

Simplex method — summary

Problem: optimize a linear objective, subject to linear constraints

1. **Step 1:** Convert to standard form:

- variables on right-hand side, positive constant on left
- slack variables for \leq constraints
- surplus variables for \geq constraints
- $x = x^- - x^+$ with $x^-, x^+ \geq 0$ if x unrestricted
- in standard form, all variables ≥ 0 , all constraints equalities

2. **Step 2:** Add artificial variables:

- one for each constraint without a slack variable

3. **Step 3:** Create an objective constraint:

- add new variable z , and add new constraint $z - \text{objective} = 0$

4. **Step 4:** Form the initial tableau:

- first column to identify basic variables
- last column for constants on right-hand sides of constraints
- in between, one column for each variable (beginning with z)
- first row for labels
- remaining rows for constraints (beginning with objective — but see Step 5 below)

5. **Step 5:** Identify the initial objective function ($z = ?$)

- if all constraints were \leq , so slack variable in each constraint, use objective function from original problem
- if there are artificial variables, and M -method is being used, objective function is original objective plus
 - large positive multiple of each artificial variable (if minimization problem)
 - large negative multiple of each artificial variable (if maximization problem)
- if there are artificial variables, and two-phase method is being used, objective function is sum of artificial variables, and this should be minimized (whether or not original problem was minimization)

6. **Step 6:** Identify initial basic variables:

- slack variables together with artificial variables
- looking at constraint rows only in columns of these initial basic variables, should see permutation of columns of identity matrix
- label each constraint row by the basic variable occurring once in that row

7. **Step 7:** Modify the z -row

- if entry in z -row in column of basic variable is not zero, add appropriate multiple of the row in which that basic variable appears, so that entry becomes 0
- at end of process, objective is expressed entirely in terms of non-basic variables
- if initial basic variables consist of all slack variables, this step not necessary

8. **Step 8:** Identify an entering basic variable and pivot column:

- maximization problem — most negative coefficient in z -row
- minimization problem — most positive coefficient in z -row
- break ties by choosing left-most column
- column of entering variable is pivot column
- if no entering variable, STOP — optimum reached
 - current basic feasible solution is optimal
 - optimal objective value is last entry (solution column) of objective row

9. **Step 9:** Identify a departing basic variable and pivot row:

- for each non-basic variable, take ratio of entry in solution column and entry in pivot column
- non-basic variable with smallest non-negative ratio is departing variable, and corresponding row is pivot row
- break ties by choosing top-most column

10. **Step 10:** Pivot on pivot entry:

- pivot entry is intersection of pivot row and pivot column
- scale pivot row so pivot element is one
- add multiples of pivot row to other rows (including objective row) so rest of pivot column is zero
- change label of pivot row to that of entering variable

11. **Step 11:** Iterate:

- repeat steps 8 through 10 until optimal is reached
- if using M -method or all-slack starting solution, problem is completely done; if using two-phase method, go onto step 12

12. **Step 12:** Phase 2 of two-phase method:

- as long as phase 1 of two-phase method returns minimum of zero, continue to phase 2
- create a new initial tableau
 - objective row given by original objective of problem
 - constraint rows given by constraint rows of final tableau of phase 1, with artificial columns removed
 - initial basic variables given by basic variables at end of phase 1
- go back to step 7

Four quirky situations

1. Degeneracy:

- Geometric idea
 - can happen when more constraints meet at a point than would be normal (three or more two variable constraints, four or more three variable constraints, etc.)
 - typically one of these constraints is redundant (its removal doesn't change the feasible space)
 - at the degenerate point, one (or more) of the basic variables is zero, so in fact the same point corresponds to numerous basic feasible solutions
- Simplex manifestation
 - occurs whenever there is a tie for departing variable
 - at next iteration, entering variable will be constrained to enter at value zero
 - simplex algorithm will move to a new basic feasible solution, but it's geometrically the same point, and the objective doesn't change
- Implications
 - typically, slows down simplex algorithm
 - in worst case, can lead to cycling — algorithm loops, staying at the same (suboptimal) point forever
 - this is so wildly unlikely (and difficult to deal with) that no commercial implementation of simplex algorithm bothers to deal with it

2. **Alternative optima:**

- Geometric idea
 - happens when one of the constraints which is satisfied tightly at the optimum is parallel to the objective
 - there is more than one optimal basic feasible solution, and infinitely many optimum solutions that are not basic
- Simplex manifestation
 - when optimality is reached, one (or more) of the non-basic variables has coefficient zero in objective
 - each one can enter into the set of basic variables, without changing the objective value
- Implications
 - gives a variety of choices for optimum, some of which may be more desirable than others
 - doesn't affect the running of the algorithm

3. **Unbounded solution:**

- Geometric idea
 - happens when the constraints do not trap a finite region in space, but allow at least one variable to go to infinity inside feasible region
 - the objective value can be made as large (or small, if a minimization problem) as one wishes
- Simplex manifestation
 - when ratio test is being used to determine constraints on entering variable, all ratios are either negative or infinity
 - the current entering variable is the one that can be made as large as desired
- Implications
 - suggests that the original problem may have been poorly posed, or fed into solver incorrectly
 - simplex algorithm should be coded to stop when finding an unbounded variable

4. Unfeasible problem:

- Geometric idea
 - happens when the constraints are inconsistent
 - there is no feasible point that satisfies all the constraints
 - cannot occur when all constraints are \leq , because all-zero solution (all-slack solution) is feasible in this case
- Simplex manifestation
 - occurs only when M -method or two-phase method are being used
 - * M -method: no matter how large M is, one of the artificial variables is always basic in optimum solution
 - * two-phase method: phase 1 ends by discovering that minimum of sum of artificial variables is positive
- Implications
 - suggests that the original problem may have been poorly posed, or fed into solver incorrectly