

Math 221
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Name: _____
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1. (25 pts – 5 each.) Define the following notions:

(a). Linear independence.

(b). Orthogonal vectors.

(c). Orthogonal projection.

(d). Linear transformation.

(e). Least-square solution to $A\vec{x} = \vec{b}$.

2. (20pts – 2 each.) Mark each of the following True or False. There is no need to justify your answers.

- (a) If 3 vectors span \mathbb{R}^3 then the vectors are linearly independent.
- (b) If an $n \times n$ -matrix A is invertible then every $\vec{v} \in \mathbb{R}^n$ is in the column space of A .
- (c) If A is an 3×4 -matrix then the columns of A are linearly independent.
- (d) The map $T : \mathbf{R}^3 \rightarrow \mathbf{R}^2$ defined by $T(x, y, z) = (x - y + z, x(y + z))$ is a linear transformation.
- (e) For all matrices A, B, C , if $AC = BC$ then $A = B$.
- (f) $\text{rank}(A) = \dim \text{Nul}(A) + \dim \text{column space of } A$.
- (g) Let A be an $n \times n$ matrix then A is diagonalizable if it has n eigenvalues.
- (h) For any $m \times n$ -matrix A and any $\vec{b} \in \mathbb{R}^m$ the system $A^T A \vec{x} = A^T \vec{b}$ always has a solution.
- (i) The orthogonal projection of \vec{x} onto V is orthogonal to V .
- (j) If \hat{x} is a least square solution to $A\vec{x} = \vec{b}$ then $\vec{b} - A\hat{x}$ is orthogonal to rowspace of A .

3. (20pts.) Find a basis for the column space, a basis for the row space, a basis for the null-space, the rank, and the dimension of the null-space of

$$\begin{bmatrix} 1 & -2 & 2 & -1 \\ -3 & 6 & 1 & 10 \\ 1 & -2 & -4 & -7 \\ 1 & -2 & 2 & 0 \end{bmatrix}$$

4. (10pts.) Let $A = \begin{bmatrix} 0 & 1 & 0 & 3 \\ 0 & 0 & 1 & -2 \end{bmatrix}$ and $\vec{b} = \begin{bmatrix} -4 \\ 7 \end{bmatrix}$.

(a). Find one solution to the linear equation $A\vec{x} = \vec{b}$.

(b). Find a basis for the nullspace of A .

(c). Using the above two parts find *all* the solutions to $A\vec{x} = \vec{b}$.

5. (15pts.) Let $\mathbf{b}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$, $\mathbf{b}_2 = \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}$, $\mathbf{b}_3 = \begin{bmatrix} -3 \\ 1 \\ 1 \end{bmatrix}$.

(a). Show that $\mathcal{B} = \{\mathbf{b}_1, \mathbf{b}_2, \mathbf{b}_3\}$ is a basis.

(b). Let $x = \begin{bmatrix} 1 \\ -2 \\ 3 \end{bmatrix}$. Find the coordinates of \mathbf{x} with respect to the basis \mathcal{B} .

(c). Let V be the subspace spanned by $\{\mathbf{b}_2, \mathbf{b}_3\}$. Find an orthonormal basis for V .

6. (15pts.) Find the least square solution to the system

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \\ -1 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \\ 0 \\ 1 \end{bmatrix}.$$

7. (10pts.) Let $\mathbf{v}_1 = (\frac{2}{3}, -\frac{1}{3}, -\frac{2}{3})$, $\mathbf{v}_2 = (\frac{1}{\sqrt{2}}, 0, \frac{1}{\sqrt{2}})$.

(a). Show that $\mathbf{v}_1, \mathbf{v}_2$ is an orthonormal basis of the span $W = \text{span} \{\mathbf{v}_1, \mathbf{v}_2\}$.

(b). Let $\mathbf{x} = (2, 1, 3)$ find the distance from \mathbf{x} to $W = \text{span} \{\mathbf{v}_1, \mathbf{v}_2\}$.

8. (15 pts.) Let $T : \mathbf{R}^4 \rightarrow \mathbf{R}^2$ be the linear transformation $T(x_1, x_2, x_3, x_4) = (x_1 + x_2, x_3 - x_4)$.

(a). Find the matrix representing T relative to the standard basis on \mathbf{R}^4 and the standard basis on \mathbf{R}^2 .

(b). $\mathcal{B} = \{(1, 1), (1, -1)\}$ is a basis of \mathbf{R}^2 . Find the matrix representing T relative to the standard basis on \mathbf{R}^4 and the basis $\mathcal{B} = \{(1, 1), (1, -1)\}$ on \mathbf{R}^2 .

9. (10pts.) Let T be a linear transformation from \mathbb{R}^k to \mathbb{R}^k . Show that the set of $\vec{v} \in \mathbb{R}^k$ such that $T(\vec{v}) = 4\vec{v}$ is a subspace of \mathbb{R}^k .

10. (10pts.) Let A be an $m \times n$ matrix with row vectors $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_m$ (so $A = \begin{bmatrix} \mathbf{v}_1 \\ \mathbf{v}_2 \\ \vdots \\ \mathbf{v}_m \end{bmatrix}$) and let $\mathbf{v} = a_1\mathbf{v}_1 + a_2\mathbf{v}_2, \dots + a_n\mathbf{v}_m$ be a linear combination of the row vectors. Show that if $\mathbf{v} \neq \mathbf{0}$ then $A\mathbf{v} \neq \mathbf{0}$.