

Problem 1



At Equil point

$$F_E = F_M \Rightarrow \frac{M_E}{S_E^2} = \frac{M_M}{S_M^2} \Rightarrow \frac{S_M^2}{S_E^2} = \frac{M_M}{M_E} \Rightarrow S_M = \sqrt{\frac{M_M}{M_E}} S_E$$

$$\tan \theta = \frac{x}{r}$$



$$|F| = \frac{GMm}{r^2 + x^2}$$

Components

$$F_r = |F| \cos \theta$$

$$F_x = -|F| \sin \theta$$

$$\tan \theta = \frac{x}{r} \approx \theta \approx \sin \theta$$

$$\cos \theta \approx 1 - \frac{x^2}{2r^2}$$

$$F_r \approx \frac{GMm}{r^2 + x^2} \left(1 - \frac{x^2}{2r^2}\right)$$

$$F_x \approx -\frac{GMm}{r^2 + x^2} \frac{x}{r}$$

$$(r^2 + x^2)^{-1} \approx r^{-2} \left(1 - \frac{x^2}{r^2} + \dots\right)$$

$$F_r = (GMm) r^{-2} \left(1 - \frac{x^2}{r^2}\right) \left(1 - \frac{x^2}{2r^2}\right) \approx \frac{GMm}{r^2} + O\left(\frac{x^2}{r^4}\right)$$

$$F_x = -(GMm) r^{-2} \left(1 - \frac{x^2}{r^2}\right) \frac{x}{r} \approx -\left(\frac{GMm}{r^2} \frac{x}{r} + O\left(\frac{x^3}{r^4}\right)\right)$$

So to order x/r

$$F_r = \frac{GM_E M}{S_E^2} - \frac{GM_M M}{S_M^2} \stackrel{F_E}{\leftarrow} \stackrel{F_M}{\rightarrow} = 0$$

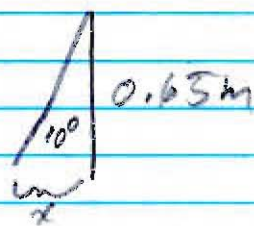
$$F_x = -\left(\frac{GM_E M}{S_E^2} \frac{x}{S_E} + \frac{GM_M M}{S_M^2} \frac{x}{S_M}\right) = -GM \left(\frac{M_E}{S_E^3} + \frac{M_M}{S_M^3}\right) x$$

Restoring Force $\propto x \Rightarrow$ SHO

$$S_M = \left(\frac{M_M}{M_E}\right)^{1/2} S_E$$

$$F_x = -GM \left(\frac{M_E}{S_E^3} + \frac{M_M}{M_E \sqrt{\frac{M_M}{M_E}} S_E^3}\right) x = -GM \frac{M_E}{S_E^3} \left(1 + \sqrt{\frac{M_E}{M_M}}\right) x$$

Problem 2



$$\omega = \sqrt{\frac{g}{L}} = \sqrt{\frac{9.8}{0.65}} = 0.26 \text{ rad/s}$$

$$\sin \theta = \frac{x}{0.65}$$

$$x = 0.65 \sin 10^\circ = A_p = 0.113 \text{ m}$$

$$x = A_p \cos \omega t$$

$$v_x = -A \omega \sin \omega t = -0.0293 \sin 0.26 t$$

v_x relative to pivot point

$$\frac{d}{dt} \downarrow x_p = x + x_c$$

Position in lab

$$v_p = v_x + v_c$$

in lab frame

$$P_x = M_c v_c + m_p v_p = 0$$

Isolated System

$$M_c v_c + m_p (v_x + v_c) = 0$$

$$(M_c + m_p) v_c + m_p v_x = 0$$

$$v_c = -\frac{m_p}{M_c + m_p} v_x = -\frac{0.5}{1.5} v_x = -\frac{1}{3} v_x$$

$$x_c = \int v_c dt = \int -\frac{1}{3} v_x dt = -\frac{1}{3} x$$

$$= -\frac{1}{3} A_p \cos \omega t = -0.0377 \cos 0.26 t$$

$$\text{So } A_c = -0.0377$$

b) Expect cart to have SHO

$$V_c = -\frac{m_p}{m_p + m_c} v_x$$

If forget to transform $v_x \rightarrow v_p$

$$M_c v_c + m_p v_x = 0$$

$$v_c = -\frac{m_p}{m_c} v_x = -\frac{1}{2} v_x$$

$$x_c = -\frac{1}{2} x$$

$$= -\frac{1}{2} A_p \cos \omega t$$

$$= -0.057 \cos 0.26 t$$

$$\text{So } A_c = -0.057$$

Problem 3

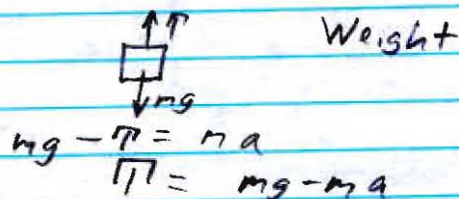
$$s = \frac{1}{2} a t^2 \Rightarrow a = \frac{2s}{t^2} = \frac{2 \cdot 1.8}{(2)^2} = 0.9 \text{ m/s}^2$$

$$\tau = r \times F = I \alpha$$

$$r \pi = I \alpha$$

$$I = M r^2$$

$$r \alpha = a$$



$$\rightarrow r \pi = M r^2 \frac{a}{r} = M r a$$

$$M = \frac{\pi}{a} = \frac{mg - ma}{a} = m \frac{g}{a} - m = m \left(\frac{g}{a} - 1 \right)$$

$$M = 4.0 \text{ kg} \cdot \left(\frac{9.8}{0.9} - 1 \right) = 39.6 \text{ kg}$$

Problem 4

$$s = \frac{1}{2} a t^2$$

$$26 \text{ m} = \frac{1}{2} 9.8 t^2 \quad t = \sqrt{\frac{26 \cdot 2}{9.8}}$$

$$= 2.30 \text{ s}$$

$$y = v_x t$$

$$= 3.6 \text{ m/s} \cdot 2.30 = 8.3 \text{ m}$$

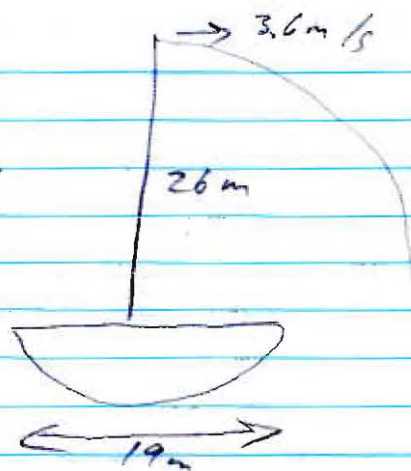
$$8.3 \text{ m} < 19/2$$

Onto Deck

Max Tilt

$$15^\circ \quad \frac{19}{2} \cos 15^\circ = 9.18 \text{ m}$$

$$8.3 \text{ m} < 9.18 \text{ m}$$



Problem 5

$$r = 4x^3 - x$$

$$s = 4x^4 - \frac{x^2}{2} + s_0 = x^4 - \frac{x^2}{2} + s_0$$

$$\Delta s = s(1.5) - s(0.5) = (1.5)^4 - \frac{(1.5)^2}{2} - (0.5)^4 + \frac{(0.5)^2}{2}$$

$$\bar{v} = \frac{\Delta s}{\Delta x} = \frac{4 \text{ m}}{1.5 - 0.5} = 4 \text{ m/s}$$

$$v_{\max} = v(1.5) = 12 \text{ m/s}$$

$$v_{\min} = v(0.5) = 0 \text{ m/s}$$

Problem 6

$$a) \quad mgh_s - mgh_f = F \cdot d$$

$$F = \mu N = \mu mg$$

$$mgh_s - mgh_f = \mu mg d$$

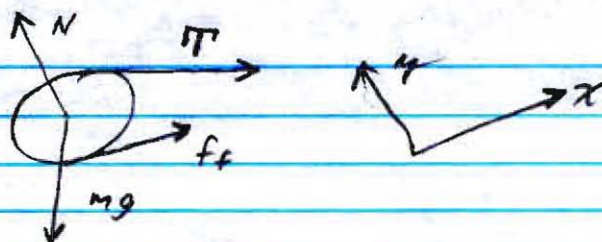
$$d = \frac{gh_s - gh_f}{\mu g} = \frac{h_s - h_f}{\mu} = \frac{1.3 - 0.55}{0.18} = 4.17 \text{ m}$$

$$b) \quad mgh_f = F \cdot d_L = \mu mg d_L$$

$$d_L = \frac{mgh_f}{\mu mg} = \frac{h_f}{\mu} = \frac{0.55}{0.18} = 3.06 \text{ m}$$

Problem 7

Forces $f_f \leq \mu_s N$



$$\begin{aligned} N &= N \hat{y} \\ \vec{F}_s &= -mg \cos \theta \hat{y} \\ &\quad - mg \sin \theta \hat{x} \\ f_f &\leq \mu_s N \\ \vec{T} &= T \cos \theta \hat{x} \\ &\quad - T \sin \theta \hat{y} \end{aligned}$$

$$(1) \quad \sum F_x = -mg \sin \theta + \mu_s N + T \cos \theta$$

$$(2) \quad \sum F_y = -mg \cos \theta + N - T \sin \theta$$

τ about center

$$\begin{aligned} Tr &= f_f r = \mu_s N r \\ T &= \mu_s N \end{aligned}$$

$$(2) \quad -mg \cos \theta + N - \mu_s N \sin \theta = 0$$

$$N(1 - \mu_s \sin \theta) = mg \cos \theta$$

$$N = \frac{mg \cos \theta}{1 - \mu_s \sin \theta}$$

$$(1) \quad -mg \sin \theta + \mu_s \frac{mg \cos \theta}{1 - \mu_s \sin \theta} + \mu_s \frac{mg \cos \theta}{1 - \mu_s \sin \theta} \cos \theta = 0$$

$$-\sin \theta + \frac{\mu_s \cos \theta}{1 - \mu_s \sin \theta} + \frac{\mu_s \cos^2 \theta}{1 - \mu_s \sin \theta} = 0$$

$$-\sin \theta + \mu_s \sin^2 \theta + \mu_s \cos \theta + \mu_s \cos^2 \theta = 0$$

$$\mu_s (\sin^2 \theta + \cos^2 \theta + \cos \theta) = +\sin \theta$$

$$\mu_s = \frac{+\sin \theta}{(1 + \cos \theta)}$$