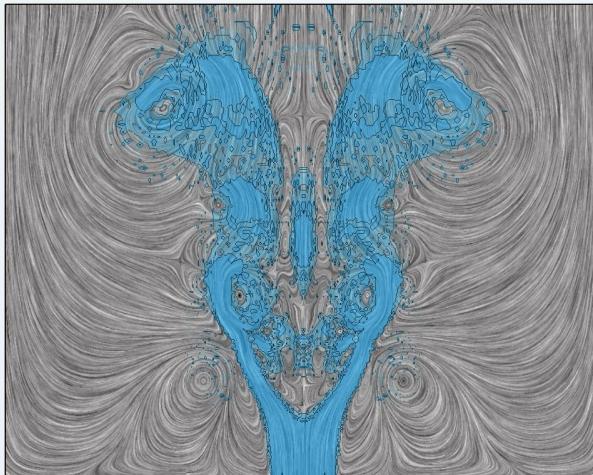
Swirling Flow



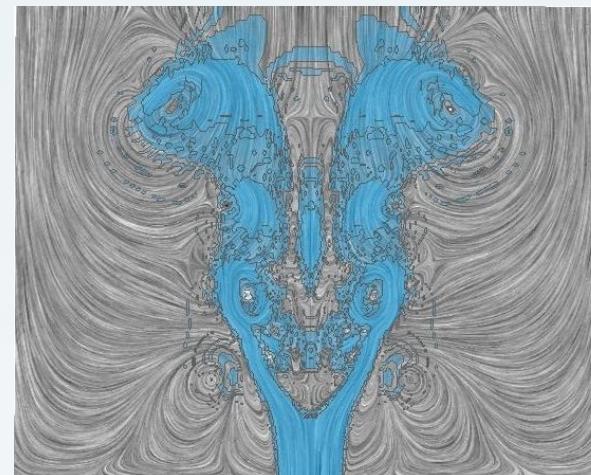
Line Integral Convolution



LIC + EulerianLSC (Cone)



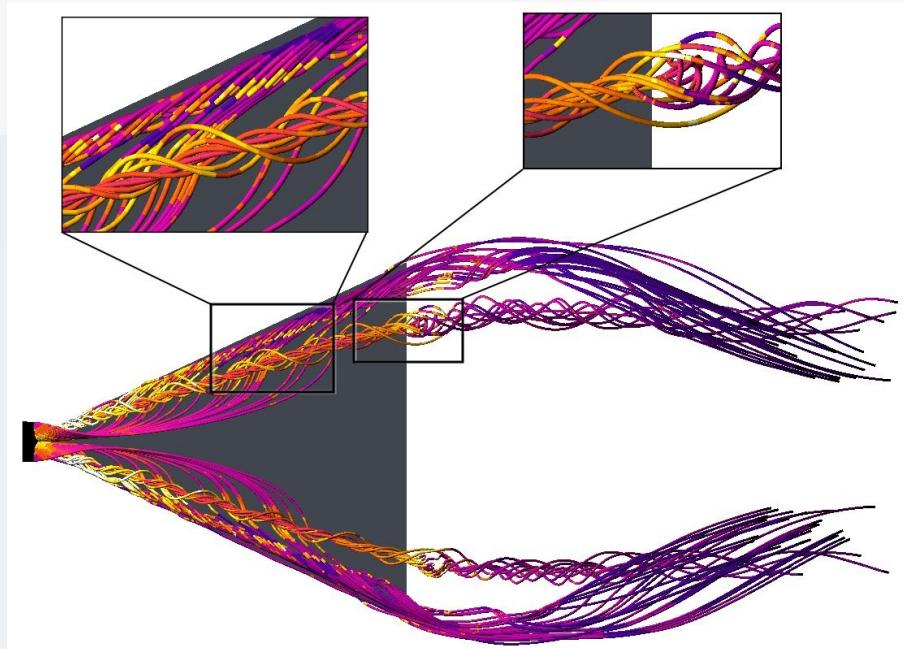
LIC + EulerianLSC (Line)



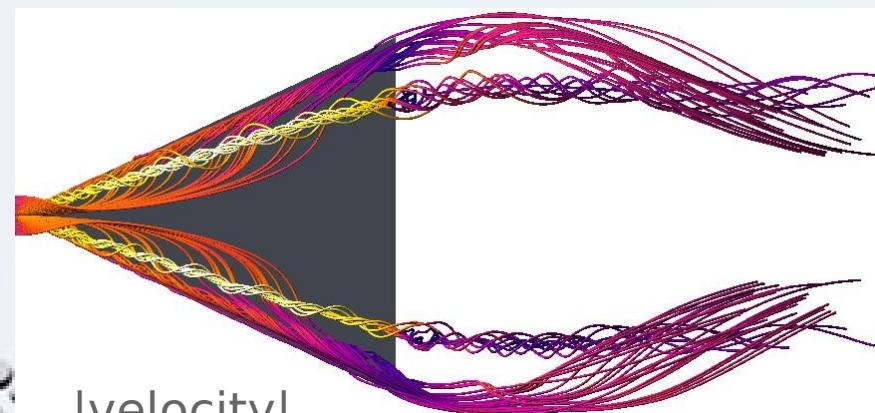
LIC + LagrangianLSC



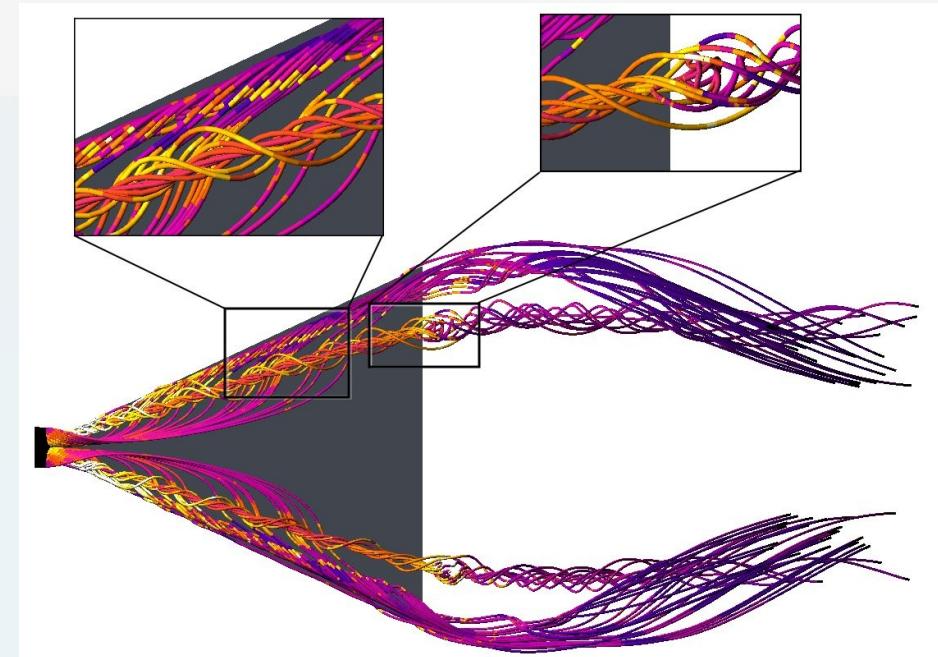
Particle-based complexity



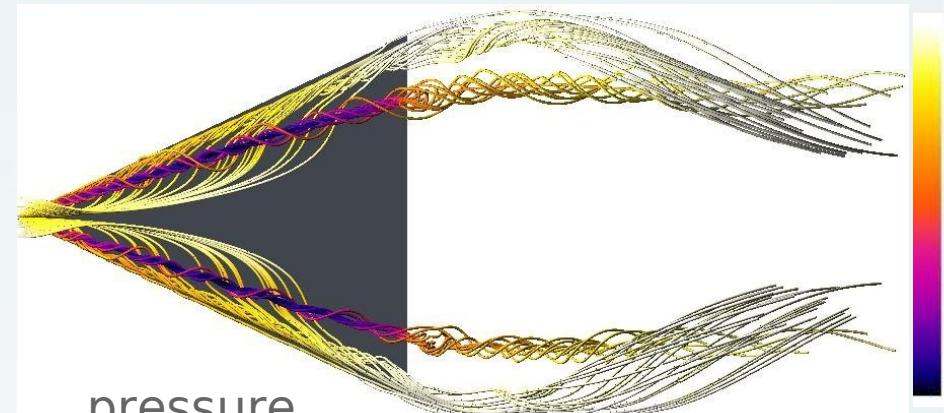
LagrangianLSC for norm of velocity



velocity
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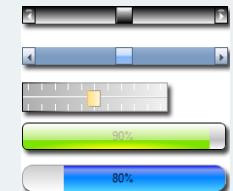
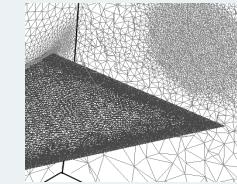
LagrangianLSC for pressure



pressure

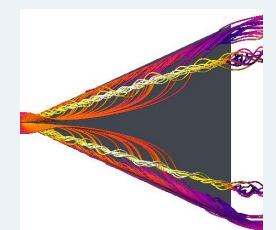
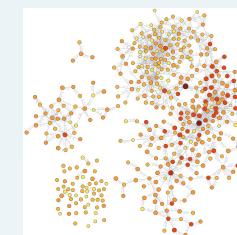
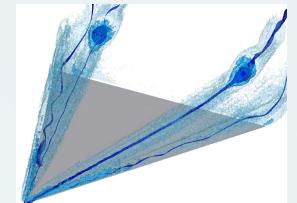
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$$I(X;Y)$$

$$H(X) H(Y)$$



Conclusion/ Future Work

- **Conclusion**
 - Challenges in visualization
 - Multivariate data
 - Time-dependent data
 - (Automatic) feature detection
 - Automatic detection of relevant structures based on information theory
 - Steady visualization of unsteady data
 - Application to real world data sets
- **Future work**
 - Detecting structures in multivariate data
 - Better analysis of temporal changes



Thank you for your attention!

Questions?





Related publications

- H. Jänicke**, A. Wiebel, G. Scheuermann, W. Kollmann. Multifield Visualization Using Local Statistical Complexity. IEEE TVCG 2007.
- H. Jänicke** und G. Scheuermann. Principals of Information Theory Applied to Visualization. Workshop at IEEE Visualization 2007.
- T. Salzbrunn, **H. Jänicke**, Th. Wischgoll und G. Scheuermann. The State of the Art in Flow Visualization: Partition-based Techniques. SCS Publishing House 2008.
- H. Jänicke**, M. Böttinger, X. Tricoche und G. Scheuermann. Automatic Detection and Visualization of Distinctive Structures in 3D Unsteady Multi-Fields. Computer Graphics Forum 2008.
- H. Jänicke**, M. Böttinger und G. Scheuermann. Brushing of Attribute Clouds for the Visualization of Multivariate Data. IEEE TVCG 2008.
- H. Jänicke** und G. Scheuermann. Towards Automatic Feature Based Visualization. To appear in Proc. Dagstuhl Seminar – Scientific Visualization 2007.
- H. Jänicke** und G. Scheuermann. Steady Visualization of the Dynamics in Fluids Using ϵ -Machines. Accepted for publication in Computers and Graphics (Special issue on knowledge-assisted visualization) 2009.
- H. Jänicke**. Information Theoretic Methods for the Visual Analysis of Climate and Flow Data. PhD thesis, University of Leipzig, 2009.