

1.3. Classification of differential equations

05/05/2018

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- ordinary and partial diff. eq. (ODE and PDE)

ODE: unknown fun. depends on a single independent variable t

Ex: falling object, mice-owls ; $\left[\frac{d^2 Q(t)}{dt^2} + R \frac{dQ(t)}{dt} + \frac{1}{C} Q(t) = E(t) \right] \quad (3)$
 v(t) p(t) - eq. on $Q(t)$ - charge on a capacitor in an electric circuit.

PDE: $\left(\frac{\partial^2 u(x,t)}{\partial x^2} = \frac{\partial u(x,t)}{\partial t} \right)$ heat equation

$\left(\frac{\partial^2 u(x,t)}{\partial x^2} = \frac{\partial^2 u(x,t)}{\partial t^2} \right)$ wave equation

- single diff. eq. vs systems of diff. eq.

if there are several unknown factors:

Lotka-Volterra equations: $\begin{aligned} \frac{dx}{dt} &= ax - \alpha xy && \text{- system of eq. } x(t) \text{ - prey population} \\ (\text{predator-prey}) \quad (6) \quad \frac{dy}{dt} &= -cy + \gamma xy && \text{for } y(t) \text{ - predator population} \end{aligned}$

• Order

Order of an eq. - highest derivative that appears in the eq.

(*) $F(t, y, y', \dots, y^{(n)}) = 0$ ODE of order n.

Ex: (*) $y''' + 2e^t y'' + yy' = t^4$ - 3rd order ODE on $y(t)$

we assume that (*)
 - can be solved for $y^{(n)}$,
 expressing it via $t, y, y', \dots, y^{(n-1)}$
 $y^{(n)} = f(t, y, y', \dots, y^{(n-1)})$

• Linear vs nonlinear diff. eq.

an ODE $F(t, y, y', \dots, y^{(n)}) = 0$ is linear if F is a linear function in $y, y', \dots, y^{(n)}$.
 (no linearity int. assumed!)

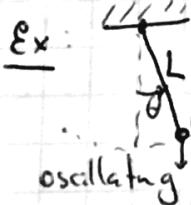
General linear nth order ODE:

$$a_0(t)y^{(n)} + a_1(t)y^{(n-1)} + \dots + a_n(t)y = g(t)$$

Ex: falling object, mice-owls, (3), (4,5) - PDE.

(each equation)

Ex: (7) is non-linear, because of yy' term. (6) are non-linear due to xy terms.

Ex:  (8) $\frac{d^2 \theta}{dt^2} + \frac{g}{L} \sin \theta = 0$ $\theta(t)$ - unknown function
 - non-linear ODE! due to $\sin \theta$ term.
 oscillating pendulum

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linear eq. - easier, well-developed theory

non-linear eq. - harder, less satisfactory methods of solution.

non-linear (sometimes) can be approximated by linear:

for θ small, $\sin \theta \approx \theta$ and (8) can be approximated by $\frac{d^2\theta}{dt^2} + \frac{g}{L}\theta = 0$ - linear.
- "Linearization" of (8).

Solutions a solution of the n^{th} order ODE (***)

on the interval $a < t < \beta$ is a fun. φ s.t. $\varphi', \varphi'', \dots, \varphi^{(n)}$ exist and satisfy

$$\varphi^{(n)}(t) = f(t, \varphi(t), \varphi'(t), \dots, \varphi^{(n-1)}(t)) \quad \text{for every } a < t < \beta.$$

Ex: $\frac{dp}{dt} = \frac{p}{2} - 450$ has the sol. $p(t) = 900 + C e^{-\frac{t}{2}}$, C arbitrary const.

given an eq., it is generally not easy to find a sol.; given a fun. - easy to verify whether it is a sol.
(by substitution)

Ex: $y'' + y = 0$, Q: $y_1(t) = \cos t$ a solution?

Sol: $y_1'(t) = -\sin t$, $y_1''(t) = -\cos t \Rightarrow y_1'' + y_1 = 0 \quad \checkmark$

Existence: (***) does not automatically always have solutions. (but for some classes of eq., it does)

Uniqueness: usually, solutions are in a family (***)
but one may ask about uniqueness for the initial value problem.

Determining actual solutions (explicitly) - not always possible; sometimes can do only numerically.

2.1 Integrating Factors.

general 1st order linear ODE

$$\frac{dy}{dt} + p(t)y = g(t)$$

divide by $P(t)$ if $P(t) \neq 0$ (**)

$$P(t) \frac{dy}{dt} + Q(t)y = R(t)$$

$$\text{Ex: } \left[(4+t^2) \frac{dy}{dt} + 2ty = 4t \right] \quad (1)$$

$\nearrow = \frac{d}{dt} ((4+t^2)y)$
derivative of
a product

$$\text{Thus: eq. (1) } \Leftrightarrow \frac{d}{dt} ((4+t^2)y) = 4t$$

$$\xrightarrow{\text{integrate wrt. } t} (4+t^2)y = 2t^2 + C \quad \begin{array}{l} \text{due to } \\ \text{arbitrary const} \end{array} \quad \boxed{y = \frac{2t^2}{4+t^2} + \frac{C}{4+t^2}}$$

Generally $r(t)$ is not a derivative of a product

of integration

- general sol. for (1).

Idea (Leibniz): find a function $p(t)$ s.t. once we multiply (1) by $p(t)$, LHS becomes a der. of a product.

$$Ex: \frac{dy}{dt} + \frac{1}{2}y = \frac{1}{2}e^{t/3} \quad (2) \quad \text{Find the general sol.}$$

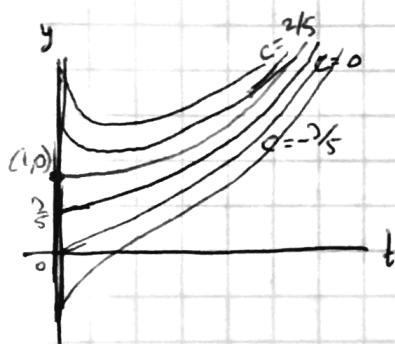
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$$\underline{\text{Sol:}} \quad \underbrace{\mu(t) \cdot (2)}_{(\text{yell undetermined function})} : \underbrace{\mu(t) \frac{dy}{dt} + \left(\frac{1}{2}\mu(t) \right)y}_{\text{WANT IT TO BE } \frac{d}{dt}(\mu(t)y)} = \frac{1}{2}\mu(t)e^{t/3} \quad (1)$$

$$\text{Solve (1): } \frac{1}{\mu(t)} \frac{d\mu(t)}{dt} \frac{d}{dt}(\mu(t)) = \frac{1}{2} \rightarrow \frac{d}{dt} \ln |\mu(t)| = \frac{1}{2} \rightarrow \ln |\mu(t)| = \frac{t}{2} + C \rightarrow \mu(t) = c e^{t/2} \quad \begin{matrix} \text{We do not need the most general } \mu(t), \\ \text{just need one, } \mu \neq 0. \text{ Choose } c=1. \end{matrix}$$

$$\rightarrow \mu(t) = e^{t/2}$$

$$\rightsquigarrow \text{So: (1) is } \underbrace{e^{t/2} \frac{dy}{dt} + \frac{1}{2}e^{t/2}y}_{\frac{d}{dt}(e^{t/2}y)} = \frac{1}{2}e^{t/2} \rightarrow \underbrace{e^{t/2}y}_{\text{integrate}} = \frac{3}{5}e^{t/2} + c \rightarrow \underbrace{y}_{\text{solve for } y} = \frac{3}{5}e^{t/2} + c e^{-t/2} \quad (5)$$



Ex: (2) + init. condition $y(0)=1$

$$y(0) = \frac{3}{5} + c = 1 \Rightarrow c = \frac{2}{5} \Rightarrow \underbrace{y(t) = \frac{3}{5}e^{t/2} + \frac{2}{5}e^{-t/2}}_{\text{from gen. sol. (5)}}$$