

2/5/2020 | 2.8. Subspaces

def A subspace of \mathbb{R}^n is any set H in \mathbb{R}^n s.t.

(a) $\vec{0} \in H$

(b) $\vec{u} + \vec{v} \in H$ if $\vec{u}, \vec{v} \in H$

(c) $c\vec{u} \in H$ if $\vec{u} \in H, c$ a scalar

Ex: $\vec{v}_1, \vec{v}_2 \in \mathbb{R}^n$, then $H = \text{Span}\{\vec{v}_1, \vec{v}_2\}$ is a subspace of \mathbb{R}^n

Let's check: (a) $\vec{0} = 0 \cdot \vec{v}_1 + 0 \cdot \vec{v}_2 \in H$ ✓

(b) $\vec{u} = s_1 \vec{v}_1 + s_2 \vec{v}_2$
 $\vec{v} = t_1 \vec{v}_1 + t_2 \vec{v}_2 \Rightarrow \vec{u} + \vec{v} = (s_1 + t_1) \vec{v}_1 + (s_2 + t_2) \vec{v}_2 \in H$
- lin. comb. of \vec{v}_1, \vec{v}_2 ✓

(c) $c \cdot \vec{u} = (cs_1) \vec{v}_1 + (cs_2) \vec{v}_2 \in H$

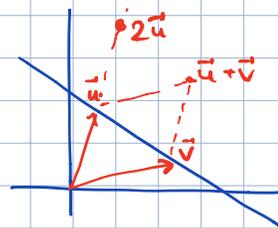
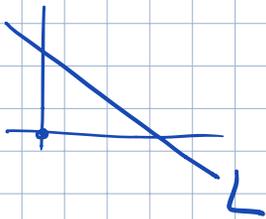
Thus: for $\vec{v}_1 \neq \vec{0}, \vec{v}_2 \neq c\vec{v}_1$, $\text{Span}\{\vec{v}_1, \vec{v}_2\}$ - a plane in \mathbb{R}^n through $\vec{0}$

for $\vec{v}_1 \neq \vec{0}, \vec{v}_2 = c\vec{v}_1$, $\text{Span}\{\vec{v}_1, \vec{v}_2\}$ - a line in \mathbb{R}^n through $\vec{0}$

examples of subspaces

Ex: a line L not through the origin is not a subspace

(a, b, c all fail)
 $\vec{0} \notin L, \vec{u} + \vec{v} \notin L, 2\vec{u} \notin L$



Ex: for $\vec{v}_1, \dots, \vec{v}_p \in \mathbb{R}^n$, $H = \text{Span}\{\vec{v}_1, \dots, \vec{v}_p\}$ is a subspace of \mathbb{R}^n
- the subspace "spanned" (or "generated") by $\vec{v}_1, \dots, \vec{v}_p$

Ex: \mathbb{R}^n itself is a subspace. Also, $H = \{0\}$ is a subspace ("zero subspace").

Column space and null space of a matrix

def For $A = [\vec{a}_1, \dots, \vec{a}_n]$ an $m \times n$ matrix, its "column space" is the set of linear comb. of columns of A

$$\text{Col } A := \text{Span} \{ \vec{a}_1, \dots, \vec{a}_n \} \quad - \text{subspace of } \mathbb{R}^m$$

• $\text{Col } A = \mathbb{R}^m$ iff columns of A span $\mathbb{R}^m \Leftrightarrow$ pivot in each row of A .

$\text{Col } A =$ set of all \vec{b} s.t. $A\vec{x} = \vec{b}$ has a solution.

def The null space of A , $\text{Nul } A$, is the set of all solutions of homog. eq. $A\vec{x} = \vec{0}$.

• $\text{Nul } A$ is a subspace of \mathbb{R}^n

• $\text{Nul } A$ is defined implicitly (as solutions of an eq.), $\text{Col } A$ is defined explicitly.

Basis for a subspace

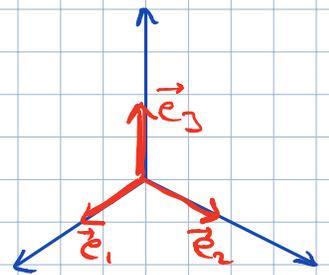
want to describe a subspace by the smallest possible set spanning it.

def A basis for a subspace H of \mathbb{R}^n is a lin. indep. set in H which spans H

Ex: columns of an invertible $n \times n$ matrix A form a basis for $H = \mathbb{R}^n$
(they are lin. indep. and span \mathbb{R}^n by Inv. Mat. Thm.)

E.g. for $A = I_n$, its columns $\vec{e}_1 = \begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$, $\vec{e}_2 = \begin{bmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{bmatrix}$, ..., $\vec{e}_n = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 1 \end{bmatrix}$

set $\{ \vec{e}_1, \dots, \vec{e}_n \}$ - standard basis for \mathbb{R}^n .



Ex: Find a basis for Nul A ,

$$A = \begin{bmatrix} -3 & 6 & -1 & 1 & -7 \\ 1 & -2 & 2 & 3 & -1 \\ 2 & -4 & 5 & 8 & -4 \end{bmatrix}$$

Sol: write the sol. of $A\vec{x} = \vec{0}$ in parametric form:

Aug. Mat. $[A \vec{0}] \sim \begin{bmatrix} \textcircled{1} & -2 & 0 & -1 & 3 & 0 \\ 0 & 0 & \textcircled{1} & 2 & -2 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$

$\underbrace{x_2 \quad x_4 \quad x_5}_{\text{free}}$

RREF $x_1 - 2x_2 - x_4 + 3x_5 = 0$
 $x_3 + 2x_4 - 2x_5 = 0$
 $0 = 0$

$\Rightarrow x_1 = 2x_2 + x_4 - 3x_5$
 $x_3 = -2x_4 + 2x_5$
 x_2, x_4, x_5 free

$$\Rightarrow \vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} 2x_2 + x_4 - 3x_5 \\ x_2 \\ -2x_4 + 2x_5 \\ x_4 \\ x_5 \end{bmatrix} = x_2 \begin{bmatrix} 2 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} 1 \\ 0 \\ -2 \\ 1 \\ 0 \end{bmatrix} + x_5 \begin{bmatrix} -3 \\ 0 \\ 2 \\ 0 \\ 1 \end{bmatrix}$$

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$$\vec{x} = x_2 \vec{u} + x_4 \vec{v} + x_5 \vec{w}$$

Thus: $\text{Nul } A = \text{Span} \{ \vec{u}, \vec{v}, \vec{w} \}$.

Moreover, $\vec{u}, \vec{v}, \vec{w}$ are lin. indep.

$$(x_2 \vec{u} + x_4 \vec{v} + x_5 \vec{w} = \vec{0} \Rightarrow x_2, x_4, x_5 = 0)$$

So, $\{ \vec{u}, \vec{v}, \vec{w} \}$ - basis for $\text{Nul } A$.

Ex:

$$B = \begin{bmatrix} 1 & 2 & 0 & 3 & 0 \\ 0 & 0 & 1 & 4 & 0 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \quad \text{- RREF}$$

$\vec{b}_1 \quad \vec{b}_2 \quad \vec{b}_3 \quad \vec{b}_4 \quad \vec{b}_5$

Q: find a basis for $\text{Col } B$

Sol: note: $\vec{b}_2 = 2\vec{b}_1$, $\vec{b}_4 = 3\vec{b}_1 + 4\vec{b}_3$

So, any lin. comb. of $\vec{b}_1, \dots, \vec{b}_5$ is in fact a lin. comb. of $\vec{b}_1, \vec{b}_3, \vec{b}_5$ (pivot columns)

$$\vec{v} = c_1 \vec{b}_1 + c_2 \vec{b}_2 + c_3 \vec{b}_3 + c_4 \vec{b}_4 + c_5 \vec{b}_5 = \underbrace{(c_1 + 2c_2 + 3c_4)}_{2\vec{b}_1} \vec{b}_1 + \underbrace{(c_3 + 4c_4)}_{3\vec{b}_1 + 4\vec{b}_3} \vec{b}_3 + c_5 \vec{b}_5 \in \text{Span} \{ \vec{b}_1, \vec{b}_3, \vec{b}_5 \}$$

Also, $\vec{b}_1, \vec{b}_3, \vec{b}_5$ are columns of I_3 and thus are lin. indep.

$\Rightarrow \{ \vec{b}_1, \vec{b}_3, \vec{b}_5 \}$ - basis for $\text{Col } B$.

Ex:

$$A = \begin{bmatrix} 1 & 2 & 1 & 7 & 1 \\ -2 & -4 & -1 & -10 & -2 \\ 3 & 6 & 0 & 9 & 1 \\ 1 & 2 & -2 & -5 & 7 \end{bmatrix} \sim B$$

$\vec{a}_1 \quad \vec{a}_2 \quad \vec{a}_3 \quad \vec{a}_4 \quad \vec{a}_5$

↑ ↑ ↑
pivot columns

Q: find a basis of $\text{Col } A$.

Sol: A lin. dependence rel. among col. of A is a sol of $A\vec{x} = \vec{0}$ and $A\vec{x} = \vec{0}$ has same solutions as $B\vec{x} = \vec{0}$!

So: $\vec{b}_2 = 2\vec{b}_1$, $\vec{a}_2 = 2\vec{a}_1$
 $\vec{b}_4 = 3\vec{b}_1 + 4\vec{b}_3 \Rightarrow \vec{a}_4 = 3\vec{a}_1 + 4\vec{a}_3$
 $\vec{b}_1, \vec{b}_3, \vec{b}_5$ lin. indep. $\vec{a}_1, \vec{a}_3, \vec{a}_5$ lin. indep.

Thus: $\{ \vec{a}_1, \vec{a}_3, \vec{a}_5 \}$ is a basis for $\text{Col } A$

Thm Pivot columns of A form a basis for $\text{Col } A$.

④

Warning: we need pivot columns of A itself, not of a REF of A .