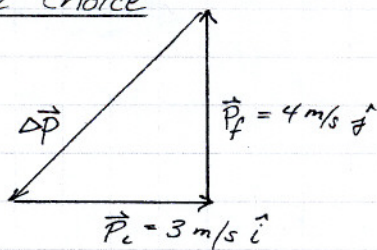


I. Multiple Choice

1. (b)



$$\Delta \vec{p} = \vec{p}_f - \vec{p}_i, = \vec{J} = \vec{F} \Delta t$$

$$|\Delta \vec{p}| = |\vec{F}| \Delta t, \quad 5 = F(0.5)$$

$$\underline{10 \text{ N} = F}$$

2. (b)

$$mv_i + MV_i = (m+M)v_f \Rightarrow -(500)(2 \text{ m/s}) + (2000)(5 \text{ m/s}) = 9000 \text{ kg m/s}$$

$$9000 = 2500 v_f, \quad v_f = 3.6 \text{ m/s} \Rightarrow KE_f = \frac{1}{2}(2500)(3.6)^2$$

$$= 16,200 \text{ J}$$

$$KE_i = \frac{1}{2}Mv_i^2 + \frac{1}{2}mv_i^2 = \frac{1}{2}(2000)(5)^2 + \frac{1}{2}(500)(2)^2 = 26,000 \text{ J}$$

$$KE_f/KE_i = \underline{0.623}$$

3. (e)

two ways: $\alpha = \frac{\Delta \omega}{\Delta t} = -\frac{2\pi}{10}, \quad \omega^2 = \omega_0^2 + 2\alpha(\Delta \theta), \quad 0 = (2\pi)^2 - 2\left(\frac{2\pi}{10}\right)\Delta \theta$

$$4\pi^2 = \frac{4\pi}{10}\Delta \theta, \quad \underline{\Delta \theta = 10\pi}$$

or: $\theta_f = \omega_0 t + \frac{1}{2}\alpha t^2 = (2\pi)(10) - \frac{1}{2}\left(\frac{2\pi}{10}\right)(100) = 20\pi - 10\pi = \underline{10\pi}$

4. (d)

Use the Parallel Axis Theorem: $I = I_{cm} + Mh^2$, where h is the distance to the new axis. Since $R_2 > R_1$,

$$I_2 = I_{cm} + MR_2^2 > I_1 = I_{cm} + MR_1^2 > I_{cm}$$

5. (d)

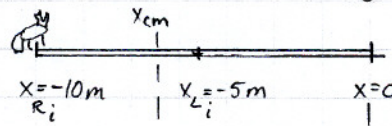
$$P = \tau \cdot \omega = 50,000 \times \left(\frac{100 \text{ rev.}}{\text{min.}} \cdot \frac{1 \text{ min.}}{60 \text{ sec.}} \cdot \frac{2\pi}{1 \text{ rev.}} \right) = \underline{523 \text{ kW}}$$

or, $P = F \cdot v$, @ 0.5 m radius, a torque of 50,000 N requires a force of 100,000 N. The angular velocity is 10.47 rad/s, which implies a linear velocity of 5.23 m/s at the edge of the winch. $F \cdot v = (100,000)(5.23) = \underline{523 \text{ kW}}$

Problems

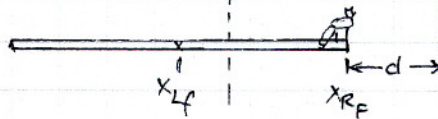
II. There are a couple of different ways to solve this problem
Center of Mass (Isolated System) $\rightarrow$ CoM remains in same place.

Initially:



$$x_{cm} = \frac{m_R x_{Ri} + M_L x_{Li}}{m_R + M_L} = \frac{(25)(-10) + (100)(-5)}{125} = -6m$$

Finally



$$x_{Rf} = -d, \quad x_{Lf} = -(5+d)$$

$$x_{cm} = -6m = \frac{25(-d) + 100(-(5+d))}{125}$$

$$250 = 125d \quad \Leftarrow \quad 750 = 25d + 500 + 100d \quad \Leftarrow$$

$$\underline{d = 2m} \rightarrow \text{answer to (b)}$$

Then, for (a) we know the raccoon moves with $u = 0.1 \text{ m/s}$ with respect to the log, so it takes him $(0.1)t = 10m$, $t = 100 \text{ sec}$ to walk the length of the log. In that time, the log moves $\underline{-2m}$, so, $v_{\log(100)} = -2$, $\underline{v_{\log} = -0.02 \hat{i} \text{ m/s}} \rightarrow (a)$

Conservation of Momentum: (a.) $\vec{P}_{tot} = 0 \Rightarrow m\vec{V}_{R,s} + M\vec{V}_{L,s} = 0$, where

$$\vec{V}_{R,s} = \vec{V}_{R,L} + \vec{V}_{L,s}$$

(velocity of raccoon w.r.t. shore is the velocity of raccoon w.r.t. log plus vel. log w.r.t. shore).

$$\text{So, } m\vec{V}_{R,s} = -M\vec{V}_{L,s}, \quad \vec{V}_{R,s} = -\frac{M}{m}\vec{V}_{L,s} \Rightarrow -\frac{M}{m}\vec{V}_{L,s} = \vec{V}_{R,L} + \vec{V}_{L,s}$$

$$-\vec{V}_{L,s} \left(1 + \frac{M}{m}\right) = \vec{V}_{R,L}, \quad \vec{V}_{L,s} = -\frac{\vec{V}_{R,L}}{1 + \frac{M}{m}} = -\frac{1}{5}\vec{V}_{R,L} = \underline{-0.02 \text{ m/s} \hat{i}}$$

(b.) It takes the raccoon $v \cdot t = d \Rightarrow t = \frac{d}{v} = \frac{10}{0.1} = 100 \text{ sec}$ to travel down the log. If the log moves at -0.02 m/s , then it will move $\underline{-2m}$ during this time.

Problems, (cont.)

III a.) Conservation of Momentum - Inelastic Collision

$$mv_i = (M+m)v_f, \quad v_f = \frac{m}{m+M} v_i = \frac{0.005}{20.005} (1000 \text{ m/s}) = 0.25 \text{ m/s}$$

b.) Conservation of Energy: $KE_i = U_f \Rightarrow \frac{1}{2}(m+M)v_f^2 = \frac{1}{2}kx^2$

$$\frac{1}{2}(20.005)(0.25)^2 = \frac{1}{2}(500)x^2, \quad x = 0.05 \text{ m} = 5 \text{ cm}$$

c.) Work-Energy Theorem: $E_f - E_i = W_{\text{ext}}, \quad W_{\text{ext}} = W_{F_k} = -F_k \cdot x$
(Friction does negative work)

$$U_f - U_i + KE_f - KE_i = -F_k \cdot x, \quad \frac{1}{2}kx^2 - \frac{1}{2}(m+M)v^2 = -F_k \cdot x$$

$$\frac{1}{2}kx^2 + F_k \cdot x - \frac{1}{2}(m+M)v^2 = 0 \Rightarrow \text{calculate numerical coefficients, use quadratic equation to solve for } x.$$

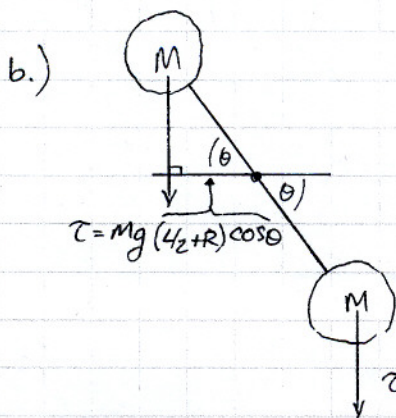
$$F_k = \mu_k N = \mu_k Mg = 39.2 \text{ N}, \quad \frac{1}{2}(m+M)v^2 = 0.625 \text{ J}$$

$$\text{So, } 250x^2 + 39.2x - 0.625 = 0, \quad x = \frac{-39.2 \pm \sqrt{(39.2)^2 + 4(250)(0.625)}}{500}$$

$$x = \frac{-39.2 \pm 46.5}{500} \xrightarrow{\text{choose } \oplus} = 0.015 \text{ m} = \underline{\underline{1.5 \text{ cm}}}$$

IV a.) $I = \frac{1}{12}mL^2 + 2\left(\frac{2}{5}MR^2 + M(R+L/2)^2\right)$

→ Parallel Axis Theorem



$$\sum \tau = Mg(L/2 + R)\cos\theta - Mg(L/2 + R)\cos\theta + 0 = 0$$

(c) $\tau = R_i F = (44)(L/2 + R) = \underline{\underline{8.8 \text{ Nm}}}$

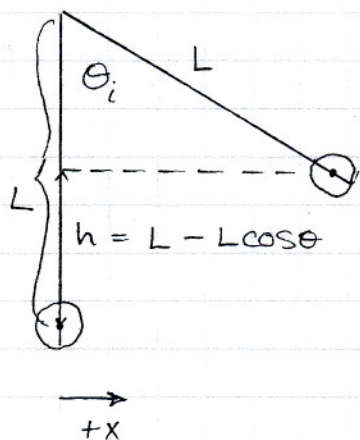
d.) $\tau = I\alpha, \quad 8.8 \text{ Nm} = I(10 \text{ rad/s}^2), \quad I = 0.88$

$$I = \frac{1}{12}mL^2 + 2M\left(\frac{2}{5}R^2 + (R+L/2)^2\right) = 0.00067 + M(0.088) = 0.88$$

$$\boxed{M = 10 \text{ kg}}$$

Problems, (cont.)

- V a.) Use Conservation of Energy to find the bob's velocity at the bottom of its swing, given the starting angle.



$$mg(L - L\cos\theta_i) = \frac{1}{2}m_p v_f^2$$

$$v_f^2 = gL(1 - \cos\theta_i), \quad v_f = \sqrt{gL(1 - \cos\theta_i)} = \underline{-3.54 \text{ m/s } \hat{i}}$$

- b.) Use conservation of Energy again on the upswing:

$$\frac{1}{2}m_p v_i^2 = m_p gL(1 - \cos\theta_f)$$

$$v_i^2 = gL(1 - \cos\theta_f), \quad \underline{v_i = 0.4 \text{ m/s } \hat{i}}$$

- c.) For an elastic collision, we can relate the velocities by:

$$v_i + v_f = v_i + v_f, \quad \text{let } v \text{ correspond to the block, } v_i \text{ to bob}$$

$$v_f = -3.54 + 0.4 = \underline{-3.14 \text{ m/s } \hat{i}}$$

- d.) Using conservation of momentum:

$$m_b v_f + m_p v_f = m_p v_i \Rightarrow m(-3.14) + m_p(0.4) = m_p(-3.54)$$

$$m(-3.14) = (0.4)(-3.94)$$

$$\boxed{m = 0.5 \text{ kg}}$$