

[time,mathptm]article

Solutions to Practice Problems Exam 1

document

The question are not guaranteed to be correct.

(3) (True/False questions)

- False. An example is obtained by taking $\vec{u} = \vec{v}$ and $\vec{w} = -\vec{v}$.
- False. An example is: $A = B = I$ (identity matrix).
- False. The set doesn't contain the zero vector.
- True. $\cos(t)$ is not a multiple of $\sin(t)$ (nor vice versa).
- True. Any spanning set contains a linearly independent spanning set.
- True. $\text{Nul}(A) = 0$ means that the columns are linearly independent.

(4) a. $H = \text{Span}(\text{bmatrix}x1$

b. The solutions are $H_1 = \text{bmatrix}x2$

(5) a. $T(\text{bmatrix}xa$

b. $T(\text{bmatrix}xa$

c. $S = \text{bmatrix}x1$

.

d. $\vec{e}_3 + \text{bmatrix}x1$

(6) a. False. $I0 = 0$.

b. False $-I + I$ is not invertible.

c. True.

d. True.

f. False. $A = 0$.

(7) a. $-KK = I$. So $(-K)K = I$. Hence by the invertible matrix theorem K is invertible.

b. Just multiple it out.

c. $KK = PJP^{-1}PJP^{-1} = PJ^2P^{-1} = P(-I)P^{-1} = -PP^{-1} = -I$.

d. There are infinitely many invertible matrices P .

(8) a. $\text{bmatrix}x01300$

b. $\text{bmatrix}x119 - a$

c. $\text{bmatrix}x \cos(\theta) - \sin(\theta)$

(9) a. No

b. Yes $x_1 = -2, x_2 = 3$.

(10) a. $a_1a_2a_3$.

b. 6.

(11) $E = \text{bmatrix}x\sqrt{[4]300}$

(12) $\det(cI - A) = c^3 - 2c$. So $cI - A$ is invertible unless $c = 0, \sqrt{2}, -\sqrt{2}$.

(13) a. Note that A is row equivalent to the reduced echelon matrix $B = \text{bmatrix}x1010$

b. The pivots in B occur in the 1st, 2nd and 4th columns. Thus columns 1, 2, 4 of A are pivot columns, hence those columns are a basis.

(14) $A\text{bmatrix}x111$

(15) Let \vec{u} be a non-zero vector in V , and let c be a scalar. Assume that $c\vec{u} = \vec{0}$. If $c \neq 0$, then we may speak of the number $1/c = c^{-1}$. Moreover, using properties of vector spaces, we see that

$$\begin{aligned}\vec{0} &= c\vec{u} \\ c^{-1}(\vec{0} = c\vec{u}) \\ 0 &= \vec{u}\end{aligned}$$

But \vec{u} is not $\vec{0}$, so the only possibility is that in fact $c = 0$.

(16) a. $T(g(t)) = \text{bmatrix}xg(0)$

b. $f \in \text{Ker}(T)$ iff $f(0) = 0$ and $f(1) = 0$. Hence $f(t) = ct(t-1)$. So $f(t) = t(t-1) = t^2 - t$ is a basis.

c. $T(1-t) = \text{bmatrix}x1$

(17) Observe that A is row equiv to the following reduced echelon matrix $\text{bmatrix}x100 - 1$

(18) Since the two elements of B are not multiples of one another, they are linearly independent. They span R^2 and hence they form a basis of R^2 .