



LAST TIME: $T: V \rightarrow W$
 $\dim V = n$ $\dim W = m$
 $B = \{\vec{v}_1, \dots, \vec{v}_n\}$ C - bases

$[T]_{C \leftarrow B} := [[T(\vec{v}_1)]_C \dots [T(\vec{v}_n)]_C]$ - matrix of T w.r.t. bases B, C .

$$[T(\vec{x})]_C = [T]_{C \leftarrow B} [\vec{x}]_B$$

Ex: $V = \text{span}(\sin x, \cos x) \subset \mathcal{F}$, $D: V \rightarrow V$
 $f(x) \mapsto f'(x)$

$[D]_{B \leftarrow B} = ?$
 $B \leftarrow$ basis $\{\sin x, \cos x\}$

Sol: $[D]_B = [[D(\sin x)]_B \quad [D(\cos x)]_B] = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$

Ex: $D: P_3 \rightarrow P_2$
 $p(x) \mapsto p'(x)$

$B = \{1, x, x^2, x^3\}$ basis for P_3
 $C = \{1, x, x^2\}$ basis for P_2

a) Find $[D]_{C \leftarrow B}$

Sol: $[D]_{C \leftarrow B} = \left[\begin{array}{cccc} [1']_C & [x']_C & [(x^2)']_C & [(x^3)']_C \\ \hline 0 & 1 & 2x & 3x^2 \end{array} \right]_{C \leftarrow B}$
 $= \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 3 \end{bmatrix} = A$

b) use $B' = \{x^3, x^2, x, 1\}$ for P_3 instead

$[D]_{C \leftarrow B'} = \left[\begin{array}{cccc} [(x^3)']_C & [(x^2)']_C & [(x)']_C & [1']_C \\ \hline 0 & 0 & 1 & 0 \\ 0 & 2 & 0 & 0 \\ 3 & 0 & 0 & 0 \end{array} \right]$

c) $[D(p(x))]_C$ can obtain directly $\Rightarrow [D(p(x))]_C = \begin{bmatrix} -1 \\ 0 \\ 6 \end{bmatrix}$
 $D(p(x)) = -1 + 6x^2$
 can obtain as $A[p(x)]_B = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 3 \end{bmatrix} \begin{bmatrix} 5 \\ -1 \\ 0 \\ 2 \end{bmatrix} = \begin{bmatrix} -1 \\ 0 \\ 6 \end{bmatrix}$

Ex: $T: P_2 \rightarrow P_2$ $B = \{1, x, x^2\}$
 $p(x) \mapsto p(2x-1)$

$[T]_B = \left[\begin{array}{ccc} [T(1)]_B & [T(x)]_B & [T(x^2)]_B \\ \hline 1 & 2x-1 & 4x^2-2x+1 \end{array} \right]_B = \begin{bmatrix} 1 & -1 & 1 \\ 0 & 2 & -2 \\ 0 & 0 & 4 \end{bmatrix}$

Rem Consider $I: V \rightarrow V$. Then $[I]_{C \leftarrow B} = P_{C \leftarrow B}$
 $B \swarrow \nearrow C$
 two bases for V
 changes $[\vec{v}]_B$ to $[\vec{v}]_C$

$[\vec{v}_1]_C \cdots [\vec{v}_n]_C$
 vectors of B

Matrices of composite and inverse lin. transformations

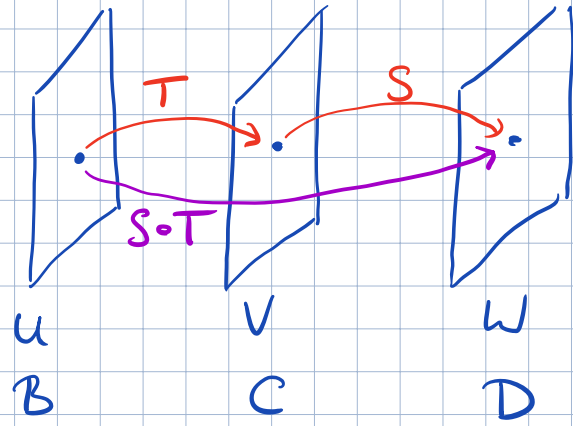
(2)

- Let U, V, W be fin. dim. vector spaces with bases B, C, D , respectively.

Let $T: U \rightarrow V$ and $S: V \rightarrow W$ be lin. transformations. Then

$$\boxed{[S \circ T]_{D \leftarrow B} = [S]_{D \leftarrow C} [T]_{C \leftarrow B}}$$

"matrix of the composite transf. is the product of the matrices"



- Let $T: V \rightarrow W$ be a lin. transf. between n -dimensional v. spaces V and W . Let B and C be bases for V, W .

Then T is invertible iff the matrix $[T]_{C \leftarrow B}$ is invertible.

In this case,
$$\boxed{[T^{-1}]_{B \leftarrow C} = ([T]_{C \leftarrow B})^{-1}}$$

Ex: $T: \mathbb{R}^2 \rightarrow \mathcal{P}_1$ find T^{-1} (if T is invertible)
 $\begin{bmatrix} a \\ b \end{bmatrix} \mapsto a + (a+b)x$

Sol: Let $\mathcal{E} = \{\vec{e}_1, \vec{e}_2\}$ in \mathbb{R}^2 , $\mathcal{E}' = \{1, x\}$ in \mathcal{P}_1 .

$$[T]_{\mathcal{E}' \leftarrow \mathcal{E}} = \left[\underbrace{[T(\vec{e}_1)]_{\mathcal{E}'}}_{1+x}, \underbrace{[T(\vec{e}_2)]_{\mathcal{E}'}}_x \right] = \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix} \Rightarrow$$

$$\Rightarrow [T^{-1}]_{\mathcal{E} \leftarrow \mathcal{E}'} = \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix}^{-1} = \begin{bmatrix} 1 & 0 \\ -1 & 1 \end{bmatrix} \Rightarrow$$

$$\Rightarrow [T^{-1}(a+bx)]_{\mathcal{E}} = [T^{-1}]_{\mathcal{E} \leftarrow \mathcal{E}'} [a+bx]_{\mathcal{E}'} = \begin{bmatrix} 1 & 0 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} a \\ -a+b \end{bmatrix}$$

Thus, $T^{-1}(a+bx) = \begin{bmatrix} a \\ b-a \end{bmatrix}$

Change of basis for a lin. transf.

(3)

Let $T: V \rightarrow V$. How are $[T]_B$ and $[T]_C$ related for B, C
two bases for V ?
 $\uparrow \quad \uparrow$
same space

Thm: Let V be a fin. dim. vector space with bases B and C and let

$T: V \rightarrow V$ be a lin. transf. (*)

Then $[T]_C = P^{-1} [T]_B P$ with $P = \underset{B \leftarrow C}{P}$

Indeed: $[T]_{C \leftarrow C} = \underbrace{P}_{C \leftarrow B} [T]_{B \leftarrow B} \underbrace{P}_{B \leftarrow C}$

Ex: $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ $B = \mathcal{E}$ stand. basis, $[T]_{\mathcal{E}} = \begin{bmatrix} 1 & 3 \\ 2 & 2 \end{bmatrix}$
 $\begin{bmatrix} x \\ y \end{bmatrix} \mapsto \begin{bmatrix} x+3y \\ 2x+2y \end{bmatrix}$ choose $C = \left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 3 \\ -2 \end{bmatrix} \right\}$

Then by (*), $[T]_C = \underbrace{\begin{bmatrix} 1 & 3 \\ 1 & -2 \end{bmatrix}^{-1}}_{P}_{C \leftarrow B} \underbrace{\begin{bmatrix} 1 & 3 \\ 2 & 2 \end{bmatrix}}_{[T]_B} \underbrace{\begin{bmatrix} 1 & 3 \\ 1 & -2 \end{bmatrix}}_{B \leftarrow C} = \dots = \begin{bmatrix} 4 & 0 \\ 0 & -1 \end{bmatrix}$
- diagonal matrix!

Determinants (Poole 4.2)

2

Recall

• for a 2×2 matrix,

$$\det \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} = \begin{vmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{vmatrix} = a_{11}a_{22} - a_{12}a_{21}$$

↑
another notation
for determinant

• for a 1×1 matrix

$$\det [a_{11}] = |a_{11}| = a_{11}$$

• for a 3×3 matrix

$$A = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix},$$

$$\det A = a_{11}a_{22}a_{33} + a_{12}a_{23}a_{31} + a_{13}a_{21}a_{32} - a_{11}a_{23}a_{32} - a_{12}a_{21}a_{33} - a_{13}a_{22}a_{31}$$

← cumbersome formula

mnemonic

rule for 3×3 matrices:

$$\begin{array}{ccc|cc} a_{11} & a_{12} & a_{13} & a_{11} & a_{12} \\ a_{21} & a_{22} & a_{23} & a_{21} & a_{22} \\ a_{31} & a_{32} & a_{33} & a_{31} & a_{32} \end{array}$$

+ terms

- terms

↑ col 1 repeated
↑ col 2 repeated