

Impact of Autocorrelation on OLS Estimates
ECON 30331/Evans

Consider a simple bivariate time-series model of the form: $y_t = \beta_0 + x_t\beta_1 + \varepsilon_t$

The four key assumptions about ε in this model are

- i) $E(\varepsilon_t) = E[\varepsilon_t | x_t] = 0$
- ii) $\text{Var}(\varepsilon_t) = \text{Var}(\varepsilon_t | x_t) = \sigma_\varepsilon^2$
- iii) $\text{Cov}(\varepsilon_t, \varepsilon_j) = 0$ for $t \neq j$

There are n observations in the sample, so $t=1,2,3,\dots,n$

Assume that the third assumption is violated and there is first order auto-correlation, which is characterized by the following equation

$$\varepsilon_t = \rho\varepsilon_{t-1} + v_t$$

Where $|\rho| < 1$ and we make the following assumptions about v

- i) $E(v_t) = 0$
- ii) $\text{Var}(v_t) = \sigma_v^2$
- iii) $\text{Cov}(v_t, v_j) = 0$ for $t \neq j$
- iv) $\text{Cov}(\varepsilon_{t-1}, v_t) = 0$

With autocorrelation, consider the value of $\text{Cov}(\varepsilon_t, \varepsilon_{t-1})$. By definition

$$(1) \quad \text{Cov}(\varepsilon_t, \varepsilon_{t-1}) = E[(\varepsilon_t - E(\varepsilon_t))(\varepsilon_{t-1} - E(\varepsilon_{t-1}))]$$

but because $E(\varepsilon_t) = E(\varepsilon_{t-1}) = 0$, equation (1) reduces to

$$(2) \quad \text{Cov}(\varepsilon_t, \varepsilon_{t-1}) = E[\varepsilon_t \varepsilon_{t-1}]$$

Using the fact that we have first-order autocorrelation, $\varepsilon_t = \rho\varepsilon_{t-1} + v_t$, we can substitute this equation into (2) for ε_t

$$(3) \quad \text{Cov}(\varepsilon_t, \varepsilon_{t-1}) = E[\varepsilon_t \varepsilon_{t-1}] = E[(\rho\varepsilon_{t-1} + v_t)\varepsilon_{t-1}] = E[\rho\varepsilon_{t-1}^2] + E[v_t \varepsilon_{t-1}]$$

Recall that by definition $\text{Var}(\varepsilon_{t-1}) = E[(\varepsilon_{t-1} - E(\varepsilon_{t-1}))^2] = \sigma_\varepsilon^2$, but because $E(\varepsilon_t) = 0$, then $\text{Var}(\varepsilon_{t-1}) = E[\varepsilon_{t-1}^2] = \sigma_\varepsilon^2$. Notice also that we assume v_t and ε_{t-1} are uncorrelated so $E[v_t \varepsilon_{t-1}] = 0$, and therefore

$$(4) \quad \text{Cov}(\varepsilon_t, \varepsilon_{t-1}) = E[\rho\varepsilon_{t-1}^2] + E[v_t \varepsilon_{t-1}] = \rho\sigma_\varepsilon^2$$

This method can easily be generalized to consider the degree of covariance between any two time periods in the data. For example, suppose we are interested in $\text{Cov}(\varepsilon_t, \varepsilon_{t-2})$ which by definition equals

$$(5) \quad \text{Cov}(\varepsilon_t, \varepsilon_{t-2}) = E[\varepsilon_t \varepsilon_{t-2}].$$

Note that we can write ε_t as a function of ε_{t-1} and ε_{t-1} as a function of ε_{t-2} .

$$(6) \quad \varepsilon_t = \rho \varepsilon_{t-1} + v_t$$

$$(7) \quad \varepsilon_{t-1} = \rho \varepsilon_{t-2} + v_{t-1}$$

And therefore, substituting (7) into (6) we get

$$(8) \quad \varepsilon_t = \rho(\rho \varepsilon_{t-2} + v_{t-1}) + v_t = \rho^2 \varepsilon_{t-2} + \rho v_{t-1} + v_t$$

Substituting (8) into (5) for ε_t , we get

$$(9) \quad \text{Cov}(\varepsilon_t, \varepsilon_{t-2}) = E[(\rho^2 \varepsilon_{t-2} + \rho v_{t-1} + v_t) \varepsilon_{t-2}] = E[\rho^2 \varepsilon_{t-2}^2] + E[\rho v_{t-1} \varepsilon_{t-2}] + E[v_t \varepsilon_{t-2}]$$

And using the facts that $E[\rho v_{t-1} \varepsilon_{t-2}] = E[v_t \varepsilon_{t-2}] = 0$ and $E[\rho^2 \varepsilon_{t-2}^2] = \rho^2 \sigma_\varepsilon^2$ we find that

$$(10) \quad \text{Cov}(\varepsilon_t, \varepsilon_{t-2}) = E[\rho^2 \varepsilon_{t-2}^2] = \rho^2 \sigma_\varepsilon^2$$

We can easily generalize this result to note that if there is a j unit difference between the errors, then

$$(11) \quad \text{Cov}(\varepsilon_t, \varepsilon_{t-j}) = E[\rho^j \varepsilon_{t-j}^2] = \rho^j \sigma_\varepsilon^2$$

In what follows, we will examine the bias and variance of the OLS estimate for β_1

- a) assuming autocorrelation is present, but
- b) ignoring this fact in the model

Is $\hat{\beta}_1$ Unbiased?

Recall the definition for $\hat{\beta}_1$

$$(1) \quad \hat{\beta}_1 = \frac{\sum_{t=1}^n (y_t - \bar{y})(x_t - \bar{x})}{\sum_{t=1}^n (x_t - \bar{x})^2}$$

Note also that we can drop the \bar{y} in the numerator and we can substitute the true definition of y ($\beta_0 + x_t \beta_1 + \varepsilon_t$) into the model

$$(2) \quad \hat{\beta}_1 = \frac{\sum_{t=1}^n (y_t - \bar{y})(x_t - \bar{x})}{\sum_{t=1}^n (x_t - \bar{x})^2} = \frac{\sum_{t=1}^n y_t (x_t - \bar{x})}{\sum_{t=1}^n (x_t - \bar{x})^2} = \frac{\sum_{t=1}^n (\beta_0 + \beta_1 x_t + \varepsilon_t)(x_t - \bar{x})}{\sum_{t=1}^n (x_t - \bar{x})^2}$$

Break apart the terms in the numerator

$$(3) \quad \hat{\beta}_1 = \frac{\beta_0 \sum_{t=1}^n (x_t - \bar{x}) + \beta_1 \sum_{t=1}^n x_t (x_t - \bar{x}) + \sum_{t=1}^n \varepsilon_t (x_t - \bar{x})}{\sum_{t=1}^n (x_t - \bar{x})^2}$$

We can simplify the terms in (3) using the properties of summations:

$$\beta_0 \sum_{t=1}^n (x_t - \bar{x}) = \beta_0 (0) = 0$$

$$\sum_{i=1}^n (x_i - \bar{x})^2 = \sum_{i=1}^n x_i (x_i - \bar{x}) \text{ so}$$

And therefore, equation (3) reduces to our old friend

$$(4) \quad \hat{\beta}_1 = \beta_1 + \frac{\sum_{t=1}^n \varepsilon_t (x_t - \bar{x})}{\sum_{t=1}^n (x_t - \bar{x})^2}$$

Taking the expectation of (4), notice that

$$(5) \quad E[\hat{\beta}_1] = E \left[\beta_1 + \frac{\sum_{t=1}^n \varepsilon_t (x_t - \bar{x})}{\sum_{t=1}^n (x_t - \bar{x})^2} \right] = E[\beta_1] + E \left[\frac{\sum_{t=1}^n \varepsilon_t (x_t - \bar{x})}{\sum_{t=1}^n (x_t - \bar{x})^2} \right] = \beta_1 + \frac{E \left[\sum_{t=1}^n \varepsilon_t (x_t - \bar{x}) \right]}{\sum_{t=1}^n (x_t - \bar{x})^2}$$

Note that the given the presence of autocorrelation, the key assumption that x is fixed has not been altered. Therefore, we can still maintain assumption iv) $E(\varepsilon_t | x_t) = 0$ and as a result,

$$(6) \quad E[\hat{\beta}_1] = \beta_1$$

Even in the presence of autocorrelation, OLS estimates are unbiased.

The variance of $\hat{\beta}_1$ in the presence of autocorrelation:

By definition,

$$(7) \text{Var}(\hat{\beta}_1) = E[(\hat{\beta}_1 - E[\hat{\beta}_1])^2]$$

Previously, we demonstrated that $\hat{\beta}_1$ is an unbiased estimate even in the presence of autocorrelation and therefore, $E[\hat{\beta}_1] = \beta_1$

$$(8) \text{Var}(\hat{\beta}_1) = E[(\hat{\beta}_1 - \beta_1)^2]$$

Looking at equation (4) on the previous page, note that the difference $\hat{\beta}_1 - \beta_1$ is simply

$$(9) \hat{\beta}_1 - \beta_1 = \frac{\sum_{t=1}^n \varepsilon_t (x_t - \bar{x})}{\sum_{t=1}^n (x_t - \bar{x})^2} = \frac{\sum_{t=1}^n \varepsilon_t (x_t - \bar{x})}{SST_x} \quad \text{where } SST_x = \sum_{t=1}^n (x_t - \bar{x})^2$$

Using the definition of the variance and equation (9)

$$(10) \text{Var}(\hat{\beta}_1) = E[(\hat{\beta}_1 - \beta_1)^2] = E\left[\left(\frac{\sum_{t=1}^n \varepsilon_t (x_t - \bar{x})}{SST_x}\right)^2\right] = E\left[\left(\frac{\sum_{t=1}^n \varepsilon_t \tilde{x}_t}{SST_x}\right)^2\right]$$

Where $\tilde{x}_t = x_t - \bar{x}$. Because SST_x is a constant (x is considered fixed) we can bring it outside the expectation. Therefore

$$(11) \text{Var}(\hat{\beta}_1) = \frac{1}{SST_x^2} E\left[\left(\sum_{t=1}^n \varepsilon_t \tilde{x}_t\right)^2\right]$$

Let's work with the numerator in the far right hand term in equation (8). Complete the square on this term generates.

$$\left[\sum_{t=1}^n \varepsilon_t \tilde{x}_t\right]^2 = [\varepsilon_1 \tilde{x}_1 + \varepsilon_2 \tilde{x}_2 + \dots + \varepsilon_n \tilde{x}_n]^2 = [\varepsilon_1^2 \tilde{x}_1^2 + \varepsilon_2^2 \tilde{x}_2^2 + \dots + \varepsilon_n^2 \tilde{x}_n^2 + 2\varepsilon_1 \tilde{x}_1 \varepsilon_2 \tilde{x}_2 + 2\varepsilon_1 \tilde{x}_1 \varepsilon_3 \tilde{x}_3 + \dots + 2\varepsilon_{n-1} \tilde{x}_{n-1} \varepsilon_n \tilde{x}_n]$$

Which can be simplified to read.

$$(12) \sum_{t=1}^n \varepsilon_t^2 \tilde{x}_t^2 + 2 \sum_{t=1}^{n-1} \sum_{j=t+1}^n \varepsilon_t \varepsilon_j \tilde{x}_t \tilde{x}_j$$

Notice in the second term, the summations go from $t=1$ to $n-1$ and $j=t+1$ to n . So when $t=1$, we consider the cross terms $\varepsilon_1 \varepsilon_2 \tilde{x}_1 \tilde{x}_2$ to $\varepsilon_1 \varepsilon_n \tilde{x}_1 \tilde{x}_n$ while when $t=n-1$, we only consider the term, $\varepsilon_{n-1} \varepsilon_n \tilde{x}_{n-1} \tilde{x}_n$.

Substituting (12) into (11), we obtain that

$$\begin{aligned}
(13) \quad \text{Var}(\hat{\beta}_1) &= \frac{1}{SST_x^2} E \left[\sum_{t=1}^n \varepsilon_t^2 \tilde{x}_t^2 + 2 \sum_{t=1}^{n-1} \sum_{j=t+1}^n \varepsilon_t \varepsilon_j \tilde{x}_t \tilde{x}_j \right] \\
&= \frac{1}{SST_x^2} E \left[\sum_{t=1}^n \varepsilon_t^2 \tilde{x}_t^2 \right] + \frac{2}{SST_x^2} E \left[\sum_{t=1}^{n-1} \sum_{j=t+1}^n \varepsilon_t \varepsilon_j \tilde{x}_t \tilde{x}_j \right]
\end{aligned}$$

By definition, \tilde{x}_t^2 is fixed and therefore, the first term reduces to something we already know:

$$\begin{aligned}
(14) \quad \frac{1}{SST_x^2} E \left[\sum_{t=1}^n \varepsilon_t^2 \tilde{x}_t^2 \right] &= \frac{1}{SST_x^2} \left[\sum_{t=1}^n \tilde{x}_t^2 E[\varepsilon_t^2] \right] = \frac{1}{SST_x^2} \sum_{t=1}^n \tilde{x}_t^2 \sigma_\varepsilon^2 = \frac{\sigma_\varepsilon^2}{SST_x^2} \sum_{t=1}^n \tilde{x}_t^2 \\
&= \frac{\sigma_\varepsilon^2}{SST_x^2} \sum_{t=1}^n (x_t - \bar{x})^2 = \frac{\sigma_\varepsilon^2}{SST_x^2} SST_x = \frac{\sigma_\varepsilon^2}{SST_x}
\end{aligned}$$

Looking back at our notes for the basic OLS model, recall that the second term in equation (13)

$$\frac{2}{SST_x^2} E \left[\sum_{t=1}^{n-1} \sum_{j=t+1}^n \varepsilon_t \varepsilon_j \tilde{x}_t \tilde{x}_j \right]$$

drops out completely because we assume that $\text{Cov}(\varepsilon_t, \varepsilon_j) = 0$. In this case, however, we are allowing the errors to be correlated. Using results from page (2) of this handout, the expectation of a term inside the summation is the following

$$(15) \quad E[\varepsilon_t \varepsilon_j \tilde{x}_t \tilde{x}_j] = \tilde{x}_t \tilde{x}_j E[\varepsilon_t \varepsilon_j] = \tilde{x}_t \tilde{x}_j \sigma_\varepsilon^2 \rho^{j-t}$$

and therefore, adding (15) and (14) back into (13)

$$(16) \quad \text{Var}(\hat{\beta}_1) = \frac{\sigma_\varepsilon^2}{SST_x} + \frac{2\sigma_\varepsilon^2}{SST_x^2} \left[\sum_{t=1}^{n-1} \sum_{j=t+1}^n (x_t - \bar{x})(x_j - \bar{x}) \rho^{j-t} \right]$$

And for lack of a better term, call this variance $V_{ac(1)}$. Note in the second term in equation (11) that $\sigma_\varepsilon^2 > 0$,

$SST_x > 0$, and assuming autocorrelation is positive, then $\rho^{j-t} > 0$ as well. Finally, if the x 's are positively

correlated over time, then $\sum_{t=1}^{n-1} \sum_{j=t+1}^{n-j} (x_t - \bar{x})(x_{t+j} - \bar{x}) \rho^j > 0$.

If there is no autocorrelation in the model, the true variance of the estimate would be $\text{Var}(\hat{\beta}_1) = \frac{\sigma_\varepsilon^2}{SST_x}$ and

for lack of a better term, call this $\text{Var}(\hat{\beta}_1) = \frac{\sigma_\varepsilon^2}{SST_x} = V_{ols}$. Therefore, if the data exhibits first-order

autocorrelation and we ignore it, we will use V_{ols} as the variance. However, V_{ols} is contained in $V_{ac(1)}$ and the second term in equation (16) is positive, then by construction $V_{ac(1)} > V_{ols}$ and as a result, if we have positive autocorrelation in the data and we ignore this fact, the estimated variance will be too small, leading to more Type I errors.