

We can make a lor of assumptions, Since this is a simple geometry.  
• Steady state, so 
$$\frac{\partial V_z}{\partial t} = 0$$
  
• no flow in x - or y - directions, so  $V_x = V_y = \partial$   
• From continuity,  $\frac{\partial V_z}{\partial t} = 0$   
• the system is semi-infinite in x-direction, so  $\frac{\partial V_z}{\partial x} = 0$ .  
Therefore, N-S equation reduces to the following:  
 $0 = -\frac{\partial P}{\partial t} + \mu \frac{\partial^2 V_z}{\partial y^2} + \beta g_z$ 

We know that both  $-\frac{\partial P}{\partial z}$  and  $\int g_z$  are constraints, so let  $\int = -\frac{\partial P}{\partial z} + p g_z$  I.) Continued

Then we have the following 2nd order ODE:  $\begin{pmatrix} no-sl;r \end{pmatrix}$  (i)  $V_{z} = 0$ with B.C.  $V_{z+B}$  $\frac{\partial^2 V_2}{\partial y^2} = -\frac{\int^2}{\mu}$  $\left(SYAMETRY\right)\left(ii\right) \left.\frac{\partial V_{z}}{\partial y}\right|_{y=0} = \partial$  $\frac{\partial}{\partial \gamma} \left( \frac{\partial V_z}{\partial \gamma} \right) = -\frac{1}{\mu}$  $\int \partial \left( \frac{\partial V_{*}}{\partial Y} \right) = \int -\frac{1}{\mu} dy$  $\Rightarrow$  from B.L. (ii)  $\frac{\partial V_{\ast}}{\partial y} = \frac{\Gamma}{M} y + C,$  $\zeta_1 = D$  $\int \partial V_z = \int \frac{-\Gamma}{\mu} y \, dy$ =7 from B.L. (i)  $V_2 = -\frac{\int 1}{\mu} \frac{1}{2} \gamma^2 + C_2$  $C_{2} = \frac{\int B}{2\mu}$ 50  $V_{2} = -\frac{\Gamma}{2\mu} \frac{Y^{2}}{Y^{2}} + \frac{\Gamma B^{2}}{2\mu} = \frac{\Gamma B^{2}}{2\mu} \left(1 - \frac{Y^{2}}{B^{2}}\right)$ 

(2)

1.) continuel:  
Now for the flow rate:  

$$Q = \int \underbrace{\psi \cdot \underline{A} \, dA}_{P}$$

$$= \int_{0}^{W} \int_{0}^{B} \frac{\Gamma B^{2}}{2\mu} \left(1 - \frac{y^{2}}{B^{2}}\right) dx dy$$

$$= \frac{\Gamma B^{2}}{2\mu} W \left[ \left( \frac{y}{y} - \frac{y^{3}}{3B^{2}} \right)_{-B}^{P} \right]$$

$$= \frac{\Gamma B^{2}}{2\mu} W \left[ \left(-B\right) + B - \frac{1}{2} \left(-\frac{B^{3}}{3B^{2}}\right) - \frac{B^{3}}{3B^{2}} \right]$$

$$= \frac{\Gamma B^{2}}{2\mu} W \left[ 2B - \frac{2B}{3} \right]$$

$$Q = 2 \frac{\Gamma B^{3}}{3\mu} W \qquad \text{where } W = \text{width}_{DT} \text{ channel } (x-\text{dir})$$

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To calculare the force exerted by the fluid on the wall, Use Newton's law of Viscosity.  $T_{yz} = -\mu \frac{\partial V_z}{\partial y}$ 

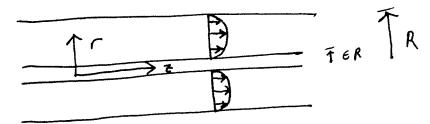
l.)

$$\begin{split} & \gamma_{\gamma z} \Big|_{\gamma = B} = -\mu \left[ -\frac{\Gamma}{\mu} \gamma \right]_{\gamma = B} \\ & \overbrace{\gamma_{\gamma z} = \Gamma B} \\ & \overbrace{\gamma_{\gamma z} = \Gamma B} \\ & This is rhotore on one wally double inforborh walls. \\ & To include or neglecr gravity, just rememberthat  $\Gamma = -\frac{\partial P}{\partial z} + gg_z$ . So, for each case:  
(a) no gravity:  
•  $\Gamma$  decreases, so  $V_z$  also decreases.  
•  $\gamma_{\gamma z}$  also decreases by  $gg_z B$ .  
(b) with gravity  
•  $V_z$  increases.  
•  $\gamma_{\gamma z}$  increases.$$



(I)

2. Pressure - driven flow through a pipe with a concentric wire:



Starr with the Navier-Stokes equation in radial Coordinates.

$$\begin{split} \mathcal{P}\left(\frac{\partial v_{z}}{\partial t} + v_{r}\frac{\partial v_{z}}{\partial r} + \frac{v_{s}}{r}\frac{\partial v_{z}}{\partial s} + \frac{v_{s}}{\partial s}\frac{\partial v_{z}}{\partial t}\right) &= -\frac{\partial P}{\partial t} + \frac{1}{2}\left[\frac{\partial v_{s}}{\partial r}\right] \\ &+ \frac{1}{r^{2}}\frac{\partial^{2} v_{z}}{\partial s^{2}} + \frac{\partial^{2} v_{z}}{\partial t^{2}}\right] + \mathcal{G}\mathcal{G}\mathcal{F} \end{split}$$

Then:

$$0 = -\frac{\partial P}{\partial z} + \frac{\mu}{\Gamma} \frac{\partial}{\partial r} \left( r \frac{\partial v_z}{\partial r} \right) + g g_z.$$

Again, let 
$$\Gamma = -\frac{\partial P}{\partial z} + ggz$$
, but gravity is unimportant, so:  

$$\Gamma = -\frac{\partial P}{\partial z}$$

2.) contributed  
We are let 
$$r$$
 with the following ODE:  

$$\frac{\partial}{\partial r} \left( r \frac{\partial V_2}{\partial r} \right) = -\frac{\Gamma}{\mu} r$$
with  $B.C.$ :  

$$\left( rostip \right) (i) V_2 \Big|_{r=R} = 0$$

$$\int d \left( r \frac{\partial V_2}{\partial r} \right) = \int -\frac{\Gamma}{\mu} r dr$$

$$\frac{d V_2}{d r} = -\frac{\Gamma}{2\mu} r + \frac{C_1}{r} r^2$$

$$\int d V_2 = -\frac{\Gamma}{2\mu} r + \frac{C_1}{r} dr$$

$$V_2 = -\frac{\Gamma}{4\mu} r^2 + C_1 \ln r + C_2$$

$$Apply both boundary conditions, we get  $2e_2$ . &  $2$  unknowns,  
 $C_1 \& C_2$ .  

$$0 = -\frac{\Gamma}{4\mu} R^2 + C_1 \ln R + C_2 e_1. (i)$$

$$0 = -\frac{\Gamma}{4\mu} e^2 R^2 + C_1 \ln (eR) + C_2 e_1. (i)$$

$$\int d V_2 = -\frac{\Gamma}{4\mu} e^2 R^2 + C_1 \ln (eR) + C_2 e_1. (i)$$$$

 $\geq$ 

2.) continued  

$$-\frac{\Gamma}{4\mu}R^{2} + C_{1}\ln R = -\frac{\Gamma}{4\mu}\epsilon^{2}R^{2} + C_{1}\ln(\epsilon R)$$

$$C_{1}\left(\ln R - \ln(\epsilon R)\right) = \frac{\Gamma R^{2}}{4\mu}(1 - \epsilon^{2})$$

$$C_{1}\left(\ln\left(\frac{R}{\epsilon R}\right)\right) = \frac{\Gamma R^{2}}{4\mu}(1 - \epsilon^{2})$$

$$\frac{C_{1}}{4\mu} = \frac{\Gamma R^{2}}{4\mu}\left(1 - \epsilon^{2}\right)$$
Substitute back into  $e_{T}$ . (i):

 $\overline{\mathcal{T}}$ 

$$O = -\frac{\Gamma}{4\mu} R^{2} + \frac{\Gamma}{4\mu} \frac{R^{2}}{\ln(\gamma_{e})} \ln R + C_{2}$$
  
So  $C_{2} = \frac{\Gamma}{4\mu} R^{2} + \frac{\Gamma}{4\mu} \frac{R^{2}}{\ln(\gamma_{e})} \ln R$ 
  
So  $V_{2} = -\frac{\Gamma}{4\mu} r^{2} + \frac{\Gamma}{4\mu} \frac{R^{2}}{\ln(\gamma_{e})} \ln r + \frac{\Gamma}{4\mu} \frac{R^{2}}{\ln(\gamma_{e})} \ln r$ 
  
This can be simplified (a limble), to:
  
 $V_{2} = \frac{\Gamma}{4\mu} R^{2} \left[ 1 - \frac{r^{2}}{R^{2}} + \frac{(1-\epsilon^{2})}{\ln(\gamma_{e})} \ln r - \frac{(1-\epsilon^{2})}{\ln(\gamma_{e})} \ln R \right]$ 
  
and a limble more:

2. Continued  

$$V_{\overline{z}} = \frac{\Gamma R^{2}}{\Psi \mu^{k}} \left[ 1 - \frac{r^{2}}{R^{2}} + \frac{(1 - \ell^{2})}{\Gamma \sqrt{4}\ell} \ln \left[ \frac{\Gamma}{R} \right] \right]$$
Now for the flow rate:  $Q = \int \vec{U} \cdot \vec{r} \, dA$   

$$Q = \int_{0}^{2\pi} \int_{\ell R}^{R} V_{\overline{z}} r \, dr \, d\Theta = 2\pi \int_{\ell R}^{R} V_{\overline{z}} r \, dr$$

$$= 2\pi \frac{\Gamma R^{2}}{\Psi \mu} \int_{\ell R}^{R} \left[ r - \frac{r^{3}}{R^{2}} + \frac{(1 - \ell^{2})}{\ln (\ell_{\theta})} r \ln \left[ \frac{\Gamma}{R} \right] \right] dr$$

$$\int_{\ell R}^{R} r \ln r \, dr + \int_{\ell R}^{R} r \ln R \, dr$$

$$= \int_{\ell R}^{R} r \ln \left[ \frac{\Gamma}{R} \right] dr = \left[ \frac{1}{2} r^{2} \ln r - \frac{1}{4} r^{2} - \frac{1}{2} r^{2} \ln R \right]_{\ell R}^{R}$$
So:  $(substrute back into the whole integral)$ 

$$Q = \frac{2\pi \Gamma R^{3}}{\Psi \mu} \left[ \frac{r^{2}}{2} - \frac{r^{4}}{\Psi R^{4}} + \frac{(1 - \theta)}{\ln (\ell_{\theta})} \left( \frac{1}{2} r^{3} \ln r - \frac{1}{4} r^{2} - \frac{1}{2} r^{2} \ln R \right]_{\ell R}^{R}$$

 $\sim$ 

2.) continued:  

$$Q = \frac{2 \pi \int^{T} \frac{R}{4}}{\frac{4}{\mu}} \left[ \left( \frac{R^{2}}{2} - \frac{\epsilon^{2} R^{2}}{2} \right) - \left( \frac{R^{2}}{4} - \frac{\epsilon^{2} R^{2}}{4} \right) + \frac{(1 - \epsilon^{2})}{\ln[1/\epsilon]} \left( \frac{\epsilon}{4} \right) \right]$$

$$= \left( \frac{R^{2} \ln R}{2} - \frac{\epsilon^{2} R^{2} \ln[\epsilon R]}{2} \right) - \left( \frac{R^{2}}{4} - \frac{\epsilon^{2} R^{2}}{4} \right)$$

$$= \left( \frac{R^{2}}{2} - \frac{\epsilon^{2} R^{2}}{2} \right) \ln \left( \frac{R}{\epsilon \mu} \right) - \frac{R^{2}}{4} \left( 1 - \epsilon^{2} \right)$$

$$= \frac{R^{2}}{4} \left( 2 - 2\epsilon^{2} \right) \ln \left( \frac{1}{\epsilon \mu} \right) - \left( 1 - \epsilon^{2} \right) - \left( 2 - 2\epsilon^{2} \right) \ln R \right]$$

$$= \frac{R^{2}}{4} \left[ \left( 2 - 2\epsilon^{2} \right) \ln \left( \frac{1}{\epsilon \mu} \right) - \left( 1 - \epsilon^{2} \right) \right]$$

Factor out 
$$\frac{R^2}{4}$$
 from the entire expression for Q:  

$$Q = \frac{2 \pi \Gamma R^4}{16 \mu} \left[ \left( 2 - 2 \epsilon^2 \right) - \left( 1 - \epsilon^4 \right) + \frac{\left( 1 - \epsilon^2 \right)}{1_n \left( \frac{1}{\epsilon_R} \right)} \left[ \left( 2 - 2 \epsilon^2 \right) \ln \left( \frac{1}{\epsilon_R} \right) - \left( 1 - \epsilon^2 \right) \right] \right]$$

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$$Q = \frac{2\pi \int_{-R^{2}}^{R} R^{2}}{\frac{\pi}{4}} \left[ \left( \frac{R^{2}}{2} - \frac{e^{2}R^{2}}{2} \right) - \left( \frac{R^{2}}{4} - \frac{e^{4}R^{2}}{4} \right) + \frac{(1 - e^{2})}{\ln(4} \right) + \frac{(1 - e^{2})}{\ln(4} \right) \right]$$

$$\# = \frac{R^{2} \ln R}{4} - \frac{e^{2}R^{2} \ln(4R)}{2} - \left( \frac{R^{2}}{4} + \frac{e^{2}R^{4}}{4} \right) - \frac{R^{2} \ln R}{4} + \frac{e^{2}R^{2} \ln R}{$$

2.) CONTINUED

No wire.  $Q_{6**} = \frac{\# \Gamma R^{4}}{8 \mu}$ 

 $if \in =0.1,$   $Q = (0.574) \frac{\pi \Gamma R^4}{8 \mu},$   $T = \frac{1}{8} \frac{1}{8} \frac{1}{8} \frac{1}{8} \frac{1}{8} \frac{1}{8} \frac{1}{1} \frac{1}$ 

Force per unit length:  

$$\gamma_{rz} = -\mu \frac{dv_z}{dr}$$

$$\begin{array}{rcl} \text{ Fe call from earlier rhar:} \\ V_{z} &= \frac{\Gamma R^{2}}{4 \mu} \left[ 1 - \frac{\Gamma^{2}}{R^{2}} + \frac{1 - 6^{2}}{\ln \left(\frac{l}{6}\right)} \ln \left(\frac{\Gamma}{R}\right) \right] \end{array}$$

$$\frac{contrinued}{\gamma_{rz}} = \frac{\Gamma}{2}r + \frac{4\kappa}{r}\frac{\Gamma}{\frac{\pi}{y_{pr}}}^{3}\frac{1-e^{2}}{\ln(\frac{1}{e})}$$

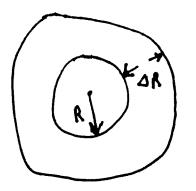
$$\gamma_{rz}\Big|_{r=eR} = \frac{\Gamma_{eR}}{2} + \frac{1}{eR}\frac{\Gamma_{R}}{\frac{\pi}{y}}\frac{(1-e^{2})}{\ln(\frac{1}{e})}$$

$$F = \gamma_{rz}A = \gamma_{rz}2\#eRL$$

$$so: \frac{F}{L} = 2\pi eR\gamma_{rz}$$

$$\frac{F/L}{L} = 2\pi e\Gamma R^{2}\left(\frac{e}{2} + \frac{1}{4}e^{-\frac{1}{\ln(\frac{1}{e})}}\right)$$

2.



Starr with the Navier - Stokes equation in Cylindrical Coordinates.

$$\begin{split} \int \left( \frac{\partial V_{\Theta}}{\partial t} + \frac{\nabla r}{\partial r} \frac{\partial V_{\Theta}}{\partial r} + \frac{V_{\Theta}}{r} \frac{\partial V_{\Theta}}{\partial \Theta} + \frac{\nabla r}{r} \frac{\partial V_{\Theta}}{\partial r} + \frac{\nabla r}{\partial \sigma} \frac{\partial V_{\Theta}}{\partial z} \right) = \\ -\frac{1}{r} \frac{\partial P}{\partial \Theta} + \mu \left[ \frac{\partial}{\partial r} \left( \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{V_{\Theta}}{\rho} \right) \right) + \frac{1}{r^2} \frac{J^2 V_{\Theta}}{\partial \theta^2} + \frac{2}{r^2} \frac{\partial V_{r}}{\partial \Theta} + \frac{\partial^2 V_{\Theta}}{\partial z^2} \right] \\ + g g_{\Theta} \end{split}$$

A Ssumptions:

• Unidirectional Flow, so  $V_r = V_z = 0$ • Continuity,  $\frac{\partial V_{\theta}}{\partial \theta} = 0$ • Steady State  $\frac{\partial V_{\theta}}{\partial t} = 0$ • Semi-infinite in z-dir  $\frac{\partial V_{\theta}}{\partial z} = 0$ • No pressure gradient in  $\theta$ -dir, no gravity in  $\theta$ -dir.

We are left with:  

$$D = \frac{d}{dr} \left( \frac{1}{r} \frac{d}{dr} (rv_{\theta}) \right)$$

Boundary conditions:  
No slip  

$$V_{0}|_{r=R} = 0$$
 (i)  
 $V_{0}|_{r=R+\Delta R} = \int (R + \Delta R)$  (ii)

$$\frac{\prod_{n} regrate}{\Gamma} \frac{\partial}{\partial r} (r V_{\theta}) = C_{1} \implies 4$$

$$\frac{\prod_{n} regrate}{\Gamma} \frac{\partial}{\partial r} (r V_{\theta}) = C_{1} \implies 4$$

$$\frac{\prod_{n} regrate}{\Gamma} \frac{\partial}{\partial r} (r V_{\theta}) = C_{1} \frac{\Gamma}{2} + C_{2}$$

$$V_{\theta} = C_{1} \frac{\Gamma}{2} + C_{2}$$

$$V_{\theta} = C_{1} \frac{\Gamma}{2} + \frac{C_{2}}{\Gamma}$$

$$\frac{A_{f} \rho V_{\theta}}{R} \frac{B.C.}{C}$$

$$(\dot{c}) \implies 0 = C_{1} \frac{R}{2} + \frac{C_{2}}{R}$$

$$(\dot{c}) \implies \Omega = C_{1} \frac{R}{2} + \frac{C_{2}}{R}$$

$$(\dot{c}) \implies \Omega = C_{1} \frac{R}{2} + \frac{C_{2}}{R}$$

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4

3. Contributed  
Solve 
$$\sum e_{Z} v_{P} v_{P} v_{P} s_{P} s_$$

$$\frac{3}{2} \underbrace{\int Continued} \\ \frac{From Newton's Law of Viscosing:}{\Gamma_{r_{\theta}} = -\mu \left[ r \frac{\partial}{\partial r} \left( \frac{V_{\theta}}{r} \right) \right]} \\ = -\mu r \left[ constraint \right] \frac{\partial}{\partial r} \left( 1 - \frac{R^{2}}{r^{2}} \right) \\ = -\mu r \left[ constraint \right] \frac{-2R^{2}}{r^{3}} \\ = \frac{2\mu R^{2}}{r^{2}} \left( \frac{\Omega R^{2}}{2RAR + \Delta R^{2}} + \Omega \right)$$

 $\overline{16}$ 

Recall that torque on the outer cylider is 
$$M = C \times F$$
  
From def. of a cross product:  

$$M = |c||F| \sin \Theta \Omega$$
and since  $\Theta = \frac{\pi}{2}$ ,  

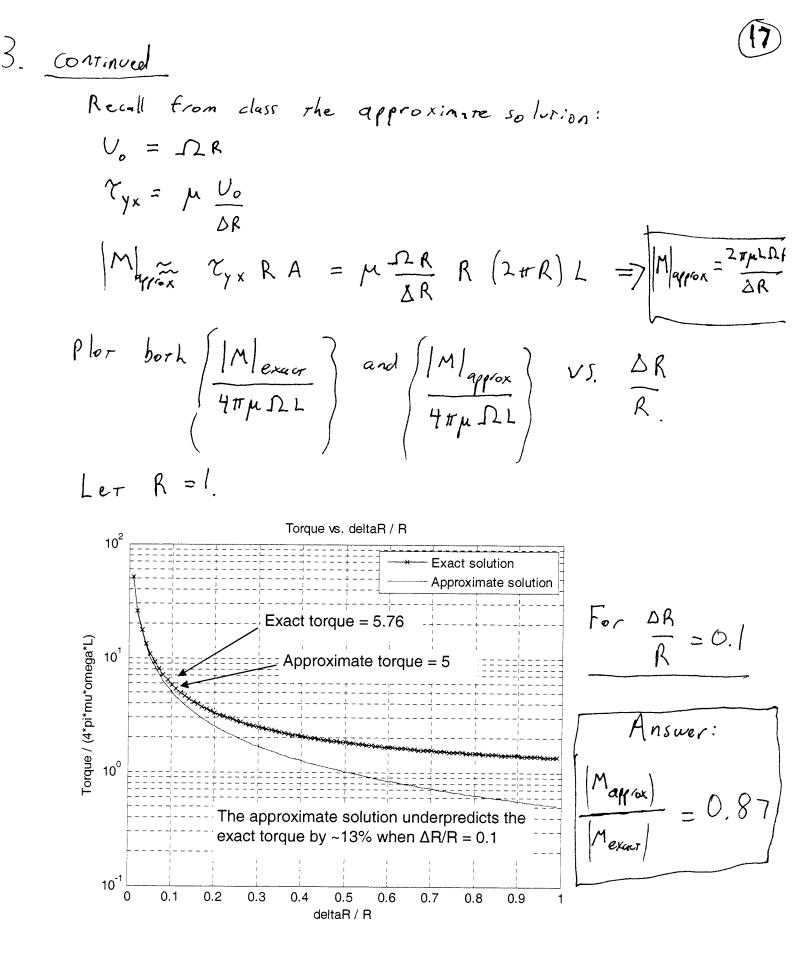
$$|M| = |r||F|$$
.  

$$F| = \gamma_{r_{\Theta}}|_{R+\Delta R}$$

$$F = (R+\Delta R)$$
So:  

$$M = 2\pi (R+\Delta R)^{2} \left(\frac{2\mu R^{2}}{(R+\Delta R)^{2}} \left(\frac{\Omega R^{2}}{2R\Delta R+\Delta R^{2}} + \Omega\right)\right)$$

$$M = 4\pi\mu L \Omega \left(\frac{R^{4}}{2R\Delta R+\Delta R^{2}} + R^{2}\right)$$



1. From 
$$HVY$$
,  

$$\frac{|V|}{|F|} = A = 0.3 \quad \frac{|V|}{|F|} = B = 0.1 \qquad \lambda_1 = B$$

$$\beta_1 = \delta_{13} \cos \theta + \delta_{11} \sin \theta$$

$$A_{13} = \lambda_1 \delta_{13} + \lambda_2 \beta_1 \beta_3$$

$$Now, if the velocity is given by:
$$V_1 = A_{13} F_3 = A_{13} F \delta_{33}$$

$$= (\lambda_1 \delta_{13} + \lambda_2 (\delta_{13} \cos \theta + \delta_{11} \sin \theta) (\delta_{33} \cos \theta + \delta_{31} \sin \theta) (\delta_{33} \cos \theta + \delta$$$$

 $U_{i} = (\lambda_{1} \delta_{i3} + \lambda_{2} (\delta_{i3} \cos \theta + \delta_{i1} \sin \theta) (\delta_{33} \delta_{31} \delta_{31})$ =  $(\lambda_{1} \delta_{i3} + \lambda_{2} (\delta_{i3} \cos \theta + \delta_{i1} \sin \theta) \cos \theta) F$ .



4. continued  
Now consider the velocity in the perpendicular case:  
$$VF_3$$
  
VF\_3

$$\frac{U_{i}}{F} = B \begin{cases} 8_{13} + (A - B)(s_{13} \cos \theta + s_{11} \sin \theta) \cos \theta \\ V & V \\ 0 & 0 & 1 \end{cases}$$

$$\frac{|V|}{|F|} = (A - B) \sin \theta \cos \theta$$

Now for the parallel case (3 - direction):  $\frac{U_3}{F} = \begin{array}{c} B 8 \\ \sqrt{33} \end{array} + (A - B) \left( \begin{array}{c} 8 \\ \sqrt{33} \end{array} \right) \left( \begin{array}{c} 8 \\ \sqrt{33} \end{array} \right) \left( \begin{array}{c} 5 \\ \sqrt{31} \end{array} \right) \left$ 

 $= B + (A - B) \cos^2 \theta$ 

$$\frac{U_1}{U_3} = \frac{(A-B) \sin \theta \cos \theta}{B + (A-B) \cos^2 \theta}$$

4. Continued  
At a maximum,  

$$\frac{d\left(\frac{U_i}{U_3}\right)}{d\theta} = 0.$$
if you grind through the derivative, you get this:  

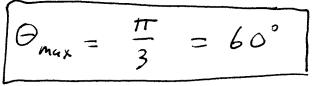
$$0 = \frac{2(A-B)^2 \sin^2 \theta \cos^2 \theta}{(B+(A-B)\cos^2 \theta)^2} + \frac{(A-B)(\cos^2 \theta - \sin^2 \theta)}{B+(A-B)\cos^2 \theta}.$$

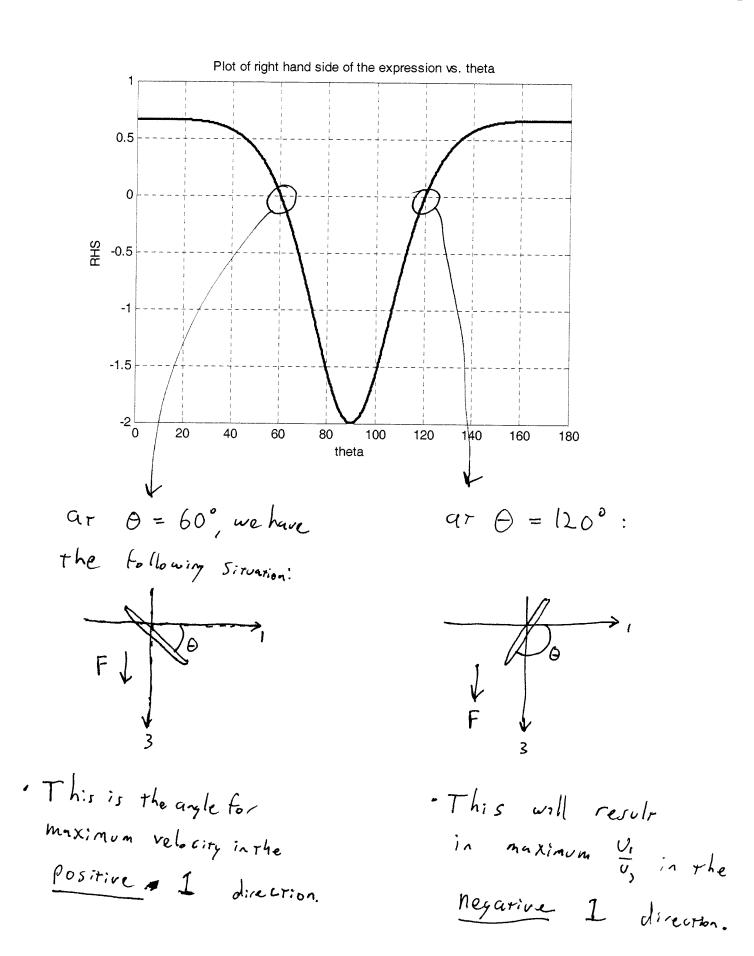
An acceptable answer would be to plot this  
expression vs. 
$$\Theta$$
 and find that  $\Theta = 60^{\circ}$   
max  
 $Or, w$  is a lot of work, you can get:  $= \frac{\pi}{3}$ .

$$\cos \Theta_{max} = \sqrt{\frac{B}{A+B}} \quad or \quad \Theta_{max} = \cos^{-1} \sqrt{\frac{O.1}{O.4}}$$

$$= los^{-1}\left(\frac{1}{2}\right)$$







[2]