

## Solutions to Homework 5

**Supplementary problem 1:** Since  $C$  is defined implicitly as the 0-level set of a function  $f : \mathbb{R}^3 \rightarrow \mathbb{R}$ , we will have that  $C$  is a codimension one (i.e. dimension 2)  $C^1$  submanifold of  $\mathbb{R}^3$  at all points where  $f'$  has maximal rank 1. Specifically,

$$f'(x, y, z) = (2x, -2y, -2z)$$

has rank one unless all three entries vanish—i.e. unless  $(x, y, z) = (0, 0, 0)$ . So  $C$  is a two dimensional submanifold of  $\mathbb{R}^3$  except at the origin (which, incidentally, actually does lie in  $C$ ).

The picture you draw should show a circular cone generated by rotating the line  $x = y$  about the  $x$  axis.

**Supplementary problem 2:** The function  $h : \mathbb{R} \rightarrow \mathbb{R}^2$  is clearly  $C^1$  and parametrizes the set  $C$ . Therefore  $C$  is a dimension one (i.e. codimension 1) submanifold of  $\mathbb{R}^2$  except at points where  $h'$  fails to have (maximal) rank one. Specifically,

$$h'(t) = (2t, 3t^2),$$

which has rank equal to one unless both entries vanish—i.e. unless  $t = 0$ . Hence  $C$  is a dimension one submanifold at all points other than  $h(0) = (0, 0)$ .

The tangent space to  $C$  at  $h(t)$  is the image of  $h'$  under the linear transformation  $h'(t)$ . In particular, since  $\{1\}$  is a basis for  $\mathbb{R}$ , the vector  $h'(t) \cdot 1 = (2t, 3t^2)$  will be a basis for the tangent space to  $C$  at  $h(t)$ .

**Supplementary problem 3:** The set  $C$  is just the  $(1, 0)$  level set of the function  $f : \mathbb{R}^4 \rightarrow \mathbb{R}$ . Therefore  $C$  will be a submanifold of  $\mathbb{R}^4$  with both dimension and codimension equal to two except at points where

$$f'(x, y, z, w) = \begin{pmatrix} 2x & -2y & -w & -z \\ w & z & y & x \end{pmatrix}$$

has rank less than two. Having rank less than two means that *all*  $2 \times 2$  submatrices of  $f'$  have zero determinant. There are six of these, and their determinants are

$$2xz + 2yw, \quad 2xy + w^2, \quad 2x^2 + wz, \quad -2y^2 + wz, \quad -2xy + z^2, \quad -xw + yz.$$

If all six vanish, then comparing the second and fourth expression shows that  $w^2 = -z^2$ , which can only happen if  $z = w = 0$ ; and the third and fifth combine to imply that  $x^2 = -y^2$ , so that again  $x = y = 0$ . Hence the only trouble occurs at  $(0, 0, 0, 0)$  which is not actually in  $C$ . So  $C$  is a submanifold of  $\mathbb{R}^4$  at all points.

Now the tangent space to  $C$  at  $(1, 1, 0, 0)$  is just the  $(1, 0)$  level set of the linear approximation of  $f$  at that point. That is, we seek all vectors  $(a, b, c, d)$  satisfying

$$\begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} + f'(1, 1, 0, 0) \begin{pmatrix} a \\ b \\ c \\ d \end{pmatrix}.$$

From this it is clear that we're just after the nullspace of

$$f'(1, 1, 0, 0) = \begin{pmatrix} 2 & -2 & 0 & 0 \\ 0 & 0 & 1 & 1 \end{pmatrix}.$$

After dividing the matrix by two, it's in reduced row echelon form with free variables  $b$  and  $d$ . The nullspace is therefore the two dimensional subspace of  $\mathbb{R}^4$  generated by the vectors  $(1, 1, 0, 0)$  and  $(0, 0, -1, 1)$  obtained by setting one free variable equal to one and the other equal to 0.

**Supplementary problem 4:** We have

$$f'(x, y) = \begin{pmatrix} 3x^2 - 4xy & -2x^2 + 1 \\ -4x & 3y^2 \end{pmatrix}$$

With a first guess of  $(x_0, y_0) = (1, 1)$ , I find a second guess  $(x_1, y_1)$  by linearly approximating  $f$  about  $(1, 1)$  and setting the result equal to  $(1.1, -0.8)$ .

$$\begin{pmatrix} .1 \\ -.8 \end{pmatrix} = \begin{pmatrix} 0 \\ -1 \end{pmatrix} + \begin{pmatrix} -1 & -1 \\ -4 & 3 \end{pmatrix} \begin{pmatrix} x_1 - 1 \\ y_1 - 1 \end{pmatrix}$$

which implies that

$$\begin{pmatrix} x_1 \\ y_1 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix} + \begin{pmatrix} -1 & -1 \\ -4 & 3 \end{pmatrix}^{-1} \begin{pmatrix} .1 \\ .2 \end{pmatrix} = \begin{pmatrix} .92857 \\ .97143 \end{pmatrix}$$

To find a better guess it is necessary to repeat this process using the linear approximation of  $f$  near  $(x_1, y_1)$  instead of  $(x_0, y_0)$ . Rather than type up the details, I have made available the mathematica worksheet (web viewable version available, too) that I used to do this computation. See the course webpage for the link.