

Vectors in \mathbb{R}^n

\mathbb{R}^n = set of vectors of form $\vec{u} = \begin{bmatrix} u_1 \\ u_2 \\ \vdots \\ u_n \end{bmatrix}$ (n x 1 - matrices)

- can add two vectors in \mathbb{R}^n (vectors must be of same size!!) $\vec{u} + \vec{v}$
 - can form a scalar multiple $c \cdot \vec{u}$
 - zero vector $\vec{0} = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$, $\vec{0} + \vec{u} = \vec{u}$
 - negative of a vector: $-\vec{u} = (-1)\vec{u} = \begin{bmatrix} -u_1 \\ -u_2 \\ \vdots \\ -u_n \end{bmatrix}$ then $(-\vec{u}) + \vec{u} = \vec{0}$
 - also, notation: $\vec{u} + (-1)\vec{v} =: \vec{u} - \vec{v}$
- * one has commutativity, associativity, distributivity, like for numbers

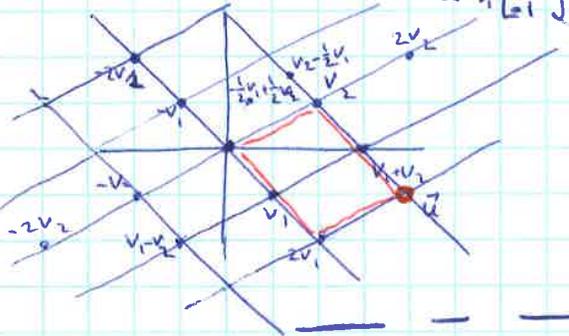
Linear combinations

for vectors $v_1, \dots, v_p \in \mathbb{R}^n$, scalars c_1, \dots, c_p , vector

$\vec{y} = c_1 \vec{v}_1 + \dots + c_p \vec{v}_p$ is called a linear combination of $\vec{v}_1, \dots, \vec{v}_p$ with weights c_1, \dots, c_p

Ex: some linear comb of v_1, v_2 : $3v_1 - \frac{5}{7}v_2$, $\frac{1}{2}v_1 = \frac{1}{2}v_1 + 0 \cdot v_2$, $\vec{0} = 0 \cdot v_1 + 0 \cdot v_2$

Ex: some linear combinations of $v_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$, $v_2 = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$:



Q: Express \vec{u} as a lin. comb. of \vec{v}_1, \vec{v}_2 .
Sol: by parallelogram rule, $\vec{u} = 2\vec{v}_1 + \vec{v}_2$.

Ex: $\vec{a}_1 = \begin{bmatrix} 1 \\ -3 \\ -1 \end{bmatrix}$, $\vec{a}_2 = \begin{bmatrix} 3 \\ -5 \\ 2 \end{bmatrix}$, $\vec{b} = \begin{bmatrix} -1 \\ -1 \\ -4 \end{bmatrix}$

Q: can \vec{b} be generated as a lin. comb. of \vec{a}_1, \vec{a}_2 , i.e., do weights x_1, x_2 exist, s.t. $x_1 \vec{a}_1 + x_2 \vec{a}_2 = \vec{b}$? (*)

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Sol: (*) means $x_1 \begin{bmatrix} 1 \\ -3 \\ -1 \end{bmatrix} + x_2 \begin{bmatrix} 3 \\ -5 \\ 2 \end{bmatrix} = \begin{bmatrix} -1 \\ -1 \\ -4 \end{bmatrix}$

lhs = $\begin{bmatrix} x_1 \\ -3x_1 \\ -x_1 \end{bmatrix} + \begin{bmatrix} 3x_2 \\ -5x_2 \\ 2x_2 \end{bmatrix} = \begin{bmatrix} x_1 + 3x_2 \\ -3x_1 - 5x_2 \\ -x_1 + 2x_2 \end{bmatrix}$

So, (*) is true iff $\begin{cases} x_1 + 3x_2 = -1 \\ -3x_1 - 5x_2 = -1 \\ -x_1 + 2x_2 = -4 \end{cases}$ - (1,2,3)sgs! (**)

Aug. Mat.: $\begin{bmatrix} 1 & 3 & -1 \\ -3 & -5 & -1 \\ -1 & 2 & -4 \end{bmatrix} \sim \begin{bmatrix} 1 & 3 & -1 \\ 0 & 4 & -4 \\ 0 & 5 & -5 \end{bmatrix} \sim \begin{bmatrix} 1 & 3 & -1 \\ 0 & 1 & -1 \\ 0 & 5 & -5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{bmatrix} \Rightarrow$ Sol of (**): $x_1 = 2, x_2 = -1$

Thus: $2 \begin{bmatrix} 1 \\ -3 \\ -1 \end{bmatrix} + (-1) \begin{bmatrix} 3 \\ -5 \\ 2 \end{bmatrix} = \begin{bmatrix} -1 \\ -1 \\ -4 \end{bmatrix}$
 $2 \vec{a}_1 + (-1) \vec{a}_2 = \vec{b}$

so, \vec{b} is a lin. comb. of \vec{a}_1, \vec{a}_2 .

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Note: the augm. matrix of our system was $[\vec{a}_1, \vec{a}_2, \vec{b}]$

$$\begin{bmatrix} 1 & 3 & -1 \\ -3 & -5 & -1 \\ -1 & 2 & -4 \end{bmatrix} \begin{matrix} \vec{a}_1 \\ \vec{a}_2 \\ \vec{b} \end{matrix}$$

not den $[\vec{a}_1, \vec{a}_2, \vec{b}]$

Equation $x_1 \vec{a}_1 + \dots + x_n \vec{a}_n = \vec{b}$ has same solution set as the lin. sys whose augm. matrix is $[\vec{a}_1, \dots, \vec{a}_n, \vec{b}]$ (***)

In particular, \vec{b} can be generated as a lin. comb. of $\vec{a}_1, \dots, \vec{a}_n$ iff there exists a sol. for the lin. sys. corresp. to matrix (***).

Def Let $\vec{v}_1, \dots, \vec{v}_p$ be in \mathbb{R}^n . The set of all linear comb. of $\vec{v}_1, \dots, \vec{v}_p$ is denoted

$\text{Span}\{\vec{v}_1, \dots, \vec{v}_p\}$ = "subset of \mathbb{R}^n spanned (or "generated") by $\vec{v}_1, \dots, \vec{v}_p$ "

I.e. $\text{Span}\{\vec{v}_1, \dots, \vec{v}_p\}$ = set of all vectors that can be written in the form $c_1 \vec{v}_1 + \dots + c_p \vec{v}_p$ with c_1, \dots, c_p scalars.

vector \vec{b} is in $\text{Span}\{\vec{v}_1, \dots, \vec{v}_p\}$ iff vector equation $x_1 \vec{v}_1 + \dots + x_p \vec{v}_p = \vec{b}$ has a solution
 \Leftrightarrow lin. sys. with aug. matrix $[\vec{v}_1, \dots, \vec{v}_p, \vec{b}]$ has a solution.

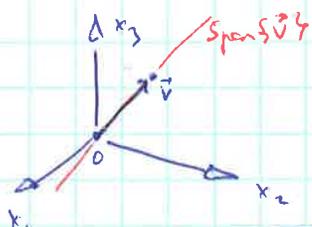
$\text{Span}\{\vec{v}_1, \dots, \vec{v}_p\}$ contains every scalar multiple of \vec{v}_i and contains $\vec{0}$.
 (particular)

Geom. description of $\text{Span}\{\vec{v}\}$ and $\text{Span}\{\vec{u}, \vec{v}\}$

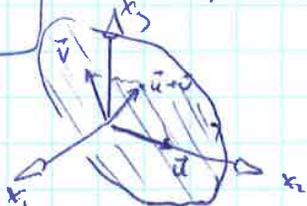
Let $\vec{v} \in \mathbb{R}^3$ nonzero vector

$\text{Span}\{\vec{v}\} = \{\text{scalar multiples of } \vec{v}\}$

= points in the line in \mathbb{R}^3 through \vec{v} and $\vec{0}$.



For $\vec{u}, \vec{v} \in \mathbb{R}^3$ nonzero vectors, s.t. \vec{v} not a multiple of \vec{u} .
 Then $\text{Span}\{\vec{u}, \vec{v}\} =$ plane in \mathbb{R}^3 that contains $\vec{u}, \vec{v}, \vec{0}$



Ex: $\vec{a}_1 = \begin{bmatrix} 1 \\ -2 \\ 3 \end{bmatrix}$, $\vec{a}_2 = \begin{bmatrix} 5 \\ -13 \\ -3 \end{bmatrix}$, $\vec{b} = \begin{bmatrix} -1 \\ -1 \\ 8 \end{bmatrix}$. Is \vec{b} in the plane $\text{Span}\{\vec{a}_1, \vec{a}_2\}$?

Sol: does $x_1 \vec{a}_1 + x_2 \vec{a}_2$ have a solution?

$$\begin{bmatrix} 1 & 5 & -3 \\ -2 & -13 & 8 \\ 3 & -3 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & 5 & -3 \\ 0 & -3 & 2 \\ 0 & -18 & 10 \end{bmatrix} \sim \begin{bmatrix} 1 & 5 & -3 \\ 0 & -3 & 2 \\ 0 & 0 & -2 \end{bmatrix}$$

last eq.: $0 = -2 \Rightarrow$ no solutions
 $\Rightarrow \vec{b}$ is not in the plane!

2.4. The matrix equation $A\vec{x} = \vec{b}$

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def for an $m \times n$ matrix $A = [\vec{a}_1 \dots \vec{a}_n]$ and \vec{x} a vector in \mathbb{R}^n ,
↑ ↑ ↑
columns

The matrix-vector product is: $A\vec{x} = [\vec{a}_1 \dots \vec{a}_n] \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} := x_1\vec{a}_1 + \dots + x_n\vec{a}_n$ - Lin. comb. of columns of A with weights given by entries of \vec{x} .

Note: $A\vec{x}$ is defined only if $\# \text{ columns in } A = \# \text{ entries in } \vec{x}$

Ex: $\begin{bmatrix} 1 & -2 & 3 \\ -4 & 5 & 0 \end{bmatrix} \begin{bmatrix} 2 \\ -1 \\ 3 \end{bmatrix} = 2 \begin{bmatrix} 1 \\ -4 \end{bmatrix} + (-1) \begin{bmatrix} -2 \\ 5 \end{bmatrix} + 3 \begin{bmatrix} 3 \\ 0 \end{bmatrix} = \begin{bmatrix} 2 \\ -8 \end{bmatrix} + \begin{bmatrix} 2 \\ -5 \end{bmatrix} + \begin{bmatrix} 9 \\ 0 \end{bmatrix} = \begin{bmatrix} 13 \\ -13 \end{bmatrix}$

↑ ↑ ↑
 \vec{a}_1 \vec{a}_2 \vec{a}_3

Q: for $\vec{v}_1, \vec{v}_2, \vec{v}_3 \in \mathbb{R}^m$, write lin. comb. $2\vec{v}_1 - 5\vec{v}_2 + 3\vec{v}_3$ as a matrix-vector product

A: $\vec{u} = \underbrace{\begin{bmatrix} \vec{v}_1 & \vec{v}_2 & \vec{v}_3 \end{bmatrix}}_{m \times 3 \text{ matrix}} \begin{bmatrix} 2 \\ -5 \\ 3 \end{bmatrix}$

Lin. sys. $\begin{matrix} x_1 - 2x_2 + 3x_3 = 5 \\ -4x_1 + 5x_2 = 7 \end{matrix} \Leftrightarrow \begin{matrix} \text{vector eq.} \\ x_1 \begin{bmatrix} 1 \\ -4 \end{bmatrix} + x_2 \begin{bmatrix} -2 \\ 5 \end{bmatrix} + x_3 \begin{bmatrix} 3 \\ 0 \end{bmatrix} = \begin{bmatrix} 5 \\ 7 \end{bmatrix} \Leftrightarrow \begin{matrix} \text{matrix eq.} \\ \begin{bmatrix} 1 & -2 & 3 \\ -4 & 5 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 5 \\ 7 \end{bmatrix} \end{matrix}$

matrix of coeffs of the lin. sys. "matrix equation" of form $A\vec{x} = \vec{b}$

If $A = [\vec{a}_1 \dots \vec{a}_n]$ $m \times n$ matrix, $\vec{b} \in \mathbb{R}^m$, then matrix eq. $A\vec{x} = \vec{b}$ has some solution set as the vector equation $x_1\vec{a}_1 + \dots + x_n\vec{a}_n = \vec{b}$ which has in turn same sol. set as lin. sys. w/ augm. matrix $[\vec{a}_1 \dots \vec{a}_n \ \vec{b}]$

Existence of solutions

Eq. $A\vec{x} = \vec{b}$ has a solution iff \vec{b} is a lin. comb. of columns of A .
 ($\Leftrightarrow \vec{b} \in \text{Span}\{\vec{a}_1, \dots, \vec{a}_n\}$)

Ex: Let $A = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix}$, $\vec{b} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$ Q: Is eq. $A\vec{x} = \vec{b}$ consistent for all \vec{b} ?

Sol: Aug. Mat: $\begin{bmatrix} 1 & 2 & 3 & b_1 \\ 4 & 5 & 6 & b_2 \\ 7 & 8 & 9 & b_3 \end{bmatrix} \sim \begin{bmatrix} 1 & 2 & 3 & b_1 \\ 0 & -3 & -6 & b_2 - 4b_1 \\ 0 & -6 & -12 & b_3 - 7b_1 \end{bmatrix} \sim \begin{bmatrix} 1 & 2 & 3 & b_1 \\ 0 & -3 & -6 & b_2 - 4b_1 \\ 0 & 0 & 0 & b_3 - 7b_1 - 2(b_2 - 4b_1) \end{bmatrix}$

$b_3 - 7b_1 - 2(b_2 - 4b_1) = b_3 - 2b_2 + b_3$

WANT THIS TO VANISH for consistency

$$\Rightarrow A\vec{x} = \vec{b} \text{ consistent iff } b_1 - 2b_2 + b_3 = 0$$

equation of a plane through the origin in \mathbb{R}^3
 $= \text{Span}\{\vec{a}_1, \vec{a}_2, \vec{a}_3\}$

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• Note $A\vec{x} = \vec{b}$ is not consistent for every \vec{b} , because REF of A has a row of zeros!

If A had a pivot in each row, REF of $[A \ \vec{b}]$ would be of form $\begin{bmatrix} \cdot & \cdot & \cdot & \cdot \\ 0 & \cdot & \cdot & \cdot \\ 0 & 0 & \cdot & \cdot \end{bmatrix}$

- consistent for every \vec{b}

THM)

• Let A be an $m \times n$ matrix. The following are equivalent:

(a) For each $\vec{b} \in \mathbb{R}^m$, eq. $A\vec{x} = \vec{b}$ has a solution

(b) Each $\vec{b} \in \mathbb{R}^m$ is a lin. comb. of columns of A

(c) Columns of A span \mathbb{R}^m (entire)

(d) A has a pivot in every row.

Notes: \uparrow coeff. matrix, not the aug. mat.

Row-vector rule for computing $A\vec{x}$.

if $A\vec{x}$ is defined, then i -th entry in $A\vec{x}$ is the sum of products of corresponding entries product from row i of A and from vector \vec{x} .

Ex: $\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = x_1 \begin{bmatrix} 1 \\ 4 \\ 7 \end{bmatrix} + x_2 \begin{bmatrix} 2 \\ 5 \\ 8 \end{bmatrix} + x_3 \begin{bmatrix} 3 \\ 6 \\ 9 \end{bmatrix} = \begin{bmatrix} x_1 + 2x_2 + 3x_3 \\ 4x_1 + 5x_2 + 6x_3 \\ 7x_1 + 8x_2 + 9x_3 \end{bmatrix}$

"dot product" $\begin{bmatrix} 1 & 2 & 3 \\ \vdots & \vdots & \vdots \\ 4 & 5 & 6 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$

Ex: $\begin{bmatrix} 1 & -2 & 3 \\ -4 & 5 & 0 \end{bmatrix} \begin{bmatrix} 2 \\ -1 \\ 3 \end{bmatrix} = \begin{bmatrix} 1 \cdot 2 + (-2) \cdot (-1) + 3 \cdot 3 \\ (-4) \cdot 2 + 5 \cdot (-1) + 0 \cdot 3 \end{bmatrix} = \begin{bmatrix} 13 \\ -13 \end{bmatrix}$

• Properties of matrix-vector product $A\vec{x}$

each for A $m \times n$ mat. $\vec{u}, \vec{v} \in \mathbb{R}^n$ and c a scalar:

(a) $A(\vec{u} + \vec{v}) = A\vec{u} + A\vec{v}$

(b) $A(c\vec{u}) = c \cdot (A\vec{u})$