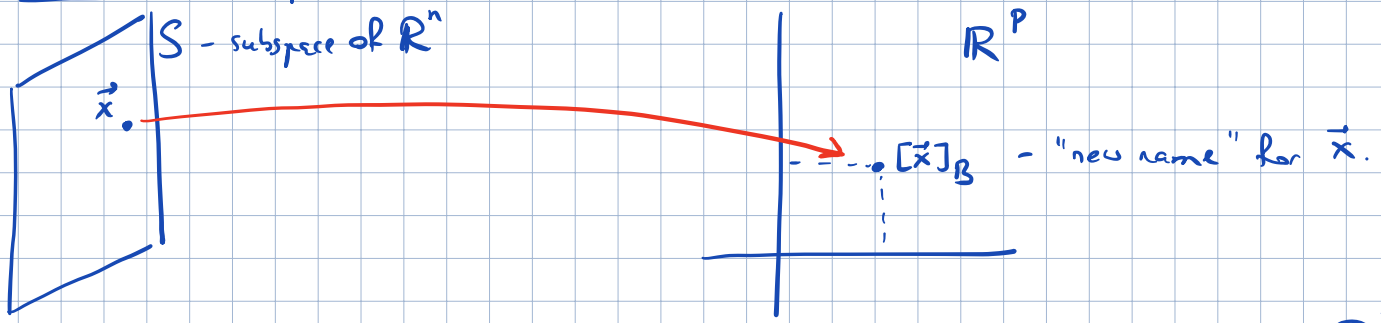


LAST TIME

• if $B = \{\vec{b}_1, \dots, \vec{b}_p\}$ - basis for $S \subset \mathbb{R}^n$, coeffs in $\vec{v} = c_1 \vec{b}_1 + \dots + c_p \vec{b}_p$ are "B-coordinates" of $\vec{v} \in S$, $[\vec{v}]_B = \begin{bmatrix} c_1 \\ \vdots \\ c_p \end{bmatrix}$ - B-coordinate vector.

• if $S = \mathbb{R}^n$, then $\vec{v} = P_B [\vec{v}]_B$ where $P_B = [\vec{b}_1 \dots \vec{b}_n]$, invertible matrix
 $[\vec{v}]_B = P_B^{-1} \vec{v}$

Coordinate mapping



Let B be a basis for S . Then the coordinate mapping $[\]_B: S \rightarrow \mathbb{R}^p$
 $\vec{x} \mapsto [\vec{x}]_B$
 is a 1-1 lin. transf. from S onto \mathbb{R}^p .

(A linear mapping $T: S \rightarrow S'$ which is 1-1 and onto
 $\begin{matrix} \mathbb{R}^n & \mathbb{R}^m \end{matrix}$ - subspaces
 is called an isomorphism.)

Every vector calculation in S is repeated in S' and vice versa,
 E.g. $c_1 \vec{v}_1 + \dots + c_k \vec{v}_k = \vec{0}$ in \mathbb{R}^n iff $c_1 [\vec{v}_1]_B + \dots + c_k [\vec{v}_k]_B = \vec{0}$ in \mathbb{R}^p

So S and S' are "the same".

Thus, a subspace S with a basis of p vectors is indistinguishable from \mathbb{R}^p .

Change of basis

Ex: S - subspace with two bases, $B = \{\vec{b}_1, \vec{b}_2\}$, $C = \{\vec{c}_1, \vec{c}_2\}$ s.t.

$$\vec{b}_1 = 4\vec{c}_1 + \vec{c}_2, \quad \vec{b}_2 = -6\vec{c}_1 + \vec{c}_2. \quad \text{Suppose that}$$

$$\vec{x} = 3\vec{b}_1 + \vec{b}_2, \quad \text{i.e., } [\vec{x}]_B = \begin{bmatrix} 3 \\ 1 \end{bmatrix}.$$

Q: find $[\vec{x}]_C$.

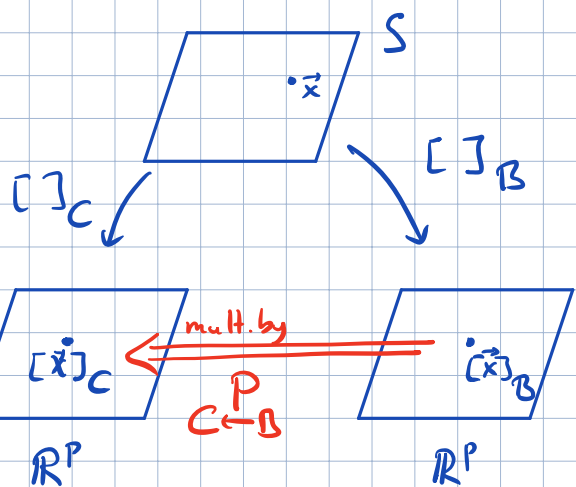
Sol: Apply the coord. mapping defined by C to (*):

$$[\vec{x}]_C = 3[\vec{b}_1]_C + [\vec{b}_2]_C = \underbrace{\begin{bmatrix} [b_1]_C & [b_2]_C \end{bmatrix}}_{\begin{bmatrix} 4 & -6 \\ 1 & 1 \end{bmatrix}} \underbrace{\begin{bmatrix} 3 \\ 1 \end{bmatrix}}_{[\vec{x}]_B} = \begin{bmatrix} 4 & -6 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 3 \\ 1 \end{bmatrix} = \begin{bmatrix} -6 \\ 4 \end{bmatrix}$$

Thm Let $B = \{\vec{b}_1, \dots, \vec{b}_p\}$, $C = \{\vec{c}_1, \dots, \vec{c}_p\}$ be two bases for S .

Then there is a unique $p \times p$ matrix $P_{C \leftarrow B}$ s.t. $[\vec{x}]_C = P_{C \leftarrow B} [\vec{x}]_B$ (#)

Explicitly: $P_{C \leftarrow B} = \begin{bmatrix} [\vec{b}_1]_C & \dots & [\vec{b}_p]_C \end{bmatrix}$ - change-of-coordinates matrix from B to C



Remark: (#) implies

$$[\vec{x}]_B = \left(P_{C \leftarrow B} \right)^{-1} [\vec{x}]_C$$

$$\text{Hence } P_{B \leftarrow C} = \left(P_{C \leftarrow B} \right)^{-1}$$

Change of basis in \mathbb{R}^n

Recall: if $B = \{\vec{b}_1, \dots, \vec{b}_n\}$, $E = \{\vec{e}_1, \dots, \vec{e}_n\}$ stand. basis in \mathbb{R}^n , then $[\vec{b}_i]_E = \vec{b}_i$ and ${}_{E \leftarrow B} P = P_B = [\vec{b}_1 \dots \vec{b}_n]$

Change between two nonstandard bases for \mathbb{R}^n

Ex^{*}: $\vec{b}_1 = \begin{bmatrix} -9 \\ 1 \end{bmatrix}$ $\vec{b}_2 = \begin{bmatrix} -5 \\ -1 \end{bmatrix}$; $\vec{c}_1 = \begin{bmatrix} 1 \\ -4 \end{bmatrix}$ $\vec{c}_2 = \begin{bmatrix} 3 \\ -5 \end{bmatrix}$ two bases for \mathbb{R}^2

Q: find ${}_{C \leftarrow B} P$

Sol: we need $[\vec{b}_1]_C = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$, $[\vec{b}_2]_C = \begin{bmatrix} y_1 \\ y_2 \end{bmatrix}$

By def., $[\vec{c}_1 \ \vec{c}_2] \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \vec{b}_1$, $[\vec{c}_1 \ \vec{c}_2] \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \vec{b}_2$

To solve two lin. systems simultaneously, augment the coeff. matrix by \vec{b}_1 and \vec{b}_2

$$[\vec{c}_1 \ \vec{c}_2 \mid \vec{b}_1 \ \vec{b}_2] = \left[\begin{array}{cc|cc} 1 & 3 & -9 & -5 \\ -4 & -5 & 1 & -1 \end{array} \right] \xrightarrow{R_2 + 4R_1} \left[\begin{array}{cc|cc} 1 & 3 & -9 & -5 \\ 0 & 7 & -35 & -21 \end{array} \right] \rightarrow$$

$$\xrightarrow{\frac{1}{7} R_2} \left[\begin{array}{cc|cc} 1 & 3 & -9 & -5 \\ 0 & 1 & -5 & -3 \end{array} \right] \xrightarrow{R_1 - 3R_2} \left[\begin{array}{cc|cc} 1 & 0 & 6 & 4 \\ 0 & 1 & -5 & -3 \end{array} \right]$$

Thus $[\vec{b}_1]_C = \begin{bmatrix} 6 \\ -5 \end{bmatrix}$ $[\vec{b}_2]_C = \begin{bmatrix} 4 \\ -3 \end{bmatrix}$ and ${}_{C \leftarrow B} P = \begin{bmatrix} 6 & 4 \\ -5 & -3 \end{bmatrix}$

Observe: $[\vec{c}_1 \ \vec{c}_2 \mid \vec{b}_1 \ \vec{b}_2] \rightarrow [I \mid {}_{C \leftarrow B} P]$
"to" basis "from" basis ← works analogously for any two bases for \mathbb{R}^n

(Gauss-Jordan method for computing ${}_{C \leftarrow B} P$)

Another way to construct ${}_{C \leftarrow B} P$:

$${}_{C \leftarrow B} P = {}_{C \leftarrow E} P \cdot {}_{E \leftarrow B} P = (P_C)^{-1} P_B$$

or: $\vec{x} = P_B [\vec{x}]_B$
 $\vec{x} = P_C [\vec{x}]_C \Rightarrow [\vec{x}]_C = P_C^{-1} \vec{x}$
 $\Rightarrow [\vec{x}]_C = \underbrace{P_C^{-1} P_B}_{{}_{C \leftarrow B} P} [\vec{x}]_B$

Ex (back to B, C of $\mathcal{E}x^*$)

(4)

$$\underbrace{\vec{b}_1 = \begin{bmatrix} -9 \\ 1 \end{bmatrix}}_B \quad \underbrace{\vec{b}_2 = \begin{bmatrix} -5 \\ -1 \end{bmatrix}}_C ; \quad \underbrace{\vec{c}_1 = \begin{bmatrix} 1 \\ -4 \end{bmatrix}}_C \quad \underbrace{\vec{c}_2 = \begin{bmatrix} 3 \\ -5 \end{bmatrix}}_C$$

$${}_{C \leftarrow B} P = \begin{bmatrix} 1 & 3 \\ -4 & -5 \end{bmatrix}^{-1} \begin{bmatrix} -9 & -5 \\ 1 & -1 \end{bmatrix} = \frac{1}{7} \begin{bmatrix} -5 & -3 \\ 4 & 1 \end{bmatrix} \begin{bmatrix} -9 & -5 \\ 1 & -1 \end{bmatrix} = \frac{1}{7} \begin{bmatrix} 42 & 28 \\ -35 & -21 \end{bmatrix} \\ = \begin{bmatrix} 6 & 4 \\ -5 & -3 \end{bmatrix}$$

Ex: $B = \left\{ \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \right\}$, $C = \left\{ \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \right\}$, $\vec{x} = \begin{bmatrix} 3 \\ 1 \\ 5 \end{bmatrix} \in \mathbb{R}^3$

• find $[\vec{x}]_B$: $\left[\begin{array}{ccc|c} 0 & 0 & 1 & 3 \\ 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 5 \end{array} \right] \rightarrow \left[\begin{array}{ccc|c} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 5 \\ 0 & 0 & 1 & 3 \end{array} \right] \Rightarrow [\vec{x}]_B = \begin{bmatrix} 1 \\ 5 \\ 3 \end{bmatrix}$

• find ${}_{C \leftarrow B} P$: $\left[\begin{array}{ccc|ccc} 1 & 0 & 1 & 0 & 0 & 1 \\ 1 & 1 & 0 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 & 1 & 0 \end{array} \right] \rightarrow \left[\begin{array}{ccc|ccc} 1 & 0 & 1 & 0 & 0 & 1 \\ 0 & 1 & -1 & 1 & 0 & -1 \\ 0 & 1 & 1 & 0 & 1 & 0 \end{array} \right] \rightarrow$

$\xrightarrow{R_3 - R_2} \left[\begin{array}{ccc|ccc} 1 & 0 & 1 & 0 & 0 & 1 \\ 0 & 1 & -1 & 1 & 0 & -1 \\ 0 & 0 & 2 & -1 & 1 & 1 \end{array} \right] \xrightarrow{\substack{\frac{1}{2} R_3 \\ R_2 + R_3 \\ R_3 - R_2}} \left[\begin{array}{ccc|ccc} 1 & 0 & 0 & \frac{1}{2} & -\frac{1}{2} & \frac{1}{2} \\ 0 & 1 & 0 & \frac{1}{2} & \frac{1}{2} & -\frac{1}{2} \\ 0 & 0 & 1 & -\frac{1}{2} & \frac{1}{2} & \frac{1}{2} \end{array} \right]$

$\underbrace{\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}}_I$
 $\underbrace{\begin{bmatrix} \frac{1}{2} & -\frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} & -\frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} & \frac{1}{2} \end{bmatrix}}_{{}_{C \leftarrow B} P}$

• find $[\vec{x}]_C$: $[\vec{x}]_C = {}_{C \leftarrow B} P [\vec{x}]_B = \frac{1}{2} \begin{bmatrix} 1 & -1 & 1 \\ 1 & 1 & -1 \\ -1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 5 \\ 3 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} -1 \\ 3 \\ 7 \end{bmatrix}$

Rem: If B, C, D three bases for \mathbb{R}^n , then

$${}_{D \leftarrow B} P = {}_{D \leftarrow C} P {}_{C \leftarrow B} P$$

(or: $P_D^{-1} P_B = (P_D^{-1} P_C)(P_C^{-1} P_B)$)