# Mapping Class Groups 

Jacob Landgraf

## 1 Mapping Class Group

Definition 1. Given a compact, orientable surface $\Sigma$, the mapping class group of $\Sigma$ is defined to be

$$
\operatorname{Mod}(\Sigma):=\operatorname{Diff}^{+}(\Sigma, \partial \Sigma) / \text { isotopy }
$$

Example 1. The mapping class group of the disk $D^{2}$ is trivial.
Example 2. The mapping class group of the torus $T^{2}$ is isomorphic to $\mathrm{SL}(2, \mathbb{Z})$. To see this, consider the map

$$
\psi: \operatorname{Mod}\left(T^{2}\right) \rightarrow \operatorname{Aut}\left(H_{1}\left(T^{2} ; \mathbb{Z}\right)\right) \cong \operatorname{Aut}\left(\mathbb{Z}^{2}\right) \cong G L(2, \mathbb{Z})
$$

induced by action on homology. However, this map preserves the algebraic intersection number $\hat{i}$. Using this fact, one can show that $\psi\left(\operatorname{Mod}\left(T^{2}\right)\right) \subseteq \operatorname{SL}(2, \mathbb{Z})$. [Exercise: show that this map $\psi: \operatorname{Mod}\left(T^{2}\right) \rightarrow \mathrm{SL}(2, \mathbb{Z})$ is an isomorphism.]

To begin talking about the mapping class group, it is helpful to see some nontrivial elements. The "simplest" such nontrivial elements are obtained by twisting about simple closed curves. Let $\alpha$ be a simple closed curve in $\Sigma$, and let $N$ be a tubular neighborhood of $\alpha$. Then $N$ is diffeomorphic to the annlus $A=S^{1} \times[0,1]$. Choose an orientation-preserving diffeomorphism $\varphi: A \rightarrow N$. Define the twist map $T: A \rightarrow A$ by $T(\theta, t)=(\theta-2 \pi t, t)$.

Definition 2. The Dehn Twist about a simple closed curve $\alpha$ is the map

$$
T_{\alpha}(x)= \begin{cases}\varphi \circ T \circ \varphi^{-1}(x) & \text { if } x \in N \\ x & \text { if } x \in \Sigma \backslash N .\end{cases}
$$

Remark. If $\alpha \simeq \beta$, then $T_{\alpha} \simeq T_{\beta}$. So, it makes sense to talk about the Dehn twist about a homotopy class of curves.

Example 3. Consider the annulus $A$. One can show that $\operatorname{Mod}(A) \cong \mathbb{Z}$, where the generator is given by the Dehn twist about the core curve of $A$.

Example 4. Earlier, we saw a map $\psi: \operatorname{Mod}\left(T^{2}\right) \rightarrow \operatorname{SL}(2, \mathbb{Z})$ given by action on homology. Let's compute this map on some Dehn twists. Consider the two simple closed curves shown below.
[picture of standard simple closed curves on torus]
Dehn twisting these curves about each other, we see
[Dehn twists on torus]
Therefore,

$$
T_{a} \mapsto\left[\begin{array}{cc}
1 & 1 \\
0 & 1
\end{array}\right] \quad T_{b} \mapsto\left[\begin{array}{cc}
1 & 0 \\
-1 & 1
\end{array}\right] .
$$

Recall that these two matrices are the "standard" generators of $\operatorname{SL}(2, \mathbb{Z})$. Therefore, we have shown that $\operatorname{Mod}\left(T^{2}\right)$ is generated by $T_{a}$ and $T_{b}$.

In the these two examples, we saw that the mapping class group is finitely generated by Dehn twists. One can then ask the question: is this always the case? The answer (at least for closed surfaces) was first proven by Dehn in 1930.

Theorem 1. If $\Sigma$ is a compact, orientable surface, then $\operatorname{Mod}(\Sigma)$ is finitely generated by Dehn twists.

In proving this theorem for closed surfaces, Dehn gave a list of $2 g(g-1)$ Dehn twists which generate the mapping class group (where $g$ is the genus of the surface). This list was then improved by Lickorish and Humphries who gave collections of size $3 g-1$ and $2 g+1$, respectively.
[picture of Lickorish twists/Humphries generators]
From here, it is very natural to ask whether the mapping class group is finitely presented. The answer to this question was first proved by McCool in 1975.

Theorem 2. If $\Sigma$ is a compact, orientable surface, then $\operatorname{Mod}(\Sigma)$ is finitely presented.
McCool proved this theorem by giving an algorithm to compute the necessary relations. However, no explicit presentation has been given using this algorithm. To remedy this, Hatcher and Thurston gave a new (topologically motivated) algorithm for computing a finite presentation of $\operatorname{Mod}(\Sigma)$. This algorithm was carried out by Harer to give a concrete finite presentation. Finally, Wajnryb simplified this presentation into 5 "classes" of relations. Some of these are easy to see.

Proposition 1. (Disjointness Relation) If $a \cap b=\emptyset$, then $T_{a} T_{b}=T_{b} T_{a}$.
Proposition 2. (Braid Relation) If $a \cap b=\{*\}$, then $T_{a} T_{b} T_{a}=T_{b} T_{a} T_{b}$.

## 2 Symplectic Representation

In one of our first examples, we studied the action of $\operatorname{Mod}\left(T^{2}\right)$ on $H_{1}\left(T^{2} ; \mathbb{Z}\right)$ to show that $\operatorname{Mod}\left(T^{2}\right) \cong \mathrm{SL}(2, \mathbb{Z})$. We would like to generalize this situation to an arbitrary
compact surface. Let $b \in\{0,1\}$, and let $\Sigma_{g}^{b}$ be the surface of genus $g$ with $b$ boundary components. Then, just as in the torus case, we have a map

$$
\Psi_{0}: \operatorname{Mod}\left(\Sigma_{g}^{b}\right) \rightarrow \operatorname{Aut}\left(H_{1}\left(\Sigma_{g}^{b} ; \mathbb{Z}\right)\right) \cong \operatorname{Aut}\left(\mathbb{Z}^{2 g}\right) \cong \mathrm{GL}(2 g, \mathbb{Z})
$$

Again, we note that elements of $\operatorname{Mod}\left(\Sigma_{g}^{b}\right)$ preserve the symplectic form $\hat{i}$ (here we are using the fact that $b \in\{0,1\}$, otherwise $\hat{i}$ is not symplectic). Therefore, $\Psi_{0}\left(\operatorname{Mod}\left(\Sigma_{g}^{b}\right)\right) \subseteq \operatorname{Sp}(2 g, \mathbb{Z})$, and so we get a representation

$$
\Psi: \operatorname{Mod}\left(\Sigma_{g}^{b}\right) \rightarrow \operatorname{Sp}(2 g, \mathbb{Z})
$$

Now, we have a homomorphism out of $\operatorname{Mod}\left(\Sigma_{g}^{b}\right)$ and a set of generators of $\operatorname{Mod}\left(\Sigma_{g}^{b}\right)$ (namely, Dehn twists); how does $\Psi$ act on these generators?

Proposition 3. Let $a, b$ be (isotopy classes of) simple closed curves, then

$$
\Psi\left(T_{b}\right)([a])=[a]+\hat{i}(a, b)[b] .
$$

In the torus case, we found that this map is an isomorphism (note that $\operatorname{Sp}(2, \mathbb{Z}) \cong$ $\mathrm{SL}(2, \mathbb{Z}))$. It turns out that this is not always the case, but $\Psi$ is always at least surjective.

Proposition 4. The map $\Psi: \operatorname{Mod}\left(\Sigma_{g}^{b}\right) \rightarrow \operatorname{Sp}(2 g, \mathbb{Z})$ is surjective.
Outline of Proof. We will use three tools in this proof:
(i) There is an action of $\operatorname{Sp}(2 g, \mathbb{Z})$ on the set of symplectic bases for $H_{1}\left(\Sigma_{g}^{b} ; \mathbb{Z}\right)$ which is simply transitive. Here, a symplectic basis is a basis $\left\{a_{1}, b_{1}, \ldots, a_{g}, b_{g}\right\}$ for $H_{1}\left(\Sigma_{g}^{b}, \mathbb{Z}\right)$ such that $\hat{i}\left(a_{i}, b_{j}\right)=\delta_{i j}$ and $\hat{i}\left(a_{i}, a_{j}\right)=0=\hat{i}\left(b_{i}, b_{j}\right)$ for all $i, j$.
(ii) There is an action of $\operatorname{Mod}\left(\Sigma_{g}^{b}\right)$ on the set of geometric symplectic bases which is transitive. Here, a geometric symplectic basis is a collection of oriented simple closed curves $\left\{\alpha_{1}, \beta_{1}, \ldots, \alpha_{g}, \beta_{g}\right\}$ in $\Sigma_{g}^{b}$ such that $\left\{\left[\alpha_{1}\right],\left[\beta_{1}\right], \ldots,\left[\alpha_{g}\right],\left[\beta_{g}\right\}\right]$ is a geometric symplectic basis for $H_{1}\left(\Sigma_{g}^{b} ; \mathbb{Z}\right)$ and $i(c, d)=\hat{i}([c],[d])$ for all $c, d$ in this basis.
(iii) If $\left\{a_{1}, b_{1}, \ldots, a_{g}, b_{g}\right\}$ is a symplectic basis for $H_{1}\left(\Sigma_{g}^{b} ; \mathbb{Z}\right)$, then there exists a geometric symplectic basis $\left\{\alpha_{1}, \beta_{1}, \ldots, \alpha_{g}, \beta_{g}\right\}$ with $\left[\alpha_{i}\right]=a_{i}$ and $\left[\beta_{i}\right]=b_{i}$ for all $i$.

From here the proof goes as follows: given any $M \in \operatorname{Sp}(2 g, \mathbb{Z})$ and symplectic basis $\mathcal{B}$, apply $M$ to $\mathcal{B}$ to get a new basis $\mathcal{B}^{\prime}$. Using (iii) realize $\mathcal{B}$ and $\mathcal{B}^{\prime}$ as two geometric symplectic bases $\mathcal{A}, \mathcal{A}^{\prime}$. By (ii), there exists an element $f \in \operatorname{Mod}\left(\Sigma_{g}^{b}\right)$ taking $\mathcal{A}$ to $\mathcal{A}^{\prime}$. Therefore, $\Psi(f)$ takes $\mathcal{B}$ to $\mathcal{B}^{\prime}$. Since the action in $(i)$ is simply transitive, this implies that $\Psi(f)=M$.

A neat consequence of this proposition is that the Humphries generating set given earlier is "minimal". To see this, we must define a transvection.

Definition 3. A transvection in $\operatorname{Sp}(2 g, \mathbb{Z})$ is an element whose fixed set (in $\left.\mathbb{R}^{2 g}\right)$ has codimension 1.

We note that, by Proposition 3, the image of Dehn twists under $\Psi$ are transvections. Next, we have maps

$$
\operatorname{Mod}\left(\Sigma_{g}^{b}\right) \xrightarrow{\Psi} \operatorname{Sp}(2 g, \mathbb{Z}) \rightarrow \operatorname{Sp}(2 g, \mathbb{Z} / 2 \mathbb{Z}) .
$$

The final tool required is a proposition of Humphries which says that at least $2 g+1$ transvections are needed to generate $\operatorname{Sp}(2 g, \mathbb{Z} / 2 \mathbb{Z})$ (here a transvection of $\operatorname{Sp}(2 g, \mathbb{Z} / 2 \mathbb{Z})$ is the image of a transvection in $\operatorname{Sp}(2 g, \mathbb{Z})$ under the map above $)$. Thus, since the two maps above are surjective, we have shown that at least $2 g+1$ Dehn twists are needed to generate $\operatorname{Mod}\left(\Sigma_{g}^{b}\right)$. So, Humphries' generating set is minimal among generating sets consisting entirely of Dehn twists.

## 3 Torelli Group

In the previous section, we showed that $\Psi: \operatorname{Mod}\left(\Sigma_{g}^{b}\right) \rightarrow \operatorname{Sp}(2 g, \mathbb{Z})$ is surjective. However, $\Psi$ is not injective in general. In fact, the kernel of $\Psi$ is a heavily studied object known as the Torelli group, denoted $\mathcal{I}\left(\Sigma_{g}^{b}\right)$. From our previous computations, we can compute the Torelli group of several surfaces.

Example 5. If $\Sigma=S^{2}, D^{2}, T^{2}$, then $\mathcal{I}(\Sigma)=1$. Increasing complexity a bit, we have $\mathcal{I}\left(\Sigma_{1}^{1}\right) \cong \mathbb{Z}$, where the generator is given by the Dehn twist about the boundary component.

Once we venture a little further though, things get pretty messy, as seen by the following theorem of Mess.

Theorem 3. The Torelli group of the genus 2 surface is an infinitely generated free group.

Beyond these examples, there is no simple description for the Torelli group. So what can be said about it? As a result of the Lefshetz fixed point theorem, we get:

Theorem 4. If $g \geq 0, b \in\{0,1\}$, then $\mathcal{I}\left(\Sigma_{g}^{b}\right)$ is torsion-free.
As we did for the mapping class group, it is helpful to describe some "nice" elements of the Torelli group. There are two simple classes of elements:
(a) Separating twists: Dehn twists about separating curves.
(b) Bounding Pair maps (BP maps): a map of the form $T_{x} T_{x^{\prime}}^{-1}$, where $x$ and $x^{\prime}$ are (isotopy classes of) homologous, nonhomotopic, non-nullhomotopic simple closed curves.

Now we can ask, how much of the Torelli group do we get from separating twists and bounding pair maps.

Theorem 5. (Powell) The Torelli group $\mathcal{I}\left(\Sigma_{g}^{b}\right)$ is generated by separating twists and bounding pair maps for $g \geq 3$.

However, there are infintely many separating twists and bounding pair maps. So, is it possible to do any better? As it turns out, Johnson showed that any separating twist is a product of bounding pair maps [Exercise]. Moreover, he showed that any bounding pair map is a product of genus 1 bounding pair maps; that is, a bounding pair map such that one of the components of the surface cut along the two simple closed curves has genus 1 [Exercise]. Finally, he gave a finite (but gigantic) list of bounding pair maps which generate the Torelli group.

Theorem 6. For $g \geq 3$, the Torelli group $\mathcal{I}\left(\Sigma_{g}^{b}\right)$ is finitely generated by bounding pair maps.

Again, the next obvious question becomes: is $\mathcal{I}\left(\Sigma_{g}^{b}\right)$ finitely presented? The answer to this question is unknown. So how can we further study the Torelli group? The Torelli group came about when we explored the action of $\operatorname{Mod}\left(\Sigma_{g}^{b}\right)$ on $H_{1}\left(\Sigma_{g}^{b} ; \mathbb{Z}\right)$; that is, the first nilpotent truncation of $\pi_{1}\left(\Sigma_{g}^{b}\right)$. Therefore, to learn more about $\mathcal{I}\left(\Sigma_{g}^{b}\right)$, it may be helpful to studying the action of $\mathcal{I}\left(\Sigma_{g}^{b}\right)$ on the second nilpotent truncation of $\pi_{1}\left(\Sigma_{g}^{b}\right)$. In doing so, we will construct the Johnson homomorphism

## 4 Johnson homomorphism

Let $\mathcal{H}=H_{1}\left(\Sigma_{g}^{1} ; \mathbb{Z}\right)$ and $\pi=\pi_{1}\left(\Sigma_{g}^{1}, *\right)$, where $* \in \partial \Sigma_{g}^{1}$ (note: here we have restricted to surfaces with one boundary component precisely so that we can choose our basepoint on the boundary). Denote by $\gamma_{k}(\pi)$ the $k$-th term in the lower central series for $\pi$; that is, $\gamma_{1}(\pi)=\pi$ and $\gamma_{k}(\pi)=\left[\gamma_{k-1}(\pi), \pi\right]$ for all $k \geq 2$. The goal of this section will be to construct a homomorphism $\tau: \mathcal{I}\left(\Sigma_{g}^{1}\right) \rightarrow \bigwedge^{3} \mathcal{H}$.

We have a short exact sequence

$$
1 \rightarrow \gamma_{2}(\pi) \rightarrow \pi \rightarrow \mathcal{H} \rightarrow 1
$$

Modding out by $\gamma_{3}(\pi)$, we get the short exact sequence

$$
1 \rightarrow \bigwedge^{2} \mathcal{H} \rightarrow \pi / \gamma_{3}(\pi)=\Gamma \rightarrow \mathcal{H} \rightarrow 1
$$

Here, we are using the fact that $\gamma_{2}(\pi) / \gamma_{3}(\pi) \cong \bigwedge^{2} \mathcal{H}$. Also, note that $\bigwedge^{2} \mathcal{H}<\Gamma$ is central.

Next, there is an action of $\operatorname{Mod}\left(\Sigma_{g}^{1}\right)$ on $\pi$ which preserves $\gamma_{k}(\pi)$ (all automorphisms of $\pi$ do this). Therefore, this action descends to an action of $\operatorname{Mod}\left(\Sigma_{g}^{1}\right)$ on $\Gamma$ which preserves $\bigwedge^{2} \mathcal{H}<\Gamma$. We claim that the restriction of this action to an action of $\mathcal{I}\left(\Sigma_{g}^{1}\right)$ on $\bigwedge^{2} \mathcal{H}$ is trivial (this requires checking to make sure the action of $\operatorname{Mod}\left(\Sigma_{g}^{1}\right)$ on $\bigwedge^{2} \mathcal{H}$ is what you think it is). Therefore, if $f \in \mathcal{I}\left(\Sigma_{g}^{1}\right)$ and $x \in \Gamma$, then $x$ and $f(x)$ project to the same element of $\mathcal{H}$. It follows that $x(f(x))^{-1} \in \bigwedge^{2} \mathcal{H}$. Therefore, we get a set map $J_{f}^{\prime}: \Gamma \rightarrow \bigwedge^{2} \mathcal{H}$ defined by $J_{f}^{\prime}(x)=x(f(x))^{-1}$. Moreover, $J_{f}^{\prime}$ is a homomorphism (this relies on the fact that $\bigwedge^{2} \mathcal{H}$ is central in $\Gamma$ ), so it factors through the abelianization:


Define the map $\tau_{0}: \mathcal{I}\left(\Sigma_{g}^{1}\right) \rightarrow \operatorname{Hom}\left(\mathcal{H}, \bigwedge^{2} \mathcal{H}\right)$ via $\tau(f) \mapsto J_{f}$. Recall that we wanted a map $\tau: \mathcal{I}\left(\Sigma_{g}^{1}\right) \rightarrow \bigwedge^{3} \mathcal{H}$. To get this map, we first note that

$$
\operatorname{Hom}\left(\mathcal{H}, \bigwedge^{2} \mathcal{H}\right) \cong \mathcal{H}^{*} \otimes \bigwedge^{2} \mathcal{H} \cong \mathcal{H} \otimes \bigwedge^{2} \mathcal{H}
$$

Now, there is a canonical embedding of $\bigwedge^{3} \mathcal{H}$ into $\mathcal{H} \otimes \bigwedge^{2} \mathcal{H}$ given by

$$
a \wedge b \wedge c \mapsto a \otimes(b \wedge c)+b \otimes(c \wedge a)+c \otimes(a \wedge b)
$$

and one can show that the image of $\tau_{0}$ is contained in the image of this embedding [Exercise]. Therefore, we get our desired map $\tau: \mathcal{I}\left(\Sigma_{g}^{1}\right) \rightarrow \bigwedge^{3} \mathcal{H}$ which is called the Johnson homomorphism. An involved computation gives:

Proposition 5. - If $T_{x}$ is a separating twist, then $\tau\left(T_{x}\right)=0$.

- Suppose $T_{x} T_{x^{\prime}}^{-1}$ is a bounding pair map. Let $\Sigma^{\prime}$ be the component of $\Sigma_{g}^{1}-\left\{x, x^{\prime}\right\}$ which does not contain the boundary of $\Sigma_{g}^{1}$. Then there exists a subsurface $\Sigma^{\prime \prime} \subset \Sigma^{\prime}$ homeomorphic to $\Sigma_{h}^{1}$ for some $1 \leq h<g$. Let $\left\{a_{1}, b_{1}, \ldots, a_{h}, b_{h}\right\}$ be a symplectic basis for $\Sigma^{\prime \prime}$. Then $\tau\left(T_{x} T_{x^{\prime}}^{-1}\right)= \pm[x] \wedge\left(a_{1} \wedge b_{1}+\cdots+a_{h} \wedge b_{h}\right)$.

Playing around with the second formula, one can show:
Theorem 7. If $g \geq 2$ then $\tau$ is surjective.
Let $\mathcal{K}\left(\Sigma_{g}^{1}\right)$ be the subgroup of $\mathcal{I}\left(\Sigma_{g}^{1}\right)$ generated by separating twists. Since $\bigwedge^{3} \mathcal{H}$ is infinite for $g \geq 3$, we get the following corollary.

Corollary 1. If $g \geq 3$, then $\mathcal{K}\left(\Sigma_{g}^{1}\right)$ has infinite index in $\mathcal{I}\left(\Sigma_{g}^{1}\right)$.
From Proposition 5, it is clear that $\mathcal{K}\left(\Sigma_{g}^{1}\right) \subseteq \operatorname{ker}(\tau)$. A deep result of Johnson shows that the reverse inequality is also true.

Theorem 8. The kernel of $\tau$ is generated by separating twists.
As a final remark, since the theme of this talk has been finiteness properties, we cite a recent result of Church, Ershov, and Putman.

Theorem 9. If $g \geq 4$, then $\mathcal{K}\left(\Sigma_{g}^{1}\right)$ is finitely generated.

