

(1)

Thm An $m \times n$ matrix U has $0/n$ columns iff $U^T U = I$

Thm Let U be an $m \times n$ matrix with $0/n$ columns; let $\vec{x}, \vec{y} \in \mathbb{R}^n$. Then:

$$a) \|U\vec{x}\| = \|\vec{x}\| \quad b) (U\vec{x}) \cdot (U\vec{y}) = \vec{x} \cdot \vec{y} \quad c) U\vec{x} \perp U\vec{y} \text{ iff } \vec{x} \perp \vec{y}$$

i.e. mapping $\mathbb{R}^n \rightarrow \mathbb{R}^m$ preserves lengths and orthogonality
 $\vec{x} \mapsto U\vec{x}$

- If $m=n$, square mat. U with $0/n$ columns is called an orthogonal matrix
- U is orthogonal iff $U^{-1} = U^T$.

Ex: matrix of rotation by angle φ :

$$U = \begin{bmatrix} \cos \varphi & -\sin \varphi \\ \sin \varphi & \cos \varphi \end{bmatrix}$$

$$U^{-1} = \frac{1}{\cos^2 \varphi + \sin^2 \varphi} \begin{bmatrix} \cos \varphi & \sin \varphi \\ -\sin \varphi & \cos \varphi \end{bmatrix} = U^T \Rightarrow U \text{ is an orthogonal matrix.}$$

Thm If $\{\vec{u}_1, \dots, \vec{u}_p\}$ is an $0/n$ basis for $W \subset \mathbb{R}^n$, then

$$(1) \text{proj}_W \vec{v} = (\vec{v} \cdot \vec{u}_1) \vec{u}_1 + \dots + (\vec{v} \cdot \vec{u}_p) \vec{u}_p.$$

$$(2) \text{If } U = [\vec{u}_1 \dots \vec{u}_p] \text{ then } \boxed{\text{proj}_W \vec{v} = UU^T \vec{v}} \text{ for all } \vec{v} \in \mathbb{R}^n$$

$\underbrace{\text{matrix of projection onto } W}_{\text{matrix of projection onto } W}$

Gram-Schmidt process

Problem: $W \subset \mathbb{R}^n$ find an orthogonal basis for W .

$$\text{Span}(\vec{x}_1, \dots, \vec{x}_p)$$

basis but not orthogonal

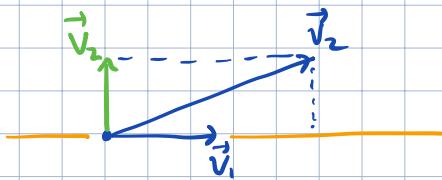
Ex: $\vec{x}_1 = \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix}, \vec{x}_2 = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$ $W = \text{span}(\vec{x}_1, \vec{x}_2) \subset \mathbb{R}^3$

Q: find an orthogonal basis

Sol: set $\vec{v}_1 = \vec{x}_1$; \vec{v}_2 in W , lin. indep. from \vec{v}_1 and \perp to \vec{v}_1

$$\vec{x}_2 = \text{proj}_{\vec{v}_1} \vec{x}_2 + \boxed{\text{perp}_{\vec{v}_1} \vec{x}_2}$$

$\perp \vec{v}_1$ \vec{v}_2



Explicitly: $\text{proj}_{\vec{v}_1} \vec{x}_2 = \frac{\vec{x}_2 \cdot \vec{v}_1}{\vec{v}_1 \cdot \vec{v}_1} \vec{v}_1 = \frac{-1}{5} \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix} = \begin{bmatrix} -1/5 \\ -2/5 \\ 0 \end{bmatrix}$

$$\text{perp}_{\vec{v}_1} \vec{x}_2 = \vec{x}_2 - \text{proj}_{\vec{v}_1} \vec{x}_2 = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} - \begin{bmatrix} -1/5 \\ -2/5 \\ 0 \end{bmatrix} = \begin{bmatrix} -4/5 \\ 2/5 \\ 1 \end{bmatrix}$$

so: $\left\{ \vec{v}_1 = \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix}, \vec{v}_2 = \begin{bmatrix} -4/5 \\ 2/5 \\ 1 \end{bmatrix} \right\}$ - orthog. basis for W .

{ rescale }

$$\left\{ \vec{v}_1 = \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix}, \vec{v}_2 = \begin{bmatrix} -4 \\ 2 \\ 5 \end{bmatrix} \right\}$$
 - more convenient,
also orthogonal

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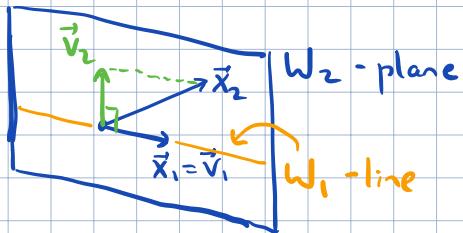
Generally Let $W = \text{span}(\underbrace{\vec{x}_1, \dots, \vec{x}_p}_{\text{basis}})$

want to construct an orthog. basis for W , $\{\vec{v}_1, \dots, \vec{v}_p\}$

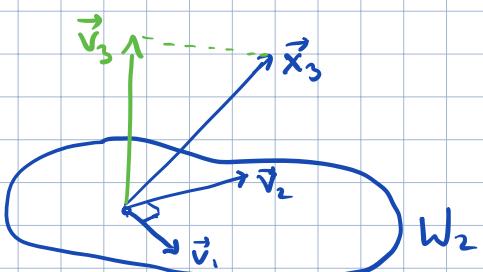
Step 1: set $\vec{v}_1 = \vec{x}_1$, $W_1 = \text{span}(\vec{x}_1) = \text{span}(\vec{v}_1)$

Step 2: $W_2 = \text{span}(\vec{x}_1, \vec{x}_2)$ orthog. basis: $\vec{v}_1 = \vec{x}_1$

$$\begin{aligned}\vec{v}_2 &= \text{perp}_{W_1} \vec{x}_2 \\ &= \vec{x}_2 - \frac{\vec{x}_2 \cdot \vec{v}_1}{\vec{v}_1 \cdot \vec{v}_1} \vec{v}_1\end{aligned}$$



Step 3: $W_3 = \text{span}(\vec{x}_1, \vec{x}_2, \vec{x}_3)$ orthog. basis: \vec{v}_1, \vec{v}_2 - already constructed



$$\begin{aligned}\vec{v}_3 &= \text{perp}_{W_2} \vec{x}_3 \\ &= \vec{x}_3 - \frac{\vec{x}_3 \cdot \vec{v}_1}{\vec{v}_1 \cdot \vec{v}_1} \vec{v}_1 - \frac{\vec{x}_3 \cdot \vec{v}_2}{\vec{v}_2 \cdot \vec{v}_2} \vec{v}_2\end{aligned}$$

$\{\vec{v}_1, \vec{v}_2\}$ - orthog. basis

Step p: $W = W_p = \text{span}(\vec{x}_1, \dots, \vec{x}_p)$

Orthog. basis: $\vec{v}_1, \dots, \vec{v}_{p-1}, \vec{v}_p = \text{perp}_{W_{p-1}} \vec{x}_p = \vec{x}_p - \frac{\vec{x}_p \cdot \vec{v}_1}{\vec{v}_1 \cdot \vec{v}_1} \vec{v}_1 - \dots - \frac{\vec{x}_p \cdot \vec{v}_{p-1}}{\vec{v}_{p-1} \cdot \vec{v}_{p-1}} \vec{v}_{p-1}$

$\{\vec{v}_1, \dots, \vec{v}_{p-1}\}$
- orthog. basis

Ex: $\vec{x}_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \vec{x}_2 = \begin{bmatrix} 0 \\ 1 \\ 1 \\ 0 \end{bmatrix}, \vec{x}_3 = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}$ - basis for $W = \text{span}(\vec{x}_1, \vec{x}_2, \vec{x}_3) \subset \mathbb{R}^4$

Q: Find an orthogonal basis for W .

Sol: $\vec{v}_1 = \vec{x}_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \\ 0 \end{bmatrix}$

$$\vec{v}_2 = \text{perp}_{\vec{v}_1} \vec{x}_2 = \vec{x}_2 - \frac{\vec{x}_2 \cdot \vec{v}_1}{\vec{v}_1 \cdot \vec{v}_1} \vec{v}_1 = \begin{bmatrix} 0 \\ 1 \\ 1 \\ 0 \end{bmatrix} - \frac{1}{2} \begin{bmatrix} 1 \\ 1 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} -\frac{1}{2} \\ \frac{1}{2} \\ 1 \\ 0 \end{bmatrix}$$

rescale by 2

$$\vec{v}_2 = \begin{bmatrix} -1 \\ 1 \\ 2 \\ 0 \end{bmatrix}$$

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$$\vec{v}_3 = \text{perp}_{\text{Span}(\vec{v}_1, \vec{v}_2)} \vec{x}_3 = \vec{x}_3 - \frac{\vec{x}_3 \cdot \vec{v}_1}{\vec{v}_1 \cdot \vec{v}_1} \vec{v}_1 - \frac{\vec{x}_3 \cdot \vec{v}_2}{\vec{v}_2 \cdot \vec{v}_2} \vec{v}_2$$

$$= \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} - \frac{2}{2} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} - \left(\frac{2}{6} \right) \begin{bmatrix} -1 \\ 1 \\ 2 \\ 0 \end{bmatrix} = \begin{bmatrix} \frac{1}{3} \\ -\frac{1}{3} \\ \frac{1}{3} \end{bmatrix} \xrightarrow{\text{rescale}} \vec{v}'_3 = \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$$

Thus, $\{\vec{v}_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \vec{v}_2 = \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix}, \vec{v}'_3 = \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}\}$ - orthogonal basis for W

Q: Find an orthonormal basis for W

Sol: normalize $\vec{v}_1, \vec{v}_2, \vec{v}'_3$ to unit length:

$$\left\{ \vec{u}_1 = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \vec{u}_2 = \frac{1}{\sqrt{6}} \begin{bmatrix} -1 \\ 1 \\ 2 \\ 0 \end{bmatrix}, \vec{u}_3 = \frac{1}{\sqrt{12}} \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} \right\} - \mathbb{R}^n \text{ basis for } W.$$

QR factorization

Thm (QR Factorization)

If A is an $m \times n$ matrix with lin. indep. columns, then A can be factored as

$A = QR$ where Q is an $m \times n$ matrix whose columns form an \mathbb{R}^n basis

for $\text{col}(A)$ and R is an $n \times n$ upper-triangular invertible matrix with positive diagonal entries.

Idea: $A = [\vec{x}_1 \dots \vec{x}_n]$ $W = \text{col}(A) = \text{Span}(\vec{x}_1, \dots, \vec{x}_n) \subset \mathbb{R}^m$

$\left\{ \vec{u}_1, \dots, \vec{u}_n \right\}$ - \mathbb{R}^n basis for W

Gram-Schmidt + normalization

$$\vec{x}_k = \underbrace{\text{proj}_{W_{k-1}} \vec{x}_k}_{\text{"}} + \vec{v}_k \quad \leftarrow \text{from Gram-Schmidt}$$

$$= r_{1k} \vec{u}_1 + \dots + r_{k-1,k} \vec{u}_{k-1} + r_{kk} \vec{u}_k + 0 \cdot \vec{u}_{k+1} + \dots + 0 \cdot \vec{u}_n$$

$$\Rightarrow A = [\vec{u}_1 \dots \vec{u}_n] \begin{bmatrix} r_{11} & r_{12} & \dots & r_{1n} \\ 0 & r_{22} & \dots & r_{2n} \\ \vdots & 0 & \ddots & \vdots \\ 0 & 0 & \dots & 0 & r_{nn} \end{bmatrix}$$

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Ex: $A = \begin{bmatrix} 1 & 0 & 1 \\ 1 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}$ find QR Factorization

↑ ↑ ↑
 $\vec{x}_1 \quad \vec{x}_2 \quad \vec{x}_3$

- vectors from Ex*

Sol: $Q = [\vec{u}_1 \vec{u}_2 \vec{u}_3] = \boxed{\begin{bmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{6}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{6}} & -\frac{1}{\sqrt{12}} \\ 0 & \frac{2}{\sqrt{6}} & \frac{1}{\sqrt{12}} \\ 0 & 0 & \frac{3}{\sqrt{12}} \end{bmatrix}}$

a short cut to get R: $A = QR \Rightarrow Q^T A = \underbrace{Q^T Q}_{I} R = R$

So, $R = Q^T A = \dots = \boxed{\begin{bmatrix} 2 & \sqrt{2} & \sqrt{2} \\ 0 & \frac{3}{\sqrt{6}} & \frac{2}{\sqrt{6}} \\ 0 & 0 & \frac{4}{\sqrt{12}} \end{bmatrix}}$