# Graph Similarity Scoring Applied to Abstract Meaning Representation

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# **Abstract Meaning Representation** (AMR)

 AMRs are a semantic formalism which models sentences



# **Abstract Meaning Representation** (AMR)

- AMRs are a semantic formalism which models sentences
  - Nodes represent concepts
  - Edges represent relations between concepts
    - Semantic roles
    - ARG0 = Agent
    - ARG1 = Patient
    - Example AMR for sentence: "John wants Mary to believe him."



## **Properties of AMRS as Graphs**

- Some properties of AMRs
  - Directed Acyclic Graphs (DAGs)
  - Single rooted (focus of sentence)
  - Each AMR represents a sentence

### Dataset

- Set of 10,312 AMRs from various news sources
- Average number of nodes is: 17.1
- Average number of edges is: 17.1
- More than half are trees

# **Kernel: Graph Similarity Scoring**

- Use some AMRs for training
  - Given multiple candidate AMRs, choose best one
  - Need a way to score each choice
  - Want pairwise digraph similarity score
- Typical metric used for AMRs is SMATCH



## **SMATCH Score**

- Semantic Match score
  - Find best matching of nodes
  - Score based on node and edge labels
  - F1 score
    - Node label
    - For each edge: edge type and end points

## **Basic Implementation Pseudocode**

Algo	orithm 1 Basic SMATCH pseudocode	20:	proc
1. r	procedure CETSMATCH(A B)	21:	a
1. 1	TI 0	22:	S
2:	$maxF1 \leftarrow 0$	23:	fe
3:	for mapping in $nodeMapping(a,b) do$	24:	
4:	$correct \leftarrow 0$	25:	
5:	for alignedPair in mapping do	26:	
6:	if labels match then	27:	
7:	$correct \leftarrow correct + 1$	28:	
8:	for edges in a do	29:	r
9:	replace end-points with aligned node	es from	b
10:	if new edge exists in b then		
11:	$correct \leftarrow correct + 1$		
12:	$precisionDenominator \leftarrow$ number of tr	iples in	b
13:	$recall Denominator \leftarrow$ number of triple	s in a	
14:	$precision \leftarrow correct/precisionDenomin$	nator	
15:	$recall \leftarrow correct/recallDenominator$		
16:	$f1 \leftarrow (recall + precision)/2$		
17:	if $f1 > maxF1$ then		
18:	$maxF1 \leftarrow f1$		
19:	return $maxF1$		

procedure NODEMAPPING(A,B)
allAlignments $\leftarrow$ empty
Select $node_a$ in a
for $node_b$ in b do
newAlignments $\leftarrow$ align $node_a$ to $node_b$
$newA \leftarrow a - node_a$
$newB \leftarrow b - node_b$
newAlignments $\leftarrow$ nodeMapping(newA, newB)
append newAlignments to allAlignments
return allAlignments

# **Basic Implementation Pseudocode**

Algo	prithm 1 Basic SMATCH pseudocode		
1: 1	procedure GETSMATCH(A,B)		
2:	$maxF1 \leftarrow 0$		
3:	for mapping in nodeMapping(a,b) do		
4:	$correct \leftarrow 0$		
5:	for alignedPair in mapping do		
6:	if labels match then		
7:	$correct \leftarrow correct + 1$		
8:	for edges in a do		
<mark>9</mark> :	replace end-points with aligned nodes from b		
10:	if new edge exists in b then		
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### Find all ways to match nodes in A with nodes in B

## **Basic Implementation Pseudocode**

Algorithm 1 Basic SMATCH pseudocode		20: p	rocedure 1
1: p	procedure getSMATCH(A,B)	21: 22:	Select no
2:	$maxF1 \leftarrow 0$	23:	for node
3:	for mapping in nodeMapping(a,b) do	24:	newA
4:	$correct \leftarrow 0$	25:	newA
5:	for alignedPair in mapping do	26:	newB
6:	if labels match then	27:	newA
7:	$correct \leftarrow correct + 1$	28:	appen
8:	for edges in a do	29:	return a
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### Check if node labels match and if edge labels match

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# Complexity

- Most direct way (previous slide) has complexity ~O(N!/(N-M)!\*|M+E|)
  - N = number of nodes in larger graph
  - M = number of nodes in smaller graph
  - E = number of edges in smaller graph
- In practice, heuristics are used
  - Faster, but no optimality guarantee

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– I want to avoid heuristics

### Improvements

- Combine mapping and scoring
  - Score nodes as they are matched
  - Avoids recomputing
- Score likely alignment first, use as cutoff
  - Number incorrect is cutoff threshold
  - Can avoid unnecessary computation
- Send subgraphs to worker processes for parallelism

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# **New Complexity**

- Previously ~O(N!/(N-M)!\*|M+E|)
- Now ~O(N!/(N-M)!\*|E|) in worst case, ~O(N!/(N-M)!) in average case
- Worst case complexity not improved greatly
- Better in practice using cutoff to eliminate parts of search space
- Effectiveness increases as SMATCH increases

# Implementation

- Implemented in Python 2.7
- Uses NetworkX
- Uses Multiprocessing library
- ~500 lines of code (separate functions for basic vs enhanced vs parallel, so some repetition)

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# **Generating Candidate AMRs**

In practice we use SMATCH on AMRs that are similar

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 Imitate this by randomly rewiring edges, relabeling edges, and relabeling nodes





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# Conclusions

- While the worst case complexity remains bad, typical use can be made much better
- Prune search space by not pursuing bad subgraphs
- Parallelize subgraph search
- Most effective when candidate is close to correct (high SMATCH)

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