New Algorithm for Polynomial Plus-minus Factorization Based on FFT

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Polynomial plus-minus factorization

Given: Discrete-time polynomial

 $p(z) = p_0 + \dots + p_n z^n$

that is nonzero on the unit circle: $|z| = 1 \implies p(z) \neq 0$,

Find: stable polynomial $p^+(z)$ and unstable $p^-(z)$ such that $p(z) = p^+(z)p^-(z)$

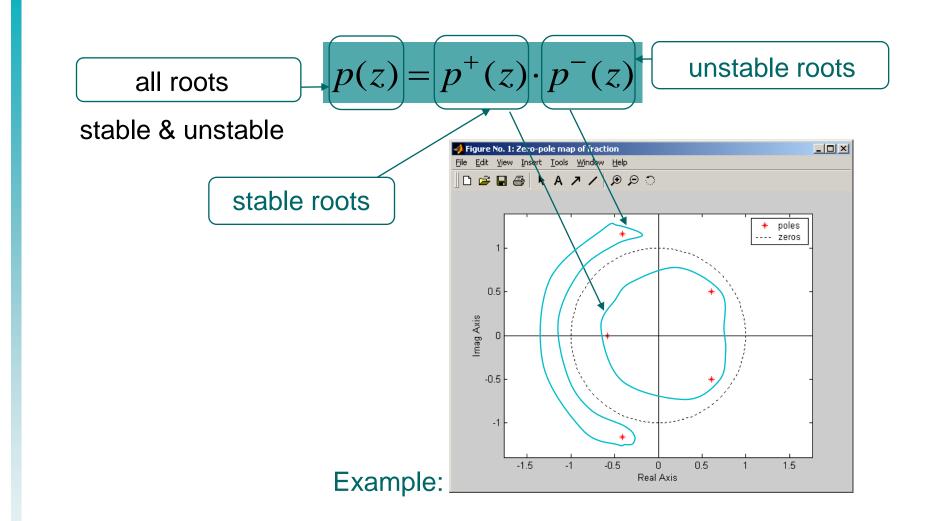
Motivation: - cancellation of stable zeros in classical control

- time-optimal control (deadbeat, FIFO)
- exact model matching
- quadratic optimal filters
- algebraic approach to I_1 optimal control

Special case - symmetric: $p(z) = p(z^{-1}) \quad \left(p^*(z) = p(z^{-1})\right)$

- less general but more popular (H₂,LQG
- many algorithms a programs

+/- factorization & polynomial roots



- not useful for high degrees for rounding errors

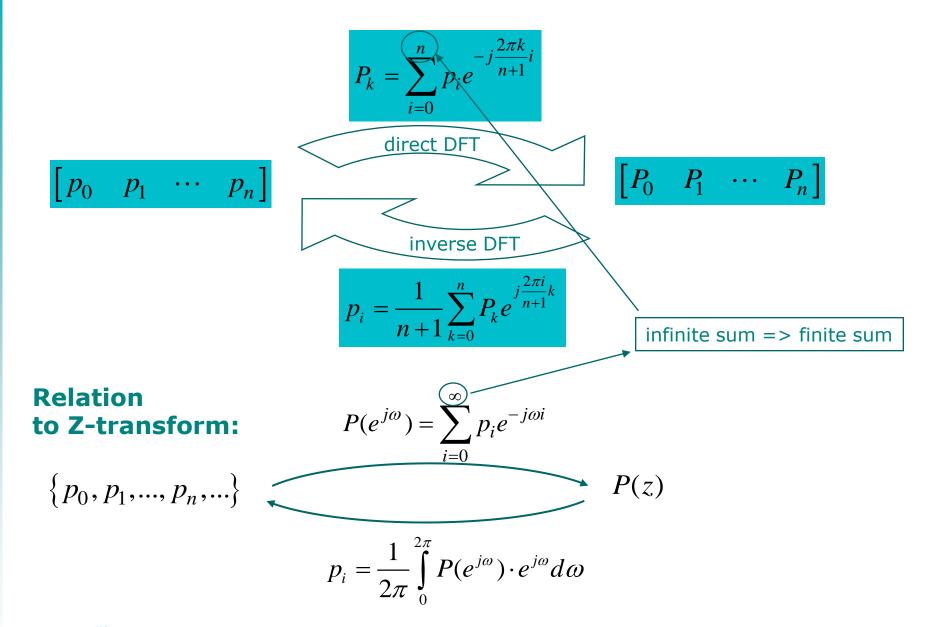
+/- factorization via symmetric factorization & GCD

Given: p(z)Compute: $P(z) = p(z) \cdot p^*(z), \ p^*(z) = p(z^{-1})$ Spectral factorization of $P(z): P(z) = q^*(z)q(z), \ q(z)$ stable Get $p^+(z)$ as greatest common divisor of q(z) and p(z)

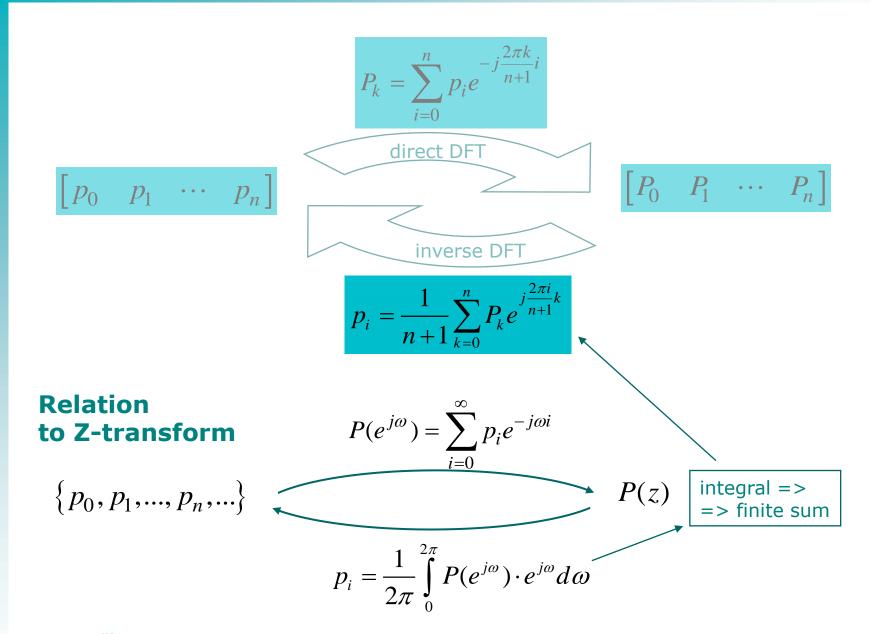
Weak point:

polynomial greatest common divisor computation - numerically demanding, unreliable for high degrees

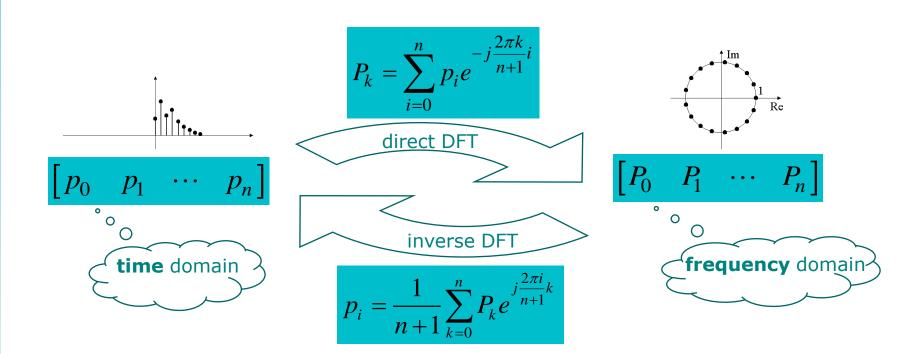
Discrete Fourier transform (DFT)



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Relation to Z-transform

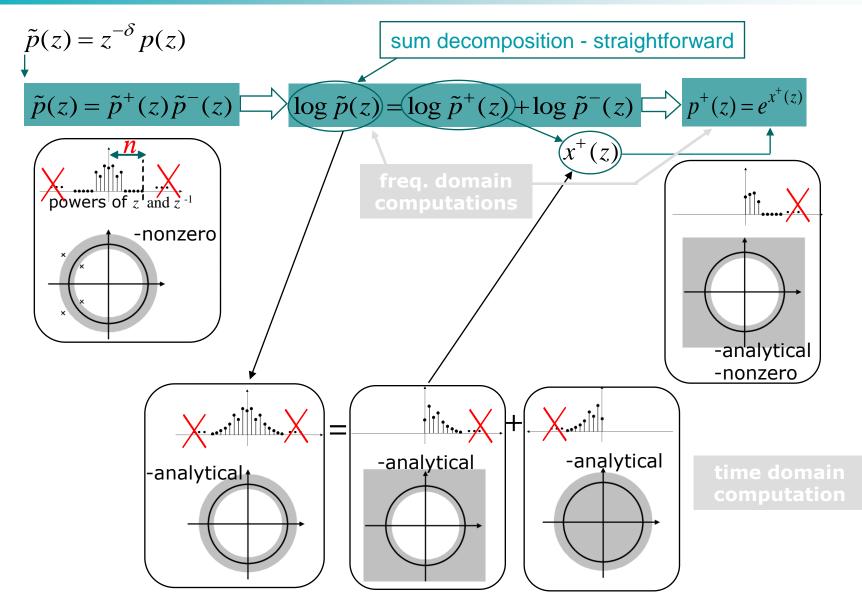
For *n* high enough, DFT approaches Z-Transform $\square >$ switch between time and freq.domains by DFT

Fast Fourier transform algorithm

- developed for practical computation of DFT
- Cooley & Tukey, 1970's
- numerically attractive high effectivity $n \log n$, numerical stability
- principle: DFT of a vector of length *n* is **recursively** decomposed into 2

DFT's of half sizes; thanks to periodicity of $s_k = \exp j \frac{2\pi k}{n+1}$, a lot of computations are saved

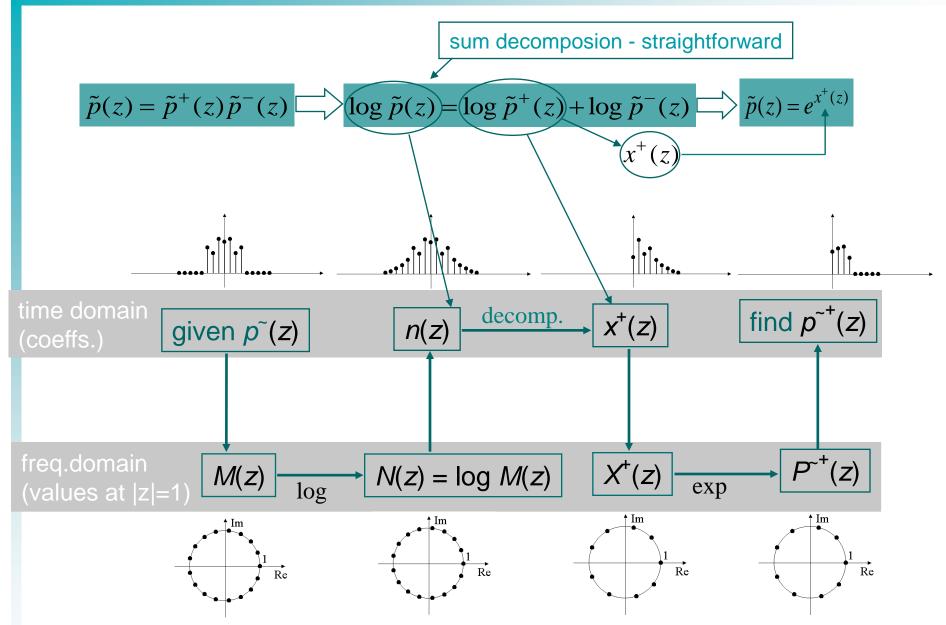
- frequently used algorithm DFT defines the spectrum of a finite or periodic discrete-time signal often required in signal processing
- FFT algorithm(s) naturally available in many computing packages as fast built-in functions (MATLAB, Mathematica, ...)

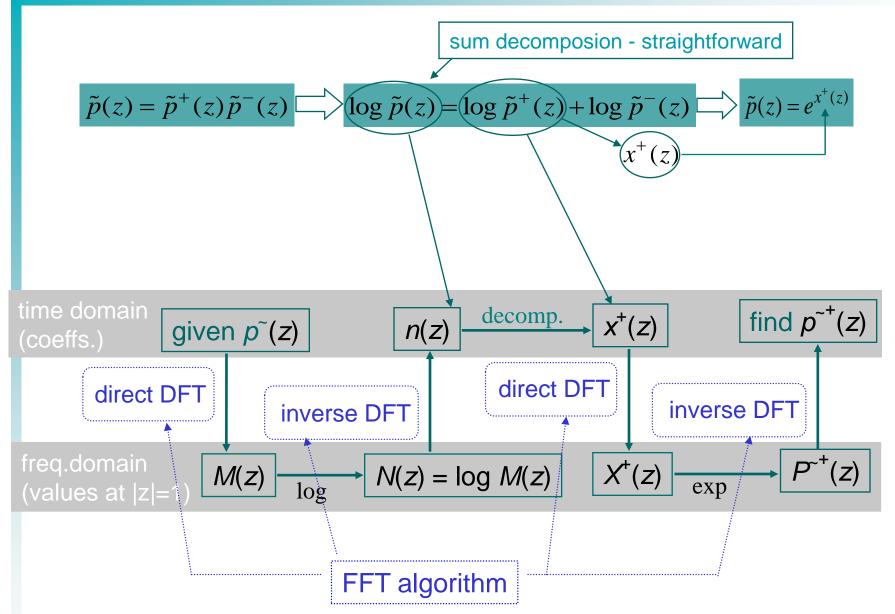


$$\tilde{p}(z) = z^{-\delta} p(z)$$

$$\tilde{p}(z) = \tilde{p}^{+}(z) \tilde{p}^{-}(z) \longrightarrow \log \tilde{p}(z) = \log \tilde{p}^{+}(z) + \log \tilde{p}^{-}(z) \longrightarrow p^{+}(z) = e^{x^{+}(z)}$$

For *n* high enough, DFT approaches Z-Transform $\square >$ switch between time and freq.domains by DFT

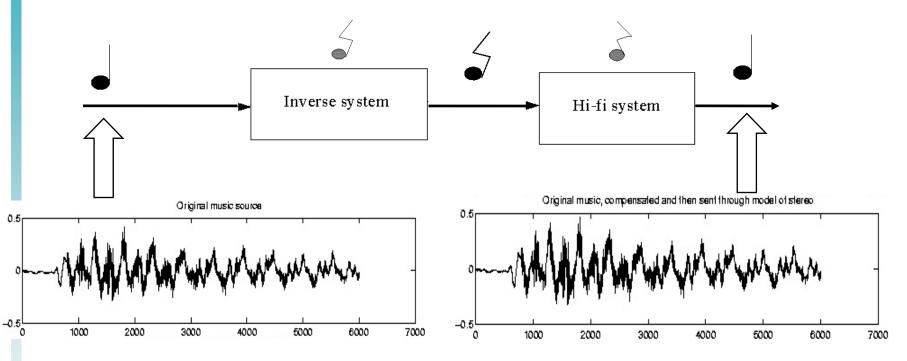




Upgrading loudspeakers dynamics

Inverse dynamics filter for moderate quality loudspeaker proposed and tested by Mikael Sternad and colleagues (U. of Uppsala)

http://www.signal.uu.se/Courses/Descr9899/sigproject.html



Upgrading loudspeakers dynamics

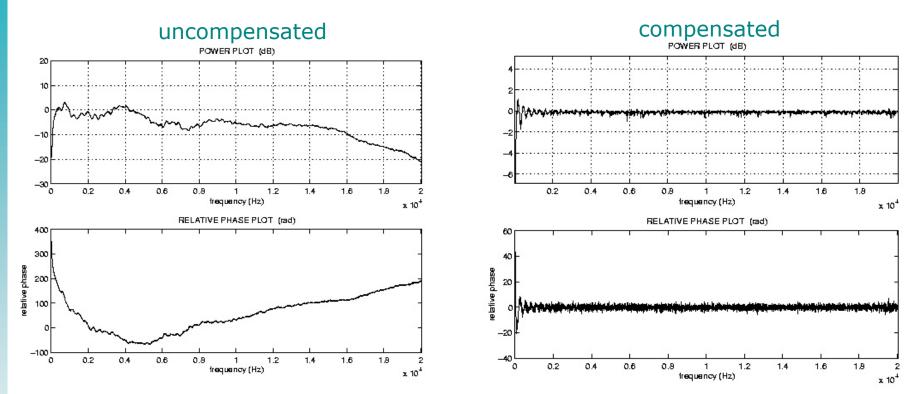
Identification: in an anechoic chamber



High sampling frequency (44 kHz) models of high orders (200, 500, 1000)

Upgrading loudspeakers dynamics

Bode plots



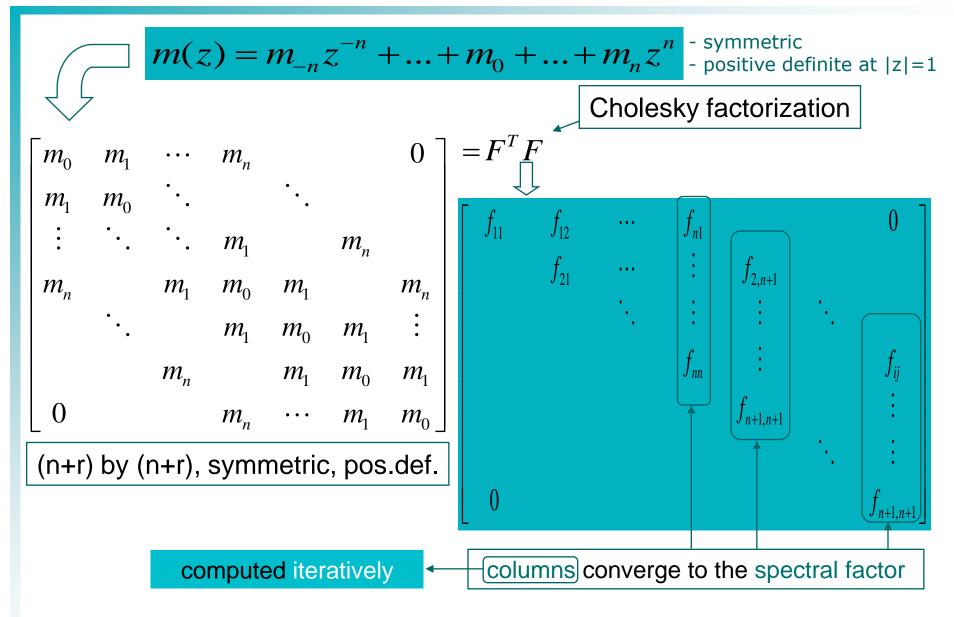
Sound examples http://www.signal.uu.se/Courses/Descr9899/sigproject.html

Bauer-type Algorithm for Polynomial plus-minus Factorization

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Bauer's method for spectral factorisation



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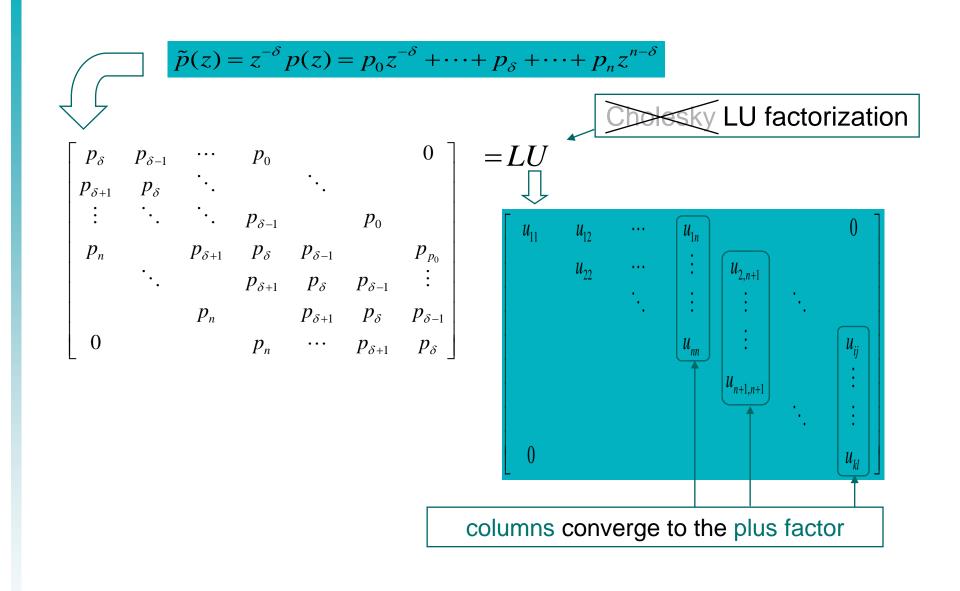
Modification for +/- factorisation

- relax the symmetry condition
- substitute LU non-symmetric factorisation for symmetric Cholesky decomposition

Necessary preliminary step:

perform degree shift - construct $\tilde{p}(z) = z^{-\delta} p(z) = p_0 z^{-\delta} + ... + p_n z^{n-\delta}$ prior to LU factorisation, where δ is the number of stable roots (given e.g. by the Schur stability test).

Resulting algorithm for +/- factorisation

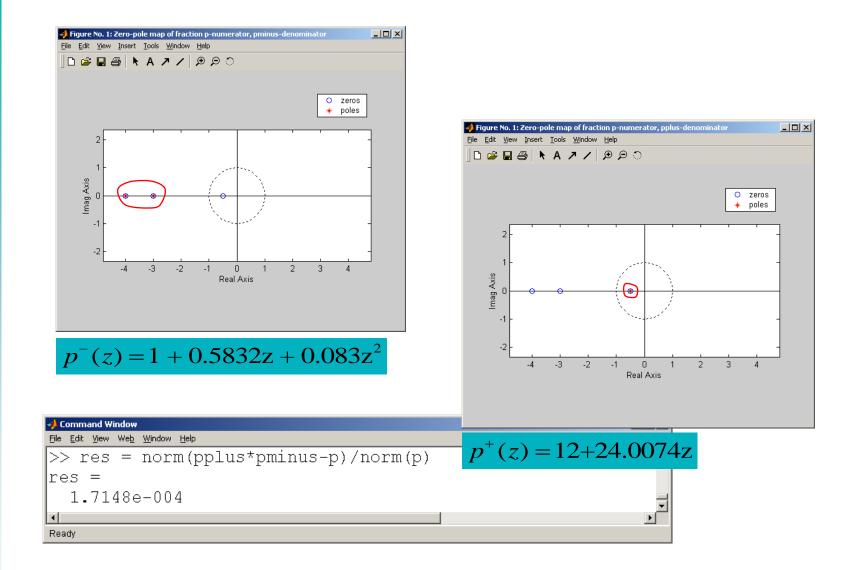


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| >> | р | | | | | | | | | - | |
| p = | - | | | | | | | | | | |
| Ľ | 12 | 2 + 31z + | 15z | ^2 + 2z^ | `3 ← | $-\delta = 1$ | | | | | |
| >> | T = | toeplitz | ([31 | ,15,2,0, | 0,0, | 0,0], | [31,12, | 0,0,0, | 0,0,0] |) | |
| T = | = | | | | | | | | | | |
| | 31 | 12 | 0 | 0 | 0 | 0 | 0 | 0 | | | |
| | 15 | 31 | 12 | 0 | 0 | 0 | 0 | 0 | | | |
| | 2 | 15 | 31 | 12 | 0 | 0 | 0 | 0 | | | |
| | 0 | 2 | 15 | 31 | 12 | 0 | 0 | 0 | | | |
| | 0 | 0 | 2 | 15 | 31 | 12 | 0 | 0 | | | |
| | 0 | 0 | 0 | 2 | 15 | 31 | 12 | 0 | | | |
| | 0 | 0 | 0 | 0 | 2 | 15 | 31 | 12 | | | |
| | 0 | 0 | 0 | 0 | 0 | 2 | 15 | 31 | | | |
| >> | >> $[L, U] = lu(T)$ | | | | | | | | | | |
| L = | = | | | | | | | | | - | |
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| Ready | | | | | | | | | | | |

... to be continued

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| L = | | | | | _ | | |
| Columns 1 through 5 | | | | | | | |
| 1.0000 | 0 | 0 | 0 | 0 | | | |
| 0.4839 | 1.0000 | 0 | 0 | 0 | | | |
| 0.0645 | 0.5647 | 1.0000 | 0 | 0 | | | |
| 0 | 0.0794 | 0.5799 | 1.0000 | 0 | | | |
| 0 | 0 | 0.0826 | 0.5827 | (1.0000) | | | |
| 0 | 0 | 0 | 0.0832 | 0.5832 | | | |
| 0 | 0 | 0 | 0 | (0.0833) | | | |
| 0 | 0 | 0 | 0 | | | | |
| Columns 6 t | through 8 | | | | • | | |
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| Ready | | | | | | | |
| | | | | ¥ | | | |
| $p^{-}(z) = 1 + 0.5832z + 0.083z$ | | | | | | | |

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| U = | | | | | <u> </u> | | |
| Columns 1 | through 5 | | | | | | |
| 31.0000 | 12.0000 | 0 | 0 | 0 | | | |
| 0 | 25.1935 | 12.0000 | 0 | 0 | | | |
| 0 | 0 | 24.2241 | 12.0000 | 0 | | | |
| 0 | 0 | 0 | 24.0413 | (12.0000) | | | |
| 0 | 0 | 0 | 0 | 24.0074 | | | |
| 0 | 0 | 0 | 0 | 0 | | | |
| 0 | 0 | 0 | 0 | 0 | | | |
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| • | | | | | | | |
| $p^+(z) = 12 + 24.0074z$ | | | | | | | |



LU iterative scheme for indefinite Toeplitz matrix

