

LAST TIME

(1)

$$TM = \bigcup_{x \in M} T_x M$$

tangent bundle

chart on M

$$\downarrow$$
$$U \times \mathbb{R}^n \xrightarrow{\psi_u}$$

"local trivialization"

$$(x, y_1, \dots, y_n) \mapsto$$

$$\bigcup_{x \in U} T_x M =: V_u ; \left(\sum_i y_i \left(\frac{\partial}{\partial x_i} \right)_x \right)$$

- chart on TM

$$\text{transition map: } \phi_\beta \phi_\alpha^{-1} : (x_1, \dots, x_n, y_1, \dots, y_n) \mapsto$$

$$\mapsto (\tilde{x}_1, \dots, \tilde{x}_n, \sum_i \frac{\partial \tilde{x}_1}{\partial x_i} y_i, \dots, \sum_i \frac{\partial \tilde{x}_n}{\partial x_i} y_i)$$

$$T^*M = \bigcup_{x \in M} T_x^* M$$

cotangent bundle

$$U \times \mathbb{R}^n \xrightarrow{\lambda_u} \bigcup_{x \in U} T_x^* M =: W_u ; (W_u, \tilde{\psi}_u = (\psi_u, \text{id}) \circ \lambda_u^{-1})$$

- chart on T^*M

$$(x, z_1, \dots, z_n) \mapsto \sum_i z_i (dx_i)_x$$

$$\text{transition map: } \psi_\beta \psi_\alpha^{-1} : (x_1, \dots, x_n, z_1, \dots, z_n) \mapsto$$

$$\mapsto (\tilde{x}_1, \dots, \tilde{x}_n, \sum_i \frac{\partial x_i}{\partial \tilde{x}_1} z_i, \dots, \sum_i \frac{\partial x_i}{\partial \tilde{x}_n} z_i)$$

The derivative of $f \in C^\infty(M)$ is a map $df: M \rightarrow T^*M$ satisfying $p \circ df = \text{id}_M$. (but not every section of T^*M is a derivative!)

TM and T^*M are examples of vector bundles.

def A real vector bundle of rank m on a manifold M is a manifold E with a smooth projection map $p: E \rightarrow M$ s.t.

- each fiber $p^{-1}(x)$ has the structure of an m -dimensional real vector space. "local trivialization"
- M is covered by open sets $\{U_\alpha\}$ equipped with trivializing neighborhoods diffeomorphisms $\psi_\alpha: p^{-1}(U_\alpha) \xrightarrow{\cong} U_\alpha \times \mathbb{R}^m$ s.t. $\text{proj}_2 \circ \psi_\alpha = p$ and $\text{proj}_1 \circ \psi_\alpha$ is a linear isomorphism from the v.sp. $p^{-1}(x), x \in U_\alpha$, for any to the v.space \mathbb{R}^m .
 ($\Rightarrow \psi_\alpha: p^{-1}(x) \rightarrow \{x\} \times \mathbb{R}^m$)

< consequence of the previous >

• on the intersection $U_\alpha \cap U_\beta$,

$$\psi_\alpha \circ \psi_\beta^{-1}: (U_\alpha \cap U_\beta) \times \mathbb{R}^m \rightarrow (U_\alpha \cap U_\beta) \times \mathbb{R}^m$$

is of the form $(x, v) \mapsto (x, g_{\alpha\beta}(x) v)$

where $g_{\alpha\beta}(x)$ is a smooth function on $U_\alpha \cap U_\beta$ with values in invertible $m \times m$ matrices.

"transition function"

for TM , $g_{\alpha\beta}$ is the Jacobian matrix $\left(\frac{\partial \tilde{x}_i}{\partial \tilde{x}_j} \right)$

for T^*M , $g_{\alpha\beta}$ is its inverse transpose $\left(\frac{\partial \tilde{x}_j}{\partial \tilde{x}_i} \right)$

Ex: $E = M \times \mathbb{R}^m$ - "trivial" vector bundle

• Morphism of vector bundles $\begin{matrix} E & & E' \\ p \downarrow & & p' \downarrow \\ M & \xrightarrow{f} & N \end{matrix}$ is a pair of maps $f: M \rightarrow N, F: E \rightarrow E'$ s.t.

$$\begin{matrix} E & \xrightarrow{F} & E' \\ p \downarrow & & p' \downarrow \\ M & \xrightarrow{f} & N \end{matrix}$$

(i.e. $F: p^{-1}(x) \rightarrow p'^{-1}(f(x))$) and $\forall x \in M$ F gives a linear map

$$F|_{p^{-1}(x)}: p^{-1}(x) \rightarrow p'^{-1}(f(x)).$$

Vector fields as derivations

X -vector field is a mapping $X: C^\infty(M) \rightarrow C^\infty(M)$
 $\rightarrow X_x \in T_x^{Alg} \quad \forall x \in M$ $f \mapsto (x \mapsto X_x f)$
 $=: X(f)$

locally: $X(f)(x) = \sum_i y_i(x) \left(\frac{\partial}{\partial x_i} \right)_x (f) = \sum_i y_i(x) \frac{\partial f}{\partial x_i}(x)$

- smooth; Leibnitz property: $X(fg) = f \cdot X(g) + g \cdot X(f)$ (*)

Linear transformations $X: C^\infty(M) \rightarrow C^\infty(M)$ satisfying (*) are called derivations of the ring $C^\infty(M)$.

* Derivations of $C^\infty(M) =$ vector fields on M .

Proposition: Let $X: C^\infty(M) \rightarrow C^\infty(M)$ be a lin. map which satisfies (*).
 Then X is a vector field.

Proof: $\forall a \in M, X_a(f) = X(f)(a)$ satisfies the conditions of a tangent vector at a .
 So, X defines a map $X: M \rightarrow TM$ with $p \circ X = id_M$. So, locally it can be written as $X_x = \sum_i y_i(x) \left(\frac{\partial}{\partial x_i} \right)_x$. We need to check that $y_i(x)$ are smooth.

$X(x_i \cdot \mu) = y_i(x)$ near a . Since $X: C^\infty \rightarrow C^\infty, y_i(x)$ is C^∞ .
 ↑
 bump function in the coord. nbhd = (around a) □

Lie bracket of vector fields

Let X, Y two vector fields on M . We can compose them as operators $C^\infty \rightarrow C^\infty$.

$$XY(fg) = X(f Y(g) + g Y(f)) = X(f) Y(g) + f XY(g) + X(g) Y(f) + g XY(f)$$

$$YX(fg) = Y(f X(g) + g X(f)) = Y(f) X(g) + f YX(g) + Y(g) X(f) + g YX(f)$$

$\Rightarrow [X, Y] = XY - YX$ satisfies

$$[X, Y](fg) = f \cdot [X, Y](g) + g [X, Y](f)$$

$\Rightarrow [X, Y]$ is a vector field.



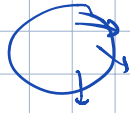
def The Lie bracket of two vector fields X, Y is the vector field $[X, Y]$.

(3)

Ex: $M = \mathbb{R}$, $X = f \frac{d}{dx}$, $Y = g \frac{d}{dx} \Rightarrow [X, Y] = (fg' - gf') \frac{d}{dx}$

One-parameter groups of diffeomorphisms

intuition: wind velocity vector field on S^2



moves a particle at x to a new point $\varphi_t(x)$ after time t . after time s , it is at $\varphi_s(\varphi_t(x)) = \varphi_{s+t}(x)$

def A one-parameter group of diffeomorphisms ^{<"flows">} of a manifold M

is a smooth map $\varphi: \mathbb{R} \times M \rightarrow M$ s.t.
 $(t, x) \mapsto \varphi_t(x)$

- $\varphi_t: M \rightarrow M$ is a diffeomorphism
- $\varphi_0 = \text{id}$
- $\varphi_{s+t} = \varphi_s \circ \varphi_t$

idea: a vector field gives rise to a 1-param grp of diffeo, under certain assumptions.

• Given a 1-param grp of diffeo φ_t , we can produce a vector field out of it:

for $f \in C^\infty(M)$, set $X_a(f) := \left. \frac{d}{dt} \right|_{t=0} f(\varphi_t(a))$

- this X_a satisfies Leibnitz property: $X_a(fg) = \left. \frac{\partial}{\partial t} \right|_{t=0} f(\varphi_t(a))g(\varphi_t(a))$
 $= f(a) \left. \frac{d}{dt} \right|_{t=0} g(\varphi_t(a)) + g(a) \left. \frac{d}{dt} \right|_{t=0} f(\varphi_t(a))$
 $= f(a) X_a(g) + g(a) X_a(f)$

$\Rightarrow X_a$ is a tangent vector at a .

- Locally: $\varphi_t(x_1, \dots, x_n) = (y_1(t, x), \dots, y_n(t, x))$

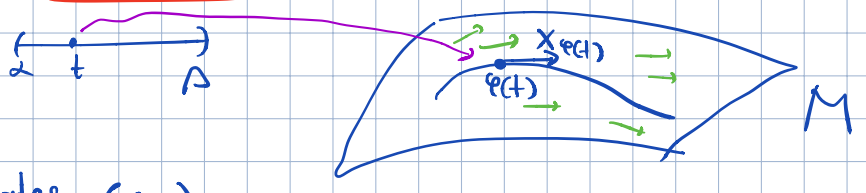
$$\left. \frac{d}{dt} \right|_{t=0} f(y_1, \dots, y_n) = \sum_i \frac{\partial f}{\partial y_i}(y) \underbrace{\left. \frac{dy_i}{dt}(x) \right|_{t=0}}_{C_i(x)} = \sum_i C_i(x) \frac{\partial f}{\partial x_i}(x) = X(f)$$

with $X = \sum_i C_i(x) \frac{\partial}{\partial x_i}$
 - vector field.

• We want to reverse this process and go from a vector field to the diffeomorphism.
 - First, we want to track the "trajectory of a single particle".

def An integral curve of a vector field X is a smooth map

$\varphi: (a, b) \rightarrow M$ such that $D\varphi_t \left(\frac{d}{dt} \right) = X_{\varphi(t)}$ (*)



Example $M = \mathbb{R}^2$ with coordinates (x, y)

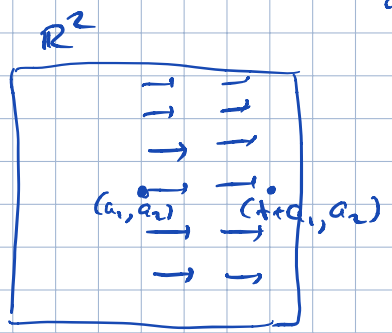
and $X = \frac{\partial}{\partial x}$. The derivative $D\varphi$ of a smooth fun. $\varphi(t) = (x(t), y(t))$

is $D\varphi_t \left(\frac{d}{dt} \right) = \frac{dx}{dt} \frac{\partial}{\partial x} + \frac{dy}{dt} \frac{\partial}{\partial y}$. So, the equation (*) is:

$\begin{cases} \frac{dx}{dt} = 1 \\ \frac{dy}{dt} = 0 \end{cases}$
system of ODE

$\Rightarrow \varphi(t) = (t + a_1, a_2)$
a solution (general)

- particle at (a_1, a_2)
is transported in time t
to $(t + a_1, a_2)$



Theorem* Given a vector field X on a manifold M and $a \in M$, there exists a maximal integral curve of X with $\varphi(t_0) = a$.
i.e. the interval (a, b) is maximal

for the proof, we need

10.4 in Hitchin with values in \mathbb{R}^n
Thm (Picard-Lindelöf): Let $f(t, x)$ be a continuous function on $|t - t_0| \leq a, \|x - x_0\| \leq b$ and suppose f satisfies Lipschitz condition $\|f(t, x_1) - f(t, x_2)\| \leq L \|x_1 - x_2\|$. (for some L "Lipschitz constant")
If $\lambda = \sup |f(t, x)|$ and $h = \min(a, b/\lambda)$, then the differential equation $\frac{dx}{dt} = f(t, x), x(t_0) = x_0$ has a unique solution for $|t - t_0| \leq h$.

Proof of THM* Consider (U_r, ψ_r) - chart around a . Then if $X = \sum_i c_i(x) \frac{\partial}{\partial x_i}$,
the eq. $D\varphi_t \left(\frac{d}{dt} \right) = X_{\varphi(t)}$ can be written as a sys. of ODEs

$\frac{dx_i}{dt} = c_i(x_1, \dots, x_n)$. By Picard-Lindelöf, $\exists!$ sol. on some interval
with init. cond. $(x_1(0), \dots, x_n(0)) = \psi_r(a)$.

Suppose $\varphi(\alpha, \beta) \rightarrow M$ is any integral curve with

$\varphi(0) = a \quad \forall x \in (\alpha, \beta)$, interval $[0, x]$ is compact \Rightarrow can be covered by a fin. number
of coord. charts, in each of which we can apply P-L to intervals $[0, x_1], [x_1, x_2], \dots, [x_n, x]$.

Uniqueness \Rightarrow these local solutions agree with φ on any sub-interval containing 0.

\rightarrow then we take the maximal interval on which we can define φ .

□