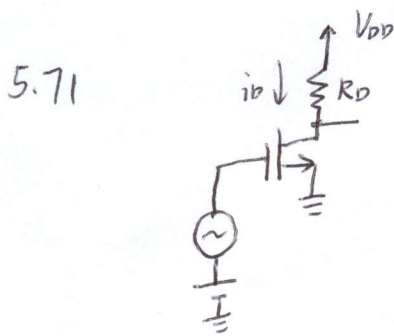


5.63 $A_v = -k_n V_{ov} R_D = \frac{-I_D R_D}{\frac{1}{2} V_{ov}}$
 $A_v = \frac{-(V_{DD} - V_{ov})}{\frac{1}{2} V_{ov}}$ for $V_{bs} = V_{ov}$

The maximum of this expression is reached at $V_{gs} = V_t$. The allowable or $V_{ov} \rightarrow 0$ signal swing becomes zero as $V_{ov} \rightarrow 0$. The condition is not a practically useful one.



(a) $I_D = \frac{1}{2} k_n V_{ov}^2 = 125 \mu A$
 $V_D = V_{DD} - I_D R_D = 0.8 V$

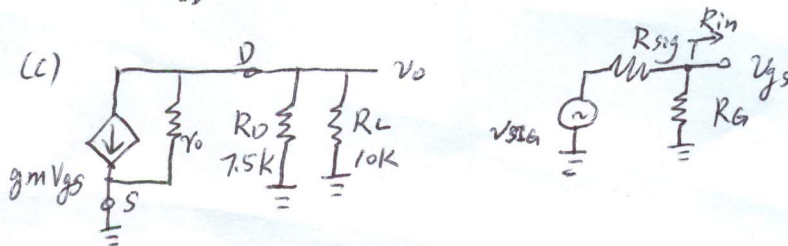
(b) $g_m = k_n V_{ov} = 1 mS$

(c) $A_v = -g_m R_D = -8.0$

(d) for $\lambda = 0.1 V^{-1}$ $r_o \approx \frac{1}{\lambda I_D} = 80 k\Omega$ $A_v = -g_m (r_o || R_D) = -7.3$

5.79 (a) $V_G = \frac{5}{15} 15 V = 5 V$, Assume $I_D = 1 mA$
 $V_s = 3 V$, $V_{gs} = 2 V$, $V_{ov} = 1 V$, $I_D = \frac{1}{2} k' V_{ov}^2 = 1 mA$
 $V_D = V_{DD} - I_D R_D = 7.5 V$

(b) $r_o = \frac{V_A}{I_D} = \frac{100 V}{1 mA} = 100 k\Omega$, $g_m = \sqrt{2 k_n I_D} = 2 mS$

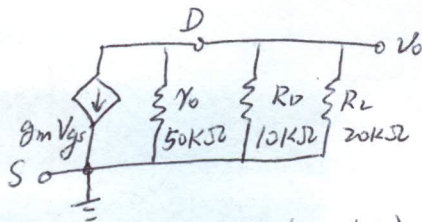
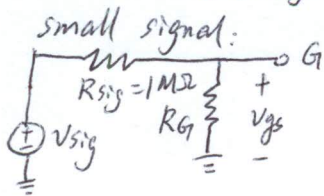


(d) $R_{in} = R_G = 3.33 M\Omega$

$\frac{V_{gs}}{V_{sig}} = \frac{R_{in}}{R_{sig} + R_{in}} = 0.97$ $\frac{v_o}{V_{gs}} = -g_m (r_o || R_D || R_L) = -8.2$ $\frac{v_o}{V_{sig}} = -8.0$

5.85

$$G_{V} = -\left(\frac{R_G}{R_G + R_{sig}}\right) g_m (r_o \parallel R_D \parallel R_L)$$



$$G_V = -\frac{R_G}{R_G + 1M\Omega} (2mA/V) (50k\Omega \parallel 10k\Omega \parallel 20k\Omega) = -\frac{R_G}{R_G + 1M\Omega} 11.76 V/V$$

If $R_G \gg 1M\Omega$, $G_V = -11.76$. otherwise, the gain is smaller.

5.93 $R_{in} = \frac{1}{g_m} = 250\Omega$

$$G_V = \frac{v_o}{v_{sig}} = \frac{R_{in}}{R_{sig} + R_{in}} g_m (R_D \parallel R_L) = 3.3 V/V$$

$g_m = \sqrt{2k_n I_D}$, so for $\frac{1}{g_m} = R_{sig}$, g_m must decrease to $1/2$ and I_D decrease to $1/4$.

