

(3)

This means that the columns of  $U$  and  $V$  are also orthogonal!

This is easy to show. Let's look at the product:

$$C = U^T U = I$$

Now the element  $C_{ij}$  is the inner product of the  $i^{\text{th}}$  column of  $U$  (e.g.,  $u_i$ ) w/ the  $j^{\text{th}}$  column!

$$C_{ij} = u_i^T u_j = I_{ij}$$

But if  $i \neq j$  this is an off-diag. element of the identity matrix!

$$\text{So } : u_i^T u_j = \begin{cases} 0 & i \neq j \\ 1 & i = j \end{cases}$$

The same applies to  $V$ !

We can use the values (magnitude) of  $\sigma_{ii}$  to explore the sensitivity of  $\hat{z}$  to variations in  $x$ .

④  
Suppose the model  $\tilde{z} = f(\tilde{x})$  represents a multiple input / multiple output model of plant operations.

$\tilde{x}$  might be the mass flow rate of input streams

$\tilde{z}$  might be the resulting products needed elsewhere in the plant.

In general, you want to minimize  $\tilde{z}'$  - the deviation from some optimal output  $\tilde{z}_0$ .

Question: what fluctuations  $\tilde{x}'$  give rise to the maximum change in  $\tilde{z}'$ ?

This is addressed by SVD, looking at the largest singular value  $\sigma_{11}$ .

The most dangerous mode is any vector of disturbances  $\tilde{x}'$  proportional to the first column of  $\tilde{V}$

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The resulting output vector is proportional to the first column of  $\underline{U}$

The amplification factor is the corresponding singular value  $\sigma_{11}$

If the  $i^{\text{th}}$  singular value is zero, then ~~that~~ a disturbance

vector  $\underline{x}' \sim V(:, i)$  ( $i^{\text{th}}$  column of  $\underline{V}$ ) has no effect on  $\underline{z}$ !

In the homework project 3 you are doing the same thing, only in reverse: what is the magnitude of  $\underline{x}$  to get some output  $\underline{z}$ .

Thus, you are interested in the smallest singular values, rather

than (as in the usual case) the largest.

This all is an example of Principal Component Analysis, or PCA.

## Data Compression

Let  $u_i$  be the columns of  $U$  and let  $v_i$  be the columns of  $V$

(or the rows of  $V^T$ )

Then:

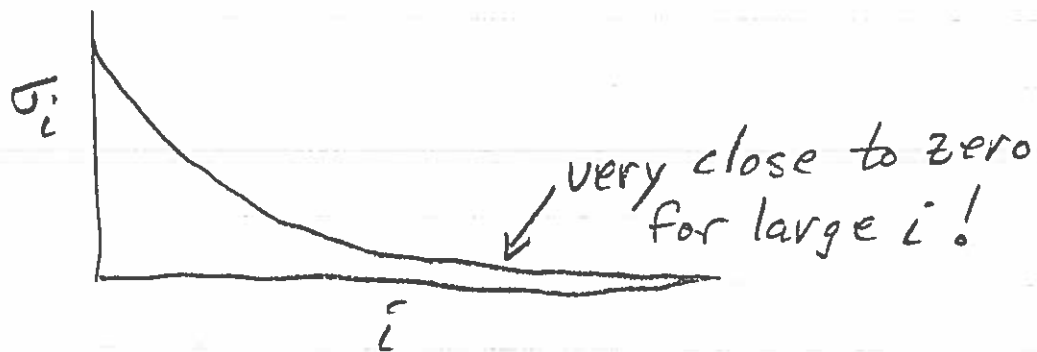
$$A \approx \sum_{i=1}^n \sigma_i u_i v_i^T$$

↑  
vector composition or  
outer product

Suppose  $A$  is a huge matrix, say

$A \approx 512 \times 512$  (usual picture size)

If we plot  $\sigma_i$  vs.  $i$  we get:



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Thus if we truncate picture after  $i \approx 20$  we can reproduce the original picture!

$$\text{Take } A \approx \sum_{i=1}^{20} \sigma_i u_i v_i^T$$

This has a total of

$$20 \times (1 + 512 + 512) = 20,500$$

vs. 262,144 elements!

For larger matrices you get even greater reduction in size

Now SVD requires a large # of computations, so it's a trade off between storage/transmission considerations and comp. speed!

Recently, transmission rates have not kept up w/ processor speed, so equation has shifted toward computationally expensive compression

An extreme example: the Galileo Jupiter probe

- stuck high gain antenna, so must use wimpy low gain antenna

- transmission rate =  $O(10 \text{ bps})$  !

=> Use on-board computers to compress images, then transmit very slowly!

They are using JPEG compression - not quite SVD, but related. It's using fourier transform of data & only transmitting some of the modes.

You really appreciate data compression when downloading images over a modem!

~~Run matlab example~~

we'll look at SVD again later

# Systems of linear equations

## Summary of Solution approaches

$$\underset{\sim}{A} \underset{\sim}{x} = \underset{\sim}{b}$$

1) If  $\underset{\sim}{A}$  is square & well conditioned

a) PLU factorization (Gaussian elimination)

b)  $\underset{\sim}{A}^{-1}$  so  $\underset{\sim}{x} = \underset{\sim}{A}^{-1} \underset{\sim}{b}$

- convenient, but

- squares  $\text{cond}(\underset{\sim}{A})$  & takes 3x longer.

c) If  $\underset{\sim}{A}$  is sparse special techniques are much faster

2) If  $\underset{\sim}{A}$  is square but close to singularity

a) QRP factorization  
(zero out rows of  $\underset{\sim}{R}$  which are very small)

b) SVD

(zero out singular values which are very small)

$\Rightarrow$  computationally intensive, but guaranteed to get sol'n w/ min 2-norm

3) If  $A$  is overdetermined ( $n > m$ )  
 $\tilde{x}$  - often occurs in regression

a) QRP

b) 
$$\underset{\tilde{x}}{A^T A} \underset{\tilde{x}}{x} = \underset{\tilde{b}}{A^T} \underset{\tilde{b}}{b}$$

both  
minimize  
2-norm of  
residual

- square.  $m \times m$  problem
- solve via LU, inverse, etc.
- if  $m$  is large, cond maybe a problem

4) If  $A$  is underdetermined ( $m > n$ )

- use SVD (min 2-norm of  $x$ )

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SVD: Uses

- 1) Solve linear equations, particularly those close to singularity
- 2) Get approx solutions which yield more robust control by zeroing out smallest singular values



3) Analyze transfer functions:

$\underline{\underline{U}}$   $\equiv$  orthonormal basis set of output vectors

$\underline{\underline{V}}$   $\equiv$  orthonormal basis set of input vectors

$\underline{\underline{\Sigma}}$   $\equiv$  amplification factors

4) Compress images  $\leftarrow$  outer product matrix yields singular values

$$\underline{\underline{A}} = \sum_i \left\{ \begin{array}{c} \underline{\underline{u}}_i \underline{\underline{v}}_i^T \sigma_{ii} \end{array} \right\}$$

col. of  $\underline{\underline{U}}$       col. of  $\underline{\underline{V}}$

- computationally expensive, but good for very large  $\underline{\underline{A}}$

5) Face detection:

The columns of  $\underline{\underline{U}}$  are an ordered (by importance) set of eigenfaces

6) Principal Component Analysis:  
By examining the projection of a data set on  $\underline{\underline{U}}$ , can distinguish pp.