

Calculation of Slow Invariant Manifolds for Reactive Systems

Ashraf N. Al-Khateeb

Joseph M. Powers

Samuel Paolucci

Department of Aerospace and Mechanical Engineering

Andrew J. Sommes

Jeffery A. Diller

Department of Mathematics

University of Notre Dame, Notre Dame, Indiana

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Outline

- Introduction
- Slow Invariant Manifold (SIM)
- Method of Construction
- Illustration Using Model Problem
- Application to Hydrogen-Air Reactive System
- Summary

Introduction

Motivation and background

- Detailed kinetics are essential for accurate modeling of real systems.
- Reactive flow systems admit multi-scale solutions.
- Severe stiffness arises in detailed gas-phase kinetics modeling.
- Computational cost for reactive flow simulations increases with the spatio-temporal scales' range, the number of species, and the number of reactions.
- Manifold methods provide a potential for computational saving.

Partial review of manifold construction in reactive systems

- ILDM, CSP, and ICE-PIC are **approximations** of the system's slow invariant manifold.
- MEPT, RCCE, and similar methods are based on minimizing a thermodynamic potential function.
- Iterative methods may not converge.
- Davis and Skodje, 1999, present a technique to construct the 1-D SIM based on global phase analysis.
- Creta *et al.* and Giona *et al.*, 2006, extend the technique to slightly higher dimensional reactive systems.

Long-term objective

Create an efficient algorithm that reduces the computational cost for simulating reactive flows based on a reduction in the stiffness and dimension of the composition phase space.

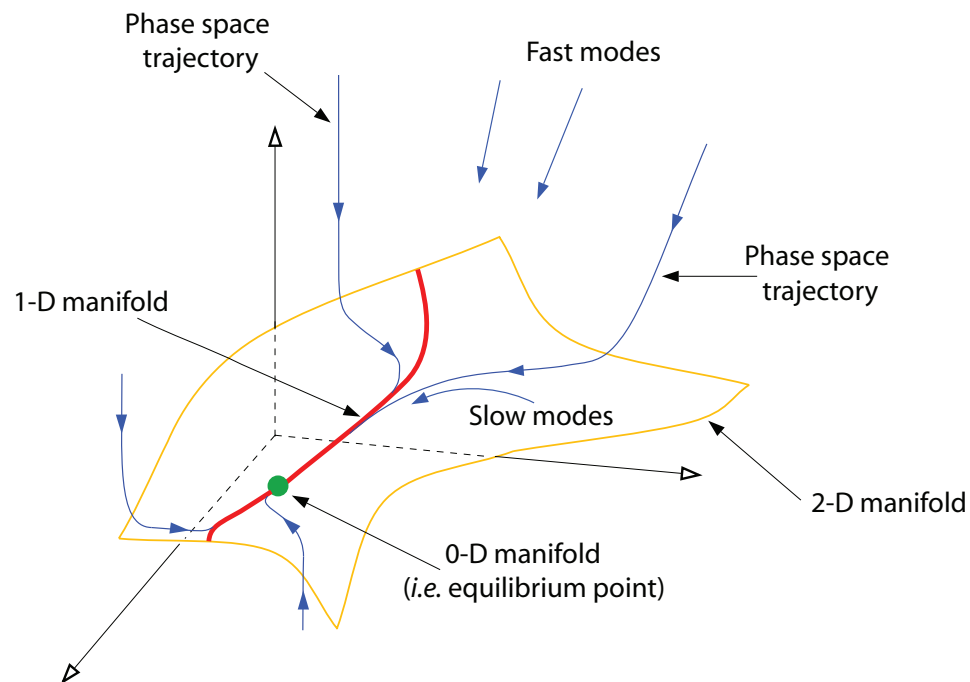
Immediate objective

Construct 1-D SIMs for dynamical system arising from modeling unsteady spatially homogenous closed reactive systems.

Slow Invariant Manifold (SIM)

- The composition phase space for closed spatially homogeneous reactive system:

$$\frac{dz}{dt} = \mathbf{f}(z), \quad z \in \mathbb{R}^3.$$



- An **invariant manifold** is defined as a subset $\mathcal{S} \subset \mathbb{R}^{N-L-Q}$ if for any solution $\mathbf{z}(t), \mathbf{z}(t_0) \in \mathcal{S}$, implies that for any $t_f > t_0$, $\mathbf{z}(t) \in \mathcal{S}$ for all $t \in [t_0, t_f]$.
- Not all invariant manifolds are attracting.
- SIMs describe the asymptotic structure of the invariant attracting trajectories.
- Attractiveness of a SIM increases as the system's stiffness increases.
- On a SIM, only slow modes are active.
- SIMs can be constructed by identifying all critical points, **finite** and **infinite**, and connecting relevant ones via heteroclinic orbits.

Mathematical Model

For a mixture of mass m confined in volume V containing N species composed of L elements that undergo J reversible reactions,

$$\frac{dn_i}{dt} = V\dot{\omega}_i, \quad i = 1, \dots, N,$$

where,

$$\dot{\omega}_i = \sum_{j=1}^J \nu_{ij} k_j \left(\prod_{i=1}^N \left(\frac{n_i}{V} \right)^{\nu'_{ij}} - \frac{1}{K_j^c} \prod_{i=1}^N \left(\frac{n_i}{V} \right)^{\nu''_{ij}} \right), \quad i = 1, \dots, N,$$

$$k_j = A_j T^{\beta_j} \exp \left(\frac{-E_j}{\mathcal{R}T} \right), \quad j = 1, \dots, J,$$

$$K_j^c = \left(\frac{p^o}{\mathcal{R}T} \right)^{\sum_{i=1}^N \nu_{ij}} \exp \left(-\frac{\sum_{i=1}^N \bar{\mu}_i^o \nu_{ij}}{\mathcal{R}T} \right), \quad j = 1, \dots, J.$$

System reduction

- In chemical reactions, the total number of moles of each element is conserved,

$$\sum_{i=1}^N \phi_{li} n_i^* = \sum_{i=1}^N \phi_{li} n_i, \quad l = 1, \dots, L.$$

- Additional Q constraints can arise in special cases.
- The reactive system is recast as an autonomous dynamical system,

$$\frac{dz_i}{dt} = f_i(z_1, \dots, z_{N-L-Q}), \quad i = 1, \dots, N - L - Q,$$

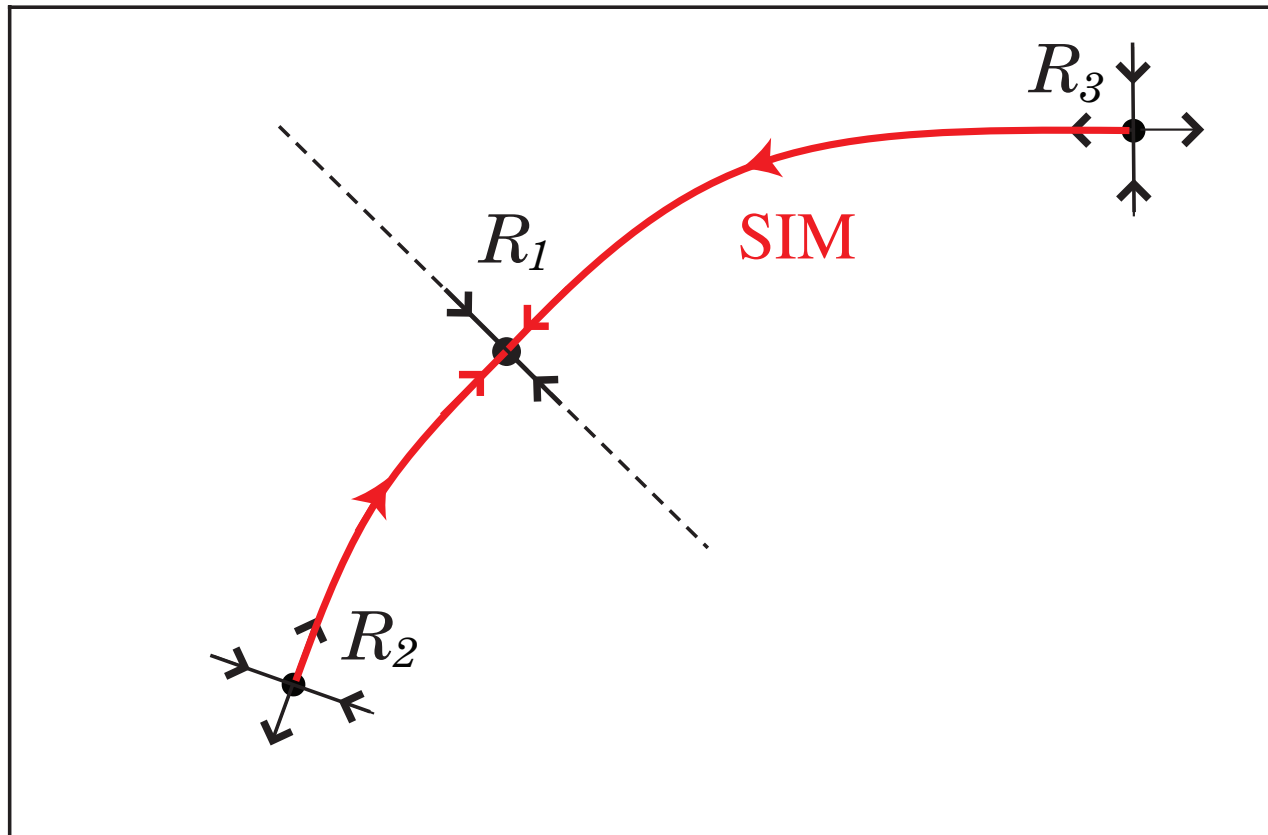
where,

$$\mathbf{z} = \mathcal{L}(\mathbf{n}) \quad | \quad \mathcal{L} : (\mathbb{R}^N \rightarrow \mathbb{R}^{N-L-Q}) .$$

Method of Construction

- For isothermal reactive systems, reaction speeds depend on combinations of polynomials of \mathbf{z} .
- The set of equilibria of the full reaction network is complex:
 $\{\mathbf{z}^e \in \mathbb{C}^{N-L-Q} \mid \mathbf{f}(\mathbf{z}^e) = \mathbf{0}\}$.
- The set consists of several different dimensional components and contains **finite** and **infinite** equilibria.
- A 1-D SIM has a maximum of two branches that connect the unique physical critical point (a sink) to two equilibria.
- These equilibria are identified by their special dynamical character: their eigenvalue spectrum typically contains only one unstable direction.

Sketch of SIM construction



Projective space

- One-to-one mapping of the composition space, $\mathbb{R}^{N-L-Q} \rightarrow \mathbb{R}^{N-L-Q}$,

$$Z_k = \frac{1}{z_k}, \quad k \in \{1, \dots, N - L - Q\},$$

$$Z_i = \frac{z_i}{z_k}, \quad i \neq k, \quad i = 1, \dots, N - L - Q.$$

- This maps equilibria located at infinity into a finite domain.
- To deal with the time singularity, we add the transformation

$$\frac{dt}{d\tau} = (Z_k)^{d-1},$$

where d is the highest polynomial degree of $\mathbf{f}(\mathbf{z})$.

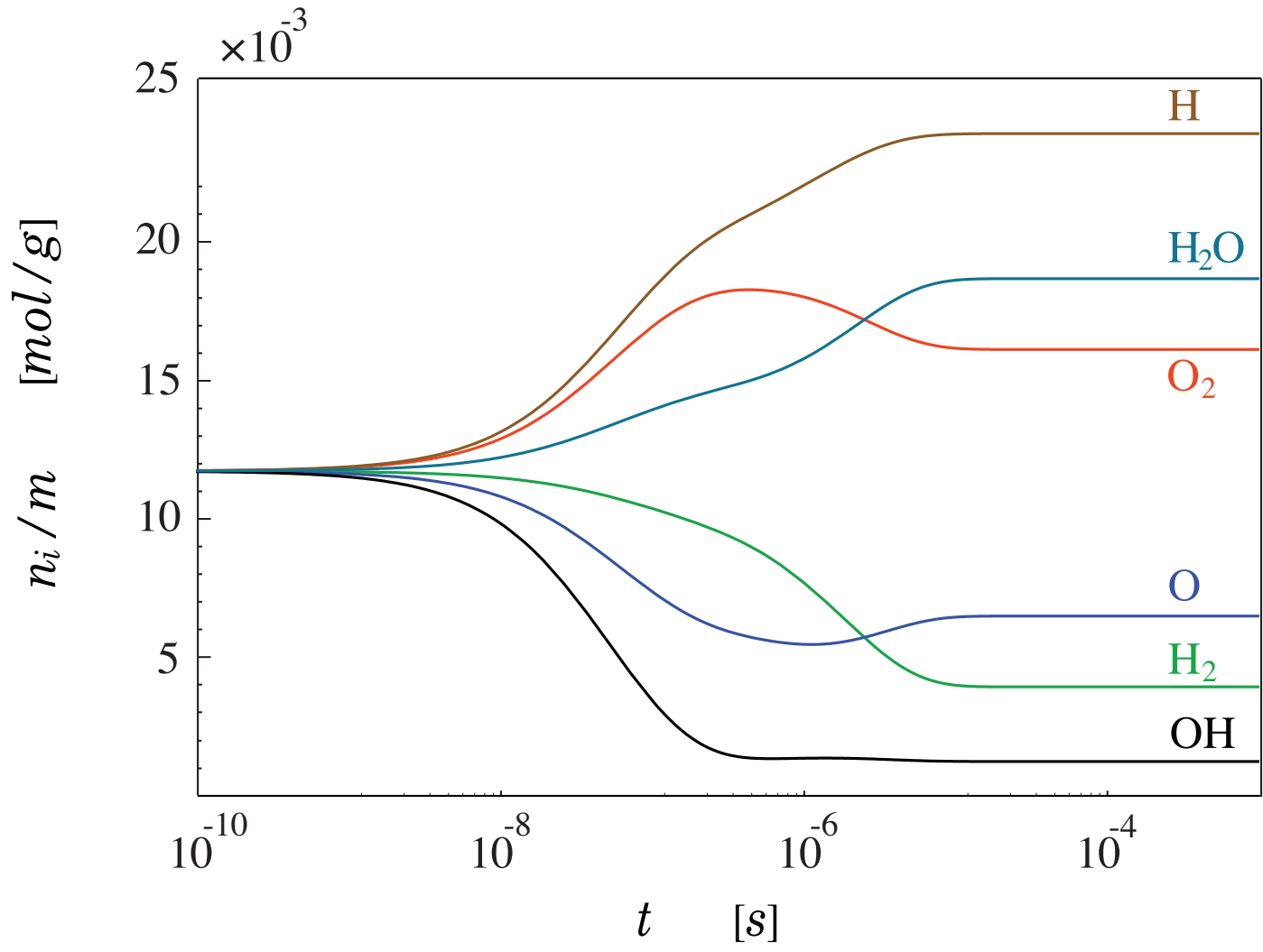
Computational strategy

- We use the `Bertini` software (based on a homotopy continuation numerical technique) to compute the system's equilibria up to any desired accuracy.
- Thermodynamic data is obtained from `Chemkin-II`.
- The SIM heteroclinic orbits are obtained by numerical integration of the species evolution equations using a computationally inexpensive scheme.
- Computation time is typically less than 1 minute on a 2.16 GHz Mac Pro machine.

Simple Hydrogen-Oxygen Mechanism

- The kinetic model is adopted from Michael, 1992, *Prog. Energy Combust. Sci.* **18**(4), p. 327.
- The mechanism consists of $J = 8$ bimolecular elementary reactions involving $N = 6$ species $\{H, H_2, O, O_2, OH, H_2O\}$ and $L = 2$ elements $\{H, O\}$. In addition, since the total number of moles is constant, $Q = 1$. Subsequently, $\mathbf{z} \in \mathbb{R}^3$.
- The system is spatially homogenous with isothermal and isochoric conditions, $T = 1200\text{ K}$, $V = 10^3\text{ cm}^3$.
- Selected species are $i = \{1, 2, 3\} = \{H_2, O, O_2\}$.
- Initial number of moles of all species are $n_i^* = 10^{-3}\text{ mol}$.

Reactive system evolution



Dynamical system

$$\left. \begin{aligned} \frac{dz_1}{dt} &= 3.45 \times 10^4 - 1.68 \times 10^{11} z_1 - 3.47 \times 10^{16} z_1^2 \\ &\quad - 1.35 \times 10^{10} z_2 + 6.27 \times 10^{16} z_1 z_2 + 1.40 \times 10^{10} z_3 \\ &\quad + 1.11 \times 10^{17} z_1 z_3 - 1.35 \times 10^{16} z_2 z_3 - 2.04 \times 10^{16} z_3^2, \\ \\ \frac{dz_2}{dt} &= 7.69 \times 10^5 + 2.66 \times 10^{11} z_1 + 2.25 \times 10^{16} z_1^2 \\ &\quad - 1.29 \times 10^{12} z_2 - 2.47 \times 10^{17} z_1 z_2 \\ &\quad + 3.91 \times 10^{17} z_2^2 - 8.66 \times 10^{11} z_3 - 1.51 \times 10^{17} z_1 z_3 \\ &\quad 7.49 \times 10^{17} z_2 z_3 + 2.46 \times 10^{17} z_3^2, \\ \\ \frac{dz_3}{dt} &= 6.84 \times 10^{11} z_2 + 1.37 \times 10^{17} z_1 z_2 - 2.74 \times 10^{17} z_2^2 \\ &\quad - 4.10 \times 10^{17} z_2 z_3 - 2.24 \times 10^{15} z_3 (10^{-6} - z_1 + z_3), \end{aligned} \right\} \equiv \mathbf{f}(\mathbf{z}).$$

Finite equilibria

$$R_1 \equiv (z_1^e, z_2^e, z_3^e) = (-5.84 \times 10^{-2}, 6.85 \times 10^{-4}, -3.52 \times 10^{-4}) \text{ mol/g},$$

$$(\lambda_1, \lambda_2, \lambda_3) = (5.93 \times 10^6 \pm i5.10 \times 10^5, -1.18 \times 10^6) \text{ 1/s},$$

$$R_2 \equiv (z_1^e, z_2^e, z_3^e) = (4.65 \times 10^{-2}, 0, 3.49 \times 10^{-2}) \text{ mol/g},$$

$$(\lambda_1, \lambda_2, \lambda_3) = (-1.01 \times 10^7, -3.35 \times 10^6, 7.93 \times 10^5) \text{ 1/s},$$

$$R_3 \equiv (z_1^e, z_2^e, z_3^e) = (3.73 \times 10^{-3}, 6.32 \times 10^{-3}, 1.61 \times 10^{-2}) \text{ mol/g},$$

$$(\lambda_1, \lambda_2, \lambda_3) = (-1.02 \times 10^7, -1.23 \times 10^6, -4.30 \times 10^5) \text{ 1/s},$$

$$R_4 \equiv (z_1^e, z_2^e, z_3^e) = (6.33 \times 10^{-3}, -1.86 \times 10^{-3}, 2.49 \times 10^{-2}) \text{ mol/g},$$

$$(\lambda_1, \lambda_2, \lambda_3) = (6.88 \times 10^6, 3.51 \times 10^6, 1.57 \times 10^6) \text{ 1/s},$$

$$R_5 \equiv (z_1^e, z_2^e, z_3^e) = (1.28 \times 10^{-3}, -5.98 \times 10^{-2}, 6.00 \times 10^{-2}) \text{ mol/g},$$

$$(\lambda_1, \lambda_2, \lambda_3) = (5.65 \times 10^7, 3.56 \times 10^6, -1.06 \times 10^4) \text{ 1/s},$$

$$R_6 \equiv (z_1^e, z_2^e, z_3^e) = (1.43 \times 10^{-3}, -7.58 \times 10^{-2}, 7.08 \times 10^{-2}) \text{ mol/g},$$

$$(\lambda_1, \lambda_2, \lambda_3) = (7.19 \times 10^7, 4.47 \times 10^6, 1.05 \times 10^4) \text{ 1/s}.$$

Infinite equilibria

- Employ the projective space mapping with $d = 2$ and $k = 2$:

$$\frac{d}{d\tau} \begin{pmatrix} t \\ Z_1 \\ Z_2 \\ Z_3 \end{pmatrix} = Z_2^2 \cdot \begin{pmatrix} Z_2^{-1} \\ f_1(Z_1, Z_2, Z_3) - Z_1 f_2(Z_1, Z_2, Z_3) \\ -Z_2 f_2(Z_1, Z_2, Z_3) \\ f_3(Z_1, Z_2, Z_3) - Z_3 f_2(Z_1, Z_2, Z_3) \end{pmatrix} \equiv \mathbf{F}(\mathbf{Z}),$$

$$I_1 \equiv (Z_1^e, Z_2^e, Z_3^e) = (-9.77, 0, -4.59),$$

$$(\lambda_1, \lambda_2, \lambda_3) = (-5.74 \times 10^{12} \pm i7.83 \times 10^{12}, 6.10 \times 10^{12}),$$

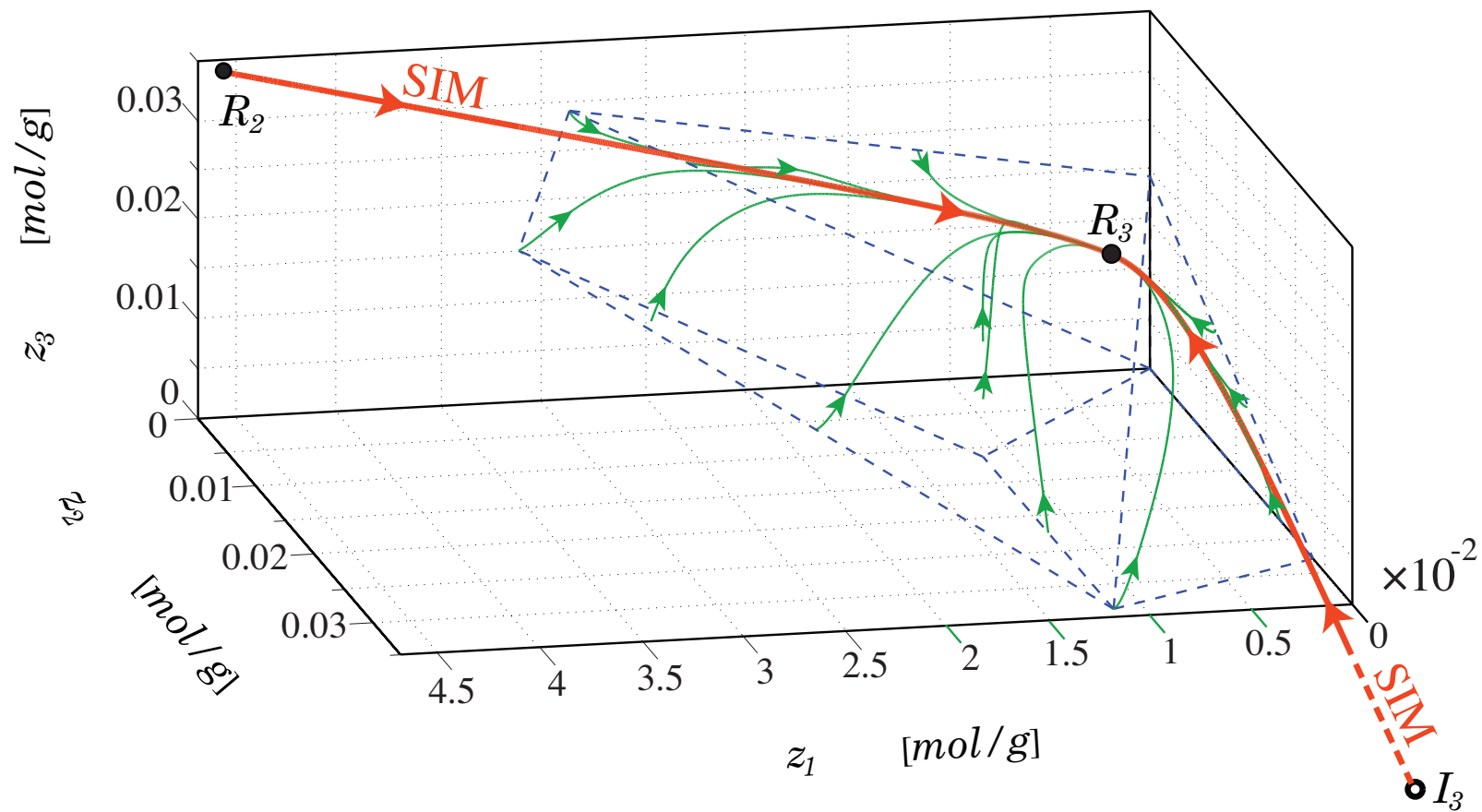
$$I_2 \equiv (Z_1^e, Z_2^e, Z_3^e) = (0.60, 0, -0.48),$$

$$(\lambda_1, \lambda_2, \lambda_3) = (-1.19 \times 10^{13}, 7.35 \times 10^{11}, 6.32 \times 10^{11}),$$

$$I_3 \equiv (Z_1^e, Z_2^e, Z_3^e) = (-0.01, 0, -0.67),$$

$$(\lambda_1, \lambda_2, \lambda_3) = (-1.12 \times 10^{13}, -6.50 \times 10^{11}, 7.62 \times 10^9).$$

The system's 1-D SIM

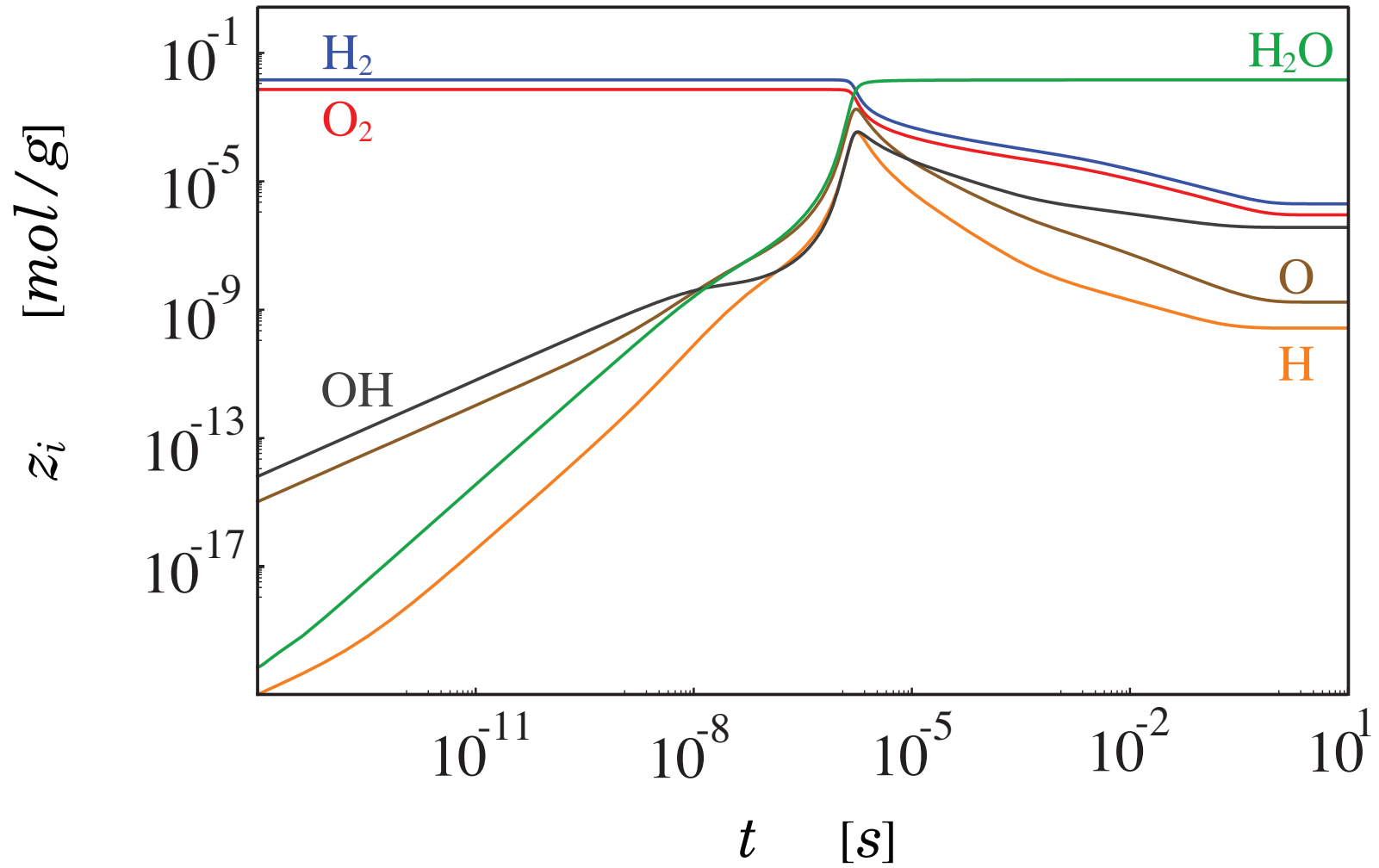


Detailed Hydrogen-Air Mechanism

- A kinetic model is adopted from Miller *et al.*, 1982, *Proc. Combust. Ins.* **19**, p. 181.
- The mechanism consists of $J = 19$ reversible reactions involving $N = 9$ species, $L = 3$ elements, and $Q = 0$, so that $\mathbf{z} \in \mathbb{R}^6$.
- Closed and spatially homogenous system with isothermal and isochoric conditions at $T = 1500\text{ K}$, and $p^* = 10^7\text{ dyne/cm}^2$.
- Stoichiometric mixture $2H_2 + (O_2 + 3.76N_2)$.
- Selected species are

$$i = \{1, 2, 3, 4, 5, 6\} = \{H_2, O_2, H, O, OH, H_2O\}.$$

Reactive system evolution

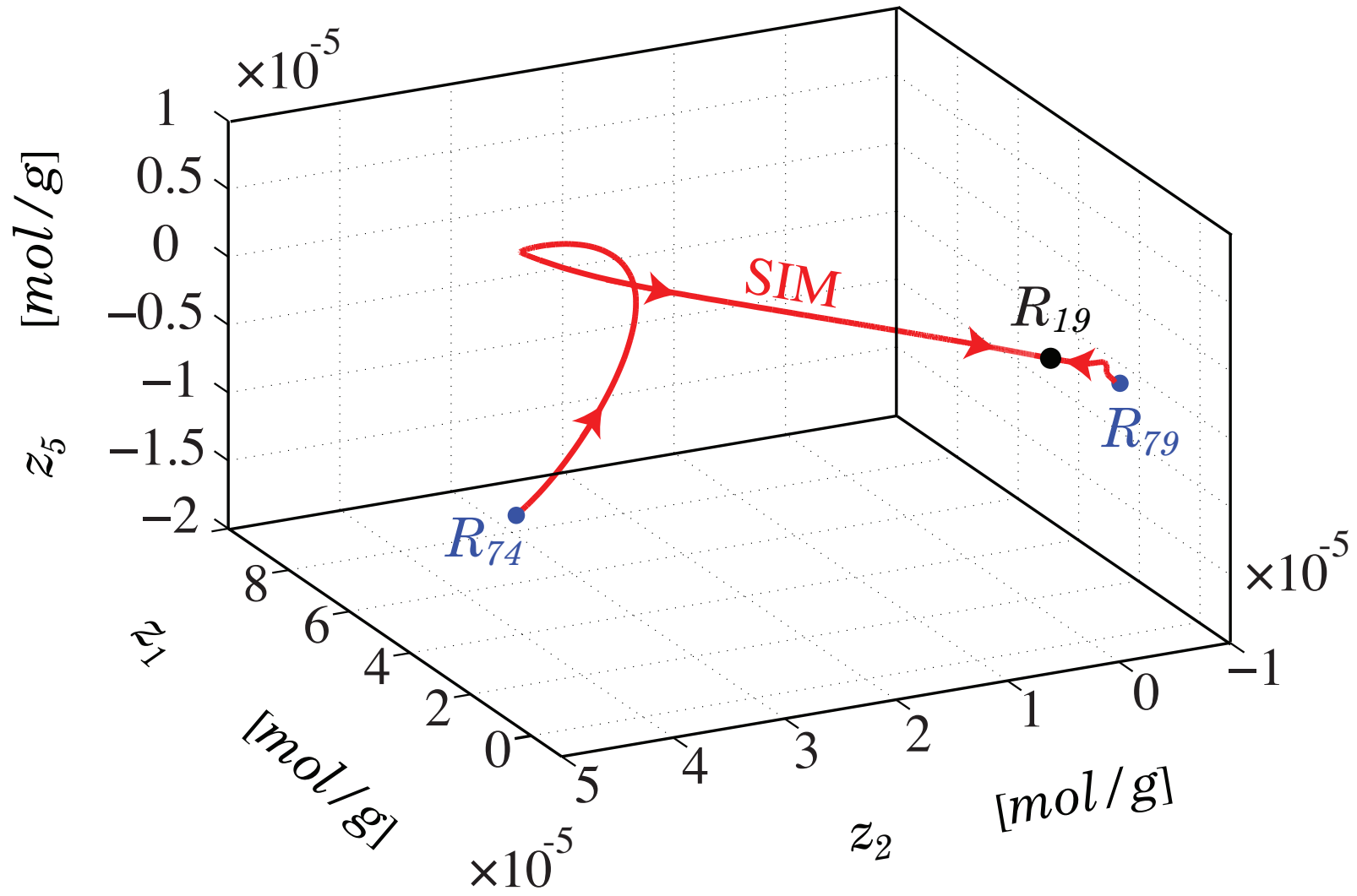


System's equilibria

- The system has 284 **finite** and 42 **infinite** equilibria.
- The set of finite equilibria contains 90 real and 186 complex 0- D , one 1- D , one 2- D , and six 3- D equilibria.
- The set of infinite equilibria contains 18 real and 18 complex 0- D , and six 1- D equilibria.
- Only 14 critical points have an eigenvalue spectrum that contains only one unstable direction.
- Inside the physical domain there is a unique equilibrium:

$$R_{19} = (1.98 \times 10^{-6}, 9.00 \times 10^{-7}, 1.72 \times 10^{-9}, \\ 2.67 \times 10^{-10}, 3.66 \times 10^{-7}, 1.44 \times 10^{-2}) \text{ mol/g.}$$

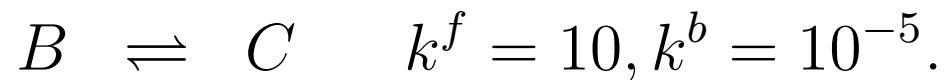
3-D projection of the system's SIM



Summary and Conclusions

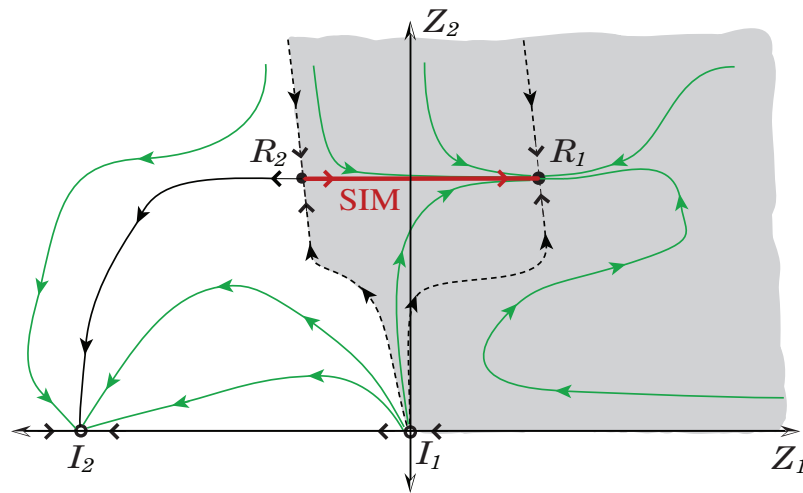
- Once the difficult task of identifying all equilibria is complete, constructing the actual SIM is computationally **efficient** and algorithmically **easy**; thus, there is **no need** to identify it only approximately.
- Identifying all critical points, **finite** and **infinite**, plays a major role in the construction of the SIM.
- The construction procedure can be systematically extended to construct higher-dimensional SIMs.

Simple Reactive System

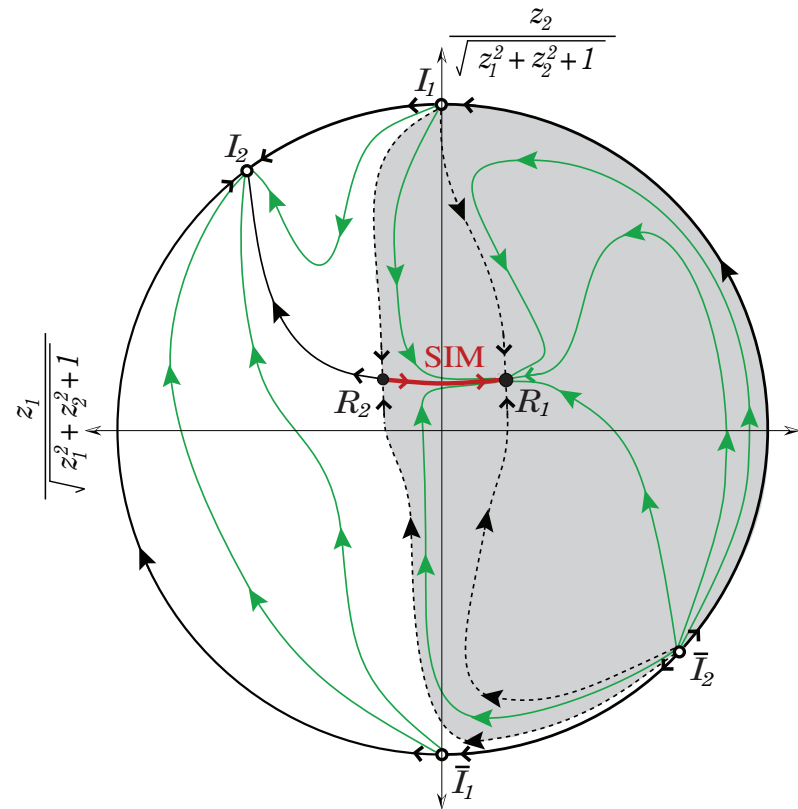


- A reactive system adopted from D. Lebiedz, 2004, *J. Chem. Phys.* **120** (15), p. 6890.
- Model consists of $J = 2$ reversible reactions involving $N = 3$ species $\{c_A, c_B, c_C\}$
- Conservation of mass, $c_A + c_B + c_C = 1$, so that $\mathbf{z} \in \mathbb{R}^2$.
- Major species are $i = \{1, 2\} = \{A, B\}$,

The system's global phase space

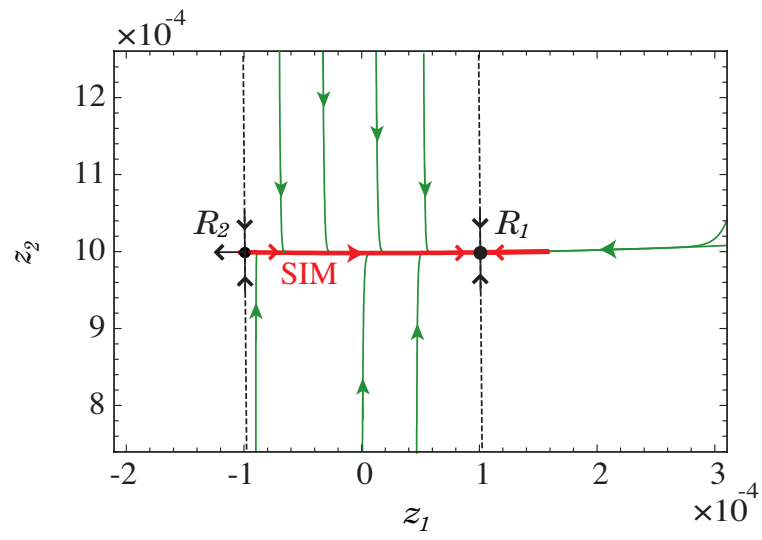
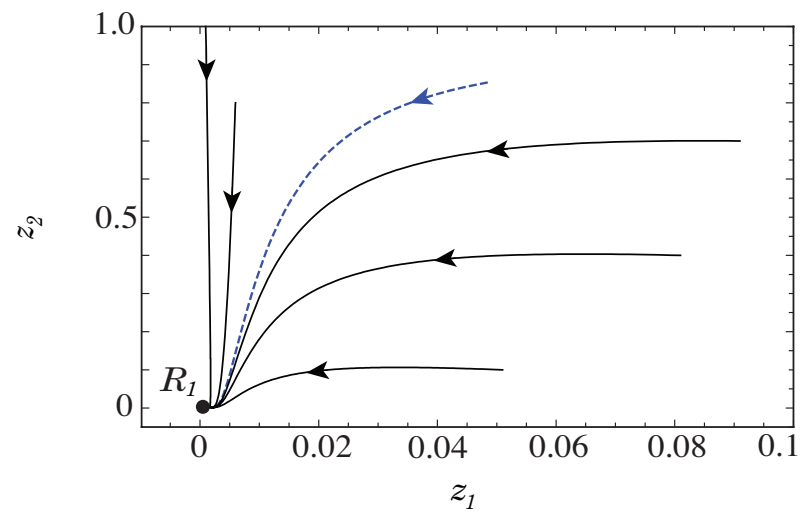
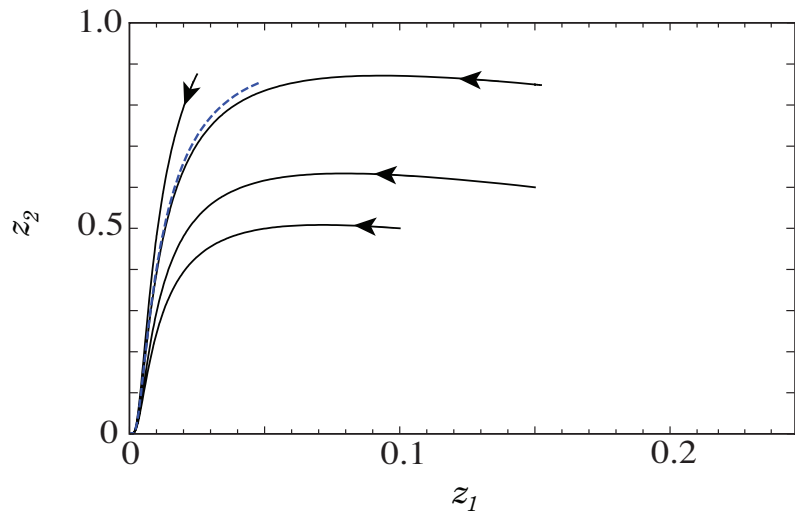


The projective space.



Projection from Poincaré's sphere.

The 1-D SIM vs. MEPT

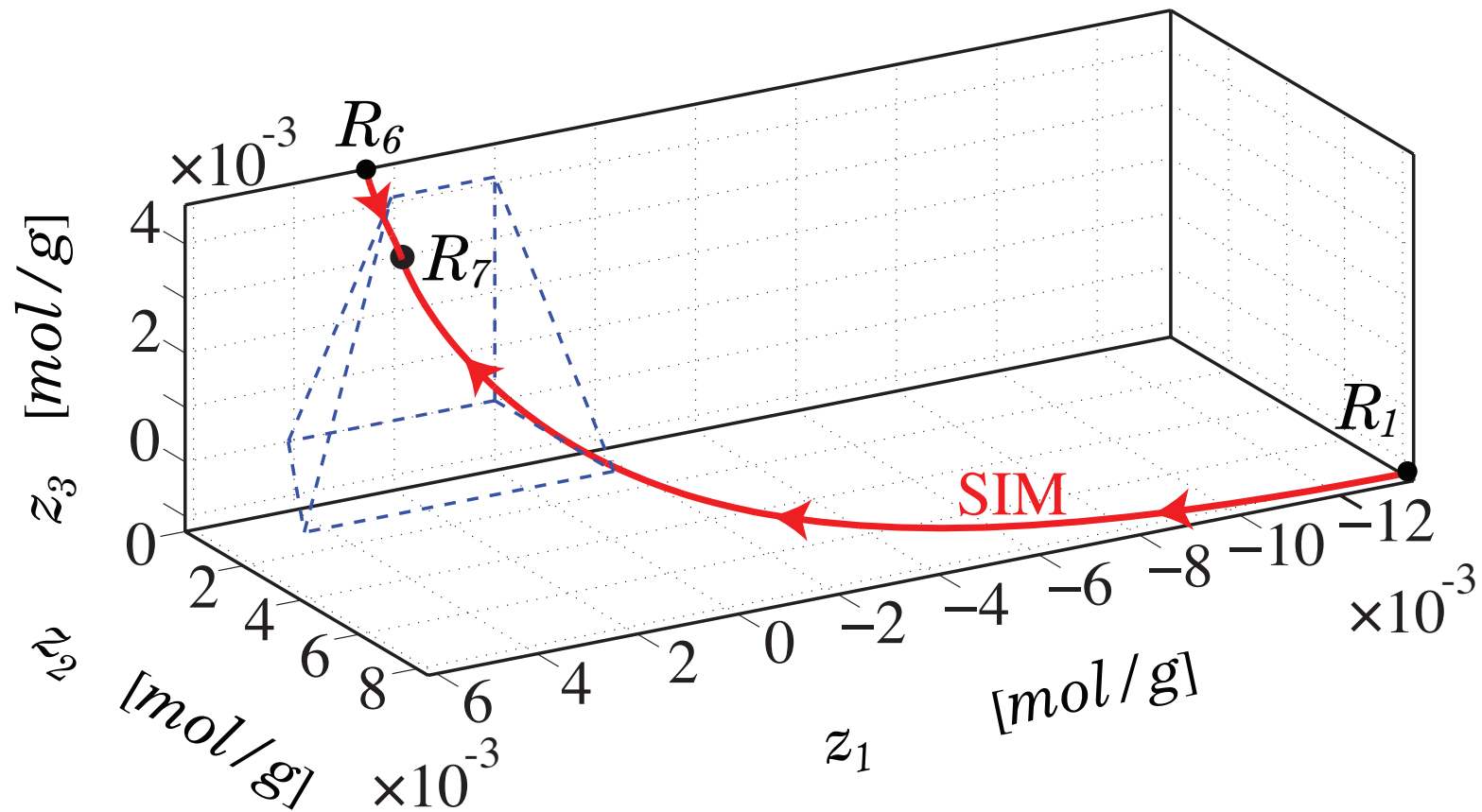


Idealized Hydrogen-Oxygen

- Kinetic model adopted from Ren *et al.*^a
- Model consists of $J = 6$ reversible reactions involving $N = 6$ species $\{H_2, O, H_2O, H, OH, N_2\}$ and $L = 3$ elements $\{H, O, N\}$, with $Q = 0$, so that $\mathbf{z} \in \mathbb{R}^3$.
- Spatially homogenous with isothermal and isobaric conditions with $T = 3000\text{ K}$, $p_o = 1\text{ atm}$.
- Major species are $i = \{1, 2, 3\} = \{H_2, O, H_2O\}$,
- Initial conditions satisfying the element conservation constraints are identical to those presented by Ren *et al.*

^aZ. Ren, S. Pope, A. Vladimirov, J. Guckenheimer, 2006, *J. Chem. Phys.* **124**, 114111.

The system's 1-D SIM



The system's 1-D SIM

