

**Wavelet Adaptive Multilevel Representation (WAMR)  
and Intrinsic Low Dimensional Manifold (ILDm) for  
Reactive Flows**

*by*

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## Outline

- Motivation
- Wavelet Adaptive Multilevel Representation (WAMR) technique (Paolucci & Vasilyev, 1997, *Journal of Computational Physics*) for spatial discretization
- Intrinsic Low Dimensional Manifold (ILDm) technique (Maas & Pope, 1992, *Combustion and Flame*) for reactive source terms
- One-dimensional results: viscous detonation in  $H_2/O_2/Ar$  system (Singh, Rastigejev, Paolucci, & Powers, 2001, *Combustion Theory and Modeling*), and laminar ozone flame (Singh, Powers, & Paolucci, ICDERS, 2001)
- Two-dimensional results: lid-driven fluid in rectangular cavity at high Reynolds number
- Conclusions

## General Motivation

- Combustion problems are among the most demanding computational problems solved in science and engineering (auto, jet, and rocket engines, atmospheric chemistry, fire safety,...)
- Combustion characterized by phenomena evolving on widely disparate space (1 *nm* to 10 *m*) and time (1 *ns* to 10 *s*) scales.
- Disparity of scales generated by
  - geometry
  - heterogeneities in material properties
  - diffusive boundary layers
  - fine and coarse reaction zones
  - interacting shock waves
  - intrinsic non-linear effects
- Solutions
  - faster and larger computational hardware
  - more efficient software
- *Our focus: adaptive methods suited for parallel architectures*

# Compressible Reactive Navier-Stokes Equations

$$\begin{aligned} \frac{\partial \rho}{\partial t} + \frac{\partial}{\partial x}(\rho u) &= 0, & \text{mass} \\ \frac{\partial}{\partial t}(\rho u) + \frac{\partial}{\partial x}(\rho u^2 + p - \tau) &= 0, & \text{momentum} \\ \frac{\partial}{\partial t}\left(\rho\left(e + \frac{u^2}{2}\right)\right) + \frac{\partial}{\partial x}\left(\rho u\left(e + \frac{u^2}{2}\right) + u(p - \tau) + q\right) &= 0, & \text{energy} \\ \frac{\partial}{\partial t}(\rho y_l) + \frac{\partial}{\partial x}(\rho u y_l + j_l) &= 0, & (l = 1, \dots, L-1), \quad \text{elements} \\ \frac{\partial}{\partial t}(\rho Y_i) + \frac{\partial}{\partial x}(\rho u Y_i + J_i^m) &= \dot{\omega}_i M_i, & (i = 1, \dots, N-L), \quad \text{species} \\ \tau &= \frac{4}{3}\mu \frac{\partial u}{\partial x}, & \text{Newtonian gas with Stokes' assumption} \\ J^q &= -k \frac{\partial T}{\partial x} + \sum_{i=1}^N J_i^m \left( h_i^o + \int_{T_o}^T c_{pi}(\hat{T}) d\hat{T} \right) - \Re T \sum_{i=1}^N \frac{\mathcal{D}_i^T}{M_i} \left( \frac{1}{\chi_i} \frac{\partial \chi_i}{\partial x} + \left(1 - \frac{M_i}{M}\right) \frac{1}{p} \frac{\partial p}{\partial x} \right), & \text{Fourier's law} \\ J_i^m &= \rho \sum_{j=1, j \neq i}^N \frac{M_i}{M} Y_j \mathcal{D}_{ij} \left( \frac{1}{\chi_j} \frac{\partial \chi_j}{\partial x} + \left(1 - \frac{M_j}{M}\right) \frac{1}{p} \frac{\partial p}{\partial x} \right) - \mathcal{D}_i^T \frac{1}{T} \frac{\partial T}{\partial x}, & (i = 1, \dots, N), \quad \text{Fick's law} \\ y_l &= m_l \sum_{i=1}^N \frac{\phi_{il}}{M_i} Y_i, & (l = 1, \dots, L-1), \quad \text{element mass fraction} \\ M &= \sum_{i=1}^N M_i \chi_i, & \text{mean molecular mass} \\ \chi_i &= \frac{M}{M_i} Y_i, & (i = 1, \dots, N), \quad \text{mole fraction} \\ j_l &= m_l \sum_{i=1}^N \frac{\phi_{il}}{M_i} J_i, & (l = 1, \dots, L-1), \quad \text{element mass flux} \\ \sum_{i=1}^N Y_i &= 1, & \text{mass fraction constraint} \\ \sum_{l=1}^L y_l &= 1, & \text{element mass fraction constraint} \\ \dot{\omega}_i &= \sum_{j=1}^J a_j T^{\beta_j} \exp\left(\frac{-E_j}{\Re T}\right) (\nu''_{ij} - \nu'_{ij}) \prod_{k=1}^N \left(\frac{\rho Y_k}{M_k}\right)^{\nu'_{kj}}, & (i = 1, \dots, N-L) \quad \text{law of mass action} \\ p &= \rho \Re T \sum_{i=1}^N \frac{Y_i}{M_i}, & \text{thermal equation of state} \\ e &= \sum_{i=1}^N Y_i \left( h_i^o + \int_{T_o}^T c_{pi}(\hat{T}) d\hat{T} - \frac{\Re T}{M_i} \right). & \text{caloric equation of state} \end{aligned}$$

$N$  species,  $L$  elements,  $J$  reactions

$4N + L + 7$  equations in  $4N + L + 7$  unknowns

## Operator Splitting Technique

- Equations are of form

$$\frac{\partial}{\partial t} \mathbf{q}(x, t) + \underbrace{\frac{\partial}{\partial x} \mathbf{f}(\mathbf{q}(x, t))}_{\text{convection/diffusion}} = \underbrace{\mathbf{g}(\mathbf{q}(x, t))}_{\text{reaction}}, \quad \mathbf{q}, \mathbf{f}, \mathbf{g} \in \mathfrak{R}^{N+2}.$$

where

$$\mathbf{q} = \left( \rho, \rho u, \rho \left( e + \frac{u^2}{2} \right), \rho y_l, \rho Y_i \right)^T.$$

- Splitting

1. Inert convection-diffusion step:

$$\begin{aligned} \frac{\partial}{\partial t} \mathbf{q}(x, t) + \frac{\partial}{\partial x} \mathbf{f}(\mathbf{q}(x, t)) &= 0, \\ \frac{d}{dt} \mathbf{q}_i(t) &= -\Delta_x \mathbf{f}(\mathbf{q}_i(t)) \quad \text{WAMR.} \end{aligned}$$

$\Delta_x$  is any spatial discretization operator, here a wavelet operator.

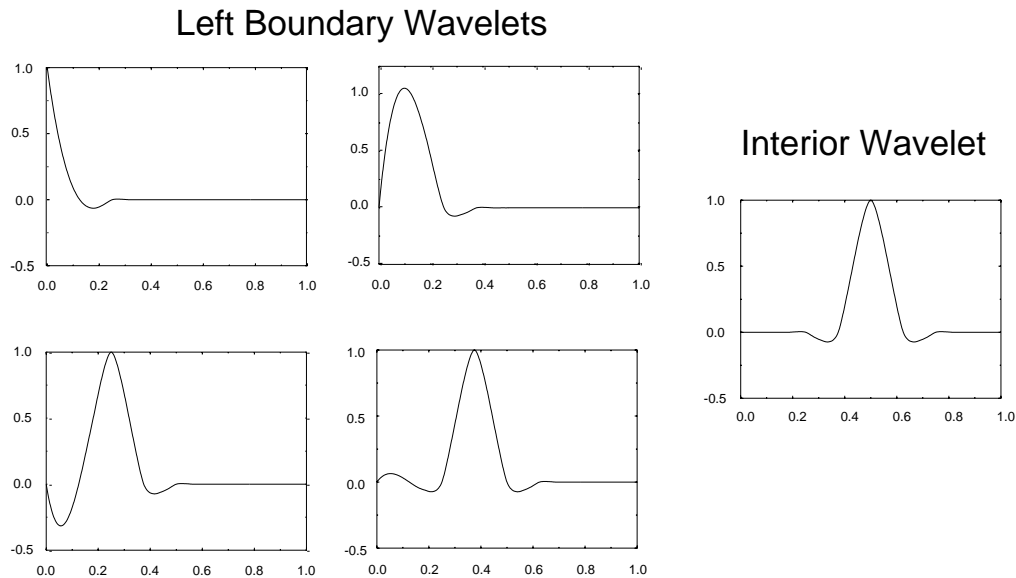
2. Reaction source term step:

$$\begin{aligned} \frac{\partial}{\partial t} \mathbf{q}(x, t) &= \mathbf{g}(\mathbf{q}(x, t)), \\ \frac{d}{dt} \mathbf{q}_i(t) &= \mathbf{g}(\mathbf{q}_i(t)) \quad \text{ILDMM.} \end{aligned}$$

## Wavelet Adaptive Multilevel Representation (WAMR) Technique

- Summary of standard spatial discretization techniques
  - Finite difference- good spatial localization, poor spectral localization, and slow convergence,
  - Finite element- good spatial localization, poor spectral localization, and slow convergence,
  - Spectral- good spectral localization, poor spatial localization, but fast convergence.
- Wavelet technique
  - See e.g. Vasilyev and Paolucci, “A Fast Adaptive Wavelet Collocation Algorithm for Multidimensional PDEs,” *J. Comp. Phys.*, 1997,
  - Basis functions have compact support,
  - Well-suited for problems with widely disparate spatial scales,
  - Good spatial and spectral localization, and fast (spectral) convergence,
  - Easy adaptable to steep gradients via adding collocation points,
  - Spatial adaptation is automatic and dynamic to achieve prescribed error tolerance.

# Wavelet Basis Functions



- Boundary-modified Daubechies autocorrelation functions and interior Daubechies autocorrelation function of order four
- Scaling function

$$\phi_{j,k}(x) = \phi(2^j x - k)$$

- Definition of the wavelet function on the first level

$$\psi_{1,0}(x) = \phi(2x - 1)$$

- Definition of the wavelet function on  $j$  level

$$\psi_{j,k+1}(x) = \psi(2^{j-1}x - k)$$



## Algorithm Description

- Approximate initial function using wavelet basis,

$$\mathbf{P}^J u(x) = \sum_k u_{0,k} \phi_{0,k}(x) + \sum_{j=1}^J \sum_k d_{j,k} \psi_{j,k}(x)$$

- Discard non-essential wavelets if amplitude below threshold value (here we look only at  $P$ ,  $T$ ,  $u$ , and  $\rho$ , species could be included),

$$\mathbf{P}^J u(x) = u_{\geq}^J(x) + u_{<}^J(x)$$

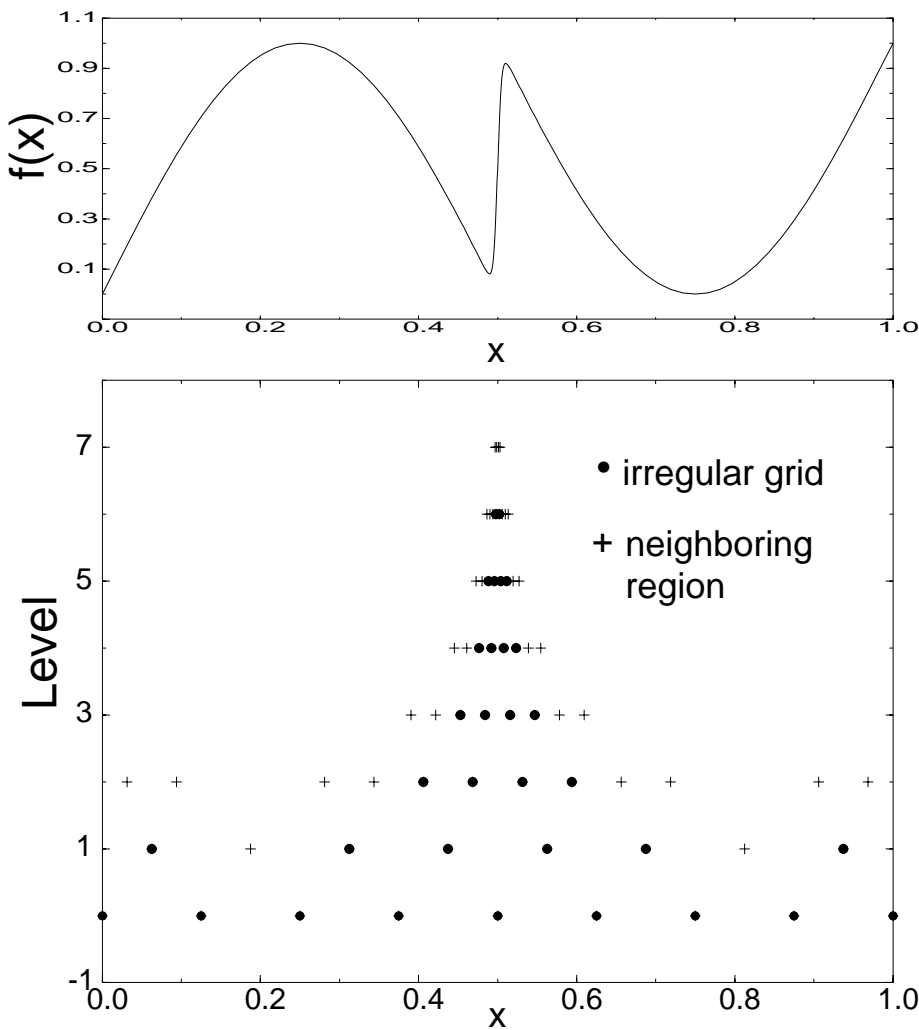
$$u_{\geq}^J(x) = \sum_k u_{0,k} \phi_{0,k}(x) + \sum_{j=1}^J \sum_k d_{j,k} \psi_{j,k}(x), |d_{j,k}| \geq \epsilon$$

$$u_{<}^J(x) = \sum_{j=1}^J \sum_k d_{j,k} \psi_{j,k}(x), |d_{j,k}| < \epsilon$$

- Assign a collocation point to every essential wavelet,
- Establish a neighboring region of potentially essential wavelets,
- Discretize the spatial derivatives; five points used here (related to order of wavelet family),
- Integrate in time; linearized trapezoidal method (implicit) used here,
- Repeat

# Sample Wavelet Approximation to Arbitrary Function

## Arbitrary Function with Variation on Long and Short Scales



- Function shown has large and small length scale variation,
- Wavelets concentrated in regions of steep gradients.

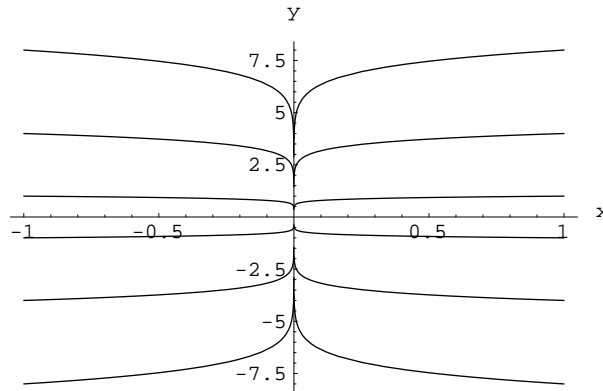
## Intrinsic Low-Dimensional Manifold Method (ILDMM)

- Uses a dynamical systems approach,
- Most appropriate for spatially homogeneous systems (ODEs)
- Does not require imposition of *ad hoc* partial equilibrium or steady state assumptions,
- Fast time scale phenomena are systematically equilibrated,
- Slow time scale phenomena are resolved in time,
- Computation time reduced by factor of  $\sim 3$  for non-trivial combustion problem considered here; manifold gives much better roadmap to find solution relative to general implicit solution techniques (Singh, *et al.*, 2001)
- Speed up factor depends on
  - initial conditions,
  - stiffness ratio
  - dimension of ILDM

## Simplest Example

$$\begin{aligned}\frac{dx}{dt} &= -10x, & x(0) &= x_o, \\ \frac{dy}{dt} &= -y, & y(0) &= y_o.\end{aligned}$$

- Stable equilibrium at  $(x, y) = (0, 0)$ ; stiffness ratio = 10.
- ILDM is  $x = 0$



- Parameterization of manifold:  $x(s) = 0; y(s) = s$ .

$$\frac{dy}{dt} = \frac{dy}{ds} \frac{ds}{dt}, \quad \text{chain rule}$$

$$-y(s) = \frac{dy}{ds} \frac{ds}{dt}, \quad \text{substitute from ODE and manifold}$$

$$-s = (1) \frac{ds}{dt}, \quad \text{no longer stiff!}$$

$$s = s_o e^{-t},$$

$$x(t) = 0; \quad y(t) = s_o e^{-t}.$$

- Projection onto manifold for  $s_o$ , induces small phase error.

## ILDm Implementation in Operator Splitting

- Form of equations in source term step:

$$\frac{d}{dt} \begin{pmatrix} \rho \\ \rho u \\ \rho \left( e + \frac{u^2}{2} \right) \\ \rho y_l \\ \rho Y_i \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \\ \dot{\omega}_i M_i \end{pmatrix}.$$

$$l = 1, \dots, L - 1, \quad i = 1, \dots, N - L.$$

- Equations reduce to

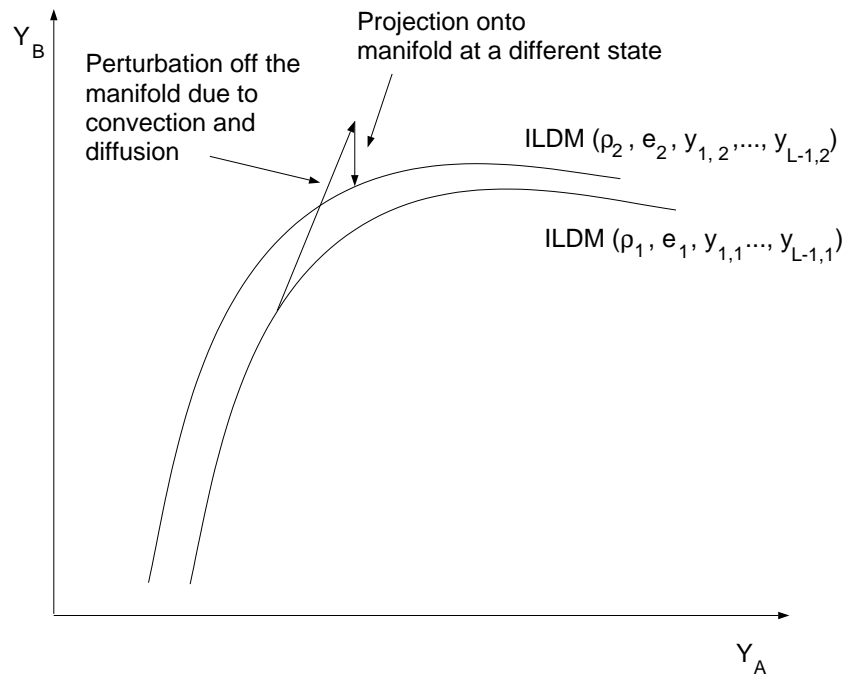
$$\rho = \rho_o, \quad u = u_o, \quad e = e_o, \quad y_l = y_{lo},$$

$$\frac{dY_i}{dt} = \frac{\dot{\omega}_i M_i}{\rho_o}, \quad i = 1, \dots, N - L$$

- $\dot{\omega}_i$  has dependency on  $\rho$ ,  $e$ ,  $y_l$ , and  $Y_i$
- ODEs for  $Y_i$  are stiff, usually solved with implicit methods.
- ODEs for  $Y_i$  can be attacked with manifold methods to remove stiffness with ILDM with  $\rho$ ,  $e$ ,  $y_l, \dots, y_{L-1}$  parameterization.

## Implementation of ILDMs with convection-diffusion and operator splitting

- To minimize phase error, must integrate full equations until sufficiently close to ILDM
- When near ILDM,  $M$  slow equations are integrated, other variables found by table lookup
- Convection-diffusion step *applied to all variables* perturbs system from ILDM
- In next reaction step, project to ILDM at *different* value of  $\rho$ ,  $e$ ,  $y_1, \dots, y_{N-1}$ .



## Formulation of General ILDMs

- A spatially homogeneous adiabatic, isochoric chemically reactive system of  $N$  species in  $L$  elements is modeled by a set of non-linear ordinary differential equations:

$$\frac{d\mathbf{x}}{dt} = \mathbf{F}(\mathbf{x}), \quad \mathbf{x}(0) = \mathbf{x}_o,$$

$\mathbf{x}$  : species concentration;  $\mathbf{x} \in \mathfrak{R}^{N-L}$

- Equilibrium points defined by

$$\mathbf{x} = \mathbf{x}_{eq} \text{ such that } \mathbf{F}(\mathbf{x}_{eq}) = 0.$$

- Consider a system near equilibrium (the argument can and must be extended for systems away from equilibrium) with  $\tilde{\mathbf{x}} = \mathbf{x} - \mathbf{x}_{eq}$ .

- Linearization gives

$$\frac{d\tilde{\mathbf{x}}}{dt} = \mathbf{F}_{\mathbf{x}} \cdot \tilde{\mathbf{x}},$$

where  $\mathbf{F}_{\mathbf{x}}$  is a *constant* Jacobian matrix.

- Schur decompose the Jacobian matrix:

$$\mathbf{F}_{\mathbf{x}} = \mathbf{Q} \cdot \mathbf{U} \cdot \mathbf{Q}^T$$

$$\mathbf{Q} = \begin{pmatrix} \vdots & \vdots & & \vdots \\ q_1 & q_2 & \cdots & q_{N-L} \\ \vdots & \vdots & & \vdots \end{pmatrix}, \quad \mathbf{U} = \begin{pmatrix} \lambda_1 & u_{1,2} & \cdots & u_{1,N-L} \\ 0 & \lambda_2 & \cdots & u_{2,N-L} \\ 0 & \cdots & \ddots & \vdots \\ 0 & \cdots & 0 & \lambda_{N-L} \end{pmatrix}, \quad \mathbf{Q}^T = \begin{pmatrix} \cdots & q_1^T & \cdots \\ \cdots & q_2^T & \cdots \\ \vdots & \vdots & \\ \cdots & q_{N-L}^T & \cdots \end{pmatrix}$$

## Formulation of General Manifolds (cont.)

- $\mathbf{Q}$  is an orthogonal matrix with real Schur vectors  $q_i$  in its columns.
- $\mathbf{U}$  is an upper triangular matrix with eigenvalues of  $\mathbf{F}_{\mathbf{x}}$  on its diagonal, sometimes placed in order of decreasing magnitude.
- The Schur vectors  $q_i$  form an orthonormal basis which spans the phase space,  $\mathfrak{R}^{N-L}$ .
- We then define  $M$  slow time scales,  $M < N - L$ .
- Next define a non-square matrix  $\mathbf{W}$  which has in its rows the Schur vectors associated with the fast time scales:

$$\mathbf{W} = \begin{pmatrix} \cdots & \cdots & q_{M+1}^T & \cdots & \cdots \\ \cdots & \cdots & q_{M+2}^T & \cdots & \cdots \\ & & \vdots & & \\ \cdots & \cdots & q_{N-L}^T & \cdots & \cdots \end{pmatrix}.$$

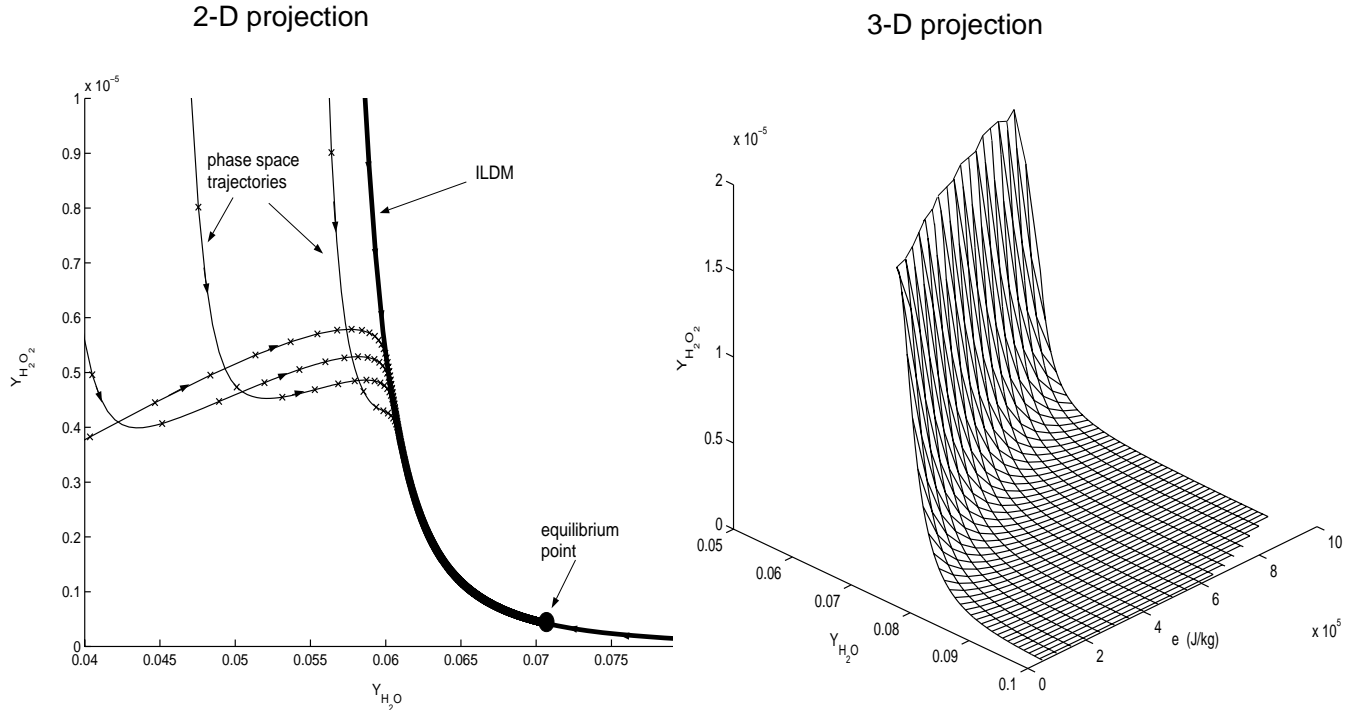
- Letting the fast time scale events equilibrate defines the manifold:

$$\mathbf{W} \cdot \mathbf{F}(\mathbf{x}) = 0.$$



## Sample ILDM for $H_2/O_2/Ar$

- Based on  $N = 9$ ,  $J = 37$  mechanism of Maas and Warnatz,
- Projection in  $Y_{H_2O}$ ,  $Y_{H_2O_2}$  plane and  $Y_{H_2O}$ ,  $Y_{H_2O_2}$ ,  $e$  space
- Adiabatic ( $e = 8 \times 10^5 \text{ J/kg}$ ), isochoric ( $\rho = 5.0 \times 10^{-4} \text{ kg/m}^3$ ),  
 $y_H = 0.01277$ ,  $y_O = 0.10137$ ,  $y_{Ar} = 0.88586$ ,
- We can get e.g.  $p(\rho, e, Y_{H_2O})$ ,  $T(\rho, e, Y_{H_2O})$ ,  $Y_H(\rho, e, Y_{H_2O})$ ,  $\dots$
- Linear interpolation used for points not in table,
- Captures  $\sim 0.1 \mu s$  reaction events.

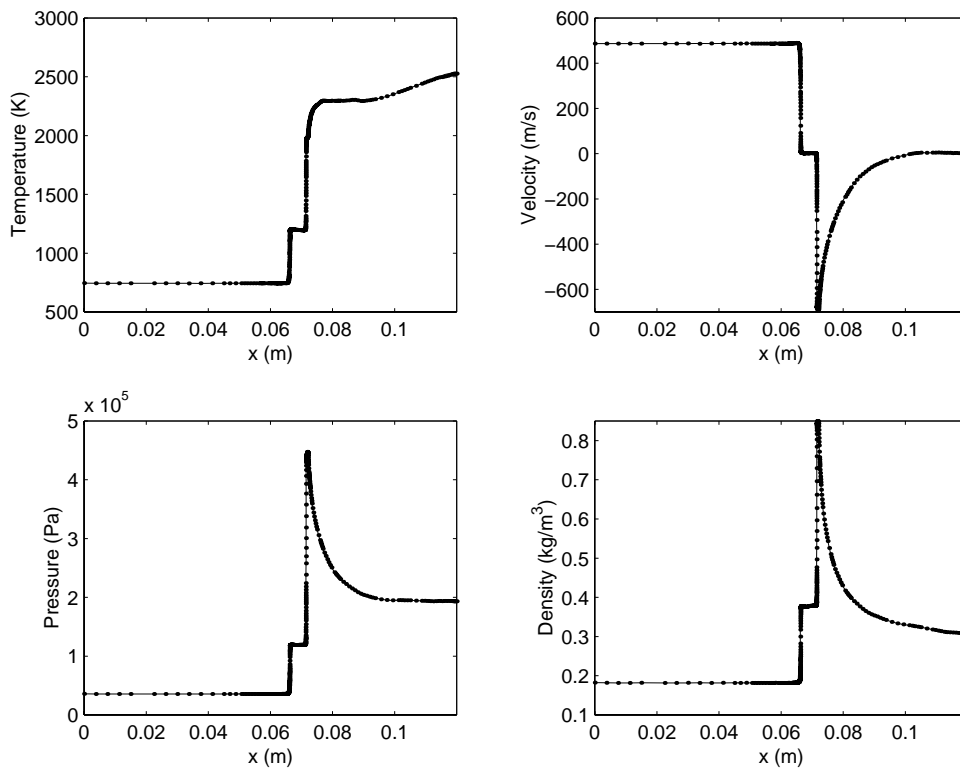


## Ignition Delay in Premixed $H_2/O_2/Ar$

- Consider standard problem of Fedkiw, Merriman, and Osher, *J. Comp. Phys.*, 1996,
- Shock tube with premixed  $H_2$ ,  $O_2$ , and  $Ar$  in 2/1/7 molar ratio,
- Initial inert shock propagating in tube,
- Reaction commences shortly after reflection off end wall,
- Detonation soon develops,
- Model assumptions
  - One-dimensional,
  - Mass, momentum, and energy diffusion,
  - Nine species, thirty-seven reactions,
  - Ideal gases with variable specific heats.

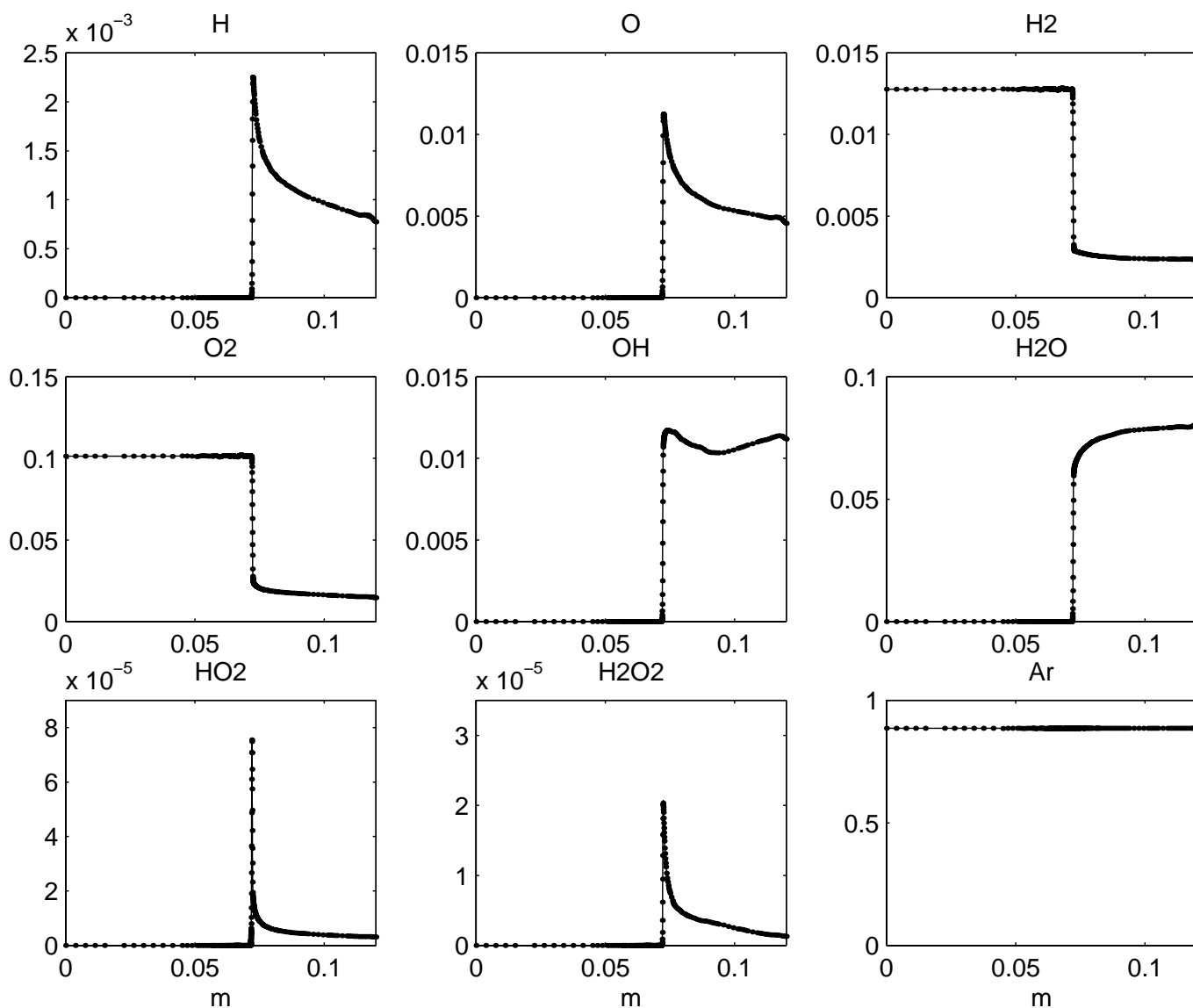
# Viscous $H_2 - O_2$ Ignition Delay with Wavelets and ILDM

- $t = 195 \mu s$ , 300 collocation points, 15 wavelet scale levels
- ILDM gives nearly identical results as full chemistry
- WAMR spatial discretization, implicit linear trapezoidal convection-diffusion time stepping, explicit (ILDM)/implicit (non-ILDM) reaction time stepping
- *Viscous shocks, inductions zones, and entropy layers spatially resolved!*



# Viscous $H_2 - O_2$ Ignition Delay with Wavelets and ILDM

- $t = 195 \mu s$
- ILDM gives nearly identical results as full chemistry

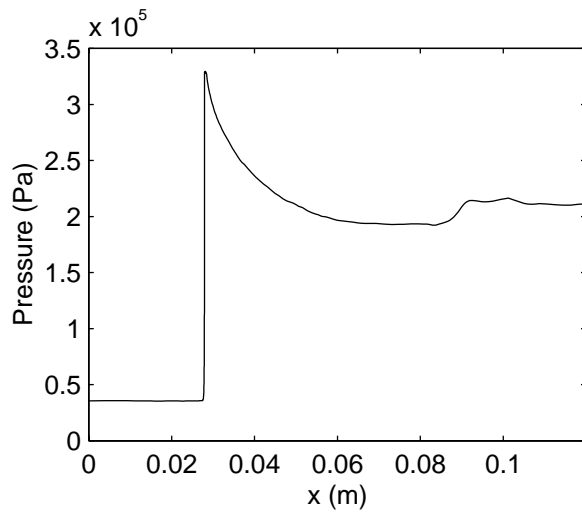


# Viscous $H_2 - O_2$ Ignition Delay with Wavelets

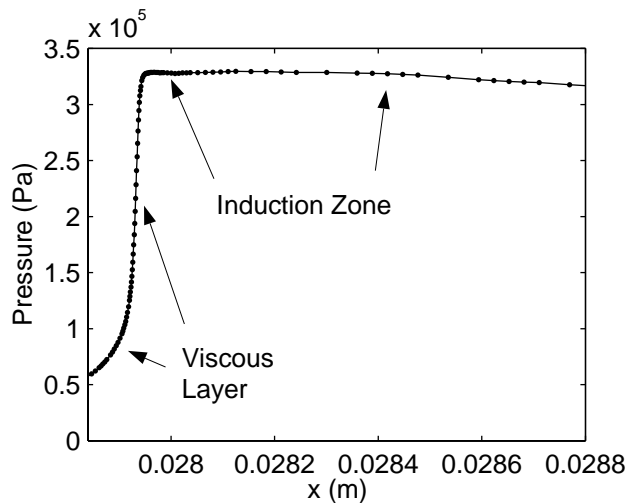
## Global and Fine Scale Structures

- $t = 230 \mu s$ , Induction zone length:  $\sim 470 \mu m$ , Viscous shock thickness:  $\sim 50 \mu m$  (should use smaller  $\mu$ ),
- No significant reaction in viscous shock zone.

Global View

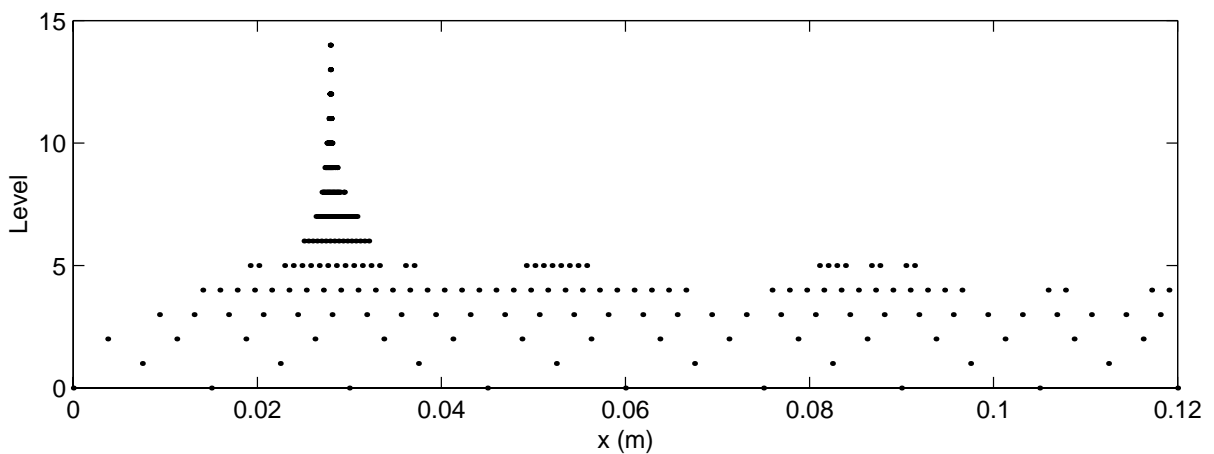
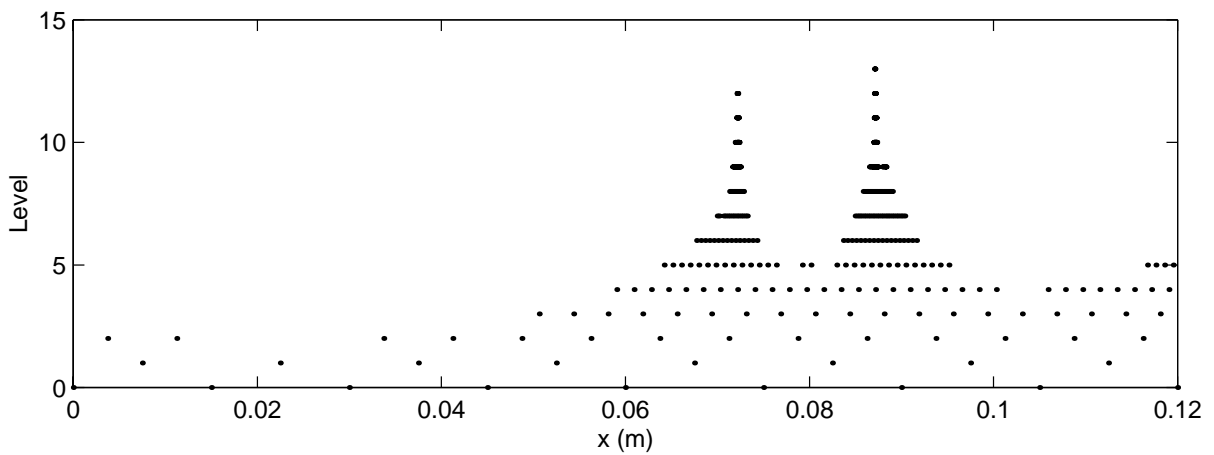


Fine Scale Structure



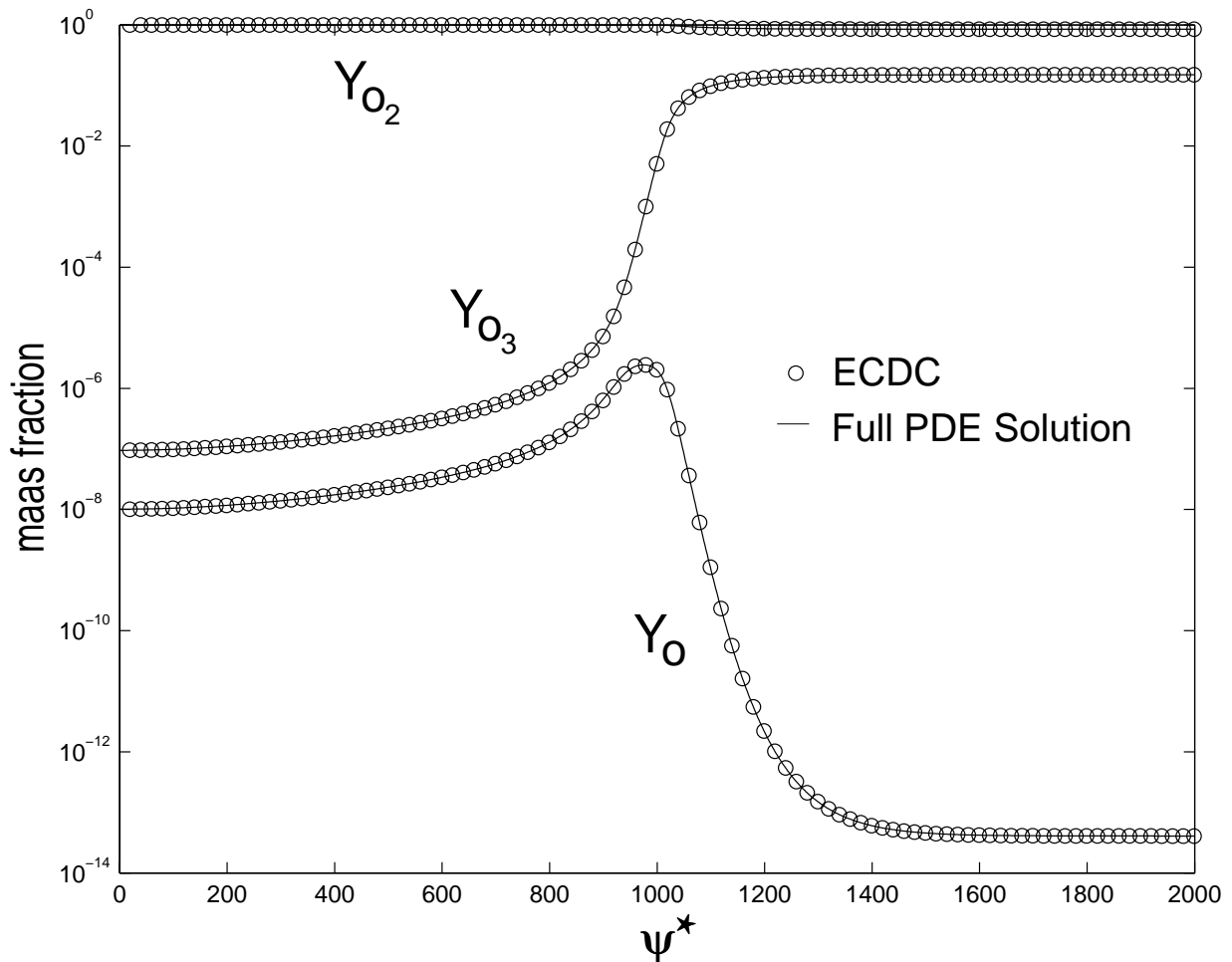
# Viscous $H_2 - O_2$ Ignition Delay with Wavelets, Instantaneous Distributions of Collocation Points

- $t = 180 \mu s$ , two-shock structure with consequent collocation point distribution,
- $t = 230 \mu s$ , one-shock structure with evolved collocation point distribution.



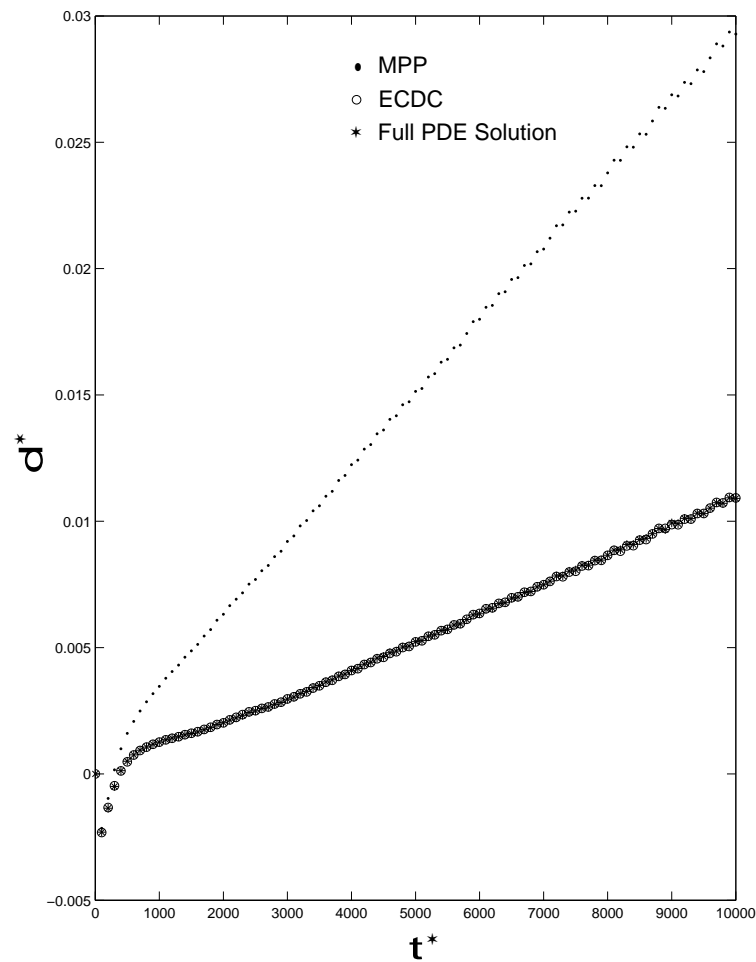
# Laminar Ozone Flame with Improved ILDM

- One dimensional, low Mach number limit
- see Margolis, *J. Comp. Phys.*, 1978
- Classical ILDM for ODEs only
- Project PDEs onto fast and slow bases defined by ILDM.
- Solve slow PDEs and new elliptic equation: *Elliptic Convection-Diffusion Corrector*, ECDC



# Laminar Ozone Flame with Improved ILDM: Phase Error

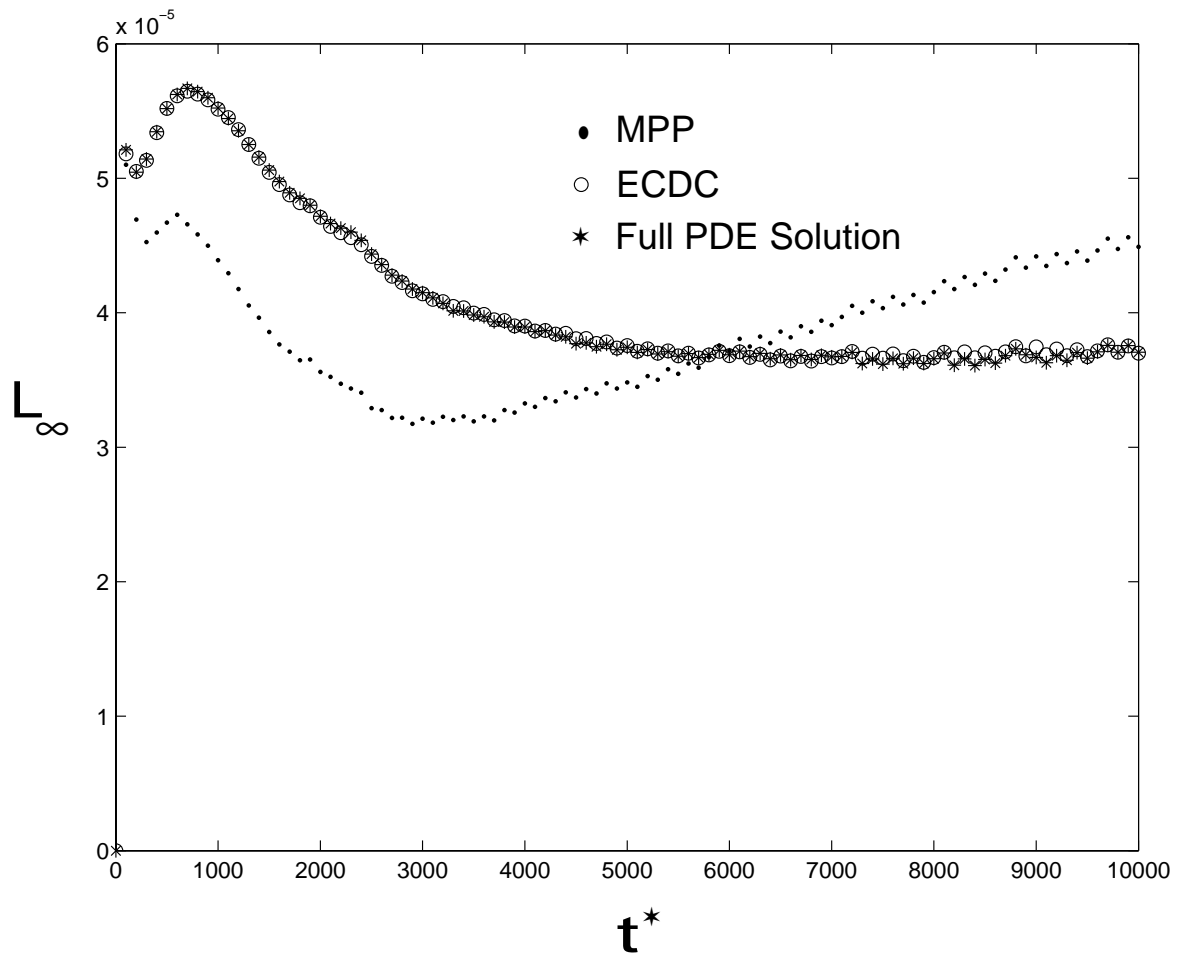
- ECDC gives improved accuracy in wave speed predictions relative to Maas-Pope projection.
- ECDC has stronger coupling with full equations.
- ECDC analagous to elliptic equation for pressure in incompressible Navier-Stokes, where fast acoustics have been filtered.





# Laminar Ozone Flame with Improved ILDM: Amplitude Error

- ECDC gives improved accuracy in amplitude predictions at long time relative to Maas-Pope projection.



## Lid-Driven Fluid in Rectangular Cavity

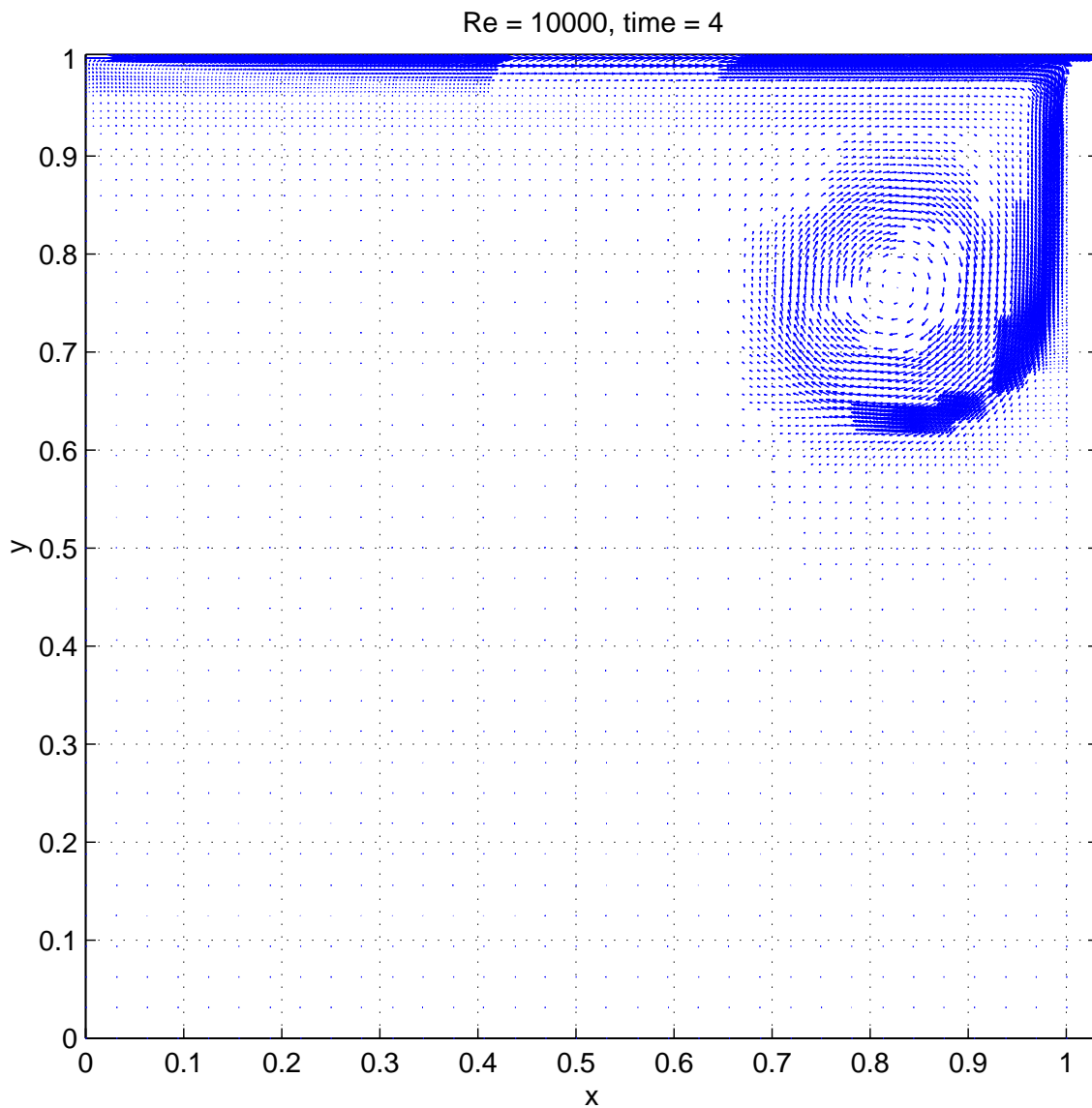
- Standard two-dimensional test problem (Ghia, *et al.*, *J. Comp. Phys.*, 1982)
- Consider incompressible Navier-Stokes equations

$$\begin{aligned}\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} &= 0, \\ \frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} &= -\frac{\partial p}{\partial x} + \frac{1}{Re} \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right), \\ \frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} &= -\frac{\partial p}{\partial y} + \frac{1}{Re} \left( \frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} \right).\end{aligned}$$

- Project dependent variables onto wavelet basis localized in two-dimensions.
- Fast Poisson solver developed for resulting equation for pressure.
- Dynamic memory allocation utilized for variable storage requirements.
- Adaptive nature of the method requires a robust computational technique for computing derivatives.
- Wavelets which are physically close may be far removed in memory storage.
- Method prepared to handle a wide variety of stencil combinations.

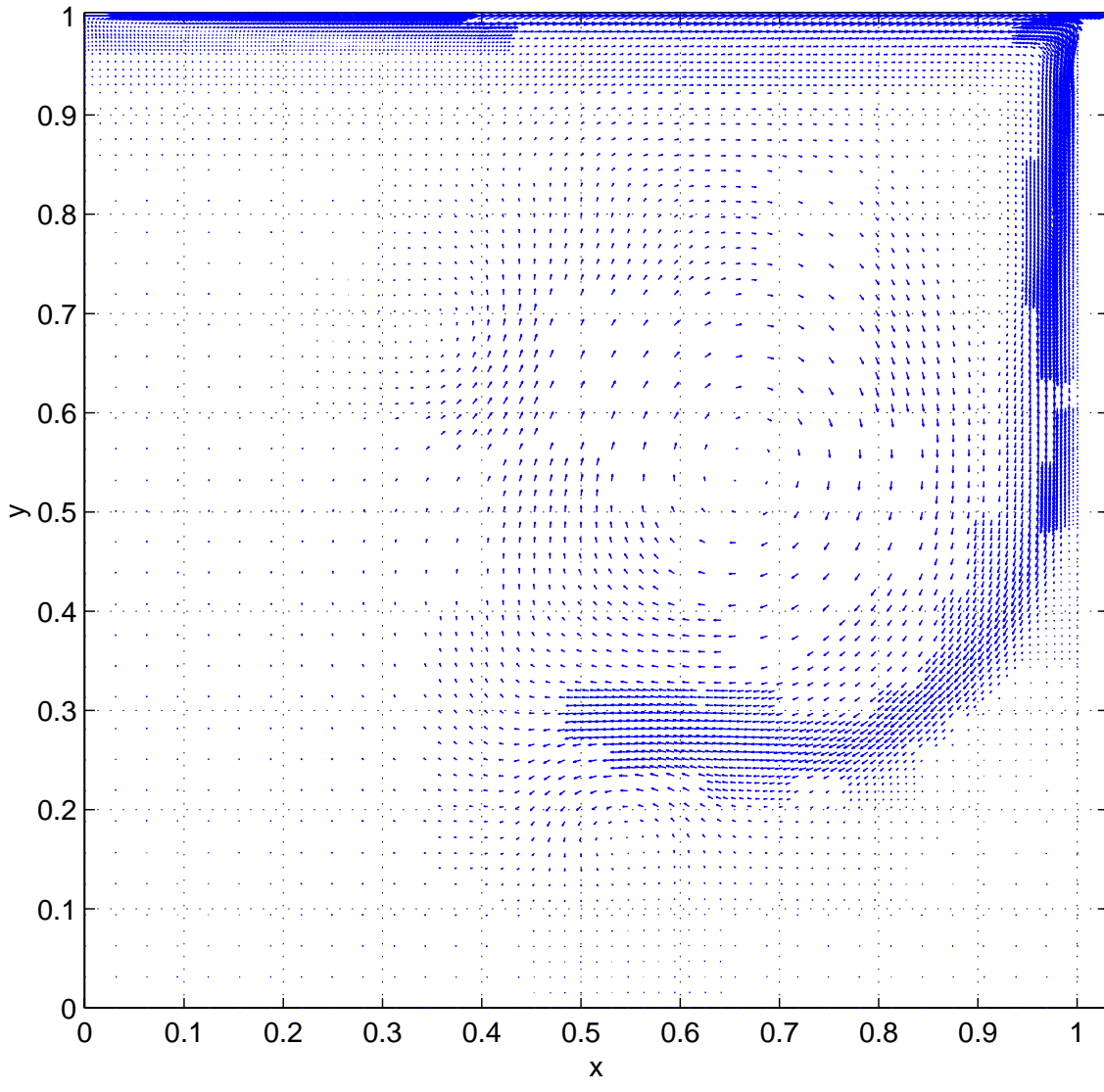
## Velocity Vector Field, $Re = 10000$ , $t = 4$

- $Re = 10000$  equivalent to highest  $Re$  for this problem in the published literature with long time steady results.
- Initial transients have not yet relaxed here.



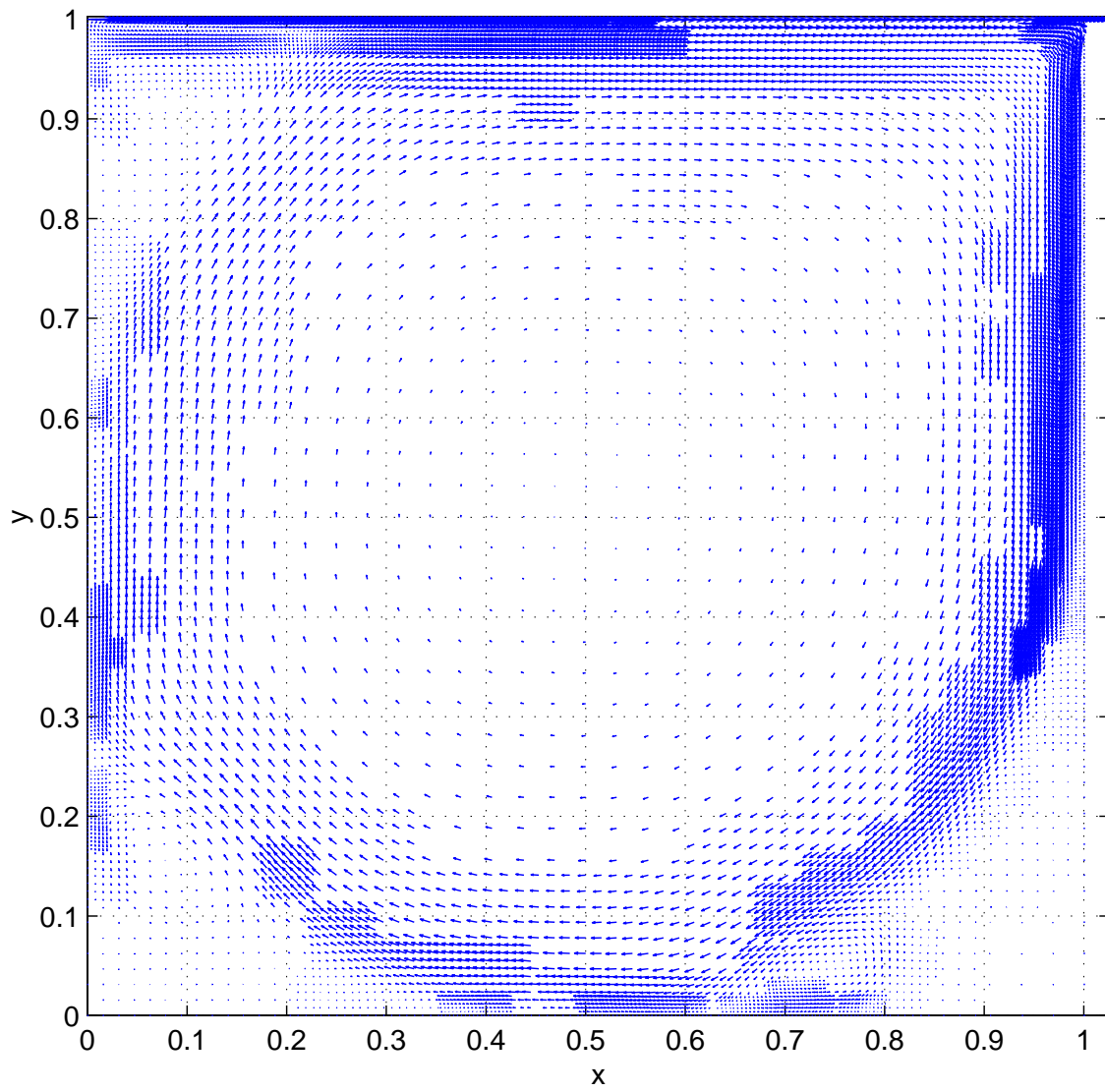
# Velocity Vector Field, $Re = 10000$ , $t = 12$

Re = 10000, time = 12



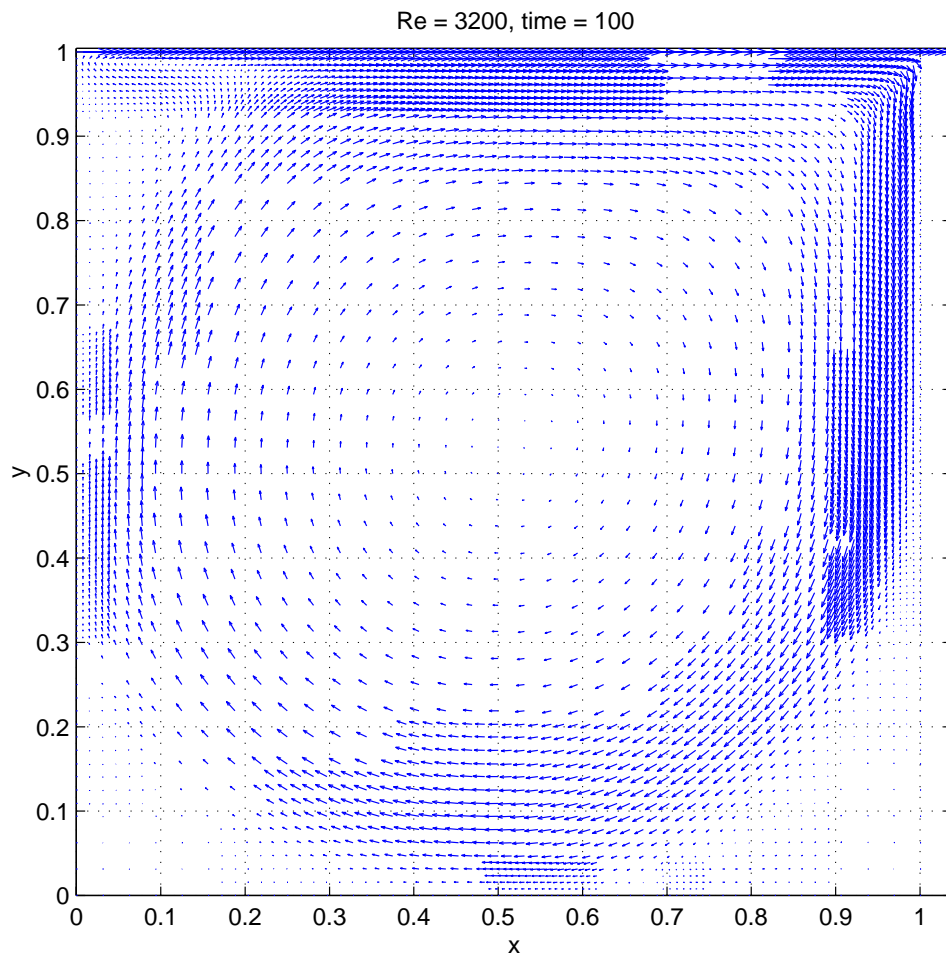
# Velocity Vector Field, $Re = 10000$ , $t = 100$

Re = 10000, time = 100



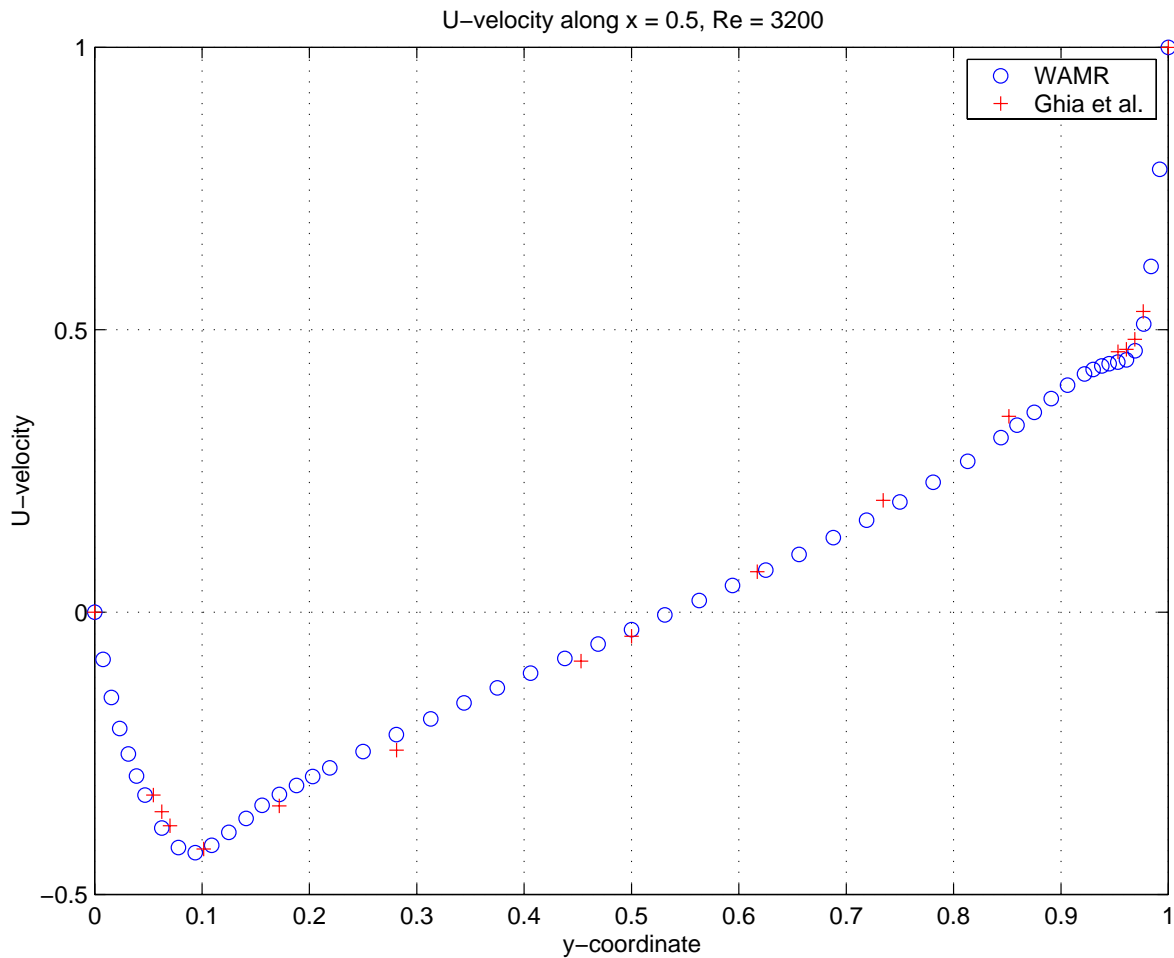
## Velocity Vector Field, $Re = 3200$

- Long time results  $t = 100$ ; initial transients have relaxed.
- Wavelets only present in regions of steep gradients.;  $\epsilon = 0.01$ .
- Five levels of wavelets: coarsest  $16 \times 16$ , finest  $257 \times 257$ ; equivalent to Ghia's uniform grid.
- Results are more accurate than Ghia, as a higher order stencil was used on an equivalent grid.



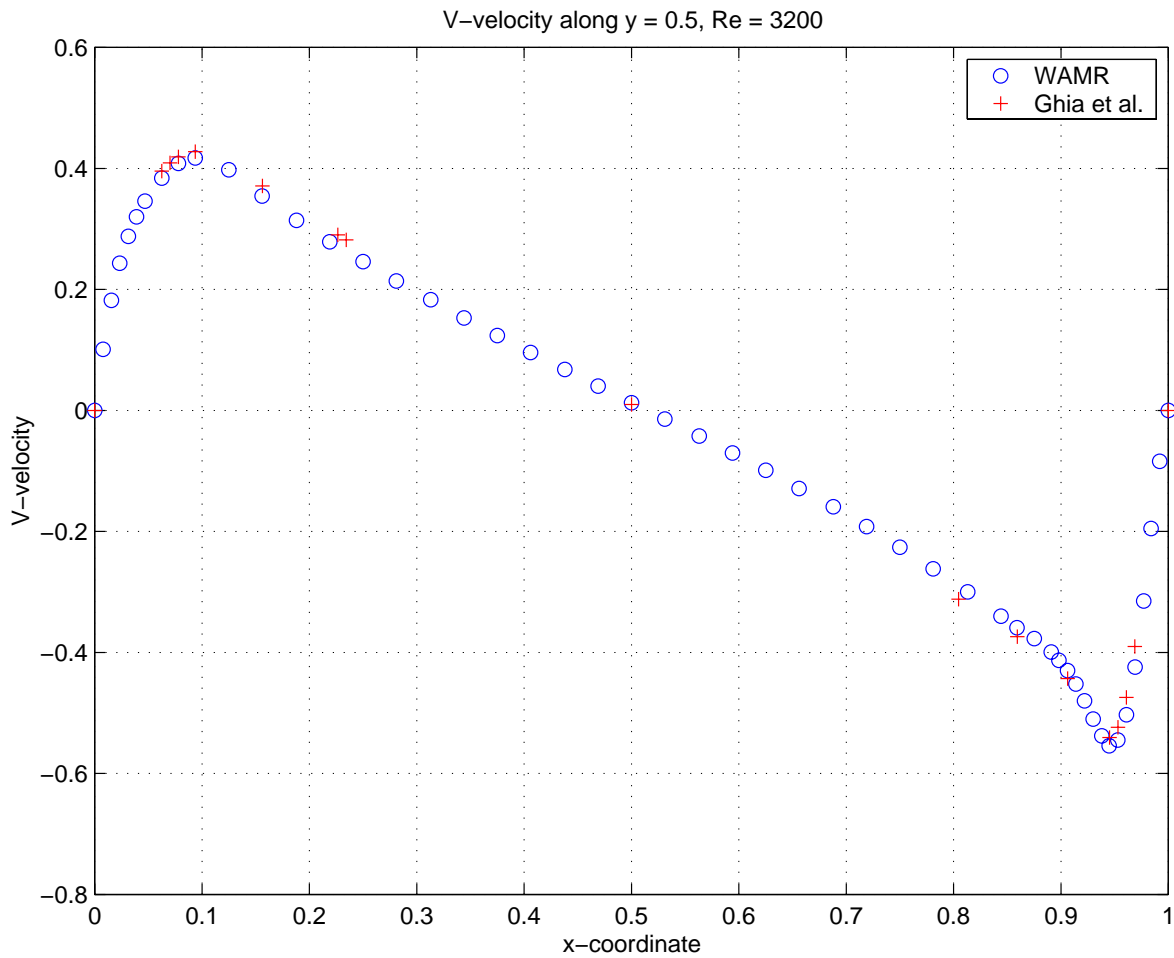
## Comparison with Ghia's Results for $u$ , $Re = 3200$

- Midplane predictions of long-time  $u$  velocity agree well with Ghia's predictions.



## Comparison with Ghia's Results for $v$ , $Re = 3200$

- Midplane predictions of long-time  $v$  velocity agree well with Ghia's predictions.





## Conclusions

- The WAMR method gives dramatic spatial resolution in viscous one-dimensional  $H_2/O_2/Ar$  detonations with detailed kinetics; viscous shocks, entropy layers, and induction zones are resolved,
- The ILDM method, coupled appropriate use of full integration, with operator spitting accurately recovers most results of full chemistry with decrease (factor of three for our case) in computational time,
- The ILDM method can be made more accurate at roughly the same computational cost by solving an elliptic equation for accounting for effects of convection and diffusion (ECDC)
- The WAMR method can be extended to multiple dimensions and can enable extremely detailed and accurate results on a challenging two-dimensional test problem.
- The extension to three-dimensional compressible reactive flows within complex geometries is underway.