

## **5.6 Multistep Methods**

**Motivation:** Consider IVP:  $y' = f(t, y)$ ,  $a \leq t \leq b$ ,  $y(a) = \alpha$ . To compute solution at  $t_{i+1}$ , approximate solutions at mesh points  $t_0, t_1, t_2, \dots, t_i$  are already obtained. Since in general error  $|y(t_{i+1}) - w_{i+1}|$  grows with respect to time  $t$ , it then makes sense to use more previously computed approximate solution  $w_i, w_{i-1}, w_{i-2}, \dots$  when computing  $w_{i+1}$ .

**Definition 5.14** An **m-step** multistep method for solving the IVP:

$$y' = f(t, y), \quad a \leq t \leq b, \quad y(a) = \alpha$$

has a difference equation for computing  $w_{i+1}$  at the mesh point  $t_{i+1}$  represented by:

$$\begin{aligned} w_{i+1} = & a_{m-1} w_i + a_{m-2} w_{i-1} + \dots + a_0 w_{i+1-m} \\ & + h[b_m f(t_{i+1}, w_{i+1}) + b_{m-1} f(t_i, w_i) \\ & + \dots + b_0 f(t_{i+1-m}, w_{i+1-m})] \end{aligned}$$

for  $i = m - 1, m, \dots, N - 1$ , where  $h = (b - a)/N$ , the  $a_0, a_1, \dots, a_{m-1}$  and  $b_0, b_1, \dots, b_m$  are constants, and the starting values  $w_0 = \alpha, w_1 = \alpha_1, \dots, w_{m-1} = \alpha_{m-1}$  are specified.

**Remark.** 1. When  $b_m = 0$ , the method is called **explicit**;  
2. When  $b_m \neq 0$ , the method is called **implicit**.

**Example.** Derive Adams-Bashforth two-step *explicit* method for solving the IVP:  $y' = f(t, y)$ ,  $a \leq t \leq b$ ,  $y(a) = \alpha$ .

Integrate  $y' = f(t, y)$  over  $[t_i, t_{i+1}]$

$$y_{i+1} - y_i = \int_{t_i}^{t_{i+1}} y'(t) dt = \int_{t_i}^{t_{i+1}} f(t, y(t)) dt$$

**Adams-Bashforth two-step *explicit* method.**

$$w_0 = \alpha, \quad w_1 = \alpha_1$$

$$w_{i+1} = w_i + \frac{h}{2} [3f(t_i, w_i) - f(t_{i-1}, w_{i-1})] \quad \text{where } i = 1, 2, \dots, N-1.$$

**Adams-Moulton two-step *implicit* method.**

$$w_0 = \alpha, \quad w_1 = \alpha_1$$

$$w_{i+1} = w_i + \frac{h}{12} [5f(t_{i+1}, w_{i+1}) + 8f(t_i, w_i) - f(t_{i-1}, w_{i-1})]$$

where  $i = 1, 2, \dots, N-1$ .

**Example 1.** Solve the IVP  $y' = y - t^2 + 1$ ,  $0 \leq t \leq 2$ ,  $y(0) = 0.5$  by Adams-Bashforth two-step explicit method and Adams-Moulton two-step implicit method respectively. Use the Runge-Kutta method of order four to get needed starting values for approximation and  $h = 0.2$ .

**Solution:**

By using Runge-Kutta method of order:

$$\begin{aligned}w_0 &= 0.5 \\y(0.2) &\approx w_1 = 0.9292933\end{aligned}$$

**Definition 5.15 Local Truncation Error.** If  $y(t)$  solves the IVP  $y' = f(t, y)$ ,

$a \leq t \leq b$ ,  $y(a) = \alpha$  and

$$w_{i+1} = a_{m-1}w_i + a_{m-2}w_{i-1} + \cdots + a_0w_{i+1-m}$$

$$h[b_m f(t_{i+1}, w_{i+1}) + b_{m-1}f(t_i, w_i) + \cdots$$

$$+ b_0 f(t_{i+1-m}, w_{i+1-m})],$$

the local truncation error is:

$$\tau_{i+1}(h) = \frac{y(t_{i+1}) - a_{m-1}y(t_i) - a_{m-2}y(t_{i-1}) - \cdots - a_0y(t_{i+1-m})}{h}$$

$$- [b_m f(t_{i+1}, y(t_{i+1})) + \cdots + b_0 f(t_{i+1-m}, y(t_i))]$$

for each  $i = m - 1, m, \dots, N - 1$ .

**NOTE:** the local truncation error of a  $m$ -step *explicit* step is  $O(h^m)$ .

the local truncation error of a  $m$ -step *implicit* step is  $O(h^{m+1})$ .

## ***m*-step explicit step method vs. (*m*-1)-step implicit step method**

- a)** both have the same order of local truncation error,  $O(h^m)$ .
- b)** Implicit method usually has greater stability and smaller round-off errors.

For example, local truncation error of Adams-Bashforth 3-step explicit method,  $\tau_{i+1}(h) = \frac{3}{8} y^{(4)}(\mu_i) h^3$ .

Local truncation error of Adams-Moulton 2-step implicit method,  $\tau_{i+1}(h) = -\frac{1}{24} y^{(4)}(\xi_i) h^3$ .

## Predictor-Corrector Method

*Motivation:* **(1)** Solve the IVP  $y' = e^y$ ,  $0 \leq t \leq 0.25$ ,  $y(0) = 1$  by the three-step Adams-Moulton method.

*Solution:* The three-step Adams-Moulton method is

$$\begin{aligned} w_{i+1} = w_i & \\ & + \frac{h}{24} [9e^{w_{i+1}} + 19e^{w_i} - 5e^{w_{i-1}} \\ & + e^{w_{i-2}}] \end{aligned} \quad Eq.(1)$$

*Eq.(1)* can be solved by Newton's method. However, this can be quite computationally expensive.

**(2)** combine explicit and implicit methods.

## 4<sup>th</sup> order Predictor-Corrector Method

(we will combine 4<sup>th</sup> order Runge-Kutta method + 4<sup>th</sup> order 4-step explicit Adams-Bashforth method + 4<sup>th</sup> order 3-step implicit Adams-Moulton method)

Step 1: Use 4<sup>th</sup> order Runge-Kutta method to compute  $w_0, w_1, w_2$  and  $w_3$ .

Step 2: For  $i = 3, 5, \dots, N$

(a) Predictor sub-step. Use 4<sup>th</sup> order 4-step explicit Adams-Bashforth method to compute a predicated value  $w_{i+1,p}$

$$w_{i+1,p} = w_i + \frac{h}{24} [55f(t_i, w_i) - 59f(t_{i-1}, w_{i-1}) \\ + 37f(t_{i-2}, w_{i-2}) - 9f(t_{i-3}, w_{i-3})]$$

(b) Correction sub-step. Use 4<sup>th</sup> order three-step Adams-Moulton implicit method to compute a correction  $w_{i+1}$  (the approximation at  $i + 1$  time step)

$$w_{i+1} = w_i + \frac{h}{24} [9f(t_{i+1}, w_{i+1,p}) + 19f(t_i, w_i) - 5f(t_{i-1}, w_{i-1}) + f(t_{i-2}, w_{i-2})]$$