

# Physics 10310 Exam #3 Formulas

$$g = 9.8 \text{ m/s}^2$$

$$|\vec{B}| = \sqrt{B_x^2 + B_y^2 + B_z^2} \quad \hat{i} = \hat{x}; \quad \hat{j} = \hat{y}; \quad \hat{k} = \hat{z} \quad \vec{v}_{A,C} = \vec{v}_{A,B} + \vec{v}_{B,C}$$

$$\text{Constant } a_x : \quad x = x_0 + v_{0,x}t + \frac{1}{2}a_xt^2 \quad v_x = v_{0,x} + a_xt \quad v_x^2 = v_{0,x}^2 + 2a_x(x - x_0)$$

$$\vec{v} = \frac{d\vec{r}}{dt} = v_x \hat{i} + v_y \hat{j} + v_z \hat{k} = \frac{dx}{dt} \hat{i} + \frac{dy}{dt} \hat{j} + \frac{dz}{dt} \hat{k} \quad \vec{a} = \frac{d\vec{v}}{dt} = a_x \hat{i} + \dots = \frac{dv_x}{dt} \hat{i} + \dots = \frac{d^2x}{dt^2} \hat{i} + \dots$$

$$at^2 + bt + c = 0 \rightarrow \quad t = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}; \quad \sum \vec{F} = \vec{F}_{\text{tot}} = m\vec{a} = \frac{d}{dt} \vec{p}_{\text{tot}}$$

$$W_{\text{on object}} = \int \vec{F}_{\text{on object}} \cdot d\vec{r} \quad \Delta U = -W \quad \Delta K = W \quad \Delta U_{\text{gravity}} = mg\Delta h$$

$$\text{Power} = \vec{F} \cdot \vec{v} = \vec{\tau} \cdot \vec{\omega} = W/\Delta t \quad F_{x, \text{ spring}} = -kx \quad U_{\text{spring}} = \frac{1}{2}kx^2 \quad \text{circular motion : } F_{\text{in}} = \frac{mv^2}{r}$$

$$K_f + U_f = K_i + U_i + W_{\text{into system}} \quad K_{\text{lin}} = \frac{1}{2}mv^2$$

$$|\vec{F}_{\text{kinetic friction}}| = \mu_k F_{\text{normal}} \quad |\vec{F}_{\text{static friction}}| \leq \mu_s F_{\text{normal}}$$

$$\vec{p} = m\vec{v} \quad \vec{J} = \Delta\vec{p} = \vec{p}_f - \vec{p}_i \quad \vec{v}_{\text{c.m.}} = \frac{d\vec{r}_{\text{c.m.}}}{dt} \quad \text{Elastic : } v_i + v_f = V_i + V_f$$

$$M_{\text{tot}} x_{\text{c.m.}} = \sum_i m_i x_i \quad \vec{p}_{\text{tot}} = M_{\text{tot}} \vec{v}_{\text{c.m.}} \quad U_{\text{grav}} = M_{\text{tot}} g y_{\text{c.m.}} \quad \vec{F}_{\text{net}} = \frac{d\vec{P}_{\text{c.m.}}}{dt}$$