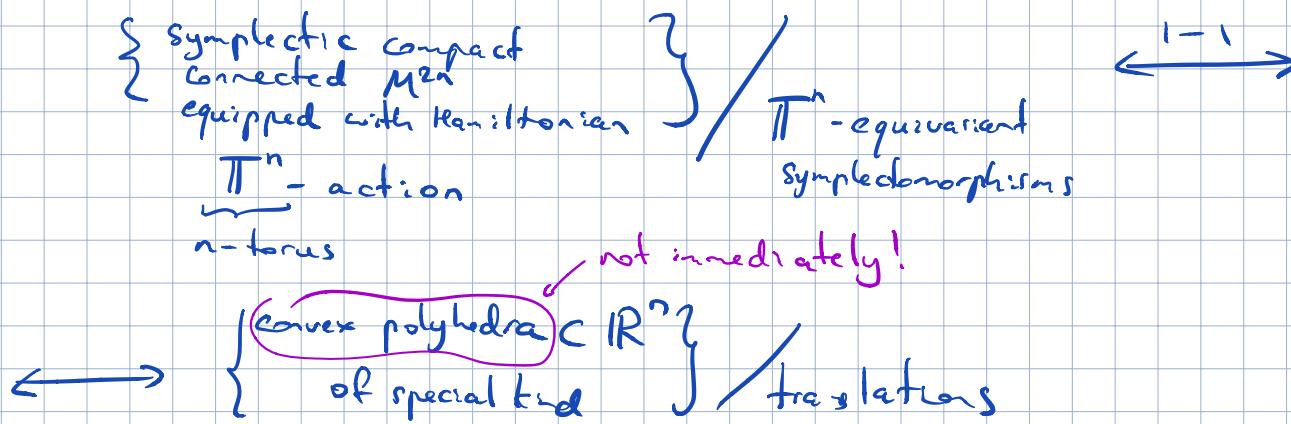


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## Convexity theorem

Motivation: Dolzent theorem



$$M \xrightarrow{\quad} \mu(M)$$

image of the moment map.  
- convex polyhedron!

In fact, there is a more general statement:

Thm (Atiyah - Goresky - Sternberg)

$(M, \omega)$  sympl. mfd, connected, compact

$\mathbb{T}^m \rightarrow \text{Symp}(M, \omega)$  - Hamiltonian torus action  
with moment map  $\mu: M \rightarrow \mathbb{R}^m$

Then: 1)  $\underbrace{\text{Fix}_{\mathbb{T}}(M)}_{\text{fixed points}} = \bigcup_{j=1}^N C_j$   
 $\bigcup_{j=1}^N C_j$   $\underset{\text{symplectic submanifolds}}{\cap}$

2)  $r|_{C_j} \equiv y_j \in \mathbb{R}^m$  const maps

!! 3)  $\mu(M)$  - convex hull of  $y_j$  for all  $1 \leq j \leq N$

4)  $\mu^{-1}(y)$  is connected for every regular value  $y \in \mu(M)$ .

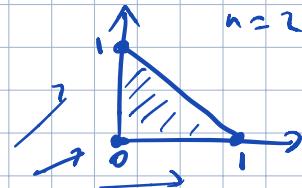
Ex:  $M = \mathbb{CP}^n$ ,  $\mathbb{T}^n$  acts on  $M$  by

$$(\theta_1, \dots, \theta_n) \circ [z_0 : z_1 : \dots : z_n] = [z_0 : e^{2\pi i \theta_1} z_1 : \dots : e^{2\pi i \theta_n} z_n]$$

$$\mu: \mathbb{CP}^n \rightarrow \mathbb{R}^n$$

$$[z_0 : \dots : z_n] \mapsto \left( \frac{|z_1|^2}{\|z\|^2}, \dots, \frac{|z_n|^2}{\|z\|^2} \right), \quad \|z\|^2 = |z_0|^2 + \dots + |z_n|^2$$

$$\mu(M) = \{x \in \mathbb{R}^n, x_i \geq 0, \sum_{i=1}^n x_i \leq 1\}$$



$$F_{x_0}(\mathbb{C}\mathbb{P}^2), \{[1:0:0], [0:1:0], [0:0:1]\}$$

Proof of (4)  $\Rightarrow$  (3):

by induction in  $m$ .

For  $m=1$ :  $\mu: M \rightarrow \mathbb{R}$  trivial

assume for  $m$ , show for  $m+1$

$$\mu: M \rightarrow \mathbb{R}^{m+1} \quad x_0, x_1 \in \mu(M) \subset \mathbb{R}^{m+1}$$

it is enough to show that  $\exists p: \mathbb{R}^{m+1} \rightarrow \mathbb{R}^m$ ,  $p(x_0) = p(x_1)$ , and

$p^{-1}p(x_0) \cap \mu(M)$  is connected

We can show this only for  
p with integer coeffs

p given by a matrix  $A \in \mathbb{Z}^{m \times (m+1)}$

when we have a sub-torus

$$\begin{array}{ccc} \mathbb{R}^m & \xrightarrow{A^T} & \mathbb{R}^{m+1} \\ \downarrow & & \downarrow \\ \mathbb{T}^m & \xrightarrow{A^T} & \mathbb{T}^{m+1}. \end{array}$$

For a smaller torus  $\hookrightarrow$   
know this by induction  
hypothesis

any point can be approximated by integer projectors  
in space of projectors.

## Talk 2 | Afiyah-Guillemin-Sternberg convexity theorem

Thm  $\overline{T}^m \xrightarrow{\Phi} \text{Symp}(M, \omega)$   $M$ -compact, connected, symplectic  
 assume  $\Phi$  is Hamiltonian,  $\mu: M \rightarrow \mathbb{R}^m$

Then: 1)  $\text{Fix}_{\overline{T}^m}(M) = \bigcap_{j=1}^N C_j$ ,  $C_j$  - symp. submanifold

2)  $\mu(C_j) = y_j \in \mathbb{R}^m$

3)  $\mu(M)$  - convex hull of  $\{y_j\}_{j=1}^N$

4)  $\mu^{-1}(y) \subset M$  is connected for every regular value  $y \in \mathbb{R}^m$ .

\* already proved (4)  $\Rightarrow$  (3)

let's prove (4). Show for  $m=1$  (then can prove by induction for  $m > 1$ )

• Hamiltonian  $S^1$ -action on  $(M, \omega)$

$H: M \rightarrow \mathbb{R} \rightsquigarrow dH \rightarrow X_H$  with periodic flow  
 han. v.f.  $H^{-1}(f(S))$  connected. (want to prove that  
 it implies  $H^{-1}(f(S))$  connected)

Ex  $\mathbb{R}/\mathbb{Z} = S^1 G \mathbb{C}$ ,  $\frac{i}{2} dz \wedge d\bar{z}$

$\Theta \cdot z = e^{2\pi i \Theta} z$  parameter of the action,  $\Theta \in \mathbb{Z}$

$H: \mathbb{C} \rightarrow \mathbb{R}$   
 $z \mapsto \lambda |z|^2$

$S^1 G \mathbb{C}^n$   $\Theta \cdot (z_1, \dots, z_n) = (e^{2\pi i \lambda_1 \Theta} z_1, \dots, e^{2\pi i \lambda_n \Theta} z_n)$

$H: \mathbb{C}^n \rightarrow \mathbb{R}$   
 $(z_1, \dots, z_n) \mapsto \lambda_1 |z_1|^2 + \dots + \lambda_n |z_n|^2$   $(*)$

$S^1 G(V, h)$   
 $\nearrow$  Hermitian form  
 v.s.p.

$z \mapsto \exp(2\pi i \langle \lambda, z \rangle) \cdot z$   
 $\nearrow$  skew-Hermitian matrix

$H: \mathbb{C}^n \rightarrow \mathbb{R}$   
 $z \mapsto h(z, \lambda z)$

- preimage of a point is connected  
 - in (\*)  $\lambda$  real coords, even # of pluses,

even # of maxes

## Morse theory

def 1)  $f: M \rightarrow \mathbb{R}$ ;  $p \in M$  is a critical point of  $f$  if  $df_p: T_p M \rightarrow \mathbb{R}$  is zero.

2)  $f: M \rightarrow \mathbb{R}$  is a Morse-Bott function if

a)  $\text{Crit}(f) \subset M$  is a submanifold  
of crit. points

b)  $\forall p \in \text{Crit}(f)$ ,  $T_p(\text{Crit}(f)) = \ker \underbrace{H_p(f)}_{\text{Hessian of } f \text{ at } p}$

||  
 a Morse fun:  
Crit( $f$ ) = 11: isolated points,  
 Hessians are non-deg.

Prop:  $f: M^n \rightarrow \mathbb{R}$  Morse-Bott fun.,  $p \in \text{Crit}(f)$

$\exists$  loc. coords near  $p \in M$  s.t.  
 $(x_1, \dots, x_n)$

$$f(x_1, \dots, x_n) = 0 \cdot x_1^2 + \dots + 0 \cdot x_k^2 + x_{k+1}^2 + \dots + x_{k+m}^2 - x_{k+m+1}^2 - \dots - x_n^2 + c$$

•  $k = \dim \text{Crit}(f)$

•  $m = \text{cond}_p(f)$

•  $n - k - m = \text{index}_p(f)$

Lemma: If  $f: M \rightarrow \mathbb{R}$  is a Morse-Bott function without crit. pts of indices 1 and condices 1, then  $f^{-1}(\gamma)$  is connected for every regular value  $\gamma \in \mathbb{R}$ .

nonex:  $f: \mathbb{R}^2 \rightarrow \mathbb{R}$

$$f(x, y) = x^2 - y^2 \quad f^{-1}(\gamma \neq 0) = \text{disconnected!}$$

Ex:  $f: \mathbb{R}^2 \rightarrow \mathbb{R}$

$$f(x, y) = x^2 + y^2 \quad f^{-1}(\gamma > 0) \quad \text{connected!}$$

back to the proof of (4) of AGS

def  $V$  -  $\mathbb{R}$ -vect. space,  $\mathcal{J}: V \rightarrow V$  is a cx structure  
if  $\mathcal{J}^2 = -\text{Id}$

Def  $(V, \omega)$  symm usp.

Then  $I$  is called compatible with  $\omega$  if

- (1)  $\omega(Ix, Iy) = \omega(x, y)$
- (2)  $\omega(x, Iy)$  is inner product

Lemma 1) Any sympl. v-spc has a compatible complex structure

2)  $G$ - compact Lie group,  $G \xrightarrow{\text{connected}} \text{Symp}(V, \omega)$ ,

then  $\exists$  compatible  $G$ -invariant complex structure on  $(V, \omega)$   
<constructed by averaging>

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$S^1 \rightarrow \text{Symp}(M, \omega)$  H- Hamiltonian

1)  $\text{Fix}_{g_1}(M) = \text{Crit}(H)$

2)  $p \in M$ ,  $S^1 \times T_p M$   
Jacobian

choose  $S^1$ -invariant ex structure on  $M$   
 $\rightsquigarrow S^1$ -invariant Riemannian structure

$\exp_{T_p M} : \text{open } U \xrightarrow{\cong} M$  -  $S^1$ -equiv. map  
 $\cong \text{open } V$