3.4 Hermite Interpolation3.5 Cubic Spline Interpolation

Illustration. Consider to interpolate tanh(x) using Lagrange polynomial and nodes $x_0 = -1.5$, $x_1 = 0$, $x_2 = 1.5$. 0.8 tanh(x) 0.6 0.4 0.2 P2(x) -0.2 -0.4 Now interpolate tanh(x)-0.6 -0.8 using nodes $x_0 = -1.5, x_1 =$ 0.5 -0.5 п -1.5 -1 1.5 0, $x_2 = 1.5$. Moreover, Let 1st derivative of interpolating 0.8 New Interpolating polynomial polynomial agree with 0.6 0.4 derivative of tanh(x) at these 0.2 nodes. 0 tanh(x) -0.2 Remark: This is called Hermite -0.4 interpolating polynomial. -0.6 -0.8

-1.5

-0.5

0.5

Hermite Polynomial

Definition. Suppose $f \in C^1[a, b]$. Let $x_0, ..., x_n$ be distinct numbers in [a, b], the Hermite polynomial P(x) approximating f is that:

1.
$$P(x_i) = f(x_i)$$
, for $i = 0, ..., n$

2.
$$\frac{dP(x_i)}{dx} = \frac{df(x_i)}{dx}$$
, for $i = 0, ..., n$

Remark: P(x) and f(x) agree not only function values but also 1st derivative values at x_i , i = 0, ..., n.

Osculating Polynomials

Definition 3.8 Let $x_0, ..., x_n$ be distinct numbers in [a, b]and for i = 0, ..., n, let m_i be a nonnegative integer. Suppose that $f \in C^m[a, b]$, where $m = \max_{0 \le i \le n} m_i$. The osculating polynomial approximating f is the polynomial P(x) of least degree such that $\frac{d^{k}P(x_i)}{dx^k} = \frac{d^k f(x_i)}{dx^k}$ for each i = 0, ..., n and $k = 0, ..., m_i$.

Remark: the degree of P(x) is at most $M = \sum_{i=0}^{n} m_i + n$.

Theorem 3.9 If $f \in C^1[a, b]$ and $x_0, ..., x_n \in [a, b]$ distinct numbers, the Hermite polynomial of degree at most 2n + 1 is:

$$H_{2n+1}(x) = \sum_{j=0}^{n} f(x_j) H_{n,j}(x) + \sum_{j=0}^{n} f'(x_j) \widehat{H}_{n,j}(x)$$

Where

$$H_{n,j}(x) = [1 - 2(x - x_j)L'_{n,j}(x_j)]L^2_{n,j}(x)$$
$$\widehat{H}_{n,j}(x) = (x - x_j)L^2_{n,j}(x)$$

Moreover, if $f \in C^{2n+2}[a, b]$, then

$$f(x) = H_{2n+1}(x) + \frac{\left(x - x_0\right)^2 \dots \left(x - x_n\right)^2}{(2n+2)!} f^{(2n+2)}(\xi(x))$$

for some $\xi(x) \in (a, b)$.

Remark:

- 1. $H_{2n+1}(x)$ is a polynomial of degree at most 2n + 1.
- 2. $L_{n,j}(x)$ is jth Lagrange basis polynomial of degree n.
- 3. $\frac{(x-x_0)^2 ... (x-x_n)^2}{(2n+2)!} f^{(2n+2)}(\xi(x)) \text{ is the error term.}$

Remark:

- 1. When $i \neq j$: $H_{n,j}(x_i) = 0$; $\hat{H}_{n,j}(x_i) = 0$.
- 2. When i = j:

$$\begin{cases} H_{n,j}(x_j) = [1 - 2(x_j - x_j)L'_{n,j}(x_j)]L_{n,j}^2(x_j) = 1\\ \widehat{H}_{n,j}(x_j) = (x_j - x_j)L_{n,j}^2(x_j) = 0\\ \Rightarrow H_{2n+1}(x_j) = f(x_j). \end{cases}$$
3. $H'_{n,j}(x) = L_{n,j}(x) [-2L'_{n,j}(x_j)L_{n,j}(x) + (1 - 2(x - x_j)L'_{n,j}(x_j)) 2L'_{n,j}(x)]\\ \Rightarrow \text{ When } i \neq j : H'_{n,j}(x_i) = 0; \text{ When } i = j : H'_{n,j}(x_j) = 0.$
4. $\widehat{H}'_{n,j}(x) = L_{n,j}^2(x) + 2(x - x_j)L_{n,j}(x)L'_{n,j}(x)$
 $\Rightarrow \text{ When } i \neq j : \widehat{H}'_{n,j}(x_i) = 0; \text{ When } i = j : \widehat{H}'_{n,j}(x_j) = 1.$

Example 3.4.1 Use Hermite polynomial that agrees with the data in the table to find an approximation of f(1.5)

k	x_k	$f(x_k)$	$f'(x_k)$
0	1.3	0.6200860	-0.5220232
1	1.6	0.4554022	-0.5698959
2	1.9	0.2818186	-0.5811571

3rd Degree Hermite Polynomial

• Given distinct x_0, x_1 and values of f and f' at these numbers.

$$H_{3}(x) = \left(1 + 2\frac{x - x_{0}}{x_{1} - x_{0}}\right) \left(\frac{x_{1} - x}{x_{1} - x_{0}}\right)^{2} f(x_{0}) + (x - x_{0}) \left(\frac{x_{1} - x}{x_{1} - x_{0}}\right)^{2} f'(x_{0}) + \left(1 + 2\frac{x_{1} - x}{x_{1} - x_{0}}\right) \left(\frac{x_{0} - x}{x_{0} - x_{1}}\right)^{2} f(x_{1}) + (x - x_{1}) \left(\frac{x_{0} - x}{x_{0} - x_{1}}\right)^{2} f'(x_{1})$$

Hermite Polynomial by Divided Differences

Suppose $x_0, ..., x_n$ and f, f' are given at these numbers. Define $z_0, ..., z_{2n+1}$ by $z_{2i} = z_{2i+1} = x_i$, for i = 0, ..., n

Construct divided difference table, but use

 $f'(x_0), f'(x_1), \dots, f'(x_n)$ to set the following undefined divided difference: $f[z_0, z_1], f[z_2, z_3], \dots, f[z_{2n}, z_{2n+1}].$ Namely, $f[z_0, z_1] = f'(x_0), f[z_2, z_3] = f'(x_1), \dots$ $f[z_{2n}, z_{2n+1}] = f'(x_n).$

The Hermite polynomial is

$$H_{2n+1}(x) = f[z_0] + \sum_{k=1}^{2n+1} f[z_0, \dots, z_k](x - z_0) \dots (x - z_{k-1})$$

Example 3.4.2 Use divided difference method to determine the Hermite polynomial that agrees with the data in the table to find an approximation of f(1.5)

k	x_k	$f(x_k)$	$f'(x_k)$
0	1.3	0.6200860	-0.5220232
1	1.6	0.4554022	-0.5698959
2	1.9	0.2818186	-0.5811571

Divided Difference Notation for Hermite Interpolation

- Divided difference notation for Hermite polynomial interpolating 2 nodes: x₀, x₁.
 H₃(x)
- $= f(x_0) + f'(x_0)(x x_0) + f[x_0, x_0, x_1](x x_0)^2$ $+ f[x_0, x_0, x_1, x_1](x - x_0)^2(x - x_1)$

Problems with High Order Polynomial Interpolation



• 21 equal-spaced numbers to interpolate $f(x) = \frac{1}{1+25x^2}$. The interpolating polynomial oscillates between interpolation points.

3.5 Cubic Splines

- Idea: Use piecewise polynomial interpolation, i.e, divide the interval into smaller sub-intervals, and construct different low degree polynomial approximations (with small oscillations) on the subintervals.
- Example. Piecewise-linear interpolation



- Challenge: If $f'(x_i)$ are not known, can we still generate interpolating polynomial with continuous derivatives?
- **Spline**: A spline consists of a long strip of wood (a lath) fixed in position at a number of points. The lath will take the shape which minimizes the energy required for bending it between the fixed points, and thus adopt the smoothest possible shape.



- In mathematics, a spline is a function that is piecewise-defined by polynomial functions, and which possesses a high degree of smoothness at the places where the polynomial pieces connect.
- **Example**. Irwin-Hall distribution. Nodes are -2, -1, 0, 1, 2. $f(x) = \begin{cases} \frac{1}{4}(x+2)^3 & -2 \le x \le -1 \\ \frac{1}{4}(3|x|^3 - 6x^2 + 4) & -1 \le x \le 1 \\ \frac{1}{4}(2-x)^3 & 1 \le x \le 2 \end{cases}$ Notice: $f'(-1) = \frac{3}{4}, f'(1) = -\frac{3}{4}, f''(-1) = \frac{6}{4}, f''(1) = \frac{6}{4}.$

 Piecewise-polynomial approximation using cubic polynomials between each successive pair of nodes is called cubic spline interpolation.

Definition 3.10 Given a function f on [a, b] and nodes $a = x_0 < b$ $\cdots < x_n = b$, a cubic spline interpolant S for f satisfies: (a) S(x) is a cubic polynomial $S_i(x)$ on $[x_i, x_{i+1}]$ with: $S_{j}(x) = a_{j} + b_{j}(x - x_{j}) + c_{j}(x - x_{j})^{2} + d_{j}(x - x_{j})^{3}$ $\forall i = 0, 1, ..., n - 1.$ (b) $S_i(x_i) = f(x_i)$ and $S_i(x_{i+1}) = f(x_{i+1}), \forall j = 0, 1, ..., n-1$. (c) $S_i(x_{i+1}) = S_{i+1}(x_{i+1}), \forall j = 0, 1, ..., n-2.$ **Remark:** (c) is derived from (b). (d) $S'_{i}(x_{i+1}) = S'_{i+1}(x_{i+1}), \forall j = 0, 1, ..., n-2.$ (e) $S''_{i}(x_{i+1}) = S''_{i+1}(x_{i+1}), \forall j = 0, 1, ..., n-2.$ (f) One of the following boundary conditions: (i) $S''(x_0) = S''(x_n) = 0$ (called free or natural boundary) (ii) $S'(x_0) = f'(x_0)$ and $S'(x_n) = f'(x_n)$ (called clamped boundary) 16



The spline segment $S_j(x)$ is on $[x_j, x_{j+1}]$. The spline segment $S_{j+1}(x)$ is on $[x_{j+1}, x_{j+2}]$. Things to match at interior point x_{j+1} :

- Their function values: $S_j(x_{j+1}) = S_{j+1}(x_{j+1}) = f(x_{j+1})$
- First derivative values: $S'_{j}(x_{j+1}) = S'_{j+1}(x_{j+1})$
- Second derivative values: $S''_{j}(x_{j+1}) = S''_{j+1}(x_{j+1})$

Example 3.5.1 Construct a natural spline S(x) through (1,2), (2,3) and (3.5).

Building Cubic Splines

- Define: $S_j(x) = a_j + b_j(x x_j) + c_j(x x_j)^2 + d_j(x x_j)^3$ and $h_j = x_{j+1} - x_j, \forall j = 0, 1, ..., (n-1).$
- Also define $a_n = f(x_n)$; $b_n = S'(x_n)$; $c_n = S''(x_n)/2$. From Definition 3.10:
- 1) $S_i(x_i) = a_i = f(x_i)$ for j = 0, 1, ..., (n-1). 2) $S_{i+1}(x_{i+1}) = a_{i+1} = a_i + b_i h_i + c_i (h_i)^2 + d_i (h_i)^3$ for j = 0, 1, ..., (n - 1). Note: $a_n = a_{n-1} + b_{n-1}h_{n-1} + c_{n-1}(h_{n-1})^2 + d_{n-1}(h_{n-1})^3$ 3) $S'_i(x_i) = b_i$, also $b_{i+1} = b_i + 2c_ih_i + 3d_i(h_i)^2$ for j = 0, 1, ..., (n - 1). 4) $S''_{i}(x_{i}) = 2c_{i}$, also $c_{i+1} = c_{i} + 3d_{i}h_{i}$ for j = 0, 1, ..., (n - 1).
- 5) Natural or clamped boundary conditions

Solve a_j , b_j , c_j , d_j by substitution:

1. Solve Eq. 4) for $d_j = \frac{c_{j+1}-c_j}{3h_j}$, and substitute into Eqs. 2) and 3) to get:

2.
$$a_{j+1} = a_j + b_j h_j + \frac{h_j^2}{3} (2c_j + c_{j+1});$$
 (3.18)
 $b_{j+1} = b_j + h_j (c_j + c_{j+1}).$ (3.19)

3. Solve for b_i in Eq. (3.18) to get:

$$b_j = \frac{1}{h_j} \left(a_{j+1} - a_j \right) - \frac{h_j}{3} \left(2c_j + c_{j+1} \right). \tag{3.20}$$

Reduce the index by 1 to get:

$$b_{j-1} = \frac{1}{h_{j-1}} \left(a_j - a_{j-1} \right) - \frac{h_{j-1}}{3} \left(2c_{j-1} + c_j \right).$$

4. Substitute b_j and b_{j-1} into Eq. (3.19):

$$h_{j-1}c_{j-1} + 2(h_{j-1} + h_j)c_j + h_jc_{j+1} = (3.21)$$

$$\frac{3}{h_j}(a_{j+1} - a_j) - \frac{3}{h_{j-1}}(a_j - a_{j-1})$$

for $j = 1, 2, ..., (n-1).$

Solving the Resulting Equations

$$\forall j = 1, 2, \dots, (n - 1)$$

$$h_{j-1}c_{j-1} + 2(h_{j-1} + h_j)c_j + h_jc_{j+1}$$

$$= \frac{3}{h_j}(a_{j+1} - a_j) - \frac{3}{h_{j-1}}(a_j - a_{j-1})$$
(3.21)

Remark: (n-1) equations for (n+1) unknowns $\{c_j\}_{j=0}^n$. Eq. (3.21) is solved with boundary conditions.

• Once compute c_i , we then compute:

$$b_{j} = \frac{(a_{j+1} - a_{j})}{h_{j}} - \frac{h_{j}(2c_{j} + c_{j+1})}{3} \quad (3.20)$$
and
$$(c_{i+1} - c_{i}) \quad (a_{j} - c_{j}) \quad (a_{j} - c_{j})$$

$$d_j = \frac{(j+1-j)}{3h_j}$$
 (3.17) for $j = 0, 1, 2, ..., (n-1)$

Building Natural Cubic Spline

• Natural boundary condition:

1.
$$0 = S''_0(x_0) = 2c_0 \to c_0 = 0$$

2.
$$0 = S''_n(x_n) = 2c_n \to c_n = 0$$

- **Step 1**. Solve Eq. (3.21) together with $c_0 = 0$ and $c_n = 0$ to obtain $\{c_j\}_{j=0}^n$.
- **Step 2**. Solve Eq. (3.20) to obtain $\{b_j\}_{j=0}^{n-1}$.
- **Step 3**. Solve Eq. (3.17) to obtain $\{d_j\}_{j=0}^{n-1}$.

Building Clamped Cubic Spline

Clamped boundary condition: a) $S'_0(x_0) = b_0 = f'(x_0)$ b) $S'_{n-1}(x_n) = b_n = b_{n-1} + h_{n-1}(c_{n-1} + c_n) = f'(x_n)$ Remark: a) and b) gives additional equations: $2h_0c_0 + h_0c_1 = \frac{3}{h_0}(a_1 - a_0) - 3f'(x_0) \qquad (a)$ $h_{n-1}c_{n-1} + 2h_{n-1}c_n = -\frac{3}{h_{n-1}}(a_n - a_{n-1}) + 3f'(x_n)$ (*b*) **Step 1**. Solve Eq. (3.21) together with Eqs. (a) and (b) to obtain $\{c_i\}_{i=0}^n$.

Step 2. Solve Eq. (3.20) to obtain $\{b_j\}_{j=0}^{n-1}$.

Step 3. Solve Eq. (3.17) to obtain $\{d_j\}_{j=0}^{n-1}$.

Example 3.5.4 Let $(x_0, f(x_0)) =$ (0,1), $(x_1, f(x_1)) = (1, e), (x_2, f(x_2)) = (2, e^2),$ $(x_3, f(x_3)) = (3, e^3)$. And $f'(x_0) = e, f'^{(x_3)} = e^3$. Determine the clamped spline S(x). **Theorem 3.11** If f is defined at the nodes: $a = x_0 < \cdots < x_n = b$, then f has a unique natural spline interpolant S on the nodes; that is a spline interpolant that satisfied the natural boundary conditions S''(a) = 0, S''(b) = 0.

Theorem 3.12 If f is defined at the nodes: $a = x_0 < \cdots < x_n = b$ and differentiable at a and b, then f has a unique clamped spline interpolant S on the nodes; that is a spline interpolant that satisfied the clamped boundary conditions S'(a) = f'(a), S'(b) = f'(b).

Error Bound

Theorem 3.13 If $f \in C^4[a, b]$, let M =

 $\max_{a \le x \le b} |f^4(x)|.$ If S is the unique clamped cubic

spline interpolant to f with respect to the nodes:

$$a = x_0 < \dots < x_n = b, \text{ then with}$$
$$h = \max_{0 \le j \le n-1} (x_{j+1} - x_j)$$
$$\max_{a \le x \le b} |f(x) - S(x)| \le \frac{5Mh^4}{384}.$$